

STALL CONDITION DETECTION

FIELD OF THE INVENTION

The invention relates to elevators and more particularly to detecting a stall condition of an elevator car or counterweight.

BACKGROUND OF THE INVENTION

Elevators comprising a traction sheave arranged to operate at least one, typically more, ropes to which an elevator car and a counterweight is attached are commonly used. The friction between ropes and traction sheave is critical in elevators. In normal operation conditions the friction between ropes and traction sheave is large enough so that when the motor operates the traction sheave the elevator moves up or down. The friction force is determined by a plurality of different factors, for example, the shape and texture of rope and traction sheave and weight of the elevator car and counterweight. Parameters of these factors are decided for various reasons, for example, energy efficiency and security requirements.

When the friction between the ropes and the traction sheave is high enough the ropes in the traction sheave do not slip even if the elevator car or the counterweight has stalled. Stalling can be caused, for example, by running failure where the elevator car or counterweight gets stuck in the elevator shaft. If the elevator car is going upwards and the downward going counterweight gets stuck there will be slack in the rope between the traction sheave and counterweight. The slack between the traction sheave and the counterweight, or the elevator car if the movement is in opposite direction, can cause inconveniences or even security risk. A further example of stalling is a situation wherein the counterweight, or an elevator

car, is at the buffer but the hoisting machine is still operating.

Conventionally this problem has been solved by designing the system so that the friction is large enough to operate in normal conditions and in case of stalling it is not too high so that the rope will slip. This kind of designing sets limitation to the overall design of the elevator system and the additional mechanical movement causes inefficiency and unnecessary wear.

In an improved method the stalling situation is detected by monitoring the current required by the hoisting machine. For example, if the counterweight has stalled the gravity caused by the counterweight does not help in hoisting of the elevator car. Thus, the hoisting machine needs more electric current in order to maintain the upward movement of the elevator car. The stalling situation is detected if the current required by the hoisting machine exceeds a predetermined threshold value.

The drawback of the current threshold implementation is that the current does not exceed the threshold in all conditions. The current threshold must be above the highest allowable current and it is possible that it is not exceeded always when stalling has occurred.

SUMMARY

Stall condition in an elevator is potentially dangerous situation if it causes slack to the ropes of the elevator. In such situation a counterweight or elevator car does not move even if the hoisting machine is still operating. This situation may be prevented by stopping the elevator as early as possible after detecting such stall condition. The detection of the

stall condition is based on monitoring the torque generated by the hoisting machine of the

elevator. When rapid change in the torque is detected a stall condition is suspected. The elevator
5 may be stopped or an alarm may be launched when the stall condition is suspected.

The present invention is applicable in all elevators having a traction sheave involving suspension means including common twisted cord steel ropes,
10 high friction coated ropes, cogged belts and similar.

In an embodiment of the invention a method for detecting a stall condition in an elevator is disclosed. In the method torque used for hoisting said elevator is monitored. From the monitored torque the
15 rate of change of said torque used is computed. A stall condition is detected when said computed rate of change exceeds a predetermined threshold value. In a further embodiment of the invention a computer program for to be executed in a controlling unit capable of
20 instructing at least one elevator is disclosed.

In a further embodiment of the invention a system for detecting a stall condition in an elevator is detected. The system further comprises a control unit configured to measure the torque used for hoisting
25 said elevator, wherein said control unit is configured to detect a stall condition when said torque changes rapidly. The rapid change may be detected with the method described above.

In a further embodiment of the invention a
30 system described above is used for controlling at least one elevator. The system may be implemented to each of the elevators or at the group controlling level.

The benefit of the invention is that it is
35 capable of detecting a stall condition in situations that are not covered by the conventional methods, such as torque or current threshold and thus solves the

problems of prior art. A further benefit of the invention is that it does not typically require structural changes to the elevator. Typically the invention can be implemented using the existing equipment, however, 5 when the elevator does not include the necessary components the needed components may be added without a need of further modifications to the existing system.

Thus, a benefit of the invention is that it improves the passenger security and is easy and cost efficient to implement. Furthermore, when the stalling 10 condition controlling can be handled according to the present invention the designer has more freedom when choosing friction properties for ropes and traction sheave. This may allow better functionality and/or 15 cheaper price of the whole elevator.

A further benefit of the invention is that it provides better passenger security also in configurations having suspension means that cannot slip. For example, when an elevator car operated with a cogged 20 belt is going downwards, it is possible that the elevator car stalls. In such case when the hoisting machine continues operating the elevator slack between the traction sheave and the elevator car emerges. When the elevator car has stopped unexpectedly due to undesired defect it is possible that elevator car stops 25 only temporarily. Thus, when the stall condition is released and there is slack in suspension means the car may fall freely. When the suspension means do not have slack any more an undesired impact may be caused. 30 Such an impact is not only uncomfortable but may be also dangerous. The benefit of the invention is that it detects such a situation rapidly so that the elevator may be stopped without causing risks or inconveniences to passengers in the elevator car. Correspondingly a stall condition of the counterweight may 35 cause risks or inconveniences.

BRIEF DESCRIPTION OF THE DRAWINGS

The accompanying drawings, which are included to provide a further understanding of the invention and constitute a part of this specification, illustrate embodiments of the invention and together with the description help to explain the principles of the invention. In the drawings:

Fig. 1 is a block diagram of an example embodiment of the present invention is disclosed,

Fig. 2 is a flowchart of an example embodiment of the present invention, and

Fig. 3 is an illustration of a rapid change according to the example of figure 2.

DETAILED DESCRIPTION OF THE INVENTION

Reference will now be made in detail to the embodiments of the present invention, examples of which are illustrated in the accompanying drawings.

In figure 1 a block diagram of an example embodiment according to the present invention is disclosed. In the embodiment a hoisting machine 10 is configured to operate an elevator comprising an elevator car 11 and a counterweight 12. The elevator car 11 and the counterweight 12 are coupled with a rope 13 that is arranged to be operated by the hoisting machine 10. The ropes are coupled to the elevator car 11 and the counterweight 12 by diverting pulleys 16, 17. The ends of the rope 13 are coupled to the elevator shaft so that the elevator can be operated. For example, the ropes may be coupled to support structures of the hoisting machine so that the traction sheave 15 can be operated by a hoisting machine. A person skilled in the art understands that there are also other configurations for the elevator ropings.

In figure 1 the hoisting machine 10 is coupled to the power source 14 so that the electric motor 18 is able to transform the electricity into torque for moving the elevator car and the counterweight through the traction sheave 15. The hoisting machine further comprises a control unit 19 that is connected to the power source such that it can measure the power consumption of the electric motor 18.

In the example of figure 1 the elevator car 11 is going upwards and the counterweight 12 downwards. For some reason the counterweight 12 get jammed to the shaft so that it stops moving downwards. Immediately there will be slack in the rope 13 on the side of the counterweight 12. Because the counterweight 12 does not help the upward movement of the elevator car 11 the electric motor 15 must do all the work. Thus, it needs more power from the power source 14.

The control unit 19 measures the electric current continuously. When it detects a rapid change in the electric current from power source 14 to electric motor 14 it determines that the counterweight is not moving anymore. After the determination the control unit 19 makes the emergency stop of the elevator in order to prevent further slack. Further actions, such as automatic emergency call, may be applied.

In the embodiment explained with referral to Figure 1 the rapid change of torque was disclosed. The torque was derived from the electric current. Thus, detecting rapid change in the electric current is an example of measuring the change of the torque applied at that moment of time. Also other means of detecting the rapid change may be applied.

In figure 2 a method according of an example embodiment is disclosed. In the method the use of the electric current is monitored, step 20. Modern elevators may be configured to monitor a plurality of different functions for various purposes. For the present

invention it is interesting to measure the torque used for hoisting and it can be derived from the electric current used for hoisting. The actual measurement process is known to a person skilled in the art of signal processing and depending on the application it may be necessary process the measured signal in order to make correct conclusion from the measurement result. For example, the processing may include filtering undesired, typically high frequency components from the torque indicating signal. During monitoring the rate of change of used torque is continuously computed, step 21. For example, the change may be measured during a predetermined time interval. Such interval may be chosen on an application basis, however, a person skilled in the art understands that the time interval must be relatively small period of time as elevators travel fast and the slack should be minimized. The computed value is continuously compared with a predetermined threshold, step 22. The threshold is also chosen on an application basis so that the ordinary movement of the elevator does not trigger the condition. If the threshold is exceeded the elevator may be stopped, step 23. Instead of stopping it is possible to launch an alarm, however, when slack in the ropes is suspected it is typical to stop the elevator for the sake of the passenger security. Typically the alarm is launched always after an emergency stop.

If the elevator does not comprise a measurement device it is possible to install an additional measurement device. The measurement device may comprise all functionality discussed. Thus, when the additional device detects rapid change it is capable of stopping the elevator and launching an alarm.

In Figure 3 a diagram disclosing a rapid change is illustrated. In figure at the moment of time x pointed by the arrow 30 a rapid change has occurred as the value of y changes rapidly as a function of x .

Thus the derivate, $f'(x)$ has a high value and hoisting must be stopped. For the sake of the clarity in Figure 3 a threshold current 31 according to prior art is disclosed. The threshold current mechanism may be used
5 together with the present invention, however, in the example of Figure 3 the threshold current is not exceeded. Thus, the conventional method would not detect the possible stall condition of the example. This can be caused, for example, when an empty elevator car is
10 hoisted. Thus, the current needed is smaller compared to the situation where full elevator car is hoisted and thus, the threshold current is not exceeded.

The above mentioned method may be implemented as computer software which is executed in a computing
15 device able to communicate with a measurement device for detecting rapid change in torque used for hoisting and to stop the elevator when such change is detected. When the software is executed in a computing device it is configured to perform the above described inventive
20 method. The software is embodied on a computer readable medium so that it can be provided to the computing device.

As stated above, the components of the exemplary embodiments can include computer readable medium
25 or memories for holding instructions programmed according to the teachings of the present inventions and for holding data structures, tables, records, and/or other data described herein. Computer readable medium can include any suitable medium that participates in
30 providing instructions to a processor for execution. Common forms of computer-readable media can include, for example, a floppy disk, a flexible disk, hard disk, magnetic tape, any other suitable magnetic medium, a CD-ROM, CD±R, CD±RW, DVD, DVD-RAM, DVD±RW,
35 DVD±R, HD DVD, HD DVD-R, HD DVD-RW, HD DVD-RAM, Blu-ray Disc, any other suitable optical medium, a RAM, a PROM, an EPROM, a FLASH-EPROM, any other suitable

memory chip or cartridge, a carrier wave or any other suitable medium from which a computer can read.

It is obvious to a person skilled in the art that with the advancement of technology, the basic
5 idea of the invention may be implemented in various ways. The invention and its embodiments are thus not limited to the examples described above; instead they may vary within the scope of the claims.

CLAIMS

1. A method for detecting a stall condition in an elevator, which method comprises the steps of:
monitoring torque of a hoisting machine used for
5 hoisting said elevator;
computing the rate of change of said torque used;
and,
detecting a stall condition when said computed
rate of change exceeds a predetermined threshold val-
10 ue.
2. The method according to claim 1, wherein the method further comprises stopping said elevator as a response to a detected stall condition.
3. The method according to claim 1 or 2,
15 wherein the method further comprises launching an alarm as a response to a detected stall condition.
4. The method according to any of preceding claims, wherein determining said torque by monitoring electric current input in or output from the hoisting
20 machine motor.
5. A computer program comprising code adapted to cause the method according to any of claims 1 - 4 when executed on a data-processing system.
6. A system for detecting a stall condition
25 in an elevator, which system further comprises:
a control unit (19) configured to measure the torque of a hoisting machine used for hoisting said elevator, wherein said control unit (19) is configured to detect a stall condition when said torque changes
30 rapidly.
7. The system according to claim 6, wherein said control unit (19) comprises a measurement device configured to determine said torque by monitoring electric current input in or output from the hoisting
35 machine motor.

8. The system according to claim 6 or 7, wherein said system further comprises a processor for determining said stall condition.

5 9. The system according to any of preceding claims 6 - 8, wherein said system is configured to stop the elevator as a response to a detected stall condition.

10 10. The system according to any of preceding claims 6 - 9, wherein said system is configured to launch an alarm as a response to a detected stall condition.

11. The system according to any of preceding claims 6 - 10, wherein said controller is configured to monitor a plurality of elevators.

15 12. The system according to any of preceding claims 6 - 11, wherein said control unit (19) is configured to detect the rapid change by computing the rate of change of said torque used; and, detecting a stall condition when said computed rate of change exceeds a predetermined threshold value.

13. An elevator comprising a system according to any of preceding claims 6 - 12.

25 14. An elevator group comprising a system according to any of preceding claims 6 - 12.