Fig 1

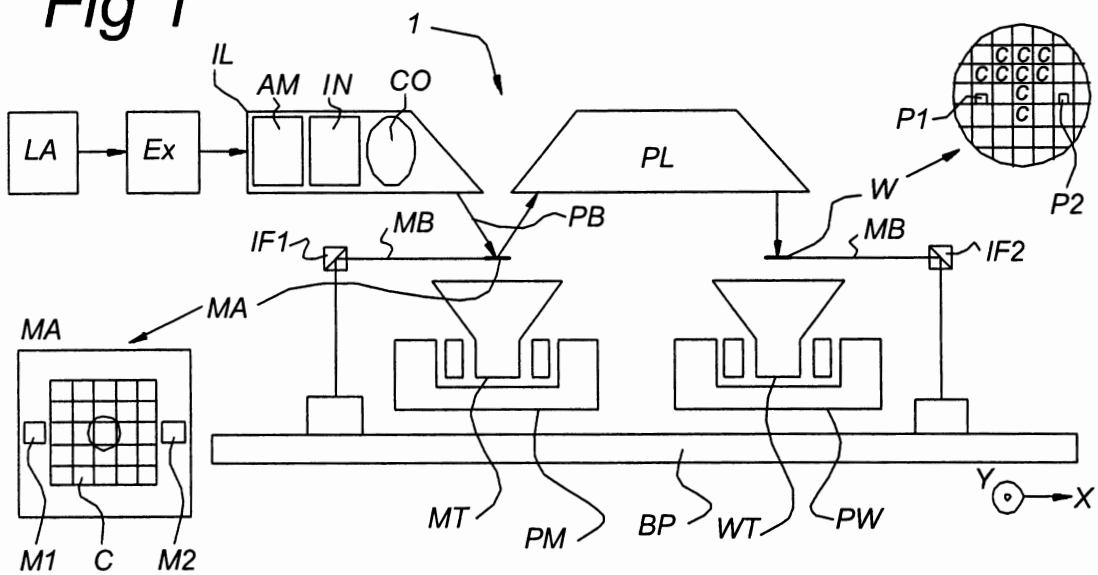

1
IL
AM
IN
CO
LA
Ex
PL
P1
P2
W
MB
PB
IF1
MB
IF2
MA
MA
M1
C
M2
MT
PM
BP
WT
PW
Y
X

Fig 2

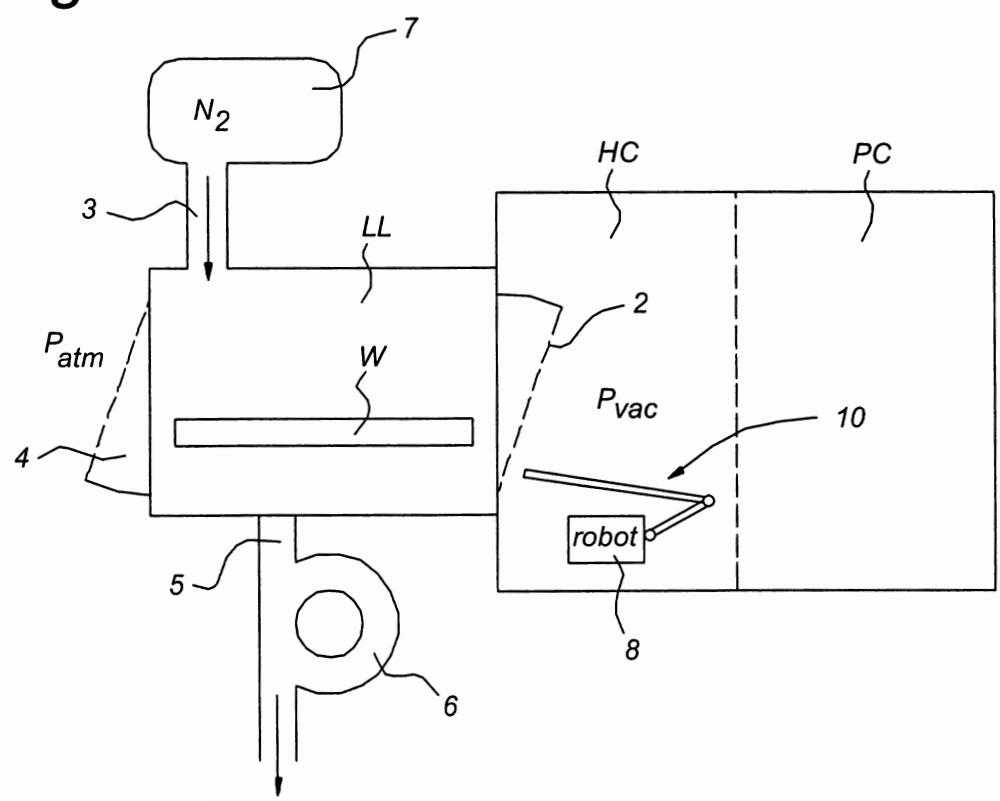

7
N_2
HC
PC
3
LL
2
P_{atm}
W
P_{vac}
10
4
robot
5
8
6

Fig 3a

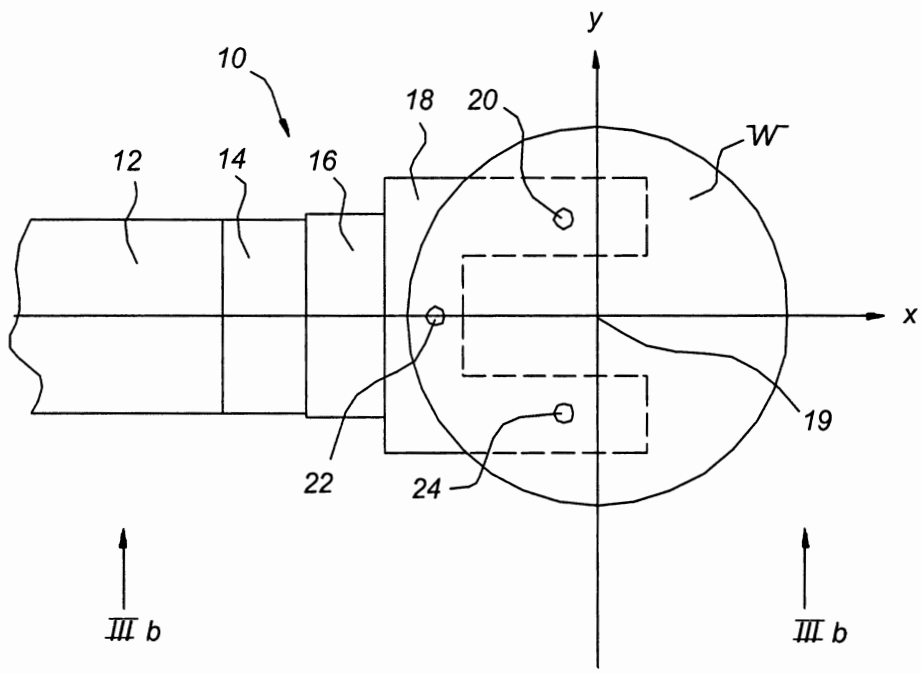

y
10
18
20
W
12
14
16
x
19
22
24
III b
III b

Fig 3b

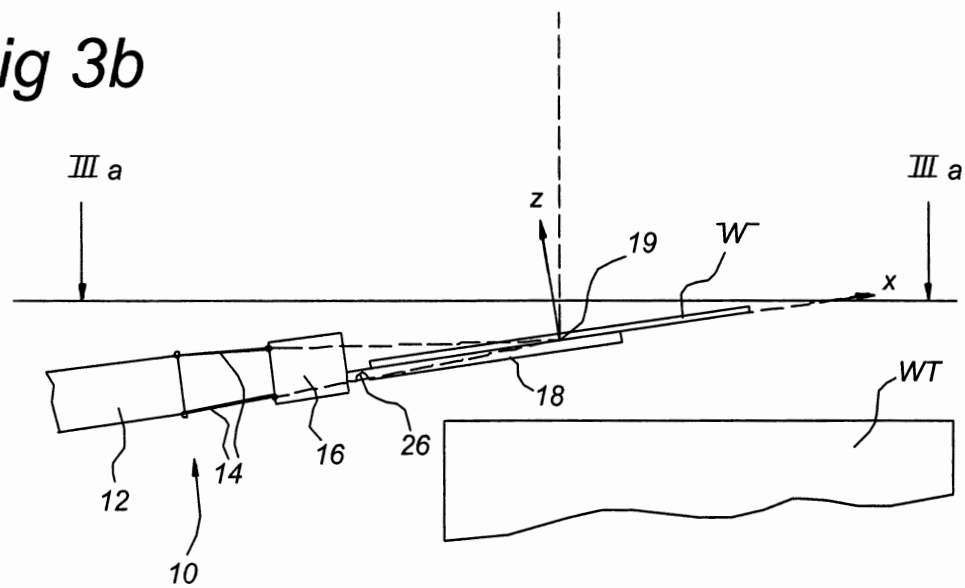

III a
III a
z
19
W
x
WT
18
26
16
14
12
10

Fig 4a

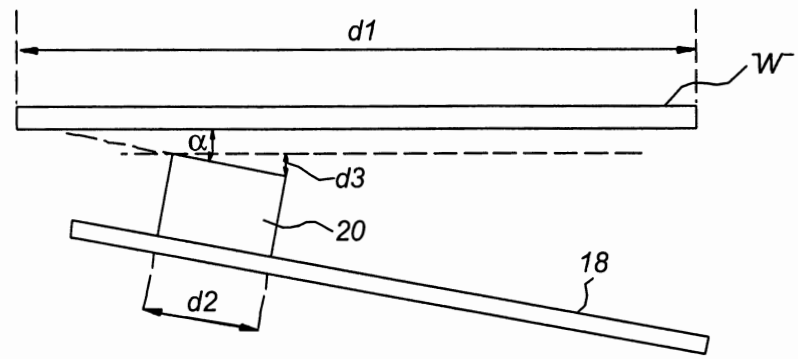


Fig 4b

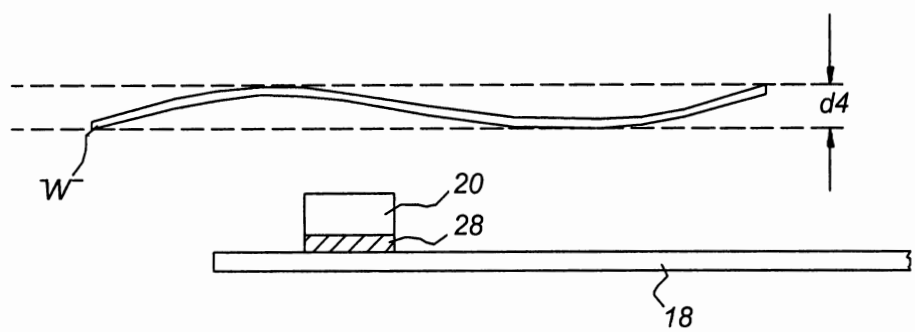


Fig 4c

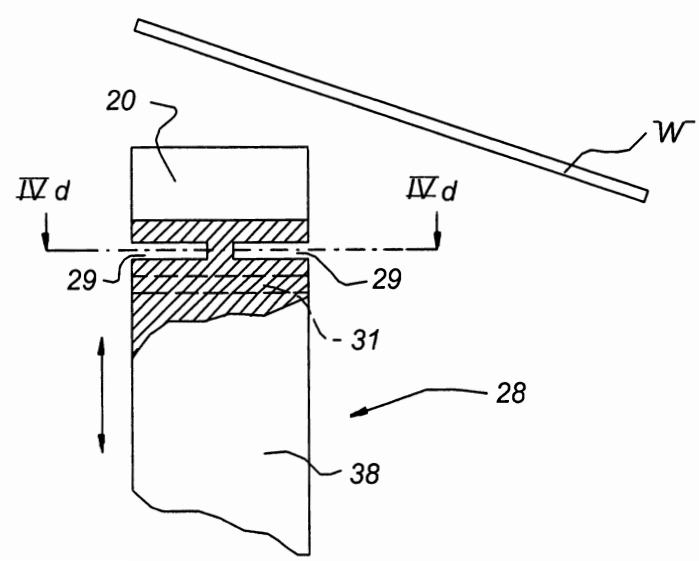


Fig 4d

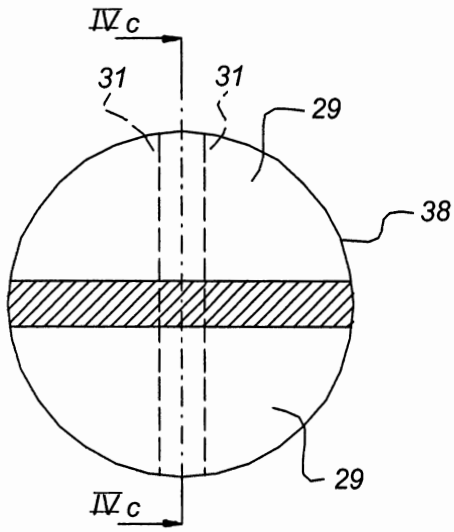


Fig 4e

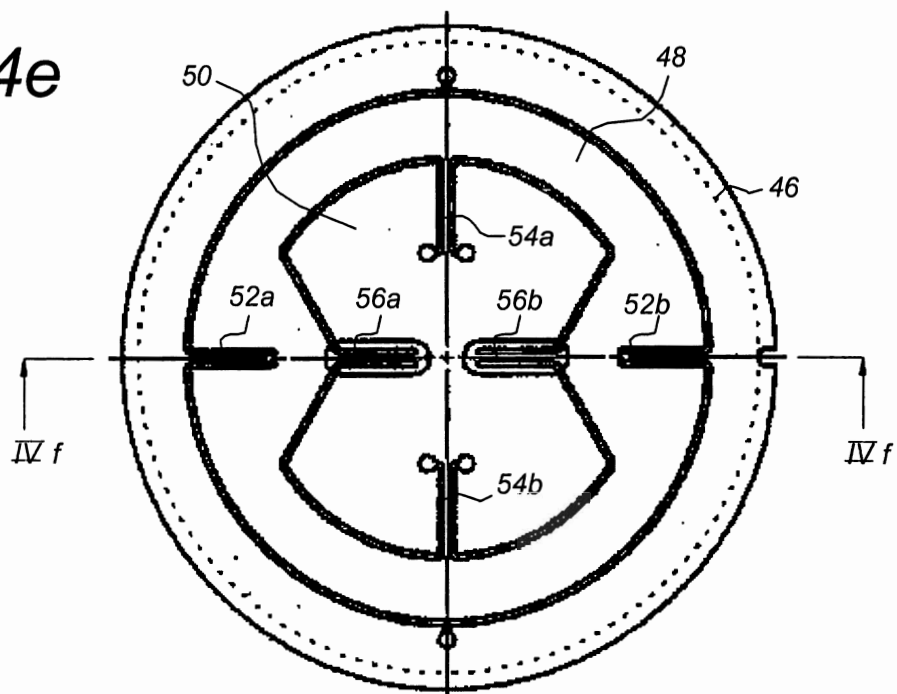


Fig 4f

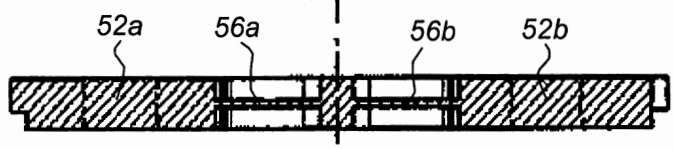


Fig 5

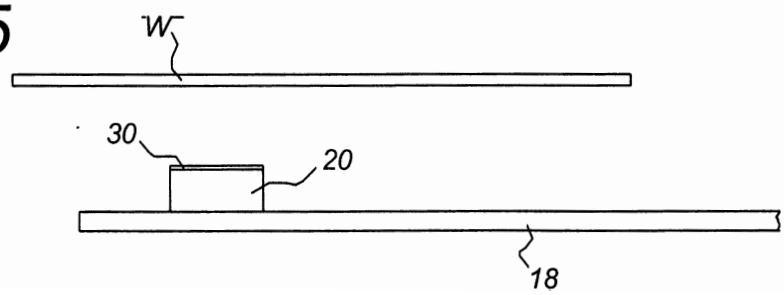


Fig 6a

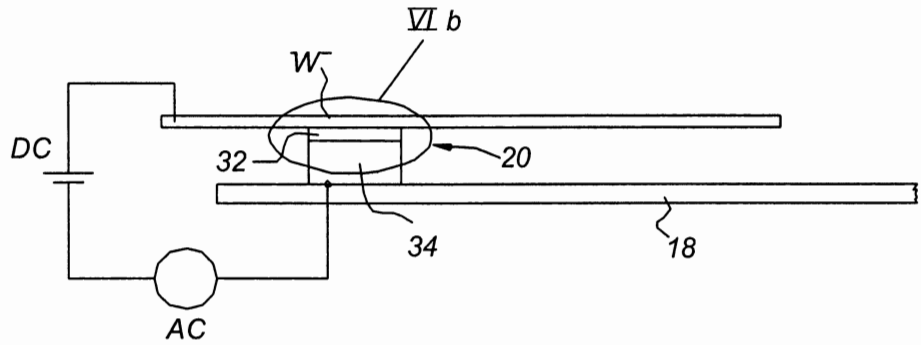


Fig 6b

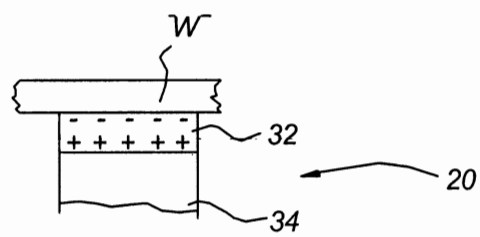


Fig 7

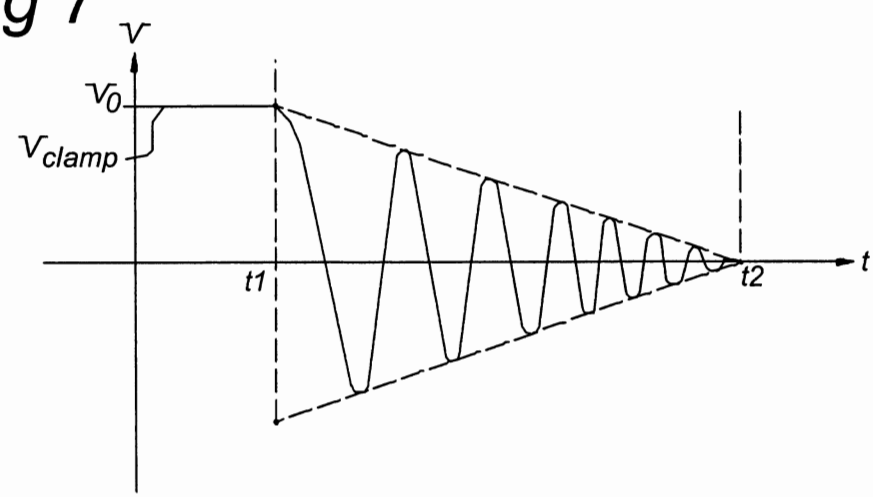


Fig 8

