

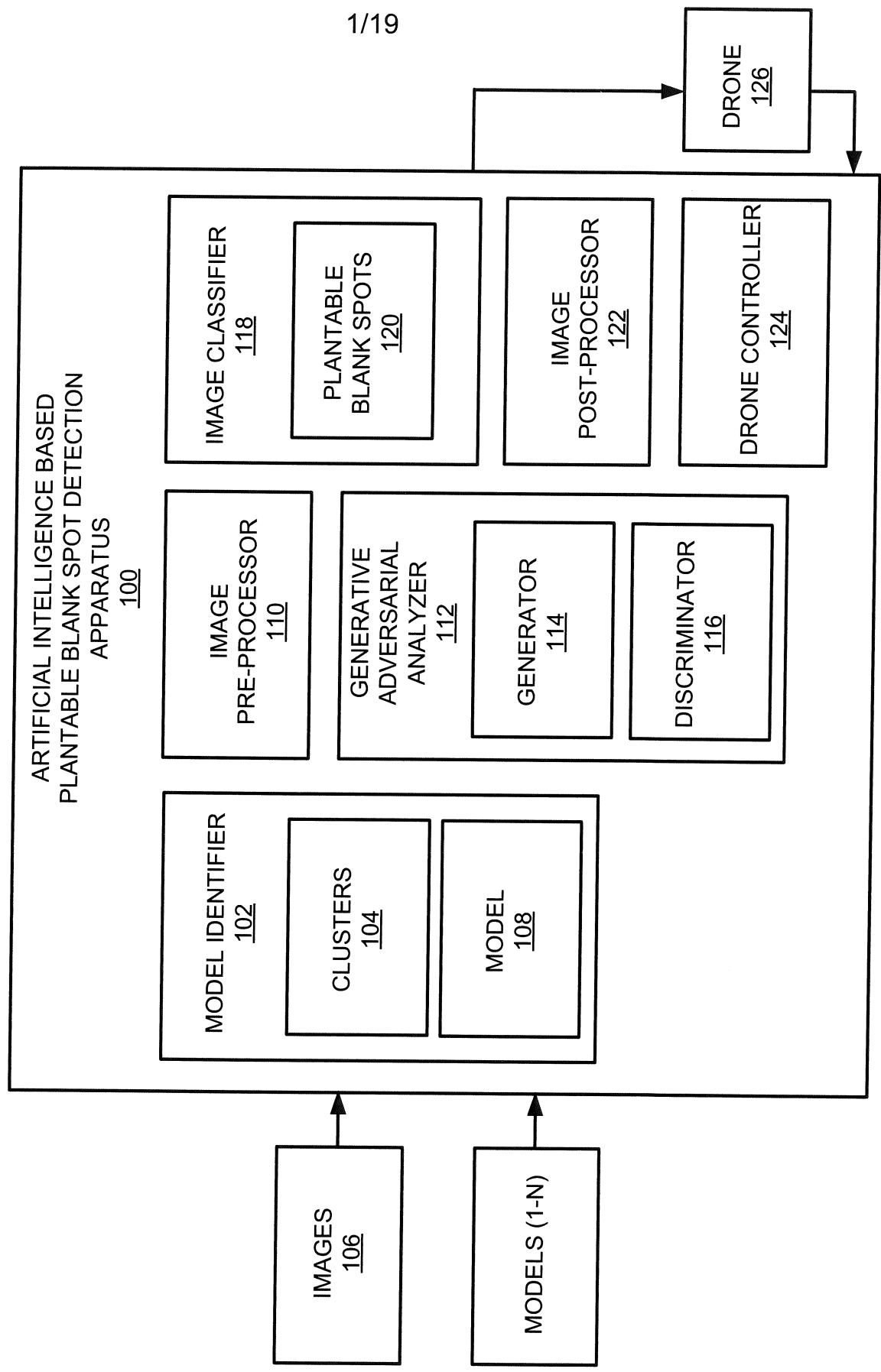


FIG. 1

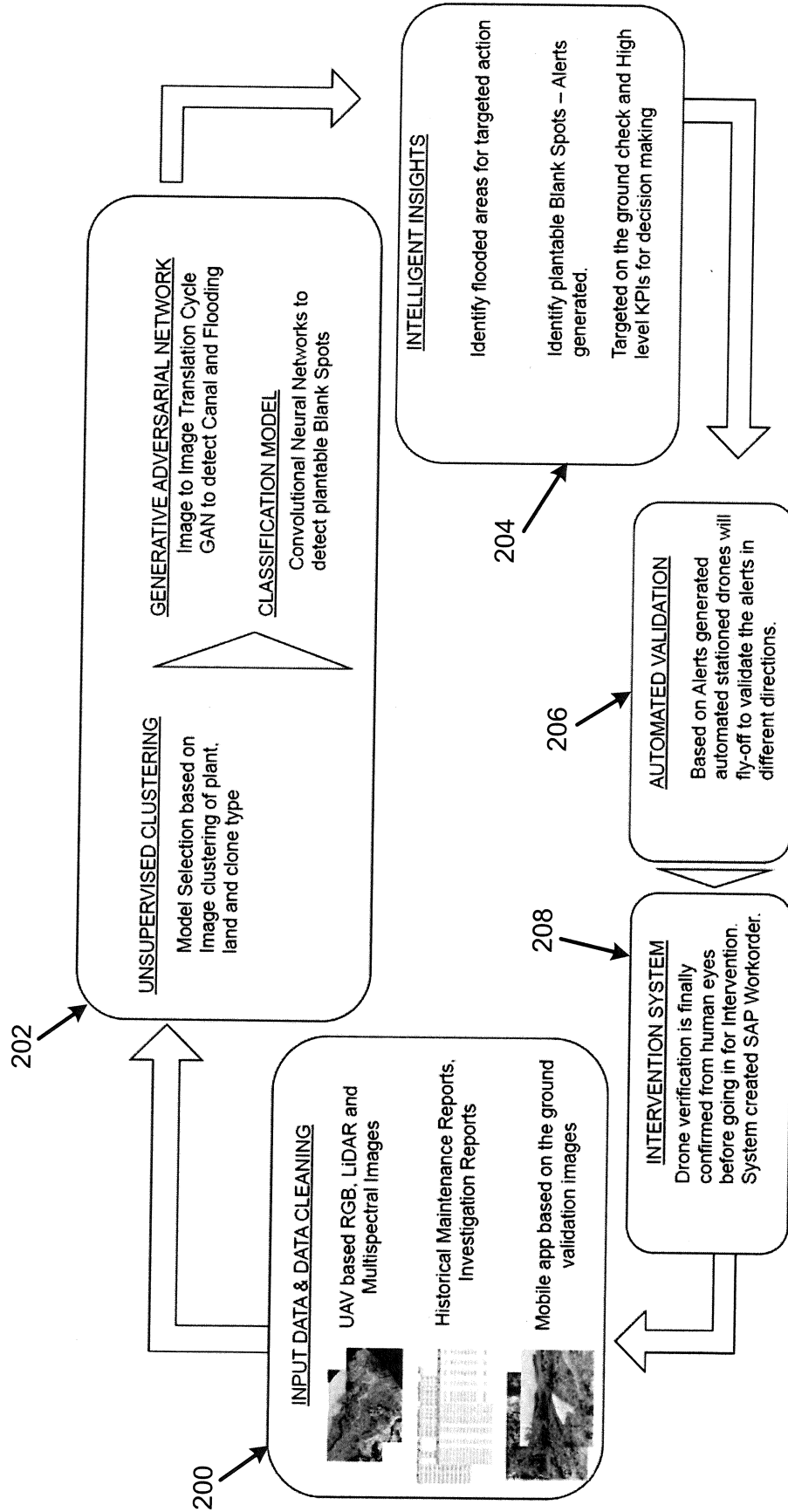


FIG. 2

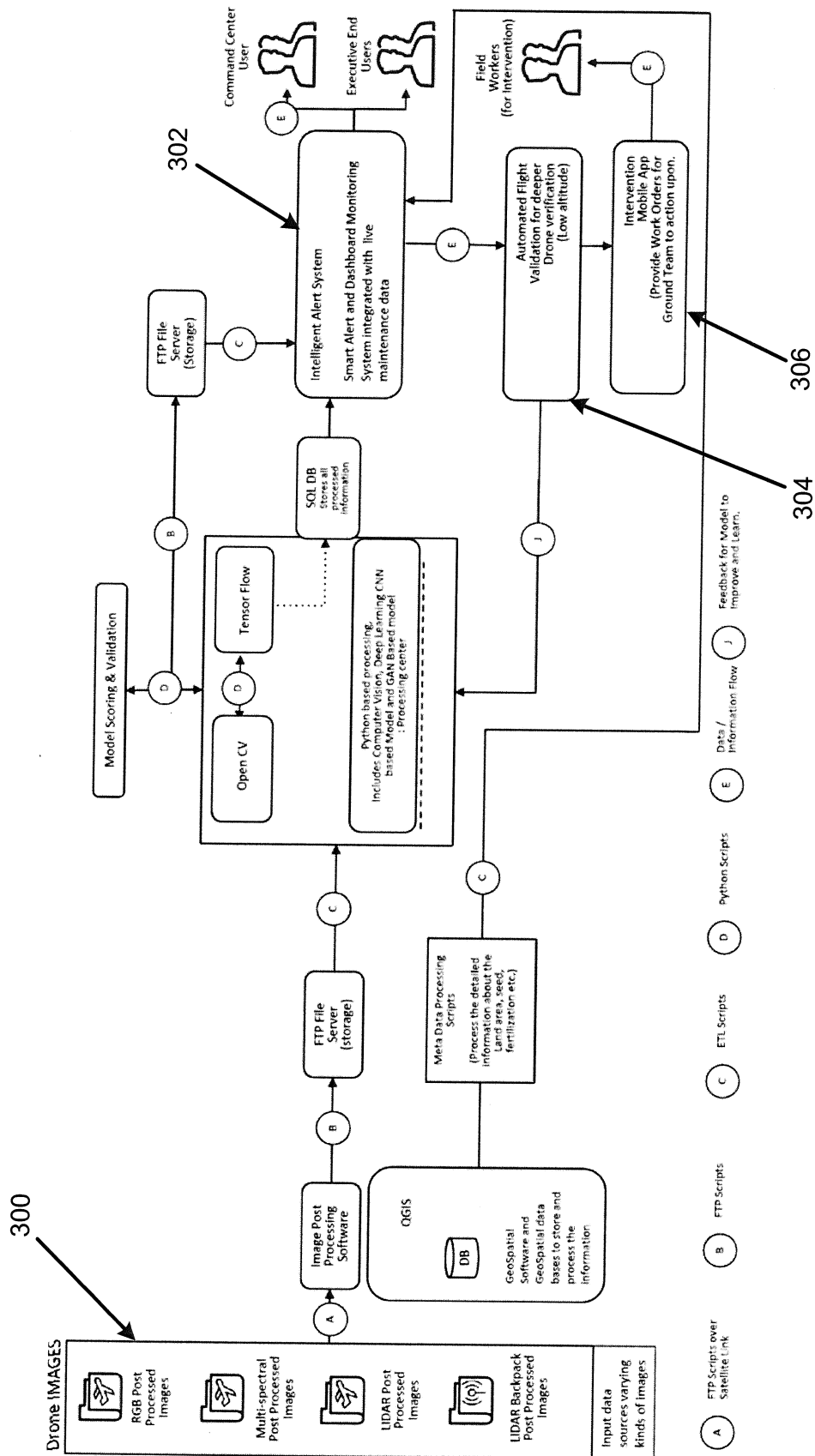


FIG. 3

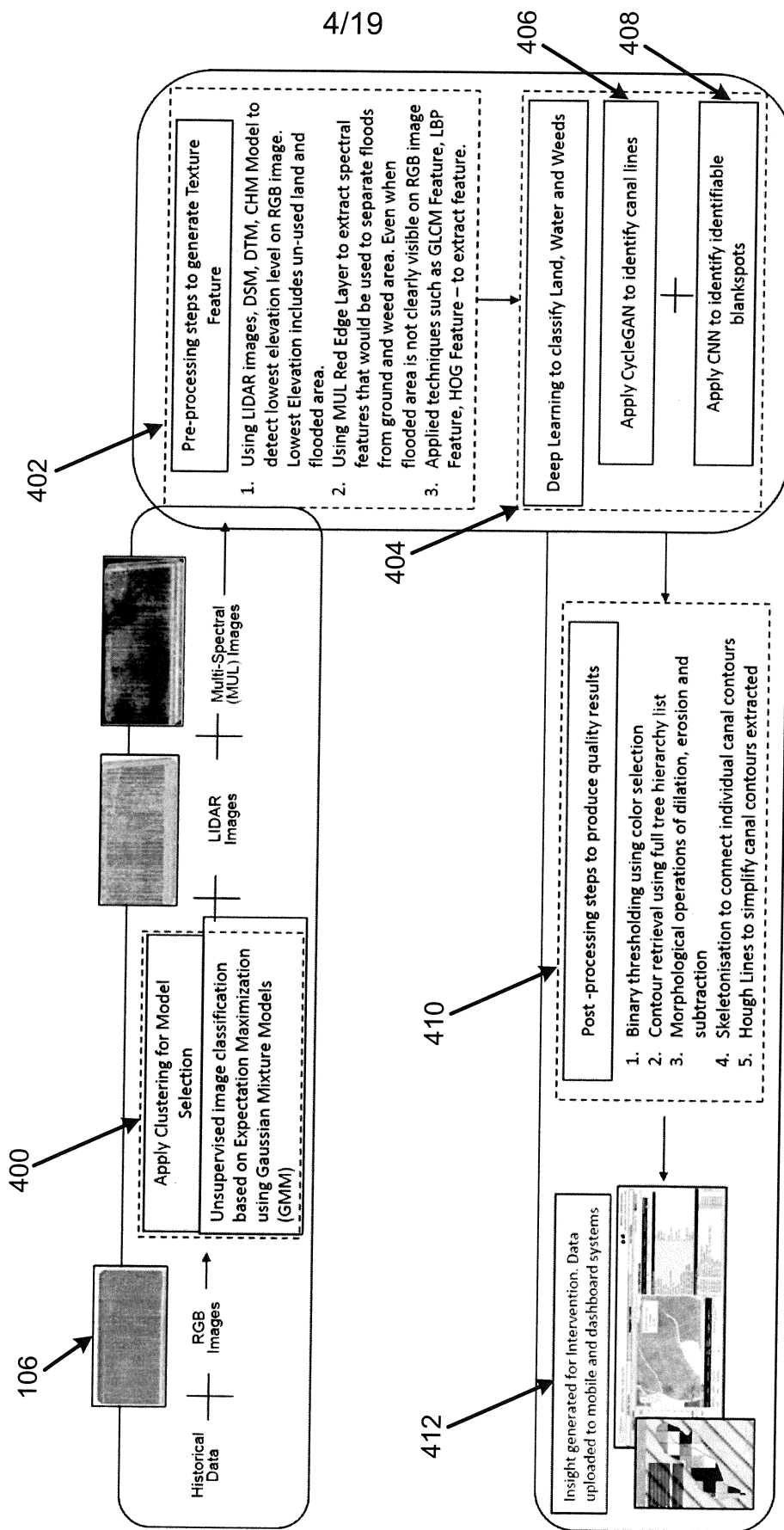


FIG. 4

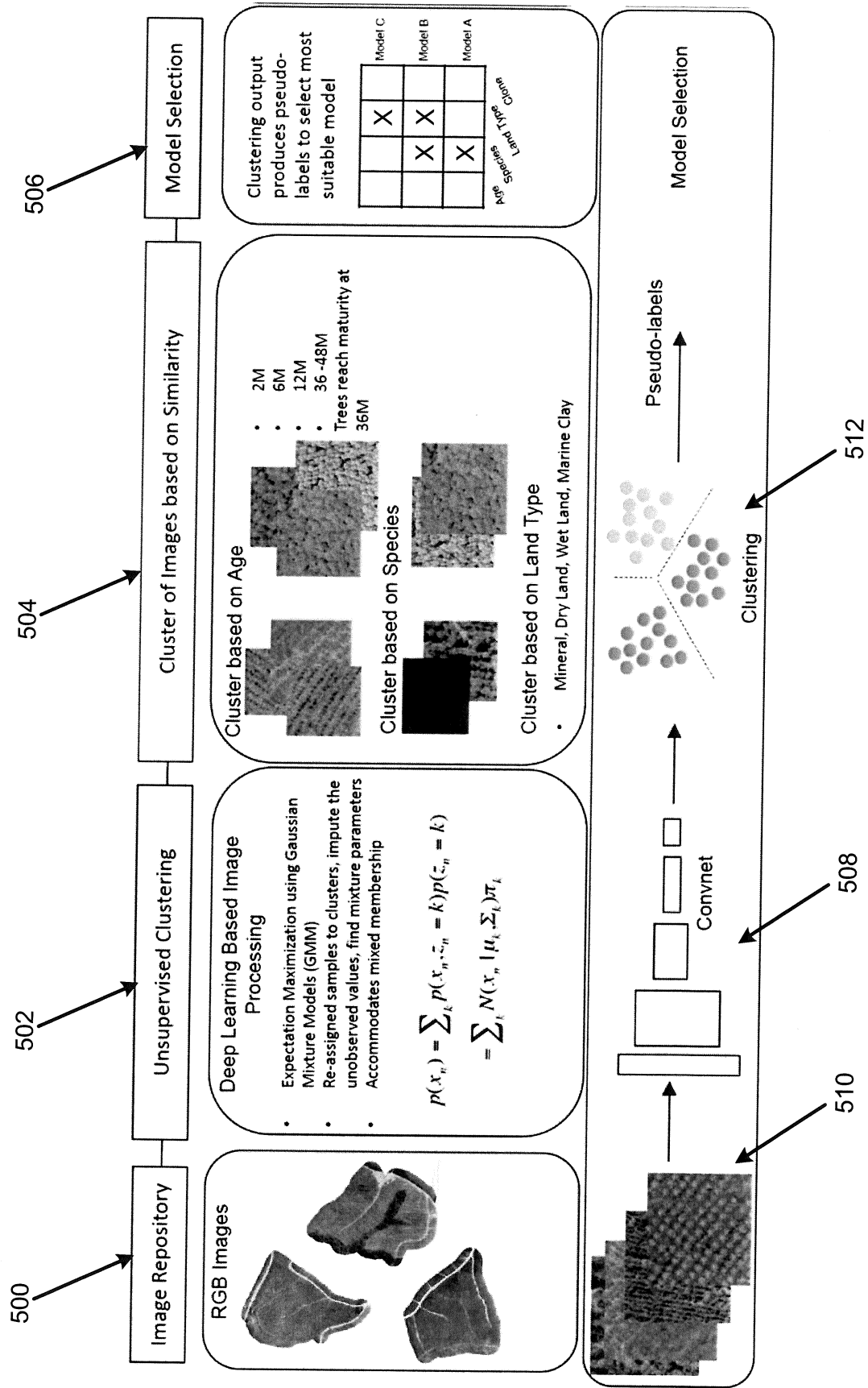


FIG. 5

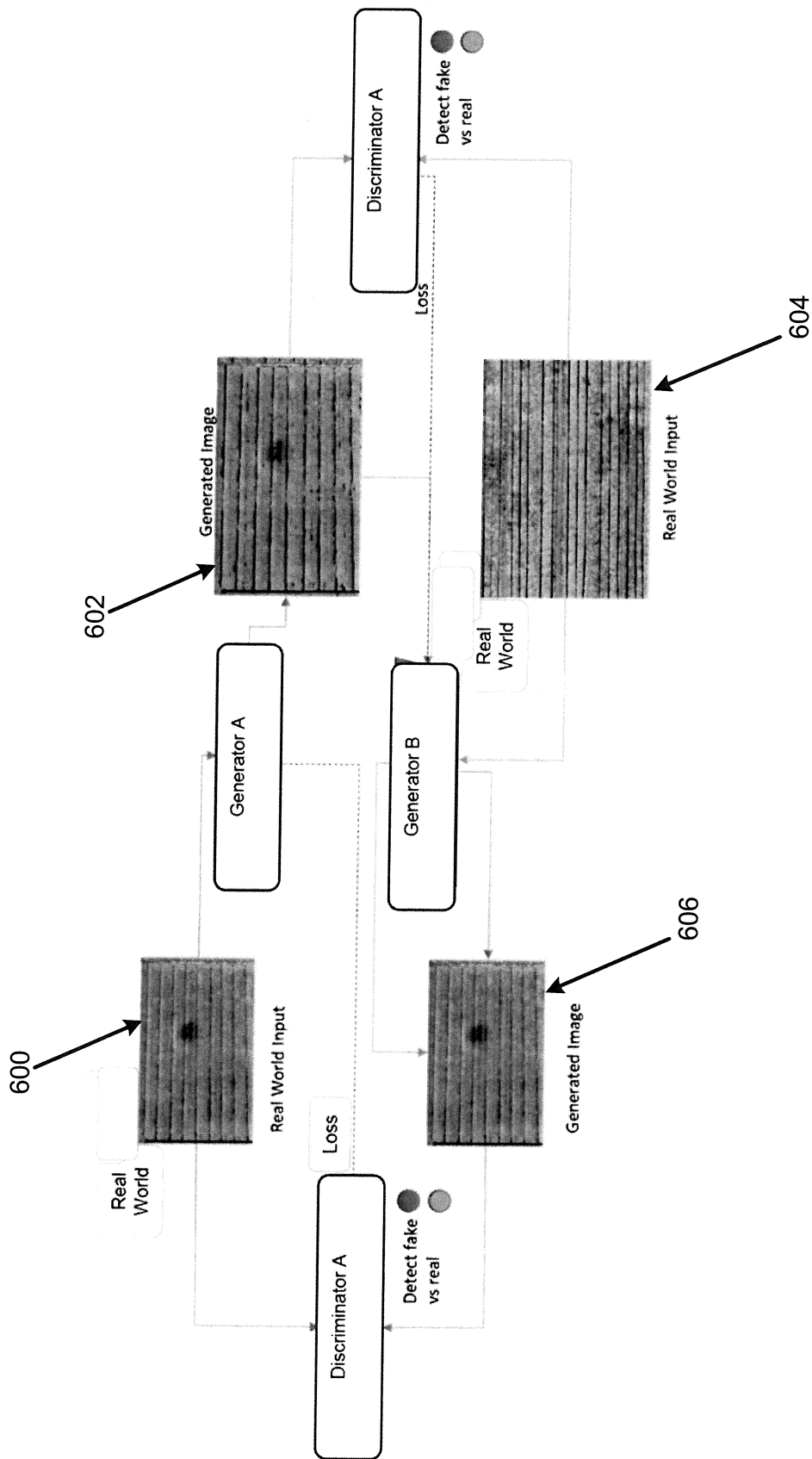


FIG. 6

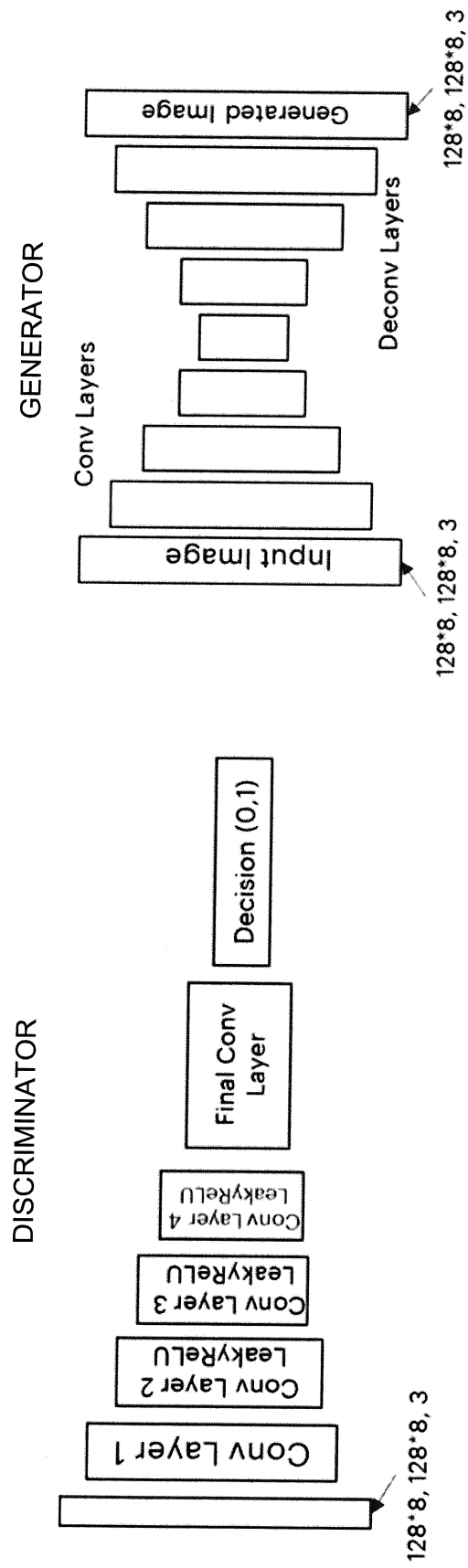


FIG. 7

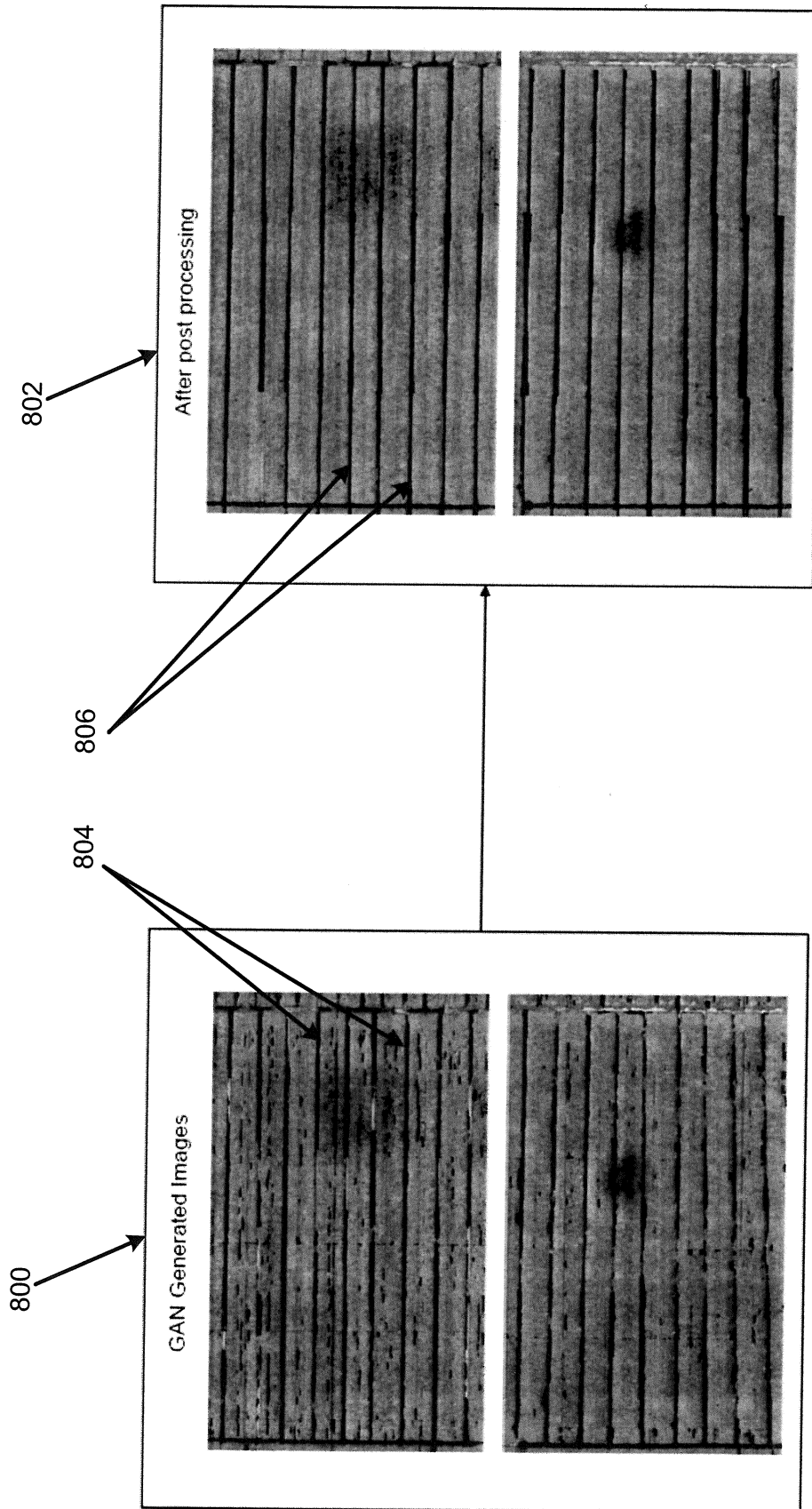


FIG. 8

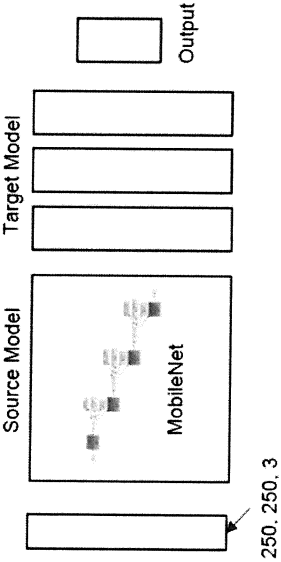
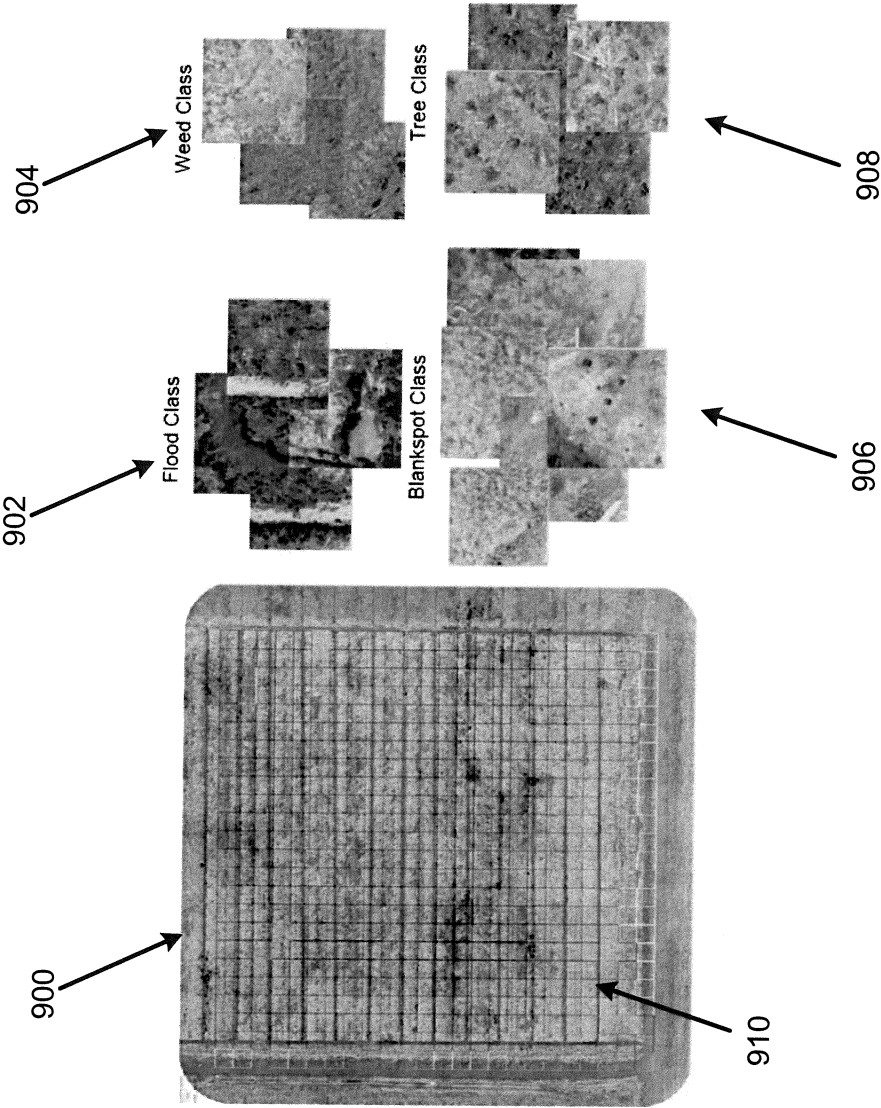
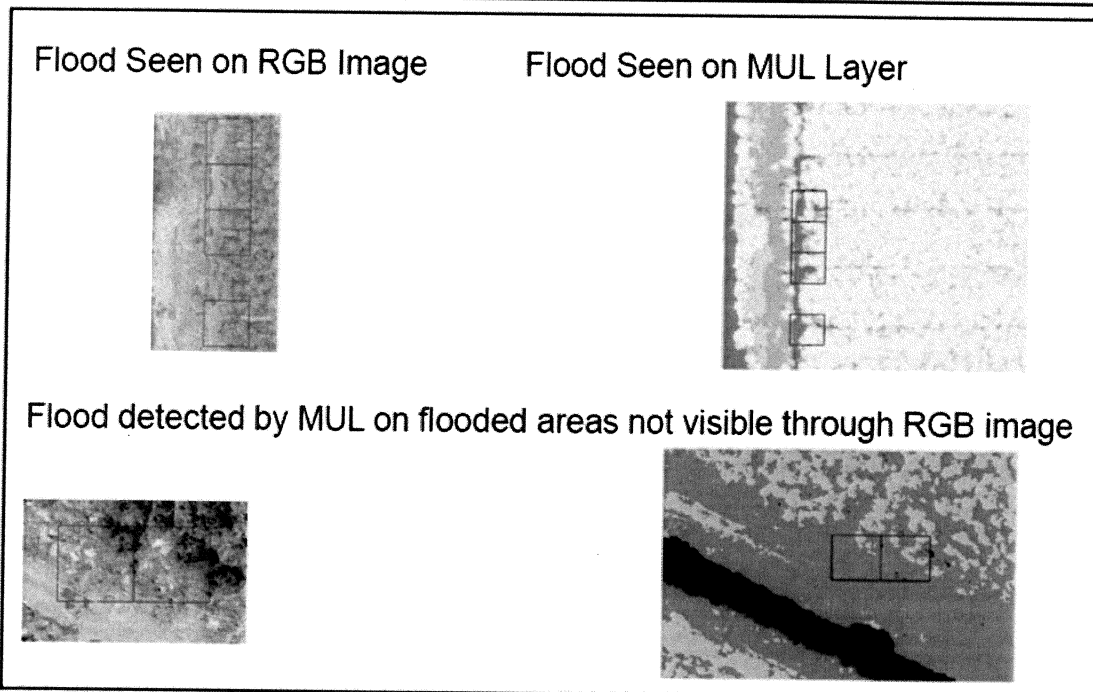
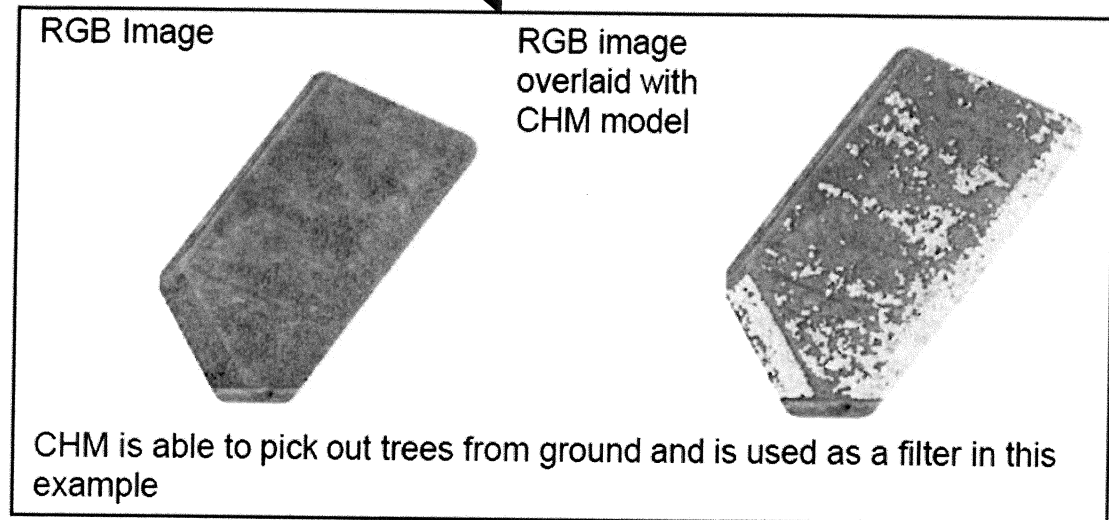


FIG. 9

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1000



1002

FIG. 10

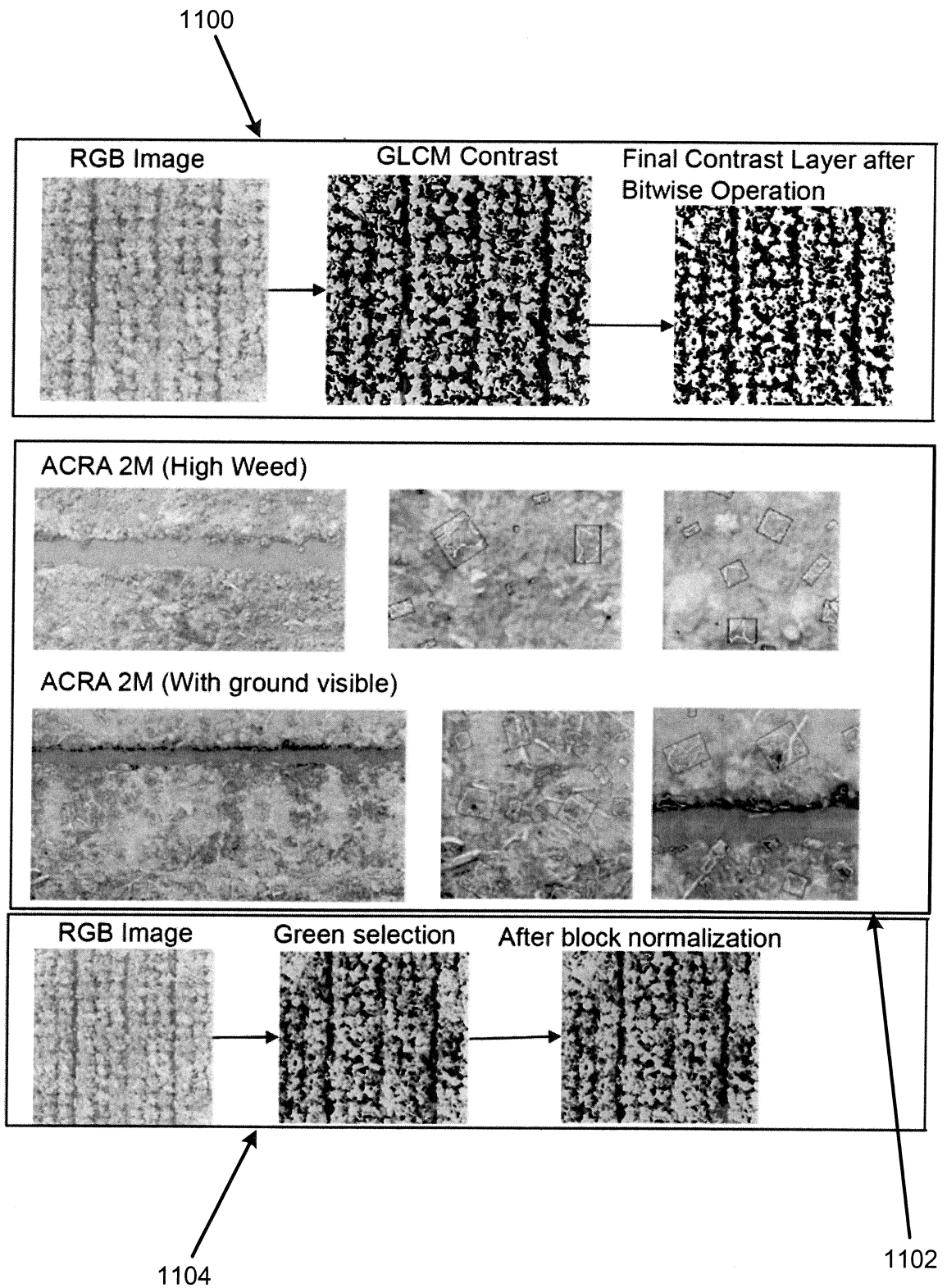


FIG. 11

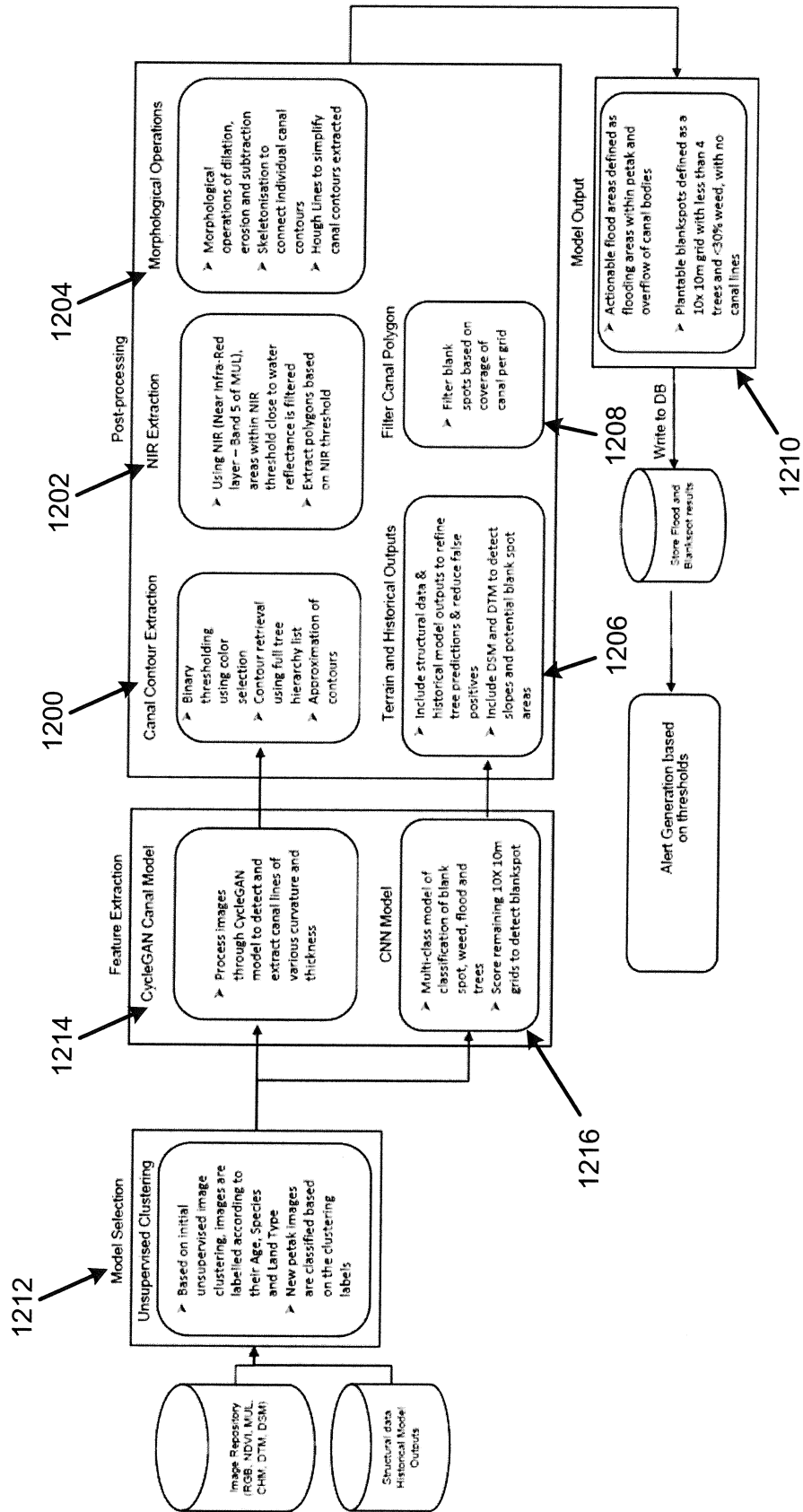


FIG. 12

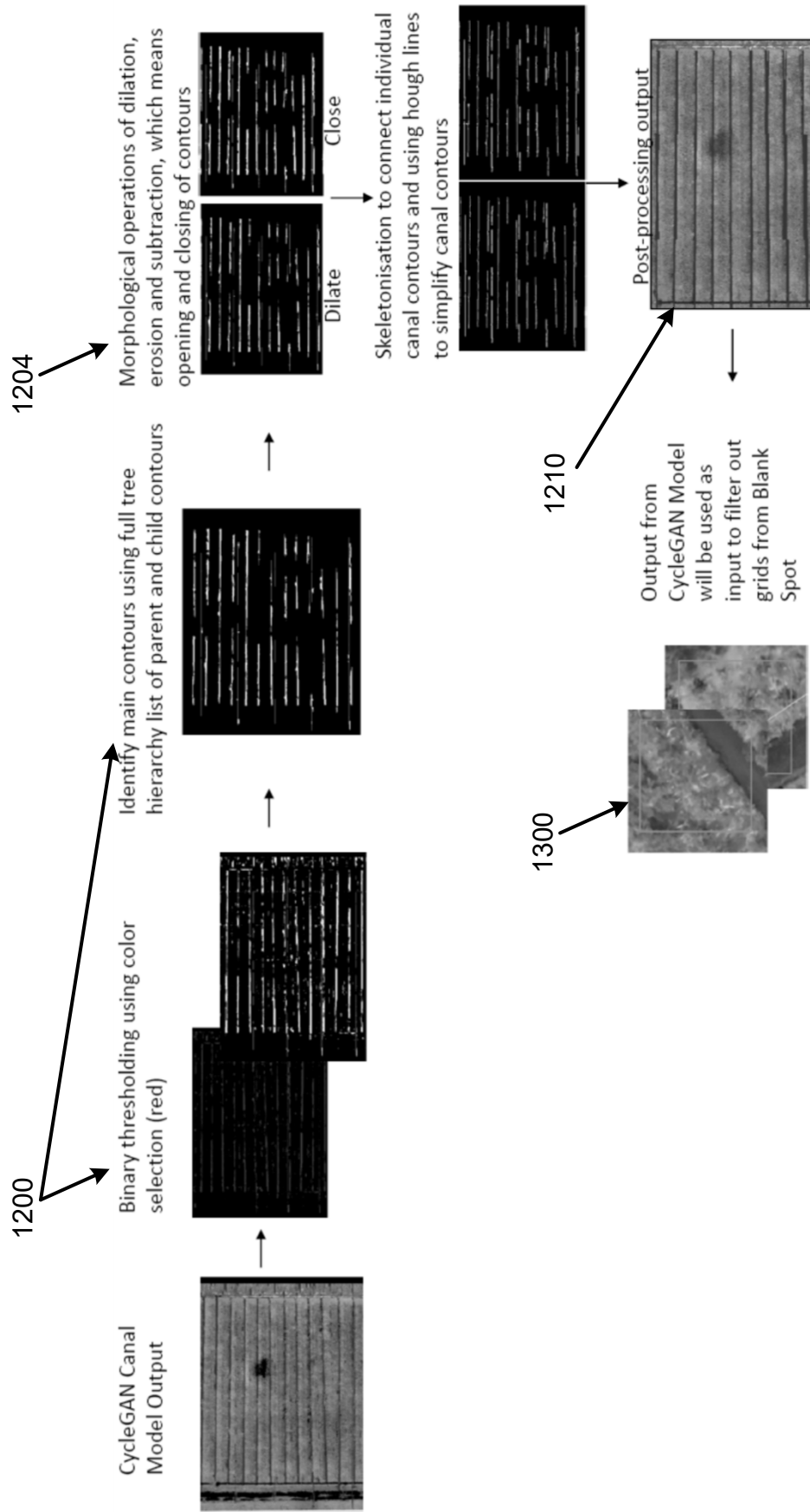
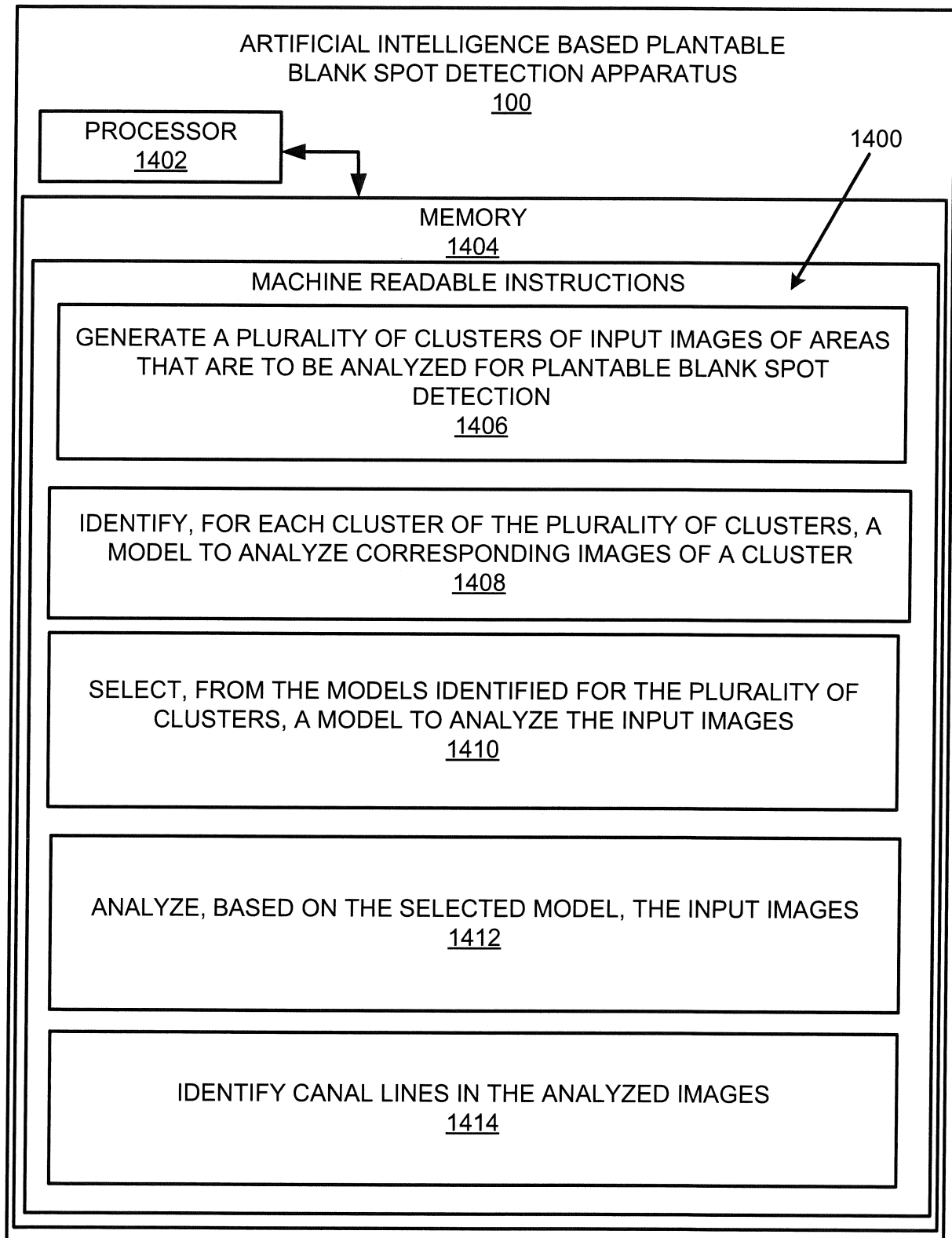


FIG. 13

**FIG. 14**

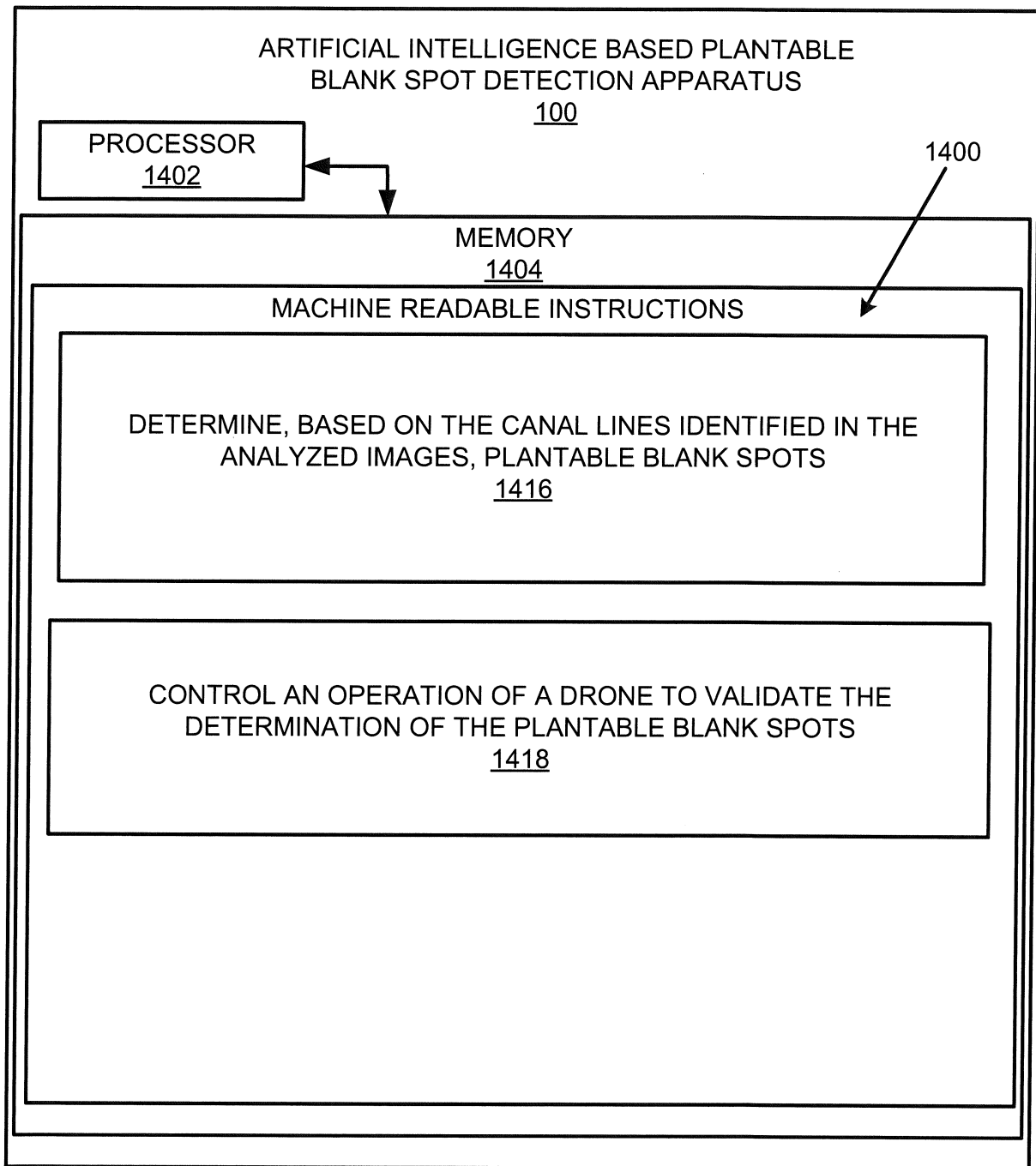


FIG. 14 (CONT.)

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1500

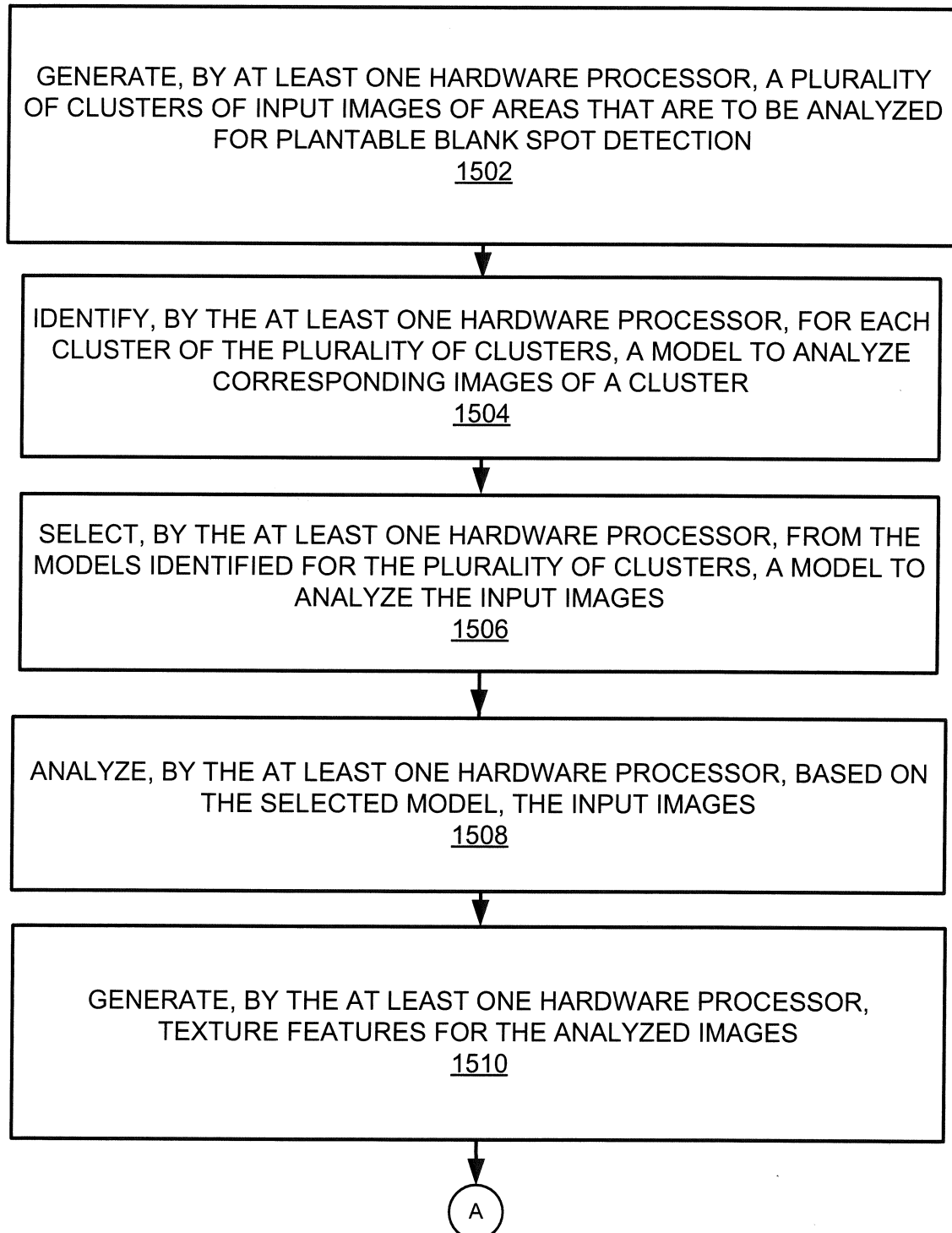


FIG. 15

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1500



IDENTIFY, BY THE AT LEAST ONE HARDWARE PROCESSOR, CANAL
LINES IN THE ANALYZED IMAGES

1512

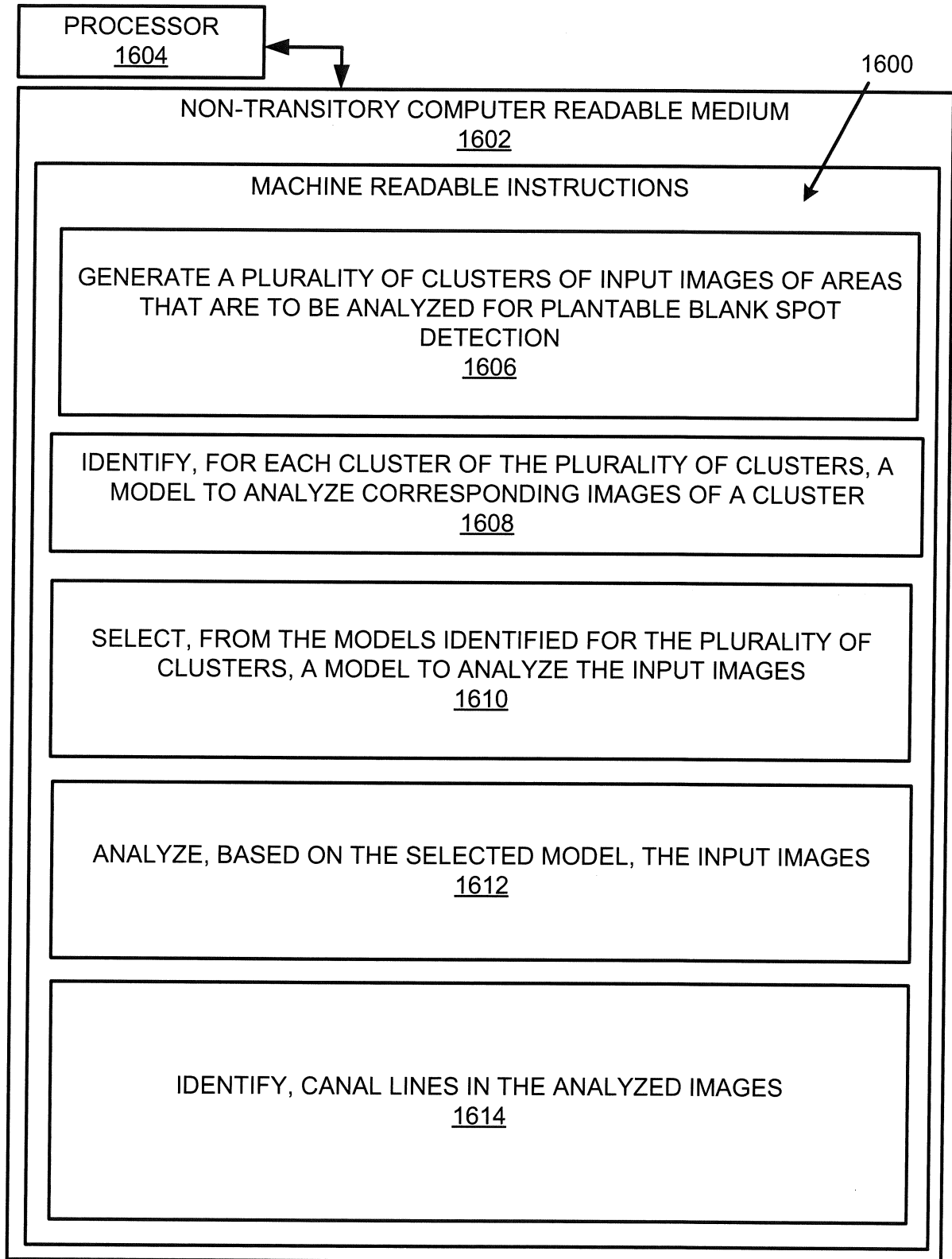
DETERMINE, BY THE AT LEAST ONE HARDWARE PROCESSOR, BASED
ON THE CANAL LINES IDENTIFIED IN THE ANALYZED IMAGES,
PLANTABLE BLANK SPOTS

1514

CONTROL, BY THE AT LEAST ONE HARDWARE PROCESSOR, AN
OPERATION OF A DRONE TO VALIDATE THE DETERMINATION OF THE
PLANTABLE BLANK SPOTS

1516

FIG. 15 (CONT.)

*FIG. 16*

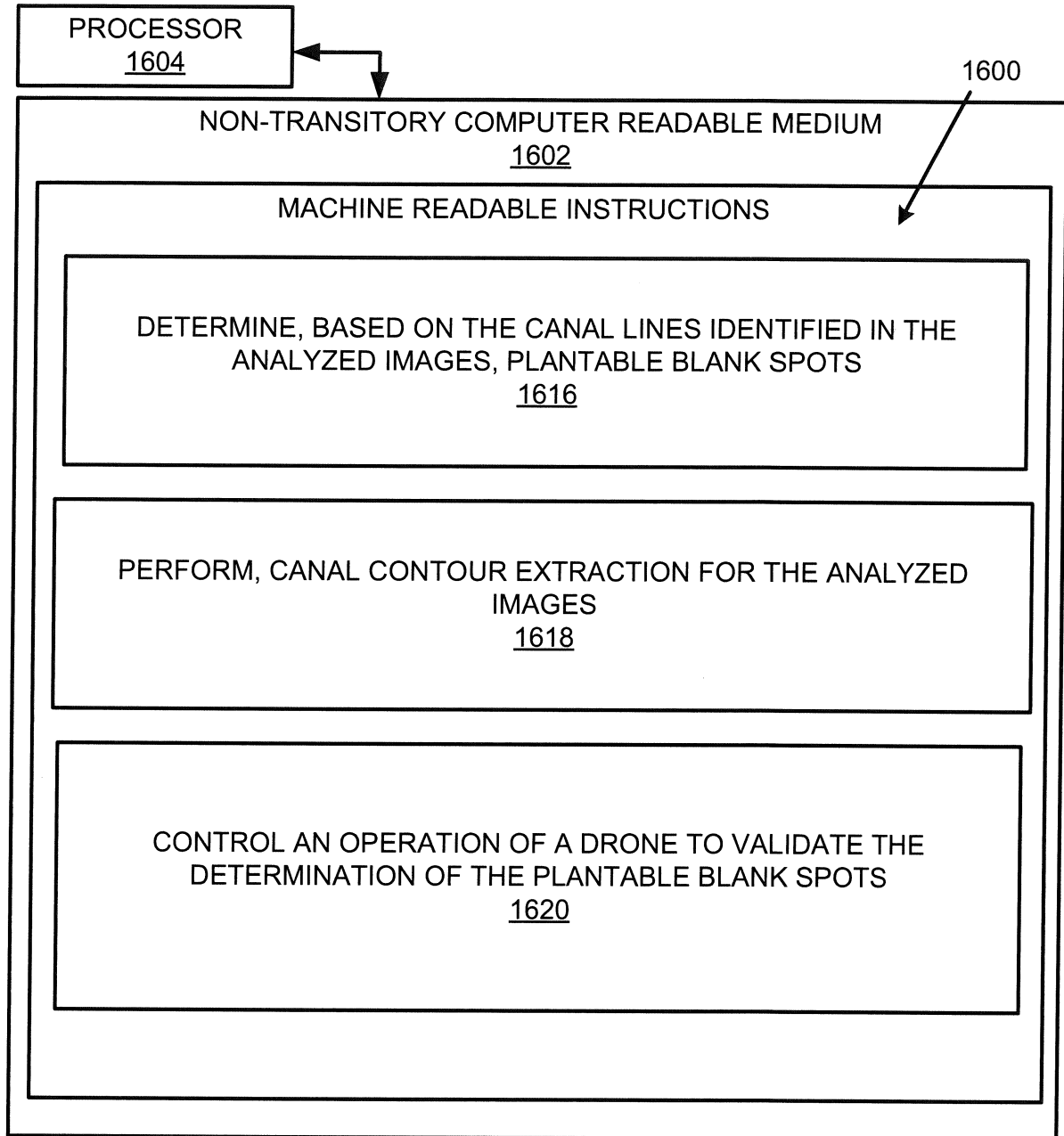


FIG. 16 (CONT.)