DESCRIPTION

Title of Invention:

BATTERY CONTROL DEVICE, BATTERY CONTROL SUPPORT DEVICE, BATTERY CONTROL SYSTEM, BATTERY CONTROL METHOD, BATTERY CONTROL SUPPORT METHOD, AND RECORDING MEDIUM

Technical Field

[0001]

The present invention relates to a battery control system, a battery control device, a battery control support device, a battery control method, a battery control support method, and a program, and particularly relates to a battery control system, a battery control device, a battery control support device, a battery control method, a battery control support method, and a program that control discharge or charge of a battery connected to a power system.

Background Art

[0002]

In a power system, as a method for adjusting power demand and supply, a method has been adopted, which mainly uses the output control function of thermal power generation equipment of a thermal electric power plant, and properly combines an output adjustment function of pumping-up hydraulic power generation.

[0003]

However, if renewable power sources, which are typified by photovoltaic power generation and wind power generation where the power generation amount depends on weather conditions, are connected to the a power system as distributed power sources, there may arise the situation in which output variations of the distributed power sources cause a greater loss of balance between power demand and supply than in the related art. As a result, in order to compensate for a variation in the balance of power demand and supply that is caused by the distributed power sources, the only method that is likely to be insufficient is the method that adjusts the balance of power demand and supply by mainly using thermal power generation equipment, as in the related art. Therefore, in addition to the related art, a more effective technology for adjusting the balance between power supply and demand is needed.

[0004]

As one technology that can address this need to adjust the power demand and supply

balance, there is a promising technology that uses distributed energy storage (hereinafter, an energy storage will be called "ES") such as "a storage battery" that interconnects to the distribution network of a power system, and is expected to come into widespread use from now on.

[0005]

Patent Literature 1 describes a power system control method that adjusts power demand and supply by using a secondary battery (ES) in a consumer side.

[0006]

In the power system control method described in Patent Literature 1, a power system control device acquires an amount of charge in a secondary battery, and further acquires a schedule of power supply to a power system that is generated based on a power demand forecast from a central power supply instruction office or the like. The power system control device determines an operation schedule of the secondary battery based on the amount of charge in the secondary battery and the power supply schedule.

[0007]

When the power system control device determines the operation schedule of the secondary battery, the power system control device transmits the operation schedule to a secondary battery control system that controls the operation of the secondary battery.

[0008]

When the secondary battery control system receives the operation schedule from the power system control device, the secondary battery control system controls charge and discharge of the secondary battery in accordance with the operation schedule, irrespective of the actual state of the power system.

[0009]

Furthermore, Patent Literature 2 describes a system in which a central controller acquires state of charge information of a plurality of battery cells sampled at the same point of time via a local monitor and an upper controller.

Citation List

Patent Literature

[0010]

Patent Literature 1: JP2006-94648A

Patent Literature 2: JP2010-146571A

Summary of Invention

Technical Problem

[0011]

The amount of power supplied from a renewable power sourse to a power system varies according to charges, over a short period of time, in the weather conditions. For example, in a photovoltaic power generation apparatus, the amount of power that is supplied varies as a result of small clouds that pass in front of the sun.

[0012]

In practice, it is difficult to design a power supply schedule that can anticipate, over a short period of time, the degree of change in weather conditions.

[0013]

Consequently, in the power system control method described in Patent Literature 1, it is difficult, in practice, to have the operation schedule (control information) of the secondary battery that is created by the power system control device that is an upper device, reflect chandes, in the amount of supplied power, that will occur due to changes, over a short period of time, in weather conditions.

[0014]

Accordingly, the power system control method described in Patent Literature 1 has the problem of being unable to cope with the actual variation state of the power system, in which the control information from the upper device is not reflected.

[0015]

The above problem is not solved either by the system described in Patent Literature 2 that does not control charge and discharge of battery cells, as a matter of course.

[0016]

An object of the present invention is to provide a battery control system, a battery control device, a battery control support device, a battery control method, a battery control support method and a program that can solve the above-described problem.

Solution to Problem

[0017]

A battery control device according to a first aspect of the present invention is a battery control device controlling an operation of a battery connected to a power system, the device includes:

detection means that detects state information that shows the state of said battery;

first communication means that transmits the state information to an external device, and receives operation control information, that is generated based on:

the state information, and

a power amount that is allotted to said batteries that are controlled by N (N is a number that is 1 or larger) battery control devices, for controlling the operation of the battery from the external device; and

control means that controls the operation of the battery based on the operation control information received by the first communication means.

[0017a]

A battery control device according to a second aspect of the present invention is a battery control device controlling an operation of a battery that is connected to a power system, the device comprising:

detection means that detects a state of an interconnection point of said power system and said battery;

first communication means that transmits the state of the interconnection point to an external device, and receives operation control information, that is generated based on;

the state of the interconnection point, and

an adjustment target voltage that is a voltage of a voltage adjustment target spot in said power system, to control the operation of said battery from the external device; and

control means that controls the operation of said battery based on the operation control information received by said first communication means.

[0018]

A battery control support device according to a third aspect of the present invention is a battery control support device communicating with a battery control device controlling an operation of a battery connected to a power system, the device includes:

second communication means that communicates with the battery control device, and receives state information that shows the state of said battery from each of N (N is an integer that is one or larger) battery control devices;

recognition means that recognizes a power amount that is allotted to said batteries that are controlled by the N battery control devices; and

processing means that generates operation control information for controlling the

operation of the battery, based on the state information and the power amount that is recognized by the recognition means, and transmits the operation control information from the second communication means to the battery control device.

[0018a]

A battery control support device according to a fourth aspect of the present invention is a battery control support device communicating with a battery control device controlling an operation of a battery connected to a power system, the device comprising:

second communication means that receives a state of the interconnection point of said power system and said battery;

recognition means that recognizes an adjustment target voltage that is a voltage of a voltage adjustment target spot in said power systems; and

processing means that generates operation control information to control the operation of said battery, based on the state of the interconnection point and the adjustment target voltage that is recognized by said recognition means, and transmits the operation control information from said second communication means to said battery control device.

[0019]

A battery control system according to a fifth aspect of the present invention is a battery control system including a first control device that controls an operation of a battery connected to a power system, and a second control device that communicates with the first control device,

the first control device includes;

detection means that detects state information that shows the state of said,

first communication means that transmits the state information to the second control device, and receives operation control information, that is generated based on:

the state information, and

a power amount that is allotted to said batteries that are controlled by N (N is a number that is 1 or larger) battery control devices, to control the operation of the battery from the second control device, and

control means that controls the operation of the battery based on the operation control information received by the first communication means, and

the second control device comprises:

second communication means that communicates with the first control means, and receives state information that shows the state of said battery from each of N (N is an integer that is one or larger) battery control devices;

recognition means that recognizes a power amount that is allotted to said batteries that are controlled by the N battery control devices; and

processing means that generates the operation control information based on the state information received by the second communication means and based on the power amount recognized by the recognition means, and transmits the operation control information from the second communication means to the first control device.

[0020]

A battery control method according to a sixth aspect of the present invention is a battery control method that is performed by a battery control device that controls an operation of a battery connected to a power system, wherein the method includes;

detecting state information that shows the state of said battery;

transmitting the state information to an external device, and receiving operation control information, that is generated based on:

the state information, and

a power amount that is allotted to said batteries that are controlled by N (N is a number that is 1 or larger) battery control devices, to control the operation of the battery from the external device; and

controlling the operation of the battery based on the operation control information.

[0021]

A battery control support method according to a seventh aspect of the present invention is a battery control support method performed by a battery control support device that communicates with a battery control device that controls an operation of a battery connected to a power system, wherein the method includes;

receiving state information that shows the state of said battery from each of N (N is an integer that is one or larger) battery control devices;

recognizing a power amount that is allotted to said batteries that are controlled by the N battery control devices; and

generating operation control information to control the operation of the battery, based on the state information and the power amount, and

transmitting the operation control information to the battery control device.

[0022]

A battery control method according to an eight aspect of the present invention is a battery control method that is performed by a battery control system including a first control device that controls an operation of a battery connected to a power system, and a second control device that communicates with the first control device, wherein

the first control device detects state information that shows the state of said battery,

the second control device recognizes a power amount that is allotted to said batteries that are controlled by the N battery control devices,

the first control device transmits the state information to the second control device,

the second control device receives the state information,

the second control device generates operation control information to control the operation of the battery, based on the state information and the power amount,

the second control device transmits the operation control information to the first control device,

the first control device receives the operation control information, and

the first control device controls the operation of the battery, based on operation control information.

[0023]

A recording medium according to a ninth aspect of the present invention is a computer-readable recording medium recording a program for causing a computer to execute:

a detection procedure of detecting state information that shows the state of said battery;

a communication procedure of transmitting the state information to an external device, and receiving operation control information, that is generated based on:

the state information, and

a power amount that is allotted to said batteries that are controlled by N (N is a number that is 1 or larger) battery control devices, to control an operation of the battery from the external device; and

a control procedure of controlling the operation of the battery, based on the operation control information.

[0024]

A recording medium according to a tenth aspect of the present invention is a computer-readable recording medium recording a program for causing a computer to execute:

a reception procedure of receiving state information that shows the state of said battery from each of N (N is an integer that is one or larger) battery control devices, from a battery control device that controls an operation of the battery connected to the power system;

a recognition procedure of recognizing a state information that shows the state of said

battery from each of N (N is an integer that is one or larger) battery control devices; and

a processing procedure of generating operation control information to control the operation of the battery, based on the state information and the power amount, and transmitting the operation control information to the battery control device.

Advantageous Effect of Invention

[0025]

According to the present invention, the first control device (the battery control device) controls the operation of the battery based on the operation control information provided from the second control device (the battery control support device) and the state of the power system, and thereby it becomes possible to adjust the operation of the battery in response to an actual change in the state of the power system while following the operation control information.

Brief Description of Drawings

[0026]

[Figure 1] Figure 1 is a diagram showing power control system 1000 that adopts a battery control system of a first exemplary embodiment of the present invention.

[Figure 2] Figure 2 is a diagram showing examples of local charge and discharge device 100, storage battery SCADA 200 and power supply instruction section 300A.

[Figure 3A] Figure 3A is a diagram showing an example of a storage battery distribution factor curve.

[Figure 3B] Figure 3B is a diagram showing an example of the storage battery distribution factor curve.

[Figure 4] Figure 4 is a diagram showing an example of a charge and discharge gain line.

[Figure 5] Figure 5 is a sequence diagram for explaining a P_{ES} derivation operation.

[Figure 6] Figure 6 is a sequence diagram for explaining a recognition operation.

[Figure 7] Figure 7 is a sequence diagram for explaining an allotment operation.

[Figure 8] Figure 8 is a diagram showing a local charge and discharge gain line.

[Figure 9] Figure 9 is a sequence diagram for explaining a charge and discharge control operation.

[Figure 10] Figure 10 is a diagram showing a storage battery distribution factor curve in which a storage battery distribution factor is kept at one irrespective of a value of SOC.

[Figure 11] Figure 11 is a diagram showing a reference local charge and discharge gain line.

[Figure 12] Figure 12 is a diagram showing an example of the reference local charge and discharge gain line that is corrected.

[Figure 13] Figure 13 is a flowchart for explaining an example of a method for correcting the reference local charge and discharge gain line.

[Figure 14] Figure 14 is a diagram for explaining another example of a method for giving an offset.

[Figure 15] Figure 15 is a diagram showing a local charge and discharge device including detector 101, communicator 102 and arithmetic operation section 104.

[Figure 16] Figure 16 is a diagram showing storage battery SCADA 200 including communicator 201, recognition section 203 and arithmetic operation section 204.

[Figure 17] Figure 17 is a diagram showing power control system 1000A that adopts a battery control system of a second exemplary embodiment of the present invention.

[Figure 18] Figure 18 is a diagram showing an example of local charge and discharge device 100A.

[Figure 19] Figure 19 is a diagram showing an example of sensor-incorporating switch slave station 700A.

[Figure 20] Figure 20 is a diagram showing an example of ESMS 200A.

[Figure 21] Figure 21 is a sequence diagram for explaining a setting operation.

[Figure 22] Figure 22 is a sequence diagram for explaining a generation operation.

[Figure 23] Figure 23 is a sequence diagram for explaining a power control operation.

Description of Embodiments

[0027]

Hereinafter, exemplary embodiments of the present invention will be described with reference to the drawings.

[0028]

(First Exemplary Embodiment)

Figure 1 is a diagram showing power control system 1000 that adopts a battery control system of a first exemplary embodiment of the present invention.

[0029]

In Figure 1, power control system 1000 includes power system 1, photovoltaic power generator 2, N (N is an integer that is 1 or larger) power storage devices 3, N local charge and discharge devices 100, storage battery SCADA (Supervisory Control And Data Acquisition) 200, and power supply instruction section 300A in central power supply instruction office 300. The power system 1 includes thermal power generation equipment 4, distribution transformer 5 and distribution line 6. Note that photovoltaic power generator 2 may be included in power system 1. The battery control system includes N of local charge and discharge devices 100, and storage battery SCADA 200.

[0030]

Power control system 1000 limits variation in system frequency that result from changes in the amount of power generated by photovoltaic power generator 2, due to whether conditions, which is of concern to power system 1, to which photovoltaic power generator 2 is

interconnected, by controlling a power generation operation of thermal power generation equipment 4 and charge and discharge operations of N of power storage devices 3.

[0031]

Power system 1 is a system for supplying power to load 7 for use by consumers. Power system 1 also includes other devices (for example, a switch, an upper electric transformer, an SVR (Step Voltage Regulator) and a pole transformer), but for simplification of explanation, these devices are omitted.

[0032]

Photovoltaic power generator 2 is an example of a renewable power source. The renewable power sources are not limited to a photovoltaic power generator and alternative renewable power sources can be used. For example, as the renewable power source, a wind power generator, a hydroelectric generator (including a small hydroelectric generator that generates power of 1,000 kilowatts or less), a geothermal power generator, or a power source in which these power generators coexist may be used.

[0033]

Power storage device 3 is an example of a battery (a storage battery), and can be, for example, a lithium ion battery, a nickel-metal hydride battery, a sodium-sulfur battery, or a redox flow battery.

[0034]

In the present exemplary embodiment, N power storage devices 3 are in one-to-one correspondence with N local charge and discharge devices 100. Power storage device 3 may be contained in corresponding local charge and discharge device 100, or does not have to be contained in corresponding local charge and discharge device 100. In the present exemplary embodiment, respective power storage devices 3 are contained in corresponding local charge and discharge devices 100 (see Figure 2).

[0035]

Respective local charge and discharge devices 100 control charge and discharge operations of corresponding power storage devices 3.

[0036]

Storage battery SCADA 200 manages respective local charge and discharge devices 100 and respective power storage devices 3.

[0037]

Power supply instruction section 300A adjusts a power generation operation of thermal power generation equipment 4, and charge and discharge operations of N of power storage

devices 3, and thereby limits a variation in the system frequency.

[0038]

Figure 2 is a diagram showing examples of local charge and discharge device 100, storage battery SCADA 200 and power supply instruction section 300A. In Figure 2, those having the same configurations as those shown in Figure 1 are assigned with the same reference signs. In order to simplify explanation, Figure 2 shows one local charge and discharge device 100 containing one power storage device 3 among N of power storage devices 3 and N of local charge and discharge devices 100.

[0039]

First, local charge and discharge device 100 will be described.

[0040]

Local charge and discharge device 100 is an example of a first control device or a battery control device. Local charge and discharge device 100 controls an operation of power storage device 3 that is connected to power system 1. Local charge and discharge device 100 includes detector 101, communicator 102, frequency meter 103 and arithmetic operation section 104.

[0041]

Detector 101 is an example of first detection means (detection means). Detector 101 detects SOC (State of Charge) of power storage device 3. The SOC of power storage device 3 takes a value within a range of 0 to 1. The SOC of power storage device 3 is an example of battery-related information that indicates a state of power storage device 3 or state information, or battery information for determining a chargeable and dischargeable capacity of power storage device 3. Note that the battery-related information, the state information and the battery information are not limited to the SOC of power storage device 3 and alternative information can be used. For example, a cell temperature, a current amount and a voltage of power storage device 3 may be used.

[0042]

Communicator 102 is an example of first communicating means. Communicator 102 communicates with storage battery SCADA 200.

[0043]

Frequency meter 103 is an example of second detection means. Frequency meter 103 detects a system frequency (a system frequency of power system 1). The system frequency varies in accordance with a power demand and supply balance state. The system frequency is an example of a state of the power system. Note that frequency meter 103 may be inside or outside local charge and discharge device 100.

[0044]

Arithmetic operation section 104 is an example of control means.

[0045]

Arithmetic operation section 104 executes an information acquiring operation (transmission and reception processing) of obtaining allotment information that shows allotment for controlling the balance between power demand and supply from storage battery SCADA 200, and a control operation (battery operation control processing) to control a charge and discharge operation of power storage device 3 by using the allotment information.

[0046]

Note that the allotment information is information that relates to the charge and discharge operation of power storage device 3 and that is allotted to local charge and discharge device 100 and power storage device 3 in order to limit a variation in the system frequency.

[0047]

Arithmetic operation section 104 repeatedly executes the information acquiring operation at time intervals, and repeatedly executes the control operation at time intervals shorter than the time intervals of the information acquiring operation.

[0048]

For example, arithmetic operation section 104 repeatedly executes the information acquiring operation at periods T (for example, T = one minute), and repeatedly executes the control operation at periods T_I (for example, T_I = 0.1 seconds). Period T is an example of a predetermined time interval.

[0049]

Note that period T and period T_I are not limited to one minute and 0.1 seconds, and period T can be longer than period T_I.

[0050]

Furthermore, both or any one of the operation time intervals of the information acquiring operation and the operation time interval of the control operation do not have to be fixed, and the shortest time among the respective operation time intervals of the information acquiring operation can be longer than the longest time among the respective operation time intervals of the control operation.

[0051]

Furthermore, arithmetic operation section 104 may execute the information acquiring operation in response to the information request that requests SOC from storage battery SCADA 200, or may autonomously execute the information acquiring operation.

[0052]

Here, the information acquiring operation of arithmetic operation section 104 will be described.

[0053]

Arithmetic operation section 104 transmits the SOC of power storage device 3 detected by detector 101 to storage battery SCADA 200 from communicator 102, together with identification information (hereinafter, called "ID") of power storage device 3.

[0054]

The ID is stored in each of local charge and discharge device 100 and storage battery SCADA 200. Storage battery SCADA 200 identifies power storage device 3, from which the SOC is reported, by using the ID transmitted with the SOC of power storage device 3.

[0055]

Communicator 102 transmits the SOC and ID of power storage device 3 to storage battery SCADA 200, and thereafter receives allotment information from storage battery SCADA 200.

[0056]

The allotment information is set in accordance with the SOC of power storage device 3 and an imbalance state of demand and supply in power. In the present exemplary embodiment, allotment coefficient K, and maximum value Δf_{max} of an integral value of a frequency deviation are used, as the allotment information. Allotment coefficient K is an example of operation control information, and becomes larger as an allotment ratio to power storage device 3 becomes higher. Maximum value Δf_{max} of the integral value of the frequency deviation is used as a threshold value of a deviation amount with respect to a reference frequency (for example, 50 Hz) of a system frequency. Note that the reference frequency of the system frequency is stored in arithmetic operation section 104.

[0057]

Subsequently, the control operation of arithmetic operation section 104 will be described.

[0058]

Arithmetic operation section 104 controls the charge and discharge operation of power storage device 3 based on the system frequency of power system 1 detected by frequency meter 103, and based on the allotment information received by communicator 102.

[0059]

Furthermore, arithmetic operation section 104 may control the charge and discharge operation of power storage device 3 based on the SOC of power storage device 3, in addition to the system frequency of power system 1 detected by frequency meter 103, and the allotment

information received by communicator 102.

[0060]

Note that arithmetic operation section 104 may use the system frequency of power system 1 received from outside instead of the system frequency of power system 1 detected by frequency meter 103. In this case, arithmetic operation section 104 also functions as second detection means.

[0061]

Arithmetic operation section 104 obtains integral value Δf of a frequency deviation that is the deviation amount of the system frequency of power system 1 with respect to the reference frequency of the system frequency. Arithmetic operation section 104 controls the charge and discharge operation of power storage device 3 by using allotment coefficient K and integral value Δf of the frequency deviation, when an absolute value of integral value Δf of the frequency deviation is maximum value Δf_{max} of the integral values of the frequency deviations, or smaller. Meanwhile, when the absolute value of integral value Δf of the frequency deviation is larger than maximum value Δf_{max} of the integral values of the frequency deviations, arithmetic operation section 104 controls the charge and discharge operation of power storage device 3 by using allotment coefficient K and maximum value Δf_{max} of the integral values of the frequency deviations.

[0062]

Next, storage battery SCADA 200 will be described.

[0063]

Storage battery SCADA 200 is an example of a second control device or a battery control support device. Storage battery SCADA 200 has N of local charge and discharge devices 100 and N of power storage devices 3 under control. Storage battery SCADA 200 includes communicator 201, database 202, recognition section 203, and arithmetic operation section 204.

[0064]

Communicator 201 is an example of second communication means. Communicator 201 communicates with respective local charge and discharge devices 100 and power supply instruction section 300A. For example, communicator 201 receives the SOC and ID of power storage device 3 from each of local charge and discharge devices 100.

[0065]

Database 202 retains a storage battery distribution factor curve that is used to determine a chargeable and dischargeable capacity of power storage device 3 from the SOC of power storage device 3 received by communicator 201. Furthermore, database 202 also retains rated output

P(n) of each of power storage devices 3 that is used to determine the chargeable and dischargeable capacity. Note that as rated output P(n) of power storage device 3, the rated output of an unillustrated power convertor (an AC/DC converter) that is connected to power storage device 3 is used.

[0066]

Figures 3A and 3B each show an example of the storage battery distribution factor curve. Figure 3A shows an example of storage battery distribution factor curve 202a at the time of discharge, and Figure 3B shows an example of storage battery distribution factor curve 202b at the time of charge.

[0067]

Recognition section 203 is an example of recognition means. Recognition section 203 recognizes power amounts (hereinafter, called "allotted power amounts") that are allotted to power storage devices 3 under control of storage battery SCADA 200 in order to adjust the power amount in power system 1. The allotted power amount is an example of a situation of the power system.

[0068]

Recognition section 203 derives total adjustable capacity P_{ES} showing the chargeable and dischargeable capacity of a storage battery group formed by N of power storage devices 3 from the SOC of N of power storage devices 3 by using the storage battery distribution factor curves in database 202. Total adjustable capacity P_{ES} is an example of notification information.

[0069]

Recognition section 203 transmits total adjustable capacity P_{ES} to power supply instruction section 300A from communicator 201, and thereafter, receives allotted power amount information showing the allotted power amount reflecting total adjustable capacity P_{ES} from power dispatching instruction section 300A via communicator 201. Recognition section 203 recognizes the allotted power amount in the allotted power amount information.

[0070]

In the present exemplary embodiment, as the allotted power amount information, a charge and discharge gain line that shows the LFC (load frequency control) allotted capacity LFC_{ES} that shows the maximum allotted power amount, and maximum value Δf_{max} of the integral values of the frequency deviation are used.

[0071]

Note that "the maximum value of the integral values of the frequency deviations" means "a maximum deflection amount of the integral value of the frequency deviation" that can be

handled with the output amount of LFC_{ES}, with respect to the total output LFC_{ES} of the number of storage batteries under control, and if the integral value becomes the maximum value or larger, handling with LFC_{ES} becomes difficult.

[0072]

Figure 4 is a diagram showing an example of the charge and discharge gain line. Details of the charge and discharge gain line will be described later.

[0073]

Arithmetic operation section 204 is an example of processing means. Arithmetic operation section 204 generates allotment information (allotment coefficient K and maximum value Δf_{max} of the integral values of frequency deviations) based on the SOC of power storage device 3 received by communicator 201, and the charge and discharge gain line recognized by recognition section 203. Arithmetic operation section 204 transmits the allotment information (allotment coefficient K and maximum value Δf_{max} of the integral values of the frequency deviations) to respective local charge and discharge devices 100 from communicator 201.

[0074]

Next, power supply instruction section 300A will be described.

[0075]

Power supply instruction section 300A is an example of an external control device. Power supply instruction section 300A includes frequency meter 301, communicator 302 and arithmetic operation section 303.

[0076]

Frequency meter 301 detects a system frequency of power system 1.

[0077]

Communicator 302 communicates with storage battery SCADA 200. For example, communicator 302 receives total adjustable capacity P_{ES} from storage battery SCADA 200.

[0078]

Arithmetic operation section 303 controls the operation of power supply instruction section 300A.

[0079]

For example, arithmetic operation section 303 calculates area requirement (Area Requirement: AR) that is an output correction amount of a power station by using the system frequency detected by frequency meter 301. Arithmetic operation section 303 derives the LFC capacity by using area requirement AR, the LFC adjustment capacity of thermal power generation equipment 4 that is to be a control target, and total adjustable capacity P_{ES} of the

storage battery group that is to be a control target. Arithmetic operation section 303 acquires the LFC adjustment capacity of thermal power generation equipment 4 from a thermal power generation equipment control section not illustrated, and total adjustable capacity P_{ES} is supplied to arithmetic operation section 303 from communicator 302.

[0080]

Arithmetic operation section 303 assigns a capacity from which an abrupt variation component is excluded out of the LFC capacity to thermal power generation equipment 4, and assigns remaining LFC capacity LFC_{ES} (note that $LFC_{ES} <= P_{ES}$) to the storage battery group. For example, arithmetic operation section 303 extracts the abrupt variation component (capacity LFC_{ES}) from the LFC capacity by using a high pass filter that passes only variation components with periods of 10 seconds or shorter among the LFC capacities.

[0081]

Alternatively, arithmetic operation section 303 allocates the LFC capacity to thermal power generation equipment 4 and the storage battery group in accordance with a ratio at which the LFC capacity is allocated to thermal power generation equipment 4 and the storage battery group.

[0082]

Arithmetic operation section 303 deals capacity LFC_{ES} as LFC assignment capacity LFC_{ES}, and generates a charge and discharge gain line (see Figure 4) that shows LFC assignment capacity LFC_{ES}, and maximum value Δf_{max} of the integral values of the frequency deviations that are fixed in advance.

[0083]

Arithmetic operation section 303 transmits the charge and discharge gain line to storage battery SCADA 200 from communicator 302.

[0084]

Next, outlines of operations will be described.

[0085]

(1) Storage battery SCADA 200 accepts SOC of each of power storage devices 3 to be a control target from each of local charge and discharge devices 100 at periods T, and thereby collects SOC of each of power storage devices 3. Period T is approximately one minute.

[0086]

(2) Storage battery SCADA 200 derives total adjustable capacity P_{ES} based on the SOC of each of power storage devices 3 each time storage battery SCADA 200 collects SOC of each of power storage devices 3.

[0087]

(3) Subsequently, storage battery SCADA 200 transmits total adjustable capacity P_{ES} to power supply instruction section 300A at periods T_m. Period T_m is period T or more, and is four minutes, for example.

[0088]

(4) Power dispatching instruction section 300A calculates LFC allotment capacity LFC_{ES} ($LFC_{ES} <= P_{ES}$) with respect to a power storage device 3 group that is controlled by storage battery SCADA 200, each time that power supply instruction section 300A receives total adjustable capacity P_{ES}.

[0089]

(5) Power dispatching instruction section 300A creates a charge and discharge gain line by using LFC assignment capacity LFC_{ES} and maximum value Δf_{max} of the integral values of the frequency deviations, each time that power supply instruction section 300A calculates LFC assignment capacity LFC_{ES}, and transmits the charge and discharge gain line to storage battery SCADA 200.

[0090]

(6) Storage battery SCADA 200 calculates allotment coefficient K in accordance with the newest charge and discharge gain line from power supply instruction section 300A.

[0091]

(7) Subsequently, storage battery SCADA 200 transmits allotment information (allotment coefficient K and maximum value Δf_{max} of the integral values of frequency deviations) to each of local charge and discharge devices 100 at periods T.

[0092]

(8) Each of local charge and discharge devices 100 calculates a local charge and discharge gain line that defines the charge and discharge operation of power storage device 3, based on allotment coefficient K and maximum value Δf_{max} of the integral values of the frequency deviations. The local charge and discharge gain line will be described later.

[0093]

(9) Each of local charge and discharge devices 100 controls the charge and discharge operation of power storage device 3 by using the local charge and discharge gain line and the system frequency.

[0094]

Next, details of the operations will be described.

[0095]

First, an operation of storage battery SCADA 200 deriving total adjustable capacity P_{ES} based on SOC of power storage device 3 (hereinafter, called a "P_{ES} deriving operation") will be described. Note that in order to derive total adjustable capacity P_{ES}, information of rated output P(n) and the like of the storage battery of each ID (the kWh of the battery, the usable SOC range, for example, the range of 30% to 90% and the like) is needed. The information thereof is basically stationary information, and therefore, in the present exemplary embodiment, storage battery SCADA 200 is assumed to acquire the information thereof from each of local charge and discharge devices 100 in advance.

[0096]

Figure 5 is a sequence diagram for explaining the P_{ES} deriving operation. In Figure 5, the number of local charge and discharge devices 100 is set at one to simplify explanation.

[0097]

Communicator 201 of storage battery SCADA 200 transmits an information request that requests SOC from each of local charge and discharge devices 100 (step S501).

[0098]

In each of local charge and discharge devices 100, arithmetic operation section 104 causes detector 101 to detect SOC of power storage device 3 when arithmetic operation section 104 receives the information request requesting SOC via communicator 102 (step S502).

[0099]

Subsequently, arithmetic operation section 104 transmits SOC detected by detector 101 together with ID, to storage battery SCADA 200 from communicator 102 (step S503). Hereinafter, explanation will be made with ID being assumed to be a consecutive number (n) from "1" to "N".

[0100]

When storage battery SCADA 200 receives SOC (hereinafter, called "SOC(n)") that is assigned with ID from each of local charge and discharge devices 100, storage battery SCADA 200 derives total adjustable capacity P_{ES} (step S504).

[0101]

Storage battery SCADA 200 and each of local charge and discharge devices 100 repeat the operation of steps S501 to S504, namely, the P_{ES} deriving operation at periods T.

[0102]

Next, a method for deriving total adjustable capacity P_{ES} will be described.

[0103]

Communicator 201 of storage battery SCADA 200 collects real-time SOC(n) from each of

local charge and discharge devices 100.

[0104]

Subsequently, recognition section 203 of storage battery SCADA 200 derives storage battery distribution factor α discharge (n) at the time of discharge and storage battery distribution factor α charge (n) at the time of charge, for each of power storage devices 3, by using SOC(n) and storage battery distribution factor curves 202a and 202b (see Figures 3A and 3B) that are retained in database 202.

[0105]

Here, as the storage battery distribution factor curves shown in Figures 3A and 3B, curves with an objective of basically keeping SOC at approximately 50% at the time of charge and at the time of discharge are used. Note that the storage battery distribution factor curves are properly changeable without being limited to the storage battery distribution factor curves shown in Figures 3A and 3B.

[0106]

Subsequently, recognition section 203 derives $P_{ES,discharge}$ and $P_{ES,charge}$ by using storage battery distribution factor α discharge (n) at the time of discharge, storage battery distribution factor α charge (n) at the time of charge, respective rated outputs P(n) of N of power storage devices 3 in total, and formulas shown in formula 1 and formula 2.

[0107]

[Formula 1]

$$P_{ES,\ discharge} = \sum_{n=1}^{N} \alpha_{discharge}(n) \cdot P(n)$$

[0108]

[Formula 2]

$$P_{ES,\ charge} = \sum_{n=1}^{N} \alpha_{charge}(n) \cdot P(n)$$

[0109]

Subsequently, recognition section 203 adopts a smaller value out of $P_{ES,discharge}$ and $P_{ES,charge}$, as total adjustable capacity P_{ES}. This is because in order to adjust the system frequency, charge and discharge in power storage device 3 is required with about the same frequency, and the total adjustable capacity with which both charge and discharge can be performed is needed. Note that the total adjustable capacity is the value with which charge and discharge are considered to be able to be continued at least during the time period of period T.

[0110]

Next, an operation of storage battery SCADA 200 communicating with power supply instruction section 300A and recognizing a charge and discharge gain line (hereinafter, called a "recognition operation") will be described.

[0111]

Figure 6 is a sequence diagram for explaining the recognition operation.

[0112]

Arithmetic operation section 303 of power supply instruction section 300A calculates area requirement AR by using the system frequency detected by frequency meter 301 (step S601).

[0113]

Subsequently, arithmetic operation section 303 collects the LFC adjustment capacity of thermal power generation equipment 4 from a thermal power generation equipment controller not illustrated (step S602).

[0114]

Meanwhile, communicator 201 of storage battery SCADA 200 transmits the newest total adjustable capacity P_{ES} among calculated total adjustable capacities P_{ES} to power supply instruction section 300A (step S603).

[0115]

Communicator 302 of power supply instruction section 300A receives the newest total adjustable capacity P_{ES} transmitted from communicator 201 of storage battery SCADA 200, and outputs the newest total adjustable capacity P_{ES} to arithmetic operation section 303.

[0116]

When arithmetic operation section 303 accepts the newest total adjustable capacity P_{ES}, arithmetic operation section 303 derives an LFC capacity by using area requirement AR, the LFC adjustment capacity of thermal power generation equipment 4, and the newest total adjustable capacity P_{ES} thereof. Subsequently, arithmetic operation section 303 assigns a capacity with an abrupt variation component excluded from the LFC capacity to thermal power generation equipment 4, and assigns the remaining LFC capacity LFC_{ES} (note that $LFC_{ES} <= P_{ES}$) to the storage battery group as LFC assignment capacity LFC_{ES} (step S604).

[0117]

In the present exemplary embodiment, arithmetic operation section 303 determines a ratio of assignment of the LFC capacity to thermal power generation equipment 4 and assignment of the LFC capacity to the storage battery group (LFC assignment capacity LFC_{ES}), with an eye to economy while considering assignment amounts of EDC (Economic power supply control) component.

[0118]

Subsequently, arithmetic operation section 303 generates a charge and discharge gain line (see Figure 4) showing LFC assignment capacity LFC_{ES}, and maximum value Δf_{max} of the integral values of the frequency deviations set in advance (step S605).

[0119]

The charge and discharge gain line shown in Figure 4 shows the charge and discharge amount of the storage battery group with respect to integral value Δf of the frequency deviation. The charge and discharge gain line changes to be line 400A and line 400B in accordance with the value (LFC_{ES} and LFC_{ES}') of LFC assignment capacity LFC_{ES} within the range of "LFC assignment capacity LFC_{ES} <= total adjustable capacity P_{ES}". Note that as the charge and discharge gain line, a charge and discharge gain line with use of a frequency deviation may be used, other than the charge and discharge gain line shown in Figure 4. In this case, the operation becomes a governor free operation, rather than an LFC operation.

[0120]

Furthermore, when the frequency deviation is used as the charge and discharge gain line, other than the charge and discharge gain line shown in Figure 4, the integral values of the frequency deviations that are used in the present exemplary embodiment, for example, the integral value of the frequency deviation that is used in the allotment information and allotment power amount information, and arithmetic operation section 104, power supply instruction section 300A and local charge and discharge device 100 is replaced with a frequency deviation.

[0121]

Subsequently, arithmetic operation section 303 transmits the charge and discharge gain line to storage battery SCADA 200 from communicator 302 (step S606).

[0122]

Storage battery SCADA 200 and power supply instruction section 300A repeat the operation of steps S601 to S606, that is, the recognition operation at periods T_m (for example, T_m = four minutes).

[0123]

Note that recognition section 203 of storage battery SCADA 200 receives charge and discharge gain lines via communicator 201, and retains only the newest charge and discharge gain line among the charge and discharge gain lines.

[0124]

Next, an operation of storage battery SCADA 200 generating allotment information and transmitting the allotment information to each of local charge and discharge devices 100, and

each of local charge and discharge devices 100 that derive the local charge and discharge gain line for controlling charge and discharge of power storage device 3 based on the allotment information (hereinafter, called an "allotment operation") will be described.

[0125]

Figure 7 is a sequence diagram for describing the allotment operation. In Figure 7, the number of local charge and discharge devices 100 is set at one in order to simplify explanation.

[0126]

Arithmetic operation section 204 of storage battery SCADA derives allotment coefficient K by using LFC assignment capacity LFC_{ES} shown in the newest charge and discharge gain line retained by recognition section 203, the newest total adjustable capacity P_{ES} which recognition section 203 has, and mathematical expression shown in formula 3 (step S701).

[0127]

[Formula 3]

$$K = \frac{LFC_{ES}}{P_{ES}}$$

[0128]

Subsequently, arithmetic operation section 204 transmits allotment information showing allotment coefficient K and maximum value Δf_{max} of the integral values of the frequency deviations shown in the newest charge and discharge gain line to each of local charge and discharge devices 100 from communicator 201 (step S702). Note that formula 3 is used as allotment coefficient K in the present exemplary embodiment, but besides the above, a flexible operation can be performed such as an operation of instructing the individual storage batteries to forcibly issue outputs that is close to a limit as the value of allotment coefficient K or the like at the time of a desperate situation.

[0129]

Note that in the present exemplary embodiment, the following processing is executed in step S702.

[0130]

Arithmetic operation section 204 determines a smaller value out of the newest storage battery distribution factor α discharge (n) at the time of discharge and storage battery distribution factor α charge (n) at the time of charge that are derived by recognition section 203 as storage battery distribution factor α (n), for each of power storage devices 3.

[0131]

Subsequently, arithmetic operation section 204 generates operation-related information

showing storage battery distribution factor $\alpha(n)$ and rated output $P(n)$ that is retained in database 202, for each of power storage devices 3.

[0132]

Subsequently, arithmetic operation section 204 adds allotment information to each operation-related information, and transmits the allotment information to which the operation-related information is added from communicator 201 to local charge and discharge device 100 corresponding to power storage device 3 corresponding to the operation-related information.

[0133]

In each of local charge and discharge devices 100, arithmetic operation section 104 receives the allotment information with the operation-related information via communicator 102.

[0134]

Arithmetic operation section 104 derives local charge and discharge gain coefficient $G(n)$ by using the allotment information with the operation-related information and the mathematical expression shown in formula 4 (step S703).

[0135]

[Formula 4]

$$G(n) = \frac{K \cdot \alpha(n) \cdot P(n)}{\Delta f_{max}}$$

[0136]

Note that the values in the mathematical expression of formula 4 are shown in the allotment information with the operation-related information.

[0137]

Subsequently, arithmetic operation section 104 derives local charge and discharge gain line 800A shown in Figure 8 by using local charge and discharge gain coefficient G(n), and maximum value Δf_{max} of the integral values of the frequency deviations shown in the allotment information with the operation-related information (step S704).

[0138]

Local charge and discharge gain line 800A shown in Figure 8 becomes a straight line that passes through origin 0, and has a gradient that is local charge and discharge gain coefficient G(n) when integral value Δf of the frequency deviation is in a range of $-\Delta f_{max} \leq \Delta f \leq \Delta f_{max}$, takes a constant value of "$-K \cdot \alpha(n) \cdot P(n)$" (the minus sign represents discharge) when integral value Δf of the frequency deviation is in a range of $\Delta f < -\Delta f_{max}$, and takes a constant value of "$K \cdot \alpha(n) \cdot P(n)$" when integral value Δf of the frequency deviation is in a range of $\Delta f_{max} < \Delta f$.

[0139]

Storage battery SCADA 200 and each local charge and discharge device 100 repeat steps S701 to S704 at periods T (for example, T = one minute).

[0140]

In each of local charge and discharge devices 100, arithmetic operation section 104 receives pieces of allotment information together with the operation-related information via communicator 102, and retains only the newest piece of allotment information with the operation-related information from among the pieces of allotment information together with the operation-related information.

[0141]

Next, the operation of local charge and discharge device 100 controlling charge and discharge of power storage device 3 based on the allotment information with the operation-related information and the system frequency (hereinafter, called a "charge and discharge control operation") will be described.

[0142]

Figure 9 is a sequence diagram for describing the charge and discharge control operation.

[0143]

In local charge and discharge device 100, arithmetic operation section 104 causes frequency meter 103 to detect a system frequency (step S901).

[0144]

Subsequently, arithmetic operation section 104 calculates integral value Δf of the frequency deviation by subtracting the reference frequency of the system frequency from the detection result of the frequency meter 103 and integrating the subtracted result (step S902).

[0145]

Subsequently, arithmetic operation section 104 calculates a charge amount or a discharge amount of power storage device 3 in accordance with integral value Δf of the frequency deviation and the local charge and discharge gain line (step S903).

[0146]

In the present exemplary embodiment, when an absolute value of integral value Δf of the frequency deviation is maximum value Δf_{max} of the integral values of the frequency deviations or smaller in step S903, arithmetic operation section 104 calculates an absolute value of a value $(G(n)\cdot\Delta f)$ that is obtained by multiplying local charge and discharge gain coefficient G(n) by integral value Δf of the frequency deviation as an adjustment power amount. Meanwhile, when the absolute value of integral value Δf of the frequency deviation is larger than maximum value Δf_{max} of the integral values of the frequency deviations, arithmetic operation section 104

calculates a value ($K \cdot \alpha(n) \cdot P(n)$) obtained by multiplying allotment coefficient K, storage battery distribution factor $\alpha(n)$ and rated output P(n) by one another as the adjustment power amount. In this example, the case where the gradients of G(n) are the same on the charge side and the discharge side, namely, symmetrical with respect to a point, is shown in Figure 8, but in reality, the case where the gradients are not symmetrical with respect to a point is assumed, and in that case, G(n) is determined in a similar concept.

[0147]

Subsequently, when integral value Δf of the frequency deviation is a positive value, arithmetic operation section 104 causes power storage device 3 to execute a charge operation by an adjustment power amount, and causes power storage device 3 to execute a discharge operation by an adjustment power amount when integral value Δf of the frequency deviation is a negative value (step S904).

[0148]

Each local charge and discharge device 100 repeats steps S901 to S904 at periods T_1 (for example, $T_1 = 0.1$ seconds). As a result, the value of the integral value of the frequency deviation changes at each time, and charge and discharge based on $G(n) \cdot \Delta f$ are performed.

[0149]

Furthermore, in general, the LFC capacity takes values in both a charge direction and a discharge direction, and therefore, it is not desirable that SOC of power storage device (battery) 3 be deviated to zero or one. If a deviation occurs, power that can be charged or discharged becomes small, and total adjustable capacity P_{ES} becomes small, as also shown in the examples of the storage battery distribution factor curves shown in Figures 3A and 3B.

[0150]

Therefore, local charge and discharge device 100 may control charge and discharge of power storage device 3 by adding a charge and discharge amount for correcting SOC (SOC correction offset), in addition to the charge and discharge amount that is calculated from the information showing the demand and supply state of the entire power system 1 measured at short periods (measurement value of the system frequency in the present exemplary embodiment) and the allotment information that is distributed from storage battery SCADA 200 at long periods.

[0151]

As a method for determining a value of the SOC correction offset (an SOC correction offset value), there is the method in which arithmetic operation section 104 accepts information necessary to determine the SOC correction offset value (SOC correction offset-related information) from storage battery SCADA 200 via communicator 102, and arithmetic operation

section 104 determines the SOC correction offset value in accordance with the SOC correction offset-related information. On that occasion, storage battery SCADA 200 may transmit the SOC correction offset-related information simultaneously with transmitting the allotment information. Note that the SOC correction offset-related information is an example of correction information.

[0152]

As an example of the SOC correction offset-related information, the SOC correction offset-related information showing the SOC correction offset value itself is cited, and storage battery SCADA 200 distributes the SOC correction offset-related information to each of local charge and discharge devices 100.

[0153]

In this case, arithmetic operation section 204 of storage battery SCADA 200 refers to SOC received from each of local charge and discharge devices 100, and distributes the SOC correction offset-related information showing the SOC correction offset value for charge to power storage device 3 in which SOC is deviated to zero out of power storage devices 3, and distributes the SOC correction offset-related information showing the SOC correction offset value for discharge to power storage device 3 in which SOC is deviated to one out of power storage devices 3.

[0154]

Hereinafter, an example of using the SOC correction offset value of a positive value as the SOC correction offset value for charge, and using the SOC correction offset value of a negative value as the SOC correction offset value for discharge will be described.

[0155]

Note that power storage device 3 in which the SOC is deviated to zero is a power storage device in which the value of SOC is a first threshold value which is larger than zero and smaller than 0.5, or smaller, for example. Furthermore, power storage device 30 in which SOC is deviated to one is a power storage device in which the value of SOC is a second threshold value that is larger than 0.5 and smaller than one, or larger, for example.

[0156]

Arithmetic operation section 104 of local charge and discharge device 100 calculates a correction power amount by adding the SOC correction offset value to the adjustment power amount when integral value Δf of the frequency deviation is a positive value.

[0157]

Furthermore, arithmetic operation section 104 of local charge and discharge device 100 calculates the correction power amount by adding the SOC correction offset value to the

multiplication result of multiplying the adjustment power amount by −1 when integral value Δf of the frequency deviation is a negative value.

[0158]

When the correction power amount is a positive value, arithmetic operation section 104 causes power storage device 3 to execute a charge operation by the correction power amount, and when the correction power amount is a negative value, arithmetic operation section 104 causes power storage device 3 to execute a discharge operation by the correction power amount. When the correction power amount is zero, arithmetic operation section 104 does not execute charge and discharge of power storage device 3.

[0159]

Note that arithmetic operation section 204 may determine each SOC correction offset-related information so that the total sum of the SOC correction offset values of all power storage devices 3 at the same time point (hereinafter, called an "offset total sum") becomes zero. In this case, the SOC correction offset does not influence capacity LFC_{ES}.

[0160]

Alternatively, arithmetic operation section 204 may determine each SOC correction offset-related information so that the speed of change of the offset total sum (speed of change of the offset total sum with a lapse of time) becomes a speed threshold value or less (the speed threshold value is, for example, total adjustable capacity P_{ES}/30 minutes.), instead of always making the offset total sum zero. Note that as the speed threshold value, the upper limit of the response speed of a power stabilizing operation (an LFC operation) performed by an external power stabilizing device (for example, thermal power generation equipment 4) connected to power system 1 is used.

[0161]

A slow change of power demand and supply at a period longer than 30 minutes, for example, is allotted as a change of power demand and supply that is absorbed by the power stabilizing operation of thermal power generation equipment 4 by EDC. Therefore, a change of power demand and supply due to a change in the offset total sum is highly likely to be absorbed by the external power stabilizing device. Accordingly, the change of power demand and supply due to the SOC correction offset value does not influence a relatively high-speed change of demand and supply accompanying charge and discharge of power storage device 3.

[0162]

Furthermore, arithmetic operation section 104 refers to SOC via detector 101, and when SOC becomes a target value (for example, reference SOC that is 0.5), arithmetic operation

section 104 may autonomously invalidate an SOC correction offset and control charge and discharge of power storage device 3.

[0163]

Note that when the SOC correction offset-related information showing the SOC correction offset value itself is used as described above, arithmetic operation section 104 does not have to execute the processing of calculating the SOC correction offset value, and an increase in the processing load of arithmetic operation section 104 can be reduced.

[0164]

As another example of the SOC correction offset-related information, there is a method in which storage battery SCADA 200 distributes parameters that are needed when each of local charge and discharge devices 100 determines the SOC correction offset value to each of local charge and discharge devices 100.

[0165]

For example, the nth local charge and discharge device 100 determines SOC correction offset value $P_{offset,n}(t)$ by using the following formula 5.

[0166]

[Formula 5]

$$P_{offset,n}(t) = (SOC_{target,n} - SOCn(t))/Tn$$

[0167]

Where $SOC_{target,n}$ is an SOC value (a reference state of power storage device 3), SOCn (t) is an SOC value of power storage device 3 of nth local charge and discharge device 100 at a time point t, and Tn is a time constant (speed-related information).

[0168]

Arithmetic operation section 104 of local charge and discharge device 100 acquires the SOC value of power storage device 3 via detector 101, acquires $SOC_{target,n}$ and Tn from storage battery SCADA 200 via communicator 102, and calculates SOC correction offset value $P_{offset,n}(t)$ from formula 5.

[0169]

In this case, SOC correction offset value $P_{offset,n}(t)$ can be changed in accordance with an actual change of SOC. Furthermore, for example, when a communication trouble occurs and $SOC_{target,n}$ and Tn are not newly received, SOC correction offset value $P_{offset,n}(t)$ can continue to be calculated by using $SOC_{target,n}$ and Tn that are already received.

[0170]

As an example of the method in which arithmetic operation section 204 of storage battery

SCADA 200 determines $SOC_{target,n}$ of each of power storage devices, there is a method that determines $SOC_{target,n}$ based on a deviation of the charge direction and the discharge direction of the LFC capacity, and in many cases, $SOC_{target,n} = 0.5$ is satisfied. Furthermore, Tn represents the speed at which SOC is corrected, and for example, arithmetic operation section 204 sets Tn so that change of the total sum of the values of the SOC correction offsets of respective power storage devices 3 becomes a change at a period longer than 30 minutes, in order that the change of power demand and supply due to the SOC correction offset value is absorbed by EDC.

[0171]

Note that in arithmetic operation section 104 in each of local charge and discharge devices 100, $SOC_{target,n}$ and Tn are registered in advance, and each of arithmetic operation sections 104 may calculate SOC correction offset value $P_{offset,n}(t)$ by using registered $SOC_{target,n}$ and Tn.

[0172]

In this case, arithmetic operation section 104 of local charge and discharge device 100 calculates the correction power amount by adding the SOC correction offset value to the adjustment power amount when integral value Δf of the frequency deviation is a positive value, and when integral value Δf of the frequency deviation is a negative value, arithmetic operation section 104 calculates the correction power amount by adding the SOC correction offset value to a multiplication result of multiplying the adjustment power amount by -1.

[0173]

When the correction power amount is a positive value, arithmetic operation section 104 causes power storage device 3 to execute a charge operation by the correction power amount. When the correction power amount is a negative value, arithmetic operation section 104 causes power storage device 3 to execute a discharge operation by the correction power amount. When the correction power amount is zero, arithmetic operation section 104 does not execute charge and discharge of power storage device 3.

[0174]

Next, another example of controlling the charge amount or the discharge amount of power storage device 3 in accordance with SOC of power storage device 3 will be described.

[0175]

Hereinafter, in order to simplify the explanation, a case having two power storage devices 3 with equal rated outputs will be shown. Here, the rated outputs of two power storage devices 3 are expressed as P(1) and P(2) (note that P(1) = P(2)). Furthermore, as for the storage battery distribution factor curve, the storage battery distribution factor is kept at one irrespective of the value of SOC as shown in Figure 10. Furthermore, arithmetic operation section 204 of storage

battery SCADA 200 determines a local charge and discharge gain line (hereinafter called a "reference local charge and discharge gain line") of each of local charge and discharge devices 100 at the time when a local charge and discharge gain line of each of local charge and discharge devices 100 at a time of distribution coefficient K being one, namely, at a time of distribution coefficient K being not taken into consideration.

[0176]

Figure 11 is a diagram showing the reference local charge and discharge gain line before the SOC correction offset is applied to each of power storage devices 3. In Figure 11, the axis of ordinates represents the local charge and discharge device output that is the charge and discharge amount of each of power storage devices 3, and axis of abscissa represents value X showing a state of a total demand and supply balance of power system 1. While integral value Δf of the frequency deviation is used in the present exemplary embodiment as an example of X, a frequency deviation (Hz), a total demand and supply adjustment amount (W) and the like are cited, besides integral value Δf of the frequency deviation.

[0177]

In the reference local charge and discharge gain line shown in Figure 11, the local charge and discharge device output is proportional to X with a gradient of local charge and discharge gain coefficient G(n) in a region in which X is from $-Xr$ to Xr inclusive. Furthermore, since power storage device 3 cannot issue output of rated output P(n) or more, in a region other than the region in which X is from $-Xr$ to Xr inclusive, the local charge and discharge device output is the rated output. A value of Xr is the value of X at the time of the local charge and discharge device output being rated output P(n). Note that here, the rated output of charge and the rated output of discharge are set as the same values as the positive and negative signs being inverted, but the case does not have to be always the same.

[0178]

Here, each of two power storage devices 3 is assumed to have different SOC. Arithmetic operation section 204 of storage battery SCADA 200 calculates an SOC correction offset amount of each of power storage devices 3 after acquiring the value of SOC of each of power storage devices 3. Note that a method for calculating the SOC correction offset amount will be described later. Arithmetic operation section 204 corrects the reference local charge and discharge gain line so that the total sum of the charge and discharge amounts of respective power storage devices 3 to which the SOC correction offset amounts are further added is in a target function shape in the region of $-Xr \leq X \leq Xr$ (for example, the total sum of the charge and discharge amounts becomes linear with respect to X in the region of $-Xr \leq X \leq Xr$).

Subsequently, arithmetic operation section 204 transmits the corrected reference local charge and discharge gain line to respective local charge and discharge devices 100. Figure 12 is a diagram showing an example of the corrected reference local charge and discharge gain line.

[0179]

Here, an example of the method in which arithmetic operation section 204 of storage battery SCADA 200 corrects the reference local charge and discharge gain line will be described with reference to Figure 13.

[0180]

First, arithmetic operation section 204 calculates target SOC by using collected SOC of each of power storage device 3 (step S1301). As an example of the calculation method of target SOC, there is a method in which arithmetic operation section 204 calculates target SOC = $\Sigma_n WH_n(t)/\Sigma_n WHr_n$. Note that $WH_n(t)$ and WHr_n represent a charge power amount (Wh) at a time point t of power storage device 3n, and a maximum charge power amount (Wh) that is the rated output. Furthermore,

[0181]

[Formula 6]

$$\sum_n = \sum_{n=1}^{N}$$

[0182]

Σ_n means formula 6.

[0183]

Subsequently, arithmetic operation section 204 obtains a difference $\Delta SOCn$ of the SOC value and target SOC of each of power storage devices 3 (step S1302).

[0184]

Subsequently, arithmetic operation section 204 calculates $\Delta WHn = WHr_n \times \Delta SOCn$ (step S1303), and obtains power amount ΔWHn(Wh) that is required until SOC reaches target SOC, for each of power storage devices 3.

[0185]

Subsequently, arithmetic operation section 204 divides ΔWHn by time constant T (for example, five minutes) set in advance and calculates offset $\Delta Poffset_n$ (W) for each of power storage devices 3 (step S1304). Time constant T is changeable without being limited to five minutes.

[0186]

Note that offset $\Delta Poffset_n$ is an offset amount that can reach target SOC in time T when X is assumed to remain constant and 0 hereinafter, and when target SOC is set with the method shown in step S1301, $\Sigma_n \Delta Poffset_n = 0$ is satisfied. Furthermore, time constant T defines the speed at which SOC is corrected. For example, in order that the change in power demand and supply due to offset $\Delta Poffset_n$ is distributed to power stabilizing devices such as thermal power generation equipment 4 by EDC, and the change is absorbed by the power stabilizing operation of the power stabilizing devices such as thermal power generation equipment 4, arithmetic operation section 204 sets T so that the change of the total sum of offsets $\Delta Poffset_n$ of respective power storage devices 3 occurs a change at a period longer than 30 minutes.

[0187]

Arithmetic operation section 204 firstly adds the value (offset $\Delta Poffset_n$) to the reference local charge and discharge gain line shown in Figure 11.

[0188]

Subsequently, arithmetic operation section 204 adds additional correction to the reference local charge and discharge gain line to which offset $\Delta Poffset_n$ is added, in steps S1305 and S1306, so that even if each of power storage devices 3 performs charge and discharge by adding offset $\Delta Poffset_n$, the total sum of the charge and discharge amounts of all power storage devices 3 at the same time point becomes linear with respect to X in the region of $-Xr \leq X \leq Xr$.

[0189]

In step S1305, arithmetic operation section 204 obtains value $Xlim_n$ of X with which the reference local charge and discharge gain line after $\Delta Poffset_n$ is added thereto has a rated output within a range of $|X| \leq Xr$, with respect to each of power storage devices 3. At this time, in the region of $0 < Xlim_n < X < Xr$ (or $-Xr < X < Xlim_n < 0$), the output of the power storage device is saturated to the rated output, and linearity with respect to X is lost.

[0190]

Thus, arithmetic operation section 204 adds an offset to the gradient of the reference local charge and discharge gain line of another power storage device, and brings the total sum of the charge and discharge amounts of respective power storage devices 3 into a linear relation with respect to X in the region of $-Xr < X < Xr$, in step S1306. Note that in the situation in which $\Delta Poffset_n$ is not added, the total charge and discharge amount of respective power storage devices 3 is in a linear relation with respect to X in the region of $-Xr < X < Xr$, and therefore, bringing the total charge and discharge amount of respective power storage devices 3 into a

linear relation with respect to X in the region of $-Xr < X < Xr$ means bringing the total sum of the offsets of respective power storage devices 3 into a linear relation with respect to X in the region of $-Xr < X < Xr$.

[0191]

For example, in the example shown in Figure 12, in a region of $Xlim_1 < X < Xr$, the output of power storage device 31 is saturated to the rated output. Therefore, arithmetic operation section 204 brings the total charge and discharge amount of respective power storage devices 3 (power storage devices 31 and 32) into a linear relation with respect to X in the region of $Xlim_1 < X < Xr$ by adding an offset to the gradient of the reference local charge and discharge gain line of power storage device 32, in the region of $Xlim_1 < X < Xr$. Further in the example shown in Figure 12, the output of power storage device 32 is saturated to the rated output in a region of $-Xr < X < Xlim_2$. Therefore, arithmetic operation section 204 brings the total charge and discharge amount of respective power storage devices 3 (power storage devices 31 and 32) into a linear relation with respect to X in the region of $-Xr < X < Xlim_2$ by adding an offset to the gradient of the reference local charge and discharge gain line of power storage device 31, in the region of $-Xr < X < Xlim_2$.

[0192]

Subsequently, arithmetic operation section 204 transmits the corrected reference charge and discharge gain lines to respective local charge and discharge devices 100 (step S1307). Note that the transmission timing may be synchronized with the timing of transmitting the allotment information.

[0193]

Note that the corrected reference local charge and discharge gain lines are examples of the operation information, and each shows a relation of a value obtained by adding the offset value and the local charge and discharge device output at the time when the offset is not added (information showing the operation content of the power storage device) and X.

[0194]

In each of local charge and discharge devices 100, arithmetic operation section 104 determines the power amount and an operation (a charge operation or a discharge operation) of power storage device 3 corresponding to integral value Δf of the frequency deviation by using the corrected reference local charge and discharge gain line, and causes power storage device 3 to execute the determined operation by the power amount of the multiplication result of multiplying the power amount corresponding to integral value Δf of the frequency deviation by allotment coefficient K.

[0195]

In this example, when the SOC correction operation that controls the charge amount or the discharge amount of power storage device 3 is executed in response to SOC of power storage device 3, the total charge and discharge amount of all power storage devices 3 can be brought into a linear relation with respect to X in the region of $-Xr < X < Xr$ similarly to the case where the SOC correction operation is not executed. Consequently, the total charge and discharge amount of power storage device 3 can be controlled with high precision based on X.

[0196]

Next, still another example of controlling the charge amount or the discharge amount of power storage device 3 in response to SOC of power storage device 3 will be described.

[0197]

Figure 14 is a diagram for explaining a way of giving an offset that is different from the aforementioned example. In this example, an offset is given to G(n).

[0198]

When SOC of power storage device 3 is higher than target SOC, arithmetic operation section 204 makes G(n) on the charge side small and makes G(n) on the discharge side large in the reference local charge and discharge gain line, and when SOC of power storage device 3 is lower than target SOC, arithmetic operation section 204 makes G(n) on the charge side large and makes G(n) on the discharge side small.

[0199]

In the way of giving an offset shown in Figure 14, in order to prevent loss of linearity of the total charge and discharge amount with respect to X, when the output of a certain power storage device reaches the rated output in a region of $|X| \leq Xr$, another power storage device provides G(n) of that amount, similarly to the example shown in Figure 12.

[0200]

In the example shown in Figure 14, the output of power storage device 31 is saturated to the rated output in the region of $Xlim_1 < X < Xr$. Therefore, arithmetic operation section 204 brings the total charge and discharge amount of respective power storage devices 3 (power storage devices 31 and 32) into a linear relation with respect to X in the region of $Xlim_1 < X < Xr$ by adding an offset to the gradient of the reference local charge and discharge gain line of power storage device 32. Furthermore, in the example shown in Figure 14, the output of power storage device 32 is saturated to the rated output in a region of $-Xr < X < Xlim_2$. Therefore, arithmetic operation section 204 brings the total charge and discharge amount of respective power storage devices 3 (power storage devices 31 and 32) into a linear relation with respect to

X in the region of $-Xr < X < Xlim_2$ by adding an offset to the gradient of the reference local charge and discharge gain line of power storage device 31.

[0201]

In this example, even when the SOC correction operation to control the charge amount or the discharge amount of power storage device 3 in response to SOC of power storage device 3 is executed, the total charge and discharge amount of respective power storage devices 3 can be brought into a linear relation with respect to X in the region of $-Xr < X < Xr$ similarly to the case where the SOC correction operation is not executed. Therefore, the total charge and discharge amount of respective power storage devices 3 can be controlled with high precision based on X. Furthermore, in this example, charge and discharge using power storage device 3 are not executed at the time of $X = 0$, and therefore, an increase in the consumption of power for causing power storage device 3 to operate can be reduced.

[0202]

When $N = 1000$ of power storage devices were controlled in power control system 1000 that is described above, a communication problem occurred for 20 seconds between power supply instruction section 300A and storage battery SCADA halfway, but since the problem occurred in the interval of four minutes during which the charge and discharge gain line was transmitted, the control state did not change before and after the communication problem, and therefore, control of reducing a system frequency variation was able to be realized stably.

[0203]

Furthermore, from the viewpoint of total optimization of the thermal power generation equipment on the system side and the power storage devices, control allotment with consideration given to economic efficiency and response speed of the thermal power generation equipment can be given to the distributed storage battery group.

[0204]

Next, an effect of the present exemplary embodiment will be described.

[0205]

In local charge and discharge device 100, arithmetic operation section 104 controls the operation of power storage device 3 based on the allotment information provided by storage battery SCADA 200 and the system frequency. Therefore, the operation of power storage device 3 can be adjusted in response to not only the allotment information but also an actual change in the state of the power system.

[0206]

Note that the above-described effect is also brought about with local charge and discharge

device 100 including detector 101, communicator 102 and arithmetic operation section 104. Furthermore, the above-described effect is also brought about with storage battery SCADA 200 including communicator 201, recognition section 203 and arithmetic operation section 204. Furthermore, the above-described effect is also brought about with the battery control system including local charge and discharge device 100 including detector 101, communicator 102 and arithmetic operation section 104, and storage battery SCADA 200 including communicator 201, recognition section 203 and arithmetic operation section 204.

[0207]

Figure 15 is a diagram showing the local charge and discharge device including detector 101, communicator 102 and arithmetic operation section 104.

[0208]

Figure 16 is a diagram showing storage battery SCADA 200 including communicator 201, recognition section 203 and arithmetic operation section 204.

[0209]

Furthermore, storage battery SCADA 200 accepts the charge and discharge gain line that is used to generate allotment information from power supply instruction section 300A that controls power system 1. Therefore, it is possible to acquire the charge and discharge gain line with consideration given to the operation of thermal power generation equipment 4 on the system side, for example. Therefore, power demand and supply balance control by the thermal power generation equipment 4 on the system side and power storage device 3 can be carried out with high precision.

[0210]

Furthermore, storage battery SCADA 200 accepts the charge and discharge gain line in which total adjustable capacity P_{ES} is reflected from power supply instruction section 300A. Therefore, the load of power storage device 3 can be adjusted in accordance with the total adjustable capacity of power storage device 3.

[0211]

Furthermore, local charge and discharge device 100 controls the operation of power storage device 3 based on integral value Δf of the frequency deviation and the allotment information (the allotment coefficient K and maximum value Δf_{max} of the integral values of the frequency deviations). Therefore, the operation of power storage device 3 can be adjusted in response to not only the allotment information but also the actual change of the system frequency.

[0212]

Furthermore, the time interval at which local charge and discharge device 100 acquires

allotment information from storage battery SCADA 200 is longer than the operation interval at which local charge and discharge device 100 controls the operation of power storage device 3 by using the allotment information. Therefore, as compared with the case in which the time interval at which allotment information is acquired is the operation time interval of power storage device 3 or less, the processing of acquiring the allotment information becomes less susceptible to a communication problem that is likely to occur between local charge and discharge device 100 and storage battery SCADA 200.

[0213]

Furthermore, arithmetic operation section 104 controls the operation of power storage device 3 based on SOC and the SOC correction offset value of power storage device 3. Therefore, SOC of power storage device 3 can be prevented from being deviated to zero or one, and total adjustable capacity P_{ES} can be prevented from being small as a result of power that can be charged or discharged with use of power storage device 3 becoming small.

[0214]

Furthermore, arithmetic operation section 104 determines the correction power amount that is the result of adjusting the power amount for stabilizing the power of power system 1 which is determined in accordance with integral value Δf of the frequency deviation based on allotment coefficient K and SOC, and executes charge or discharge with the correction power amount for power storage device 3. Therefore, while SOC of power storage device 3 is prevented from being deviated to zero or one, the operation of power storage device 3 can be adjusted in accordance with not only the allotment information but also an actual change of the state of the power system.

[0215]

Furthermore, arithmetic operation section 204 may generate SOC correction offset-related information showing the charge amount or the discharge amount that brings SOC of power storage device 3 close to reference SOC based on SOC of power storage device 3, and arithmetic operation section 104 may control power storage device 3 by using the charge amount or the discharge amount shown in the SOC correction offset-related information. In this case, arithmetic operation section 104 does not have to execute processing to calculate the SOC correction offset value, and the load of arithmetic operation section 104 can be reduced.

[0216]

Furthermore, when the SOC correction offset value for charge is set at a positive value, and the SOC correction offset value for discharge is set at a negative value, arithmetic operation section 204 may generate each SOC correction offset-related information so that the total sum of

the SOC correction offset value for charge and the SOC correction offset value for discharge becomes zero. In this case, the SOC correction offset can be prevented from influencing capacity LFC_{ES}.

[0217]

Furthermore, arithmetic operation section 204 may generate each SOC correction offset-related information so that the speed of change of the offset total sum with the lapse of time becomes the upper limit of the response time of the power stabilizing operation that is performed by thermal power generation equipment 4 or lower. In this case, change of power demand and supply due to change in the offset total sum is highly likely to be absorbed by the power stabilizing operation of thermal power generation equipment 4. Therefore, the change in power demand and supply due to the SOC correction offset value is highly unlikely to influence a relatively high-speed change in demand and supply that accompanies charge and discharge of power storage device 3.

[0218]

Furthermore, based on SOC of power storage device 3, arithmetic operation section 204 may determine the charge amount or the discharge amount that brings the SOC close to target SOC, for each of power storage devices 3, and may correct the charge amount or the discharge amount so that the total sum of the charge amounts or the discharge amounts of respective power storage devices 3 is in a linear relation with respect to integral value Δf of the frequency deviation in the situation in which integral value Δf of the frequency deviation is within a predetermined range. Furthermore, arithmetic operation section 204 may generate the corrected reference local charge and discharge gain line by using the charge amount or the discharge amount after correction. Subsequently, arithmetic operation section 104 may control the operation of power storage device 3 based on the corrected reference local charge and discharge gain line. In this case, the total charge and discharge amount of power storage device 3 can be controlled with high precision based on X.

[0219]

Furthermore, arithmetic operation section 104 may generate the SOC correction offset value based on the difference between $SOC_{target,n}$ received from storage battery SCADA 200 and SOC of power storage device 3. In this case, the SOC correction offset value can be properly changed in response to the actual change of SOC of power storage device 3. Furthermore, even if a communication problem occurs, for example, and $SOC_{target,n}$ cannot be newly received, the SOC correction offset value can continue to be calculated with use of $SOC_{target,n}$ that has already been received.

[0220]

Furthermore, arithmetic operation section 104 may generate the value of the SOC correction offset that indicates the charge amount or the discharge amount that brings SOC of power storage device 3 close to $SOC_{target,n}$ by correcting the difference between $SOC_{target,n}$ and SOC of power storage device 3 with Tn received from storage battery SCADA 200. In this case, the speed of change of the offset total sum can be adjusted with Tn. Therefore, the change in power demand and supply due to the change in the offset total sum can be absorbed by the power stabilizing operation of thermal power generation equipment 4.

[0221]

Note that in the present exemplary embodiment, when control of effective power P and reactive power Q in power storage device 3 is considered, the maximum value of the output amount of power storage device 3 that is assigned to control of reactive power P (in short, when the output of Q is separately used in parallel, the effect of the output maximum value becomes lower than the rated output of the output amount by P is taken into consideration) may be used instead of rated output P(n).

[0222]

Furthermore, in the above-described exemplary embodiment, storage battery SCADA 200, local control device 100 and the like properly collect and distribute time synchronization information in the process of information communication, and time synchronization is performed among the devices.

[0223]

Furthermore, local charge and discharge device 100 may be realized by a computer. In this case, the computer reads and executes the program recorded in a recording medium such as computer-readable CD-ROM (Compact Disk Read Only Memory), and executes the respective functions that local charge and discharge device 100 has. The recording medium is not limited to a CD-ROM and other recording media can be used.

[0224]

Furthermore, storage battery SCADA 200 may be realized by a computer. In this case, the computer reads and executes the program recorded in a computer-readable recording medium, and executes each of the functions that storage battery SCADA 200 has.

[0225]

Furthermore, instead of power supply instruction section 300A, a small-scale EMS (Energy Management System) that is installed in the vicinity of a distribution substation may be used.

[0226]

(Second exemplary embodiment)

Figure 17 is a diagram showing power control system 1000A that adopts a battery control system of a second exemplary embodiment of the present invention. In Figure 17, the components that have the same configurations as shown in Figure 1 or 2 are assigned the same reference signs.

[0227]

In Figure 17, power control system 1000A includes power system 1A, photovoltaic power generator (solar battery) 2, power storage devices (storage batteries) 3(1) to 3(n), load 7, local charge and discharge devices 100A(1) to 100A(n), ESMS (Energy Storage Management System) 200A, sensor-incorporating switch slave station 700A, SVR slave station 700B, and LRT (Load Ratio Transformer) slave station 700C.

[0228]

Local charge and discharge devices 100A(1) to 100A(n) are in one-to-one correspondence with power storage devices (storage batteries) 3(1) to 3(n). Note that Figure 17 shows local charge and discharge device 100A(i) from among local charge and discharge devices 100A(1) to 100A(n) in order to simplify the explanation.

[0229]

Each of local charge and discharge devices 100A, ESMS 200A, sensor-incorporating switch slave station 700A, SVR slave station 700B and LRT slave station 700C are connected to *communication network 800.*

[0230]

Power system 1A includes distribution substation LRT 1A1, breakers 1A2, switch 1A3, sensor-incorporating switch 1A4, SVR 1A5 and pole transformer 1A6.

[0231]

Power control system 1000A limits variation in system frequency that result from changes in the amount of power generated by photovoltaic power generator 2, due to weather conditions, which is of concern to power system 1A, to which photovoltaic power generator 2 is interconnected, by a voltage adjusting operation of SVR 1A5 and charge and discharge operations of respective power storage devices 3.

[0232]

Power system 1A is a system for supplying power to load 7 on the customer side. While power system 1A also includes other devices (for example, thermal power generation equipment), *these devices are omitted to simplify the explanation.*

[0233]

LRT 1A1, SVR 1A5 and pole transformer 1A6 are voltage adjustors. Breaker 1A2, switch 1A3 and sensor-incorporating switch 1A4 are used to disconnect a specific part of power system 1A (for example, a part where a trouble occurs) from power system 1A.

[0234]

Each local charge and discharge device 100A is an example of a first control device or a battery control device. Each local charge and discharge device 100A also bears the function of a slave station provided in corresponding power storage device 3. Note that the number of local charge and discharge devices 100A and the number of power storage devices 3 are each one or more.

[0235]

Figure 18 is a diagram showing an example of local charge and discharge device 100A(i).

[0236]

In Figure 18, local charge and discharge device 100A(i) includes voltage detector 101A1, empty capacity detector 101A2, communicator 101A3, and arithmetic operation section 101A4.

[0237]

Voltage detector 101A1 is an example of first detection means and second detection means. Voltage detector 101A1 detects voltage V_i of interconnection point i of power system 1A and power storage device 3(i) at periods T_g (for example, T_g = 10 minutes). Furthermore, voltage detector 101A1 detects voltage V_i of interconnection point i at periods T_h (for example, T_h = 0.1 seconds). Voltage V_i of interconnection point i is an example of a state of interconnection point *i*, battery-related information and a state of power system 1A. Note that the state of the interconnection point is not limited to the voltage of the interconnection point and that other values may be used.

[0238]

Empty capacity detector 101A2 detects empty capacity Q_i of power storage device 3(i) at periods T_g. Note that empty capacity Q_i of power storage device 3(i) refers to capacity that can be used by power storage device 3(i) to adjust the voltage of power system 1A at the point of time, is calculated based on SOC, for example, and is ensured for the time period T_g.

[0239]

Communicator 101A3 is an example of first communication means. Communicator 101A3 communicates with ESMS 200A.

[0240]

Arithmetic operation section 101A4 executes a control information acquiring operation of

obtaining operation control information to control the operation of power storage device 3(i) from ESMS 200A (transmission and reception processing), and a charge and discharge control operation to control a charge and discharge operation of power storage device 3(i) based on the operation control information and voltage V_i at interconnection point i (battery operation control processing).

[0241]

Arithmetic operation section 101A4 intermittently executes the control information acquiring operation, and executes the charge and discharge control operation at time intervals shorter than the time intervals of the control information acquiring operation.

[0242]

Arithmetic operation section 101A4 repeatedly executes the control information acquiring operation at periods T_g, and repeatedly executes the charge and discharge control operation at periods T_h (for example, T_h = 0.1 seconds).

[0243]

Note that period T_g and Period T_h are not limited to 10 minutes and 0.1 seconds, and period T_g can be longer than period T_h.

[0244]

Furthermore, both or any one of the operation time intervals of the control information acquiring operation and the operation time interval of the charge and discharge control operation do not or does not have to be constant, and the shortest time interval from among the respective operation time intervals of the control information acquiring operation can be longer than the longest time from among the respective operation time intervals of the charge and discharge control operation.

[0245]

Furthermore, arithmetic operation section 101A4 may execute the control information acquiring operation in response to the voltage request that requests voltage V_i of interconnection point i sent from ESMS 200A, or may execute the control information acquiring operation autonomously.

[0246]

Here, the control information acquiring operation of arithmetic operation section 101A4 will be described.

[0247]

Arithmetic operation section 101A4 transmits voltage V_i of interconnection point i detected by voltage detector 101A1, and empty capacity Q_i of power storage device 3(i) detected

by empty capacity detector 101A2 to ESMS 200A from communicator 101A3.

[0248]

Communicator 101A3 transmits voltage V_i of interconnection point i and empty capacity Q_i of power storage device 3(i) to ESMS 200A, and thereafter, receives operation control information from ESMS 200A.

[0249]

Subsequently, the charge and discharge control operation of arithmetic operation section 101A4 will be described. Arithmetic operation section 101A4 controls the charge and discharge operation of power storage device 3(i) based on the operation control information received by communicator 101A3, and voltage V_i of interconnection point i detected by voltage detector 101A1.

[0250]

Next, sensor-incorporating switch slave station 700A will be described.

[0251]

Figure 19 is a diagram showing an example of sensor-incorporating switch slave station 700A.

[0252]

Sensor-incorporating switch slave station 700A is an example of an external control device. Sensor-incorporating switch slave station 700A includes voltage detector 700A1, communicator 700A2 and arithmetic operation section 700A3.

[0253]

Voltage detector 700A1 detects adjustment target voltage V_T that is a voltage of voltage adjustment target spot T (see Figure 17) in power system 1A.

[0254]

Communicator 700A2 communicates with ESMS 200A.

[0255]

Arithmetic operation section 700A3 transmits adjustment target voltage V_T detected by voltage detector 700A1 to ESMS 200A from communicator 700A2 at periods T_g.

[0256]

Next, SVR slave station 700B will be described.

[0257]

SVR slave station 700B communicates with ESMS 200A. For example, SVR slave station 700B notifies ESMS 200A of an output voltage of SVR 1A5 at periods T_g, and further, receives an SVR settling constant from ESMS 200A at periods T_g.

[0258]

The SVR settling constant is information for determining the output range of the output voltage of SVR 1A5 (hereinafter, called the "conversion output range") at the time of adjustment-target voltage V_T falling within a proper voltage range. In the present exemplary embodiment, as the SVR settling constant, center value Vref(t) of the conversion output range, upper limit value Vref_high(t) of the conversion output range, and lower limit value Vref_low(t) of the conversion output range are used. Note that Vref(t) that expresses the center value of the conversion output range may be omitted.

[0259]

SVR slave station 700B sets the newest SVR settling constant to SVR 1A5. Note that SVR 1A5 is an example of the voltage adjustment device. SVR 1A5 switches a tap (not illustrated) of SVR 1A5 and changes adjustment target voltage V_T to be within a proper voltage range, when adjustment target voltage V_T is continuously outside the proper voltage range for settling time period Ts, namely, when the output voltage of SVR 1A5 is continuously outside the conversion output range for the settling time period Ts. Note that the control method of SVR 1A5 described above is a known technique. Furthermore, settling time period Ts is an example of a specific time period.

[0260]

Next, ESMS 200A will be described.

[0261]

Figure 20 is a diagram showing an example of ESMS 200A.

[0262]

ESMS 200A is an example of a second control device or a battery control support device. ESMS 200A includes communicator 200A1, recognition section 200A2 and arithmetic operation section 200A3.

[0263]

Communicator 200A1 is an example of second communication means. Communicator 200A1 communicates with respective local charge and discharge devices 100A and sensor-incorporating switch slave station 700A. For example, communicator 200A1 receives voltages V of respective interconnection points and empty capacities Q of corresponding power storage devices 3 from respective local charge and discharge devices 100A. Furthermore, communicator 200A1 receives adjustment target voltage V_T from sensor-incorporating switch slave station 700A.

[0264]

Recognition section 200A2 is an example of recognition means. Recognition section 200A2 recognizes (stores) the information (voltages V of the respective interconnection points, empty capacities Q of respective power storage devices 3 and adjustment target voltage V_T) received by communicator 200A1 by associating the information with reception time points. Note that adjustment target voltage V_T is an example of the situation of power system 1A.

[0265]

Arithmetic operation section 200A3 is an example of processing means. Arithmetic operation section 200A3 generates correlation information showing the correlation of voltage V of the interconnection point and adjustment target voltage V_T for each of the interconnection points based on voltage V of each of the interconnection points received by communicator 200A1, and adjustment target voltage V_T recognized by recognition section 200A2.

[0266]

Furthermore, arithmetic operation section 200A3 derives voltage adjustment allotment information α based on the newest empty capacity Q of each of power storage devices 3. For example, when arithmetic operation section 200A3 is notified of respective empty capacities Q of a plurality of power storage devices 3, arithmetic operation section 200A3 derives voltage adjustment allotment information α that makes the ratio of allotments higher for larger empty capacities Q among the empty capacities Q whose arithmetic operation section 200A3 is notified, for each of power storage devices 3.

[0267]

Arithmetic operation section 200A3 generates the operation control information including the correlation information and voltage adjustment allotment information α, for each of power storage devices 3, and transmits each piece of the operation control information to local charge and discharge device 100A corresponding to power storage device 3 that corresponds to the operation control information, from communicator 200A1.

[0268]

Furthermore, arithmetic operation section 200A3 generates SVR settling constants (Vref(t), Vref_high(t) and Vref_low(t)) based on adjustment target voltage V_T, and the output voltage of SVR 1A5 whose arithmetic operation section 200A3 is notified from SVR slave station 700B. Note that a method for generating the SVR settling constants is a known technique, and therefore, a detailed explanation will be dropped. Arithmetic operation section 200A3 transmits the SVR settling constants (Vref(t), Vref_high(t) and Vref_low(t)) to SVR slave station 700B from communicator 200A1.

[0269]

Next, operations will be described.

[0270]

First, an operation of generating the SVR settling constants and setting the SVR settling constants to SVR 1A5 (hereinafter, called a "setting operation") will be described.

[0271]

Figure 21 is a sequence diagram for describing the setting operation.

[0272]

In sensor-incorporating switch slave station 700A, arithmetic operation section 700A3 causes voltage detector 700A1 to detect adjustment target voltage V_T (step S2101), and transmits adjustment target voltage V_T detected by voltage detector 700A1 to ESMS 200A from communicator 700A2 (step S2102).

[0273]

Furthermore, SVR slave station 700B detects the output voltage of SVR 1A5, and transmits the output voltage of SVR 1A5 to ESMS 200A (step S2103).

[0274]

In ESMS 200A, when communicator 200A1 receives adjustment target voltage V_T from sensor-incorporating switch slave station 700A and the output voltage of SVR 1A5 from SVR slave station 700B, recognition section 200A2 stores adjustment target voltage V_T received by communicator 200A1 and the output voltage of SVR 1A5 by associating adjustment target voltage V_T and the output voltage with each other.

[0275]

Subsequently, arithmetic operation section 200A3 derives the SVR settling constants (Vref(t), Vref_high(t) and Vref_low(t)) based on adjustment target voltage V_T and the output voltage of SVR 1A5 in recognition section 200A2 (step S2104).

[0276]

Subsequently, arithmetic operation section 200A3 transmits the SVR settling constants to SVR slave station 700B from communicator 200A1 (step S2105).

[0277]

When SVR slave station 700B receives SVR settling constants, SVR slave station 700B sets the SVR settling constants to SVR 1A5 (step S2106). Note that when SVR settling constants are already set to SVR 1A5, SVR slave station 700B updates the SVR settling constants set to SVR 1A5 to the newest SVR settling constants.

[0278]

Sensor-incorporating switch slave station 700A, SVR slave station 700B and ESMS 200A

repeat steps S2101 to S2106 at periods T_g.

[0279]

Next, the operation of SVR 1A5 will be described.

[0280]

When the output voltage of SVR 1A5 is outside upper limit value Vref_high(t) of the conversion output range specified by the SVR settling constants continuously for settling time period Ts, SVR 1A5 switches the tap of SVR 1A5 to lower the output voltage of SVR 1A5, and changes the output voltage of SVR 1A5 to a voltage within the conversion output range.

[0281]

Furthermore, when the output voltage of SVR 1A5 is outside lower limit value Vref_low(t) of the conversion output range specified by the SVR settling constants continuously for the settling time period Ts, SVR 1A5 switches the tap of SVR 1A5 to raise the output voltage of SVR 1A5, and changes the output voltage of SVR 1A5 to a voltage within the conversion output range.

[0282]

Note that settling time period Ts may be the value set in advance or may be changed with the lapse of time with consideration given to extending the life of SVR 1A5 and a secular change of SVR 1A5.

[0283]

Though the voltage of power system 1A is adjusted by the operation of SVR 1A5, high-speed variation components from among the variation components of the system voltage, for example, the components that result from output of a renewable power supply the power generation amount of which changes irregularly in accordance with the weather, cannot be handled with only the voltage adjustment by SVR 1A5.

[0284]

Therefore, in the present exemplary embodiment, the voltage variation components that cannot be handled with the voltage adjustment by SVR 1A5 are reduced by the charge and discharge operations of respective power storage devices 3.

[0285]

Next, an operation of ESMS 200A that generates operation control information that is required to perform the charge and discharge operations of power storage devices 3, and that transmits the operation control information to respective local charge and discharge devices 100A (hereinafter, called a "generation operation") will be described.

[0286]

Figure 22 is a sequence diagram for describing the generation operation.

[0287]

In sensor-incorporating switch slave station 700A, arithmetic operation section 700A3 causes voltage detector 700A1 to detect adjustment target voltage V_T (step S2201), and transmits adjustment target voltage V_T detected by voltage detector 700A1 to ESMS 200A from communicator 700A2 (step S2202).

[0288]

In ESMS 200A, each time communicator 200A1 receives adjustment target voltage V_T from sensor-incorporating switch slave station 700A, recognition section 200A2 stores adjustment target voltage V_T received by communicator 200A1.

[0289]

Subsequently, arithmetic operation section 200A3 of ESMS 200A calculates average value $V_{T,AVE}$ of adjustment target voltage V_T in recognition section 200A2 (step S2203). Recognition section 200A2 retains average value $V_{T,AVE}$ that is the calculation result.

[0290]

Meanwhile, in each of local charge and discharge devices 100A, arithmetic operation section 101A4 causes voltage detector 101A1 to detect voltage V of the interconnection point, and retains voltage V (step S2204). Hereinafter, voltage V_i of interconnection point i will be cited as an example and described in order to simplify the explanation.

[0291]

Subsequently, arithmetic operation section 101A4 calculates average value $V_{i,AVE}$ of retained voltages V_i(step S2205).

[0292]

Subsequently, arithmetic operation section 101A4 transmits average value $V_{i,AVE}$ to ESMS 200A from communicator 101A3 (step S2206).

[0293]

In ESMS 200A, each time communicator 200A1 receives an average value (hereinafter, "average value $V_{i,AVE}$" will be described) from each of local charge and discharge devices 100A, recognition section 200A2 stores average value $V_{i,AVE}$ received by communicator 200A1.

[0294]

Subsequently, arithmetic operation section 200A3 of ESMS 200A derives a correlation function at a time point t of average value $V_{i,AVE}$ and average value $V_{T,AVE}$ in recognition section 200A2 as follows by using a mechanical learning method or the like, for example, for each interconnection point (step S2207).

Correlation function: $V_{T,AVE}(t) = a_i(t) \cdot V_{i,AVE}(t) + b_i(t)$

In the present exemplary embodiment, arithmetic operation section 200A3 derives a correlation function by using a plurality of average values $V_{i,AVE}$ (10 average values $V_{i,AVE}$ in sequence from the newest one, for example) in the interconnection point, and a plurality of average value $V_{T,AVE}$ (10 average values $V_{T,AVE}$ in sequence from the newest one, for example), for each of the interconnection points.

[0295]

Furthermore, in each of local charge and discharge devices 100A, arithmetic operation section 101A4 causes empty capacity detector 101A2 to detect empty capacity Q(t) of power storage device 3 (step S2208), and transmits empty capacity Q(t) of power storage device 3, which is detected by empty capacity detector 101A2 (for example, empty capacity $Q_i(t)$ of power storage device 3(i)) to ESMS 200A from communicator 101A3 (step S2209).

[0296]

Subsequently, arithmetic operation section 200A3 of ESMS 200A derives voltage adjustment allotment information $\alpha(t)$ of each of power storage devices 3 (for example, voltage adjustment allotment information $\alpha_i(t)$ of power storage device 3(i)) based on the latest empty capacity Q(t) of each of power storage devices 3 (step S2210).

[0297]

Subsequently, arithmetic operation section 200A3 generates operation control information including coefficients $a_i(t)$ and $b_i(t)$ of the correlation function and voltage adjustment allotment $\alpha_i(t)$ for each of power storage devices 3, and transmits the operation control information to local charge and discharge device 100A corresponding to power storage device 3 that corresponds to the operation control information, from communicator 200A1 (step S2211). Note that coefficients $a_i(t)$ and $b_i(t)$ of the correlation function are examples of correlation information.

[0298]

In local charge and discharge device 100A, when arithmetic operation section 101A4 receives the operation control information (coefficients $a_i(t)$ and $b_i(t)$ of the correlation function and voltage adjustment allotment $\alpha i(t)$) via communicator 101A3, arithmetic operation section 101A4 retains the operation control information. Note that when arithmetic operation section 101A4 already retains the operation control information, arithmetic operation section 101A4 updates the operation control information already retained to the latest operation control information.

[0299]

Sensor-incorporating switch slave station 700A, local charge and discharge device 100A

and ESMS 200A repeat steps S2201 to S2211 at periods T_g.

[0300]

Note that as adjustment target voltage V_T that is used in calculation of the average values in step S2203, adjustment target voltage V_T provided in step S2102 of Figure 21 may be used. In this case, steps S2201 and S2202 can be omitted.

[0301]

Next, the operation of each of local charge and discharge devices 100A that control reactive power output Q of power storage device 3 based on the operation control information and the voltage of the interconnection point (hereinafter, called a "power control operation") will be described. The power control operations in respective local charge and discharge devices 100A are common, and therefore, for simplification of explanation, the power control operation in local charge and discharge device 100A(i) will be described hereinafter.

[0302]

Figure 23 is a sequence diagram for describing the power control operation.

[0303]

Arithmetic operation section 101A4 causes voltage detector 101A1 to detect voltage V_i of interconnection point i (step S2301).

[0304]

Subsequently, arithmetic operation section 101A4 calculates adjustment target voltage V_T from voltage V_i of interconnection point i, by performing the following calculation and using coefficients $a_i(t)$ and $b_i(t)$ of the correlation function included in the operation control information (step S2302).

Adjustment target voltage $V_T(t) = a_i(t) \cdot V_i(t) + b_i(t)$

Subsequently, arithmetic operation section 101A4 determines the magnitude relation of the calculated adjustment target voltage V_T, and upper limit threshold value V_{mu} and lower limit threshold V_{ml} that are set in arithmetic operation section 101A4 in advance. Note that upper limit threshold value V_{mu} is a value larger than the upper limit value of the voltage range without requiring switching with respect to adjustment target voltage V_T, and lower limit threshold value V_{ml} is a value smaller than the lower limit value of the voltage range without requiring switching with respect to adjustment target voltage V_T.

[0305]

When calculated adjustment target voltage V_T is larger than upper limit threshold value V_{mu}, arithmetic operation section 101A4 calculates reactive power amount $Q_i(t)$ in accordance with mathematical expression of

$Q_i(t) = [V_T(t) - V_{mu}] \times \alpha_i(t)/(dV_i(t) / dQ_i(t))$. Subsequently, arithmetic operation section 101A4 causes power storage device 3(i) to output calculated reactive power amount Qi(t) (step S2304).

[0306]

Furthermore, when calculated adjustment target voltage V_T is smaller than lower limit threshold value V_{ml}, arithmetic operation section 101A4 calculates reactive power amount $Q_i(t)$ in accordance with mathematical expression of $Q_i(t) = [V_T(t) - Vml] \times \alpha_i(t)/(dV_i(t)/dQ_i(t))$. Subsequently, arithmetic operation section 101A4 causes power storage device 3(i) to output calculated reactive power amount $Q_i(t)$ (step S2304).

[0307]

Note that when calculated adjustment target voltage V_T is from a lower limit threshold value V_{ml} to upper limit threshold value V_{mu} inclusive, arithmetic operation section 101A4 determines that adjustment is not necessary, and does not control charge and discharge of power storage device 3(i).

[0308]

Local charge and discharge device 100 repeats steps S2301 to S2303 at periods T_l.

[0309]

Next, the effect of the present exemplary embodiment will be described.

[0310]

According to the present exemplary embodiment, in local charge and discharge device 100A, arithmetic operation section 101A4 controls the operation of power storage device 3 based on operation control information provided from ESMS 200A, and the voltage of the interconnection point measured by voltage detector 101A1. Therefore, it becomes possible to adjust the operation of power storage device 3 in response to an actual change in the state of the power system while following the operation control information.

[0311]

Furthermore, ESMS 200A generates the correlation information showing the correlation of the voltage of the interconnection point detected by local charge and discharge device 100A and the adjustment target voltage. Local charge and discharge device 100A calculates the adjustment target voltage from the voltage of the interconnection point detected by local charge and discharge device 100A by using the correlation information, and when the calculated result is outside the voltage range (the predetermined voltage range) defined by upper limit threshold value V_{mu} and lower limit threshold value V_{ml}, local charge and discharge device 100A controls the operation of power storage device 3 by using the correlation information so that the adjustment target voltage is within the voltage range.

[0312]

Therefore, the adjustment target voltage that is outside the voltage range defined by upper limit threshold value V_{mu} and lower limit threshold value V_{ml} can be restored to the voltage range by controlling the charge and discharge of power storage device 3.

[0313]

Furthermore, when the calculated result of the adjustment target voltage is larger than upper limit threshold value V_{mu}, local charge and discharge device 100A controls the operation of power storage device 3 by using the correlation information so that the adjustment target voltage is included in the range between upper limit threshold value V_{mu} and the upper limit value of the proper voltage range of adjustment target voltage V_T. Furthermore, when the calculated result of the adjustment target voltage is smaller than lower limit threshold value V_{ml}, local charge and discharge device 100A controls the operation of power storage device 3 by using the correlation information so that the adjustment target voltage is included in the range between lower limit threshold value V_{ml} and the lower limit value of the proper voltage range of adjustment target voltage V_T.

[0314]

Therefore, a deviation from the proper voltage range of the voltage of the voltage adjustment target spot, namely, the adjustment target voltage can be reduced regardless of whether it is a low-speed component or a high-speed component, by using SVR 1A5 and power storage device 3. Furthermore, voltage adjustment using power storage device 3 does not hinder the operation of SVR 1A5, and therefore, switching the tap of SVR 1A5 can be effectively executed. Therefore, voltage adjustment that can be realized by switching the tap of SVR 1A5 does not have to be realized by charge and discharge of power storage device 3, and the reactive power output of power storage device 3 can also be reduced.

[0315]

Furthermore, in the present exemplary embodiment, period T_g of communication between local charge and discharge device 100A and ESMS 200A is longer than execution period T_l of charge and discharge control of power storage device 3 that is executed by local charge and discharge device 100A, and therefore, resistance to interruption and problems in communication between local charge and discharge device 100A and ESMS 200A can be increased.

[0316]

Note that while in the present exemplary embodiment, reactive power Q of power storage device 3 is controlled for the purpose of voltage adjustment, effective power P may be controlled instead of reactive power Q, or reactive power Q and effective power P may be controlled.

[0317]

Furthermore, power storage device 3 may be interconnected under the pole transformer, or may be directly interconnected to the distribution line (however, in the case of power storage device 3 owned by a customer, reactive power output having a power factor of 0.85 or more acts as a constraint). Note that in the case of system power storage device 3, as for the interconnection point, interconnection is desirably made at a point at which coefficient dV_T/dQ becomes large, between voltage V_T of the power adjustment target spot and reactive power output Q of power storage device 3. Furthermore, in the case of using voltage control that uses effective power P, interconnection is desirably made at a point where dV_T/dP becomes large.

[0318]

Furthermore, the method that is used to derive the correction is not limited to the mechanical learning method and other methods can be used.

[0319]

Moreover, while the average values are used to derive the correlation function, the average values do not have to be always used.

[0320]

Further, local charge and discharge device 100A may be realized by a computer. In this case, the computer executes each of the functions of local charge and discharge device 100A by reading and executing a program recorded in a computer-readable recording medium.

[0321]

As well, ESMS 200A may be realized by a computer. In this case, the computer executes each of the functions of ESMS 200A has by reading and executing a program recorded in a computer-readable recording medium.

[0322]

In the respective exemplary embodiments described above, the illustrated configurations are only examples, and the present invention is not limited to the configurations.

[0323]

While the invention of the present application is described with reference to the exemplary embodiments, the invention of the present application is not limited to the above-described exemplary embodiments. The configuration and the details of the invention of the present application can be variously changed in such a manner that a person skilled in the art can understand within the scope of the invention of the present application. This application claims the benefit of Japanese Patent Application No. 2013-23210, filed in Japan on February 8, 2013, and Japanese Patent Application No. 2013-168560, filed in Japan on August 14, 2013, the entire

contents of which are incorporated herein by reference.

Reference Signs List

[0324]

1000, 1000A POWER CONTROL SYSTEM
1 POWER SYSTEM
2 PHOTOVOLTAIC POWER GENERATOR
3 POWER STORAGE DEVICE
4 THERMAL POWER GENERATION EQUIPMENT
5 DISTRIBUTION TRANSFORMER
6 DISTRIBUTION LINE
7 LOAD
100 LOCAL CHARGE AND DISCHARGE DEVICE
101 DETECTOR
102 COMMUNICATOR
103 FREQUENCY METER
104 ARITHMETIC OPERATION SECTION
200 STORAGE BATTERY SCADA
201 COMMUNICATOR
202 DATABASE
203 RECOGNITION SECTION
204 ARITHMETIC OPERATION SECTION
300 CENTRAL POWER SUPPLY INSTRUCTION OFFICE
300A POWER SUPPLY INSTRUCTION SECTION
301 FREQUENCY METER
302 COMMUNICATOR
303 ARITHMETIC OPERATION SECTION
1A POWER SYSTEM
1A1 LRT
1A2 BREAKER
1A3 SWITCH
1A4 SENSOR-INCORPORATING SWITCH
1A5 SVR
1A6 POLE TRANSFORMER

100A LOCAL CHARGE AND DISCHARGE DEVICE

101A1 VOLTAGE DETECTOR

101A2 EMPTY CAPACITY DETECTOR

101A3 COMMUNICATOR

101A4 ARITHMETIC OPERATION SECTION

200A ESMS

200A1 COMMUNICATOR

200A2 RECOGNITION SECTION

200A3 ARITHMETIC OPERATION SECTION

700A SENSOR-INCORPORATING SWITCH SLAVE STATION

700A1 VOLTAGE DETECTOR

700A2 COMMUNICATOR

700A3 ARITHMETIC OPERATION SECTION

700B SVR SLAVE STATION

700C SENSOR-INCORPORATING SWITCH SLAVE STATION

800 COMMUNICATION NETWORK

What is claimed is:

1. A battery control device controlling an operation of a battery that is connected to a power system, the device comprising:

detection means that detects state information that shows the state of said battery;

first communication means that transmits the state information to an external device, and receives operation control information, that is generated based on:

the state information, and

a power amount that is allotted to said batteries that are controlled by N (N is a number that is 1 or larger) battery control devices, to control the operation of said battery from the external device; and

control means that controls the operation of said battery based on the operation control information received by said first communication means.

2. The battery control device according to claim 1,

wherein said control means controls the operation of said battery, based on a state of said power system, and based on the operation control information received by said first communication means.

3. The battery control device according to claim 2,

wherein said control means further controls the operation of said battery based on the state information.

4. The battery control device according to claim 2,

wherein said detection means detects battery information for determining a chargeable and dischargeable capacity of said battery, as the state information,

the operation control information is a ratio of a total amount of chargeable and dischargeable capacities of the batteries controlled by the N battery control devices, and the power amount allotted to all the batteries, and

said control means determines an adjustment power amount that is obtained by adjusting the power amount, which is determined in accordance with the state of said power system, based

on the ratio, and executes charge or discharge with the adjustment power amount for said battery.

5. The battery control device according to claim 2 or 3,

wherein said detection means detects battery information for determining a chargeable and dischargeable capacity of said battery, as the state information,

the operation control information is a ratio of a total amount of chargeable and dischargeable capacities of the batteries controlled by the N battery control devices, and the power amount allotted to all the batteries, and

said control means determines a correction power amount that is obtained by adjusting the power amount, which is determined in accordance with the state of said power system, based on the ratio and the state information, and executes charge or discharge with the correction power amount for said battery.

6. The battery control device according to claim 3 or 5,

wherein said first communication means receives from the external device correction information, which is generated based on the state information, that shows a charge amount or a discharge amount that brings the state of said battery close to a reference state , and

said control means controls the operation of said battery based on the correction information received by said first communication means.

7. The battery control device according to claim 6,

wherein, in a case that, with respect to the charge amounts or the discharge amounts shown in respective pieces of correction information that are transmitted to M (M is a number that is two or more) battery control devices, the charge amount is a positive value and the discharge amount is a negative value, said first communication means receives a piece of correction information that corresponds to its own device, from among the respective pieces of correction information in each of which a total sum of a charge amount and a discharge amount is zero.

8. The battery control device according to claim 6,

wherein, in a case that, with respect to the charge amounts or the discharge amounts shown in respective pieces of correction information that are transmitted to M (M is a number that is two or more) battery control devices, the charge amount is a positive value and the discharge amount is a negative value, said first communication means receives a piece of correction information that corresponds to its own device, from among the respective pieces of correction

information each of which is generated so that a speed of a change of a total sum of the charge amount and the discharge amount as time elapses becomes an upper limit of a response speed of a power stabilizing operation that is performed by an external power stabilizing device connected to said power system, or bocoms lower.

9. The battery control device according to claim 3,

wherein said first communication means receives operation information, which shows a relation of the state of said power system and an operation content of said battery, from the external device,

said control means controls the operation of said battery based on the operation information received by said first communication means,

the state of said power system is expressed in a numeric value,

the operation information is generated by using charge amounts or discharge amounts after correction, which are obtained by correcting the charge amounts or the discharge amounts, which bring states of respective batteries controlled by M (M is a number that is two or larger) battery control devices to target states, so that a total sum of the charge amounts or the discharge amounts of the respective batteries is in a linear relation with respect to the numeric value that shows the state of said power system in a situation in which the numeric value is within a predetermined range, and

the charge amounts or the discharge amounts before correction of the respective batteries are determined based on the state information of the batteries.

10. The battery control device according to claim 3 or 5,

wherein said first communication means receives a reference state of said battery from the external device, and

said control means controls the operation of said battery based on a difference between the reference state of said battery received by said first communication means, and the state of said battery shown by the state information.

11. The battery control device according to claim 10,

wherein said first communication means receives a speed-related state for determining a correction speed, at which the state of said battery is corrected, from the external device, and

said control means corrects the difference with the speed-related information received by said first communication means, and controls the operation of said battery based on a result of

the correction.

12. The battery control device according to any one of claims 2, 3, and 6 to 11,

wherein said detection means detects battery information for determining a chargeable and dischargeable capacity of said battery as the state information.

13. The battery control device according to claims 2 to 12,

wherein said control means controls the operation of said battery based on a difference of the state of said power system with respect to a reference state of said power system.

14. A battery control device controlling an operation of a battery that is connected to a power system, the device comprising:

detection means that detects a state of an interconnection point of said power system and said battery;

first communication means that transmits the state of the interconnection point to an external device, and receives operation control information, that is generated based on;

the state of the interconnection point, and

an adjustment target voltage that is a voltage of a voltage adjustment target spot in said power system, to control the operation of said battery from the external device; and

control means that controls the operation of said battery based on the operation control information received by said first communication means.

15. The battery control device according to claim 14,

wherein said first communication means receives the operation control information that is correlation information that shows correlation between the state of the interconnection point and the adjustment target voltage,

said control means calculates the adjustment target voltage from the state of the interconnection point by using the correlation information, and when a result of the calculation is

outside a predetermined voltage range, the control means controls the operation of said battery by using the correlation information so that the adjustment target voltage is within the predetermined voltage range.

16. The battery control device according to claim 15,

wherein said power system is provided with a voltage adjustment device that changes the adjustment target voltage to a voltage within a specific voltage range in the predetermined voltage range when the adjustment target voltage is continuously outside the specific voltage

range for a specific time period, and

when the result of the calculation is larger than an upper limit value of the predetermined voltage range, said control means controls the operation of said battery by using the correlation information so that the adjustment target voltage is included in a range between the upper limit value and an upper limit value of the specific voltage range, and when the result of the calculation is smaller than a lower limit value of the predetermined voltage range, said control means controls the operation of said battery by using the correlation information so that the adjustment target voltage is included in a range between the lower limit value and a lower limit value of the specific voltage range.

17. A battery control support device communicating with a battery control device controlling an operation of a battery connected to a power system, the device comprising:

second communication means that communicates with said battery control device, and receives state information that shows the state of said battery from each of N (N is an integer that is one or larger) battery control devices;

recognition means that recognizes a power amount that is allotted to said batteries that are controlled by the N battery control devices; and

processing means that generates operation control information to control the operation of said battery, based on the state information and the power amount that is recognized by said recognition means, and transmits the operation control information from said second communication means to said battery control device.

18. The battery control support device according to claim 17,

wherein the state information is battery information for determining a chargeable and

dischargeable capacity of said battery, and

said processing means generates a ratio of a total amount of chargeable and dischargeable capacities of the batteries controlled by the N battery control devices, and the power amount

allotted to all of said batteries, as the operation control information.

19. The battery control support device according to claim 17or 18,

wherein said processing means generates correction information that shows a charge amount or a discharge amount that brings the state of said battery close to a reference state, based on the state information, and transmits the correction information from said second communication means to said battery control device.

20. The battery control support device according to claim 19,

wherein the number N of said battery control devices is M (M is an integer that is two or larger), and

said processing means generates each piece of correction information in which a total sum of a charge amount and a discharge amount becomes zero when the charge amount is a positive value and the discharge amount is a negative value with respect to the charge amount or the discharge amount shown in each piece of the correction information.

21. The battery control support device according to claim 19,

wherein the number N of said battery control devices is M (M is an integer that is two or larger), and

said processing means generates each piece of correction information so that a speed of a change of a total sum of a charge amount and a discharge amount as time elapses becomes an upper limit of a response speed of a power stabilizing operation performed by an external power stabilizing device connected to said power system, or becomes lower, when the charge amount is a positive value and the discharge amount is a negative value, with respect to the charge amount or the discharge amount shown in each piece of the correction information.

22. The battery control support device according to claim 17,

wherein the number N of said battery control devices is M (M is an integer that is two or larger),

the state of said power system is expressed in a numeric value,

said processing means:

determines a charge amount or a discharge amount that brings the state of said battery close to a target state based on the state information of said battery, for each of said batteries,

corrects the charge amounts or the discharge amounts so that a total sum of the charge amounts or the discharge amounts of the respective batteries is in a linear relation with respect to the numeric value in a situation in which the numeric value showing the state of said power system is within a predetermined range,

generates operation information that shows a relation between the state of said power system and operation contents of said batteries by using the charge amounts or the discharge amounts after correction, and

transmits the operation information from said second communication means to said battery control devices.

23. The battery control support device according to claim 17,

wherein said processing means transmits a reference state of said battery from said second communication means to said battery control device.

24. The battery control support device according to claim 23,

wherein said processing means transmits speed-related information for determining a correction speed, at which the state of said battery is corrected, from said second communication means to said battery control device.

25. The battery control support device according to any one of claims 17 to 24,

wherein said recognition means accepts power amount information for determining power amounts, which are allotted to all of said batteries controlled by the N battery control devices, from an external control device that controls said power system.

26. The battery control support device according to claim 25,

wherein the state information is battery information for determining a chargeable and dischargeable capacity of said battery, and

said recognition means transmits notification information that shows a total amount of chargeable and dischargeable capacities of batteries that are controlled by the N battery control devices, said total amount being determined by the state information from the N battery control devices, to the external control device, and receives the power amount information, which reflects the total amount of the chargeable and dischargeable amounts, from the external control device.

27. A battery control support device communicating with a battery control device controlling an operation of a battery connected to a power system, the device comprising:

second communication means that receives a state of the interconnection point of said power system and said battery;

recognition means that recognizes an adjustment target voltage that is a voltage of a voltage adjustment target spot in said power systems; and

processing means that generates operation control information to control the operation of said battery, based on the state of the interconnection point and the adjustment target voltage that is recognized by said recognition means, and transmits the operation control information from said second communication means to said battery control device.

28. The battery control support device according to claim 27,

wherein said processing means generates correlation information that shows a correlation between the state of the interconnection point and the adjustment target voltage recognized by said recognition means, as the operation control information.

29. A battery control system comprising a first control device that controls an operation of a battery connected to a power system, and a second control device that communicates with the first control device,

wherein said first control device comprises:

detection means that detects state information that shows the state of said battery,

first communication means that transmits the state information to said second control device, and receives operation control information, that is generated based on:

the state information, and

a power amount that is allotted to said batteries that are controlled by N (N is a number that is 1 or larger) battery control devices, to control the operation of the battery from said second control device, and

control means that controls the operation of the battery based on the operation control information received by said first communication means, and

said second control device comprises:

second communication means that communicates with said first control means, and receives state information that shows the state of said battery from each of N (N is an integer that is one or larger) battery control devices;

recognition means that recognizes a power amount that is allotted to said batteries that are controlled by the N battery control devices; and

processing means that generates the operation control information based on the state information received by said second communication means and based on the power amount recognized by said recognition means, and transmits the operation control information from said second communication means to said first control device.

30. A battery control method that is performed by a battery control device that controls an operation of a battery connected to a power system, the method comprising:

detecting state information that shows the state of said battery;

transmitting the state information to an external device, and receiving operation control information, that is generated based on:

the state information, and

a power amount that is allotted to said batteries that are controlled by N (N is a number that is 1 or larger) battery control devices, to control the operation of the battery from the external device; and

controlling the operation of the battery based on the operation control information.

31. A battery control support method that is performed by a battery control support device that communicates with a battery control device that controls an operation of a battery connected to a power system, the method comprising:

receiving state information that shows the state of said battery from each of N (N is an integer that is one or larger) battery control devices;

recognizing a power amount that is allotted to said batteries that are controlled by the N battery control devices; and

generating operation control information to control the operation of the battery, based on the state information and the power amount, and transmitting the operation control information to the battery control device.

32. A battery control method that is performed by a battery control system including a first control device that controls an operation of a battery connected to a power system, and a second control device that communicates with the first control device, wherein:

the first control device detects state information that shows the state of said battery,

the second control device recognizes a power amount that is allotted to said batteries that are controlled by the N battery control devices,

the first control device transmits the state information to the second control device,

the second control device receives the state information,

the second control device generates operation control information to control the operation of the battery, based on the state information and the power amount,

the second control device transmits the operation control information to the first control device,

the first control device receives the operation control information, and

the first control device controls the operation of the battery, based on the operation control information.

33. A computer-readable recording medium recording a program for causing a computer

to execute:

a detection procedure of detecting state information that shows the state of said battery;

a communication procedure of transmitting the state information to an external device, and receiving operation control information, that is generated based on:

the state information, and

a power amount that is allotted to said batteries that are controlled by N (N is a number that is 1 or larger) battery control devices, to control an operation of the battery from the external device; and

a control procedure of controlling the operation of the battery, based on the operation control information.

34. A computer-readable recording medium recording a program for causing a computer to execute

a reception procedure of receiving state information that shows the state of said battery from each of N (N is an integer that is one or larger) battery control devices , from a battery control device that controls an operation of the battery connected to the power system;

a recognition procedure of recognizing a power amount that is allotted to said batteries that are controlled by the N battery control devices; and

a processing procedure of generating operation control information to control the operation of the battery, based on the state information and the power amount, and transmitting the operation control information to the battery control device.

35. The battery control device according to claim 1, wherein said first communication means receives the operation control information from the external device at irregular intervals.

36. The battery control support device according to claim 17, wherein said processing means transmits the operation control information to said battery control device at irregular intervals.

37. The battery control system according to claim 29, wherein said first communication

means receives the operation control information from the external device at irregular intervals; and said processing means transmits the operation control information to said battery control device at irregular intervals.

38. The battery control method according to claim 30, wherein the operation control information is received from the external device at irregular intervals.

39. The battery control support method according to claim 31, wherein the operation control information is transmitted to said battery control device at irregular intervals.

40. The battery control device according to claim 1, wherein time intervals, according to which said control means controls the operation of said battery based on a state of said power system and based on the operation control information, are irregular intervals.

41. The battery control system according to claim 29, wherein time intervals, according to which said control means controls the operation of said battery based on a state of power system and based on the operation control information, are irregular intervals.

42. The battery control method according to claim 30, wherein time intervals for controlling the operation of said battery based on a state of said power system and based on the operation control information, are irregular intervals.

43. The battery control device according to claim 14, wherein said control means controls the operation of said battery, based on a state of said power system, and based on the operation control information received by said first communication means.