

METHOD AND APPARATUS FOR REGISTERING BOTTLES**Background of the Invention****Field of the Invention**

The invention relates generally to apparatuses and methods for labeling products, and more particularly, to apparatuses and methods for applying flexible, tubular labels to containers.

Reference to Related Patents and Applications.

4,944,825 issued to Eric Gifford et al. on July 31, 1990 entitled "Labeling Apparatus" (Here the Filled Bottle patent).

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Serial No. 08/129,657 filed by Dana Liebhart on September 30, 1993 entitled "Method and Apparatus for Rounding Objects" now patent _____ issued _____ (Here the DeDenter)

These 5 patents and the application are each hereby incorporated in their entireties by reference.

Background Information

Tubular, flexible, labels have become popular for labeling plastic vessels such as "two-liter" bottles. Labeling filled bottles presents special problems for labeling machines due to the added mass of the fluid and the effect of the fluid mass moving within the bottle. An apparatus and method for labeling filled bottles which is disclosed in the Filled Bottle Labeler patent has enjoyed considerable success. However, this ap-

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paratus requires costly specialized parts, does not adapt well to variations in bottle shapes and will occasionally jam and damage bottles. Fluid-filled bottles create greater problems when damaged in a labeling operation because the contents spill over the machinery and other bottles. Therefore, a need has arisen for a filled bottle labeler which can be manufactured at low cost, which accepts variations in the shapes of bottles to be labeled, and which reduces jams and down time.

The present assignee has developed an improved machine for labeling filled bottles, which is disclosed in the New Filled Bottle patent. This machine halts the bottle to be registered for labeling and the downstream labeled bottle. While this machine has been successful, it brings downstream bottles to a complete stop, which is undesirable in high speed bottling operations.

Summary of the Invention

A new labeling apparatus is provided which is insensitive to bottle shape variations and is highly reliable. The labeling apparatus of the present invention includes a label applying assembly and a product advancing assembly. The product advancing assembly includes an advancing conveyor for advancing an unlabeled product from a product presenting position to a label applying position. A slowing conveyor is located a predetermined distance downstream from the label applying position for slowing the motion of a labeled product downstream of the unlabeled product. The unlabeled product abuts and is registered with respect to the label applying position by abutting against a slowed downstream labeled product. The slowing conveyor operates to carry the labeled products downstream to isolate the product to be labeled.

In the preferred and illustrated embodiment, the labeling apparatus further includes an entrance gate for preventing products in the presenting station from approaching the labeling position until the appropriate time.

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A new method is also provided for applying labels to products. The method includes advancing a product to be labeled to a product presenting position using a conveyor. A product is engaged at the presenting position with an advancing conveyor and driven toward a labeling station. The driven product pushes a predecessor product out of the labeling station and into a slowing conveyor. The driven product is then registered by abutting against a slowed downstream product. The slowed downstream product is conveyed further downstream. As a label is applied to the registered product.

Brief Description of the Drawings

Figure 1 is a schematic plan view showing a labeling apparatus in accordance with the present invention;

Figure 2 is the view of Figure 1 at a later time in the labeling cycle;

Figure 3 is the view of Figure 1 at a still later time in the labeling cycle;

Figure 4 is a schematic view of the timing apparatus of the labeling apparatus;

Figure 5 is a front elevational view of the labeling apparatus with portions cut away;

Figure 6 is a schematic elevational view as seen approximately from a plane indicated by the line 6-6 in Figure 1.

Figure 7 is a schematic side elevational view as seen approximately from a plane indicated by the line 7-7 in Figure 1.

Figure 8 is a timing diagram showing the positions of various parts with respect to the position of the main drive shaft.

Description of the Preferred Embodiment

Referring to Figures 1-5, a labeling apparatus 10 is shown for applying sleeve labels 20 to individual bottles 30. With reference to

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Figure 1, the apparatus includes an input conveyor 40, a presenting station 50, an entrance gate 60, a slide plate 70, an advancing conveyor 80, a work station 90, a slowing conveyor 100, and an exit support 110. The labeling apparatus 10 isolates and registers individual bottles 30 in a stream of bottles. The bottles 30 are isolated and registered at the work station 90 where a labeling applying tool 220 applies a label 20 to each bottle 30.

The stream of bottles is brought to the presenting station 50 by the input conveyor 40. The preferred input conveyor 40 is a continuously running roller chain conveyor of the type disclosed in Figures 10 and 11 of the Filled Bottle. The bottles 30 on the input conveyor 40 are continuously urged in the downstream direction toward the presenting station 50. If a bottle occupies the presenting station 50, as illustrated in Figure 1, each bottle 30 on the input conveyor 40 is obstructed from moving forward by its neighboring downstream bottle. The bottles 30 on the input conveyor 40 may remain stationary while the input conveyor 40 continues to move beneath them by virtue of free-wheeling rollers 120. With this arrangement, bottles are continuously urged toward the presenting station 50 and a bottle 30 will only be pushed into the presenting station 50 when it is unoccupied.

Underlying the presenting station 50 is the slide plate 70, which is simply a smooth flat plate. Bottles 30 leaving the input conveyor 40 are pushed onto the slide plate 70 until the lead bottle abuts a stop 130. The slide plate 70 extends in the downstream direction from the presenting station 50 to the exit conveyor 110 as illustrated in Figures 1-3.

The advancing conveyor 80 is proximate the presenting station 50 and includes a pusher 140, a barrier arm 150, and a slider arm 160. The pusher 140 engages individual bottles 30 to push them along the slide plate 70 toward the work station 90 and then returns. The movement of the pusher 140 is repeated in continuous cyclic fashion. The barrier arm 150 blocks the downstream bottle on the input conveyor 60 from entering



the presenting station 50 until the pusher 140 has fully returned as illustrated in Figure 3. The slider arm 160 slides on a pair of parallel guide bars 170 for guiding the advancing conveyor's reciprocating motion. A pusher cam follower mechanism 180 is connected to the slider arm 160 for driving the slider arm 160 in a predetermined synchronized motion. Preferably, the pusher cam follower mechanism 180 is driven by a pusher cam 190 connected to a main drive shaft 200 as illustrated in Figure 4.

The entrance gate 60 is located adjacent the pusher 140 to block or unblock the path of the bottles. The entrance gate 60 is preferably opened and closed by the operation of a pneumatic cylinder 210 connected thereto as illustrated in Figure 4. The entrance gate 60 is timed to open as the pusher 140 begins driving a bottle 30 towards the work station 90. The bottle entrance gate 60 serves to restrain the bottle 30 in the presenting station 50, which is under constant force by the neighboring upstream bottle on the input conveyor 40. The bottle 30 at the presenting station 50 tends to be jostled in the downstream direction by incoming bottles on the input conveyor 40 if not restrained by the entrance gate 60.

Downstream of the presenting station 50 is the work station 90. The work station 90 includes a labeling tool 220 for continuously and cyclically applying sleeve labels 20 to individual bottles 30. The labeling tool 220 is essentially the same as that disclosed in the Filled Bottle patent which has been incorporated by reference. Further details of the labeling tool are disclosed in the ASA 60, Label Positioning and ASA 90 patents. An opposed pair of label appliers 230 are reciprocable vertically on a carriage 240 (Fig. 6). During a portion of their cycle, the label appliers 230 are clear of the bottle 30 in the work station 90 so bottles may be moved into and out of the work station 90 without interference. The label appliers 230 are synchronized to move in a predetermined relationship to the pusher 140, and the entrance gate 60. Preferably, the label appliers 230 are driven by a labeling cam follower mecha-



nism 250 which is in turn driven by a labeling cam 260 connected to the main drive shaft 200 as illustrated in Figures 4 and 5.

5 The work station 90 includes a vacuum stabilizer. Vacuum ports 270 are formed in the slider plate 160 such that the bottom of each bottle 30 being labeled substantially covers the ports 270. Vacuum is communicated with the ports 270 to hold the bottles 30 in position. This feature prevents bottles 30 from rocking while allowing a limited amount of lateral sliding even if fluid within the bottles is splashing around thus assuming proper bottle registration at the labeling station.

10 The slowing conveyor 100 is located downstream from the labeling station and above the bottle exit support 110. The disclosed slowing conveyor 100 comprises two opposed conveyor belts 282 and 284, which are positioned on opposite sides of the bottle path to form a conveyor nip. A pair of pulleys 286, 288 are shown supporting the upstream ends of the
15 belts 282, 284. The axes of the pulleys are normal to the plane of the exit support 110. The belts 282, 284 are adjustably positioned a predetermined distance apart for a given bottle size such that the bottles will be gripped with an appropriate amount of friction. The belts 282, 284 extend at least as high as the center of gravity location of the bottles in
20 the stream. The belts 282, 284 are driven by a motor (not shown) to operate at a speed which is relatively slower than the speed of the pusher conveyor 140. Bottles which just received labels are driven from the work station to the slowing conveyor 100 by a subsequent bottle to be labeled. The just labeled bottles are engaged on opposite sides by the
25 belts 282, 284 and are slowed but not stopped as they move downstream. The slowing conveyor 100 is located at a predetermined distance downstream from the work station 90 for a given bottle size.

30 Figure 6 shows schematically a device for adjusting the distance between the pulleys 286, 288 so that the conveyor 100 may accommodate bottles of different diameters. The adjusting device includes a pair of pulley supports 285, 287 and a threaded shaft 289. The shaft 289

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includes a hexagonal turning head 291. The threads on one side of the turning head 291 are opposite handed from those on the other side like a turn buckle. Each pulley support 285, 287 has a threaded opening for receiving the shaft 289. Rotation of the head 291 causes the pulleys 286, 288 either to move closer together or further apart depending on the direction of rotation. Other pulleys (not shown) on the conveyor 100 are similarly adjusted. Slots 293, Figure 7, may be formed in the support plate 110 to allow for the movement of the pulley supports 285, 287.

Figure 7 shows schematically a device for adjusting the distance between the work station 90 and the pulleys 286, 288. The device includes a pair of bolts 295, 297 which are threaded to the pulley supports 285, 287. Rotation of the bolts 295, 297 causes the pulleys 286, 288 to move further from or closer to the work station 90 depending on the direction of rotation. A pair of slots 299, 301 permit lateral movement of the bolts. Numerous other mechanisms for adjusting the positions of the pulleys are readily available to one of ordinary mechanical skill.

As an alternate to the disclosed two belt system, a fixed flat vertical element and an opposed conveyor as taught and claimed in the DeDenter Application may be employed as the slowing conveyor. This alternate slowing conveyor serves the multiple functions of 1) arresting the motion of a just labeled bottle to locate a succeeding bottle in the work station, 2) transport to a downstream conveyor and 3) at least partial rerounding of the labeled bottles that may have become dented during earlier processing.

A timing apparatus 300 is provided for synchronizing the pusher conveyor 140, the entrance gate 60, and the labeling tooling 230. As illustrated in Figure 4, the main drive shaft 200 drives the pusher and labeling cams 190, 260. The pusher cam 190 is connected to the pusher cam follower mechanism 180 for operating the advancing conveyor 80. Reciprocating motion from the pusher cam follower mechanism 180 is transferred to the slider arm 160 in a manner well understood by those

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with ordinary mechanical skill. The labeling cam 260 is connected to the labeling cam follower mechanism 250 for driving the label appliers 230 cyclically up and down:

5 The timing apparatus 300 further includes an encoder device 310 for producing digital signals corresponding to discrete rotational positions of the main drive shaft 200. For example, an encoder sold under the name BEI model H25D-CCW-8CG-7406-EM20-S may be used. The signals from the encoder device 310 are sent to a microprocessor 320 which is programmed to send operating signals to the entrance-gate valve 10 340, which controls the operation of the entrance gate pneumatic cylinder 210. The valve 340 is operable to connect or disconnect opposite ends of the pneumatic cylinder 210 with a pressurized air supply 342. Thus, at the appropriate times in the labeling cycle, as determined by the rotational position of the main drive shaft 200, the entrance gate 60 is 15 either opened or closed with air pressure.

Figure 8 illustrates a timing diagram showing the rotational position of the main drive shaft 200 on the horizontal axis. The various positions of the entrance gate 60, pusher 140, and label appliers (tooling) 230 are designated on the vertical axis. The bottle entrance gate 20 positions are designated as open or closed on the vertical axis of Figure 6. The "closed" position is the position where the path of the bottles is blocked. The position of the pusher 140 is designated as "bottle feed." The position labeled "in" is the pusher position away from the presenting station 50 and toward the work station 90. The position of the label 5 appliers 230 is labeled as "tooling." A horizontal broken line labeled "clears bottle" indicates the point in the cycle at which the label appliers 230 are clear of the bottle 30. During the portion of the tooling cycle which is above the broken line, the bottle 30 may move in or out of the work station 90 without interference.

As shown in Figure 8, the pusher 140 pushes a bottle to be labeled toward the work station 90 only when the entrance gate 60 is open. The

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predecessor (labeled) bottle is driven out of the work station 90 at a relatively fast speed and into the slowing conveyor 100 where it is slowed but not stopped. The bottle to be labeled, which is moving relatively fast, then abuts the slowed predecessor bottle and is caused to stop. The relative speeds of the pusher 140 and the slowing conveyor 100 are adjusted such that the bottle to be labeled is properly registered at the work station by its impact with the predecessor bottle. The slowing conveyor 100 carries the slowed bottle downstream thus isolating the bottle being labeled. Since the bottle being labeled is isolated from the stream, there is ample clearance around it for operation of the label

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appliers 230.

Operation

To be labeled bottles 30 are advanced to the presenting station 50 using the input conveyor 40. The bottles 30 are then sequentially engaged by the pusher 140 and driven toward the work station 90. A downstream labeled bottle 30, in the work station is pushed out of the work station 90 by the bottle to be labeled being driven by the pusher 140. The labeled bottle is pushed into position to be gripped and slowed by the slowing conveyor 100 to serve as a registration abutment to locate the bottle to be labeled in the work station. The just labeled bottle is conveyed downstream by the slowing conveyor to isolate the bottle now registered in the work station 90 as a label 20 is applied to the registered bottle. The process is then repeated.

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Although the invention has been described in its preferred form with a certain degree of particularity, it is understood that the present disclosure of the preferred form has been made only by way of example and that numerous changes in the details of construction and the combination and arrangement of parts may be resorted to without departing from the spirit and the scope of the invention as hereinafter claimed.

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CLAIMS

1. In a labeling apparatus having a labeling assembly for applying sleeve labels to individual products in a stream of products, a product advancing mechanism comprising:

5 (a) an advancing conveyor for advancing an unlabeled product from a product presenting position to a label applying position; and

10 (b) a slowing conveyor located a predetermined distance in a downstream direction from said label applying position for slowing the speed of a second and labeled product downstream from said unlabeled product, thereby registering said unlabeled product with respect to said label applying position by abutting against a slowed downstream product, and wherein said slowing conveyor carries said second product in the downstream direction

2. The labeling apparatus of claim 1 further comprising a slide plate for supporting products conveyed by said advancing conveyor, wherein said slide plate comprises a vacuum port for stabilizing products at said labeling position.

3. The labeling apparatus of claim 1, wherein said slowing conveyor comprises a pair of opposed belt conveyors which are spaced apart a predetermined distance to permit each product to be engaged on opposite sides.

4. The labeling apparatus of claim 1, wherein said slowing conveyor comprises a vertical stationary element and an opposed con-

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veyor which element and conveyor are spaced apart a predetermined distance to permit each product to be engaged on opposite sides.

5. A conveyor system for a stream of discrete objects for temporarily registering individual ones of said objects, said system comprising:

a supply conveyor for conveying said stream;

5 a work station located along said flow path where an operation is performed on each object in said stream;

10 an entrance gate located upstream of said work station, said entrance gate comprising a first movable blocking mechanism for alternately moving into and out of said flow path to block passage of an object when moved into said flow path and to permit passage of a object when moved out of said flow path; and

5 a slowing conveyor located downstream of said work station, said slowing conveyor comprising a conveyor nip located a predetermined distance downstream from said work station such that each object is gripped by said slowing conveyor and slowed wherein each slowed object serves as a registration abutment for registering a subsequent object in said stream.

6. A conveyor system according to claim 5 further comprising a pusher for pushing objects from an entrance gate location towards said work station.

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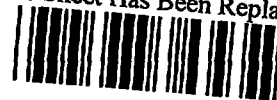


7. A conveyor system according to claim 5 wherein said work station includes a vacuum hold-down device for stabilizing objects at said work station.

8. A bottle registration system for registering individual bottles in a stream of bottles, said system comprising:
an entry conveyor defining a portion of a flow path;
a slide plate adjacent to said entry conveyor for receiving bottles delivered by said entry conveyor;
a work station located on said slide plate;
a pusher for pushing bottles along said slide plate toward said work station; a slowing conveyor located downstream from said work station, whereby such said pusher being operable to drive a bottle from said entry conveyor to said work station;
said slowing conveyor being adapted to slow a bottle exiting the work station and whereby such driven bottle abuts and is stopped by a slowed downstream bottle; and,
said slowing conveyor being located a predetermined distance downstream of said work station such that each such driven bottle is properly registered at said work station when stopped by one such slowed bottle.

9. A bottle registration system according to claim 8 wherein said slide plate comprises a vacuum port for stabilizing bottles stopped at said work station.

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ABSTRACT OF THE DISCLOSURE

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An apparatus and method are shown and described for labeling bottles in a stream. An input conveyor is provided for supplying bottles to a presenting station. Bottles are restrained at the presenting station until the appropriate time by an entrance gate. Bottles are conveyed from the presenting station to a work station by an advancing conveyor. Bottles entering the work station drive the predecessor bottle out of the work station to a slowing conveyor. Slowed bottles are abutted by subsequent relatively faster moving bottles to be labeled. Abutment with a slowed labeled bottle serves to register each bottle to be labeled at the labeling station.

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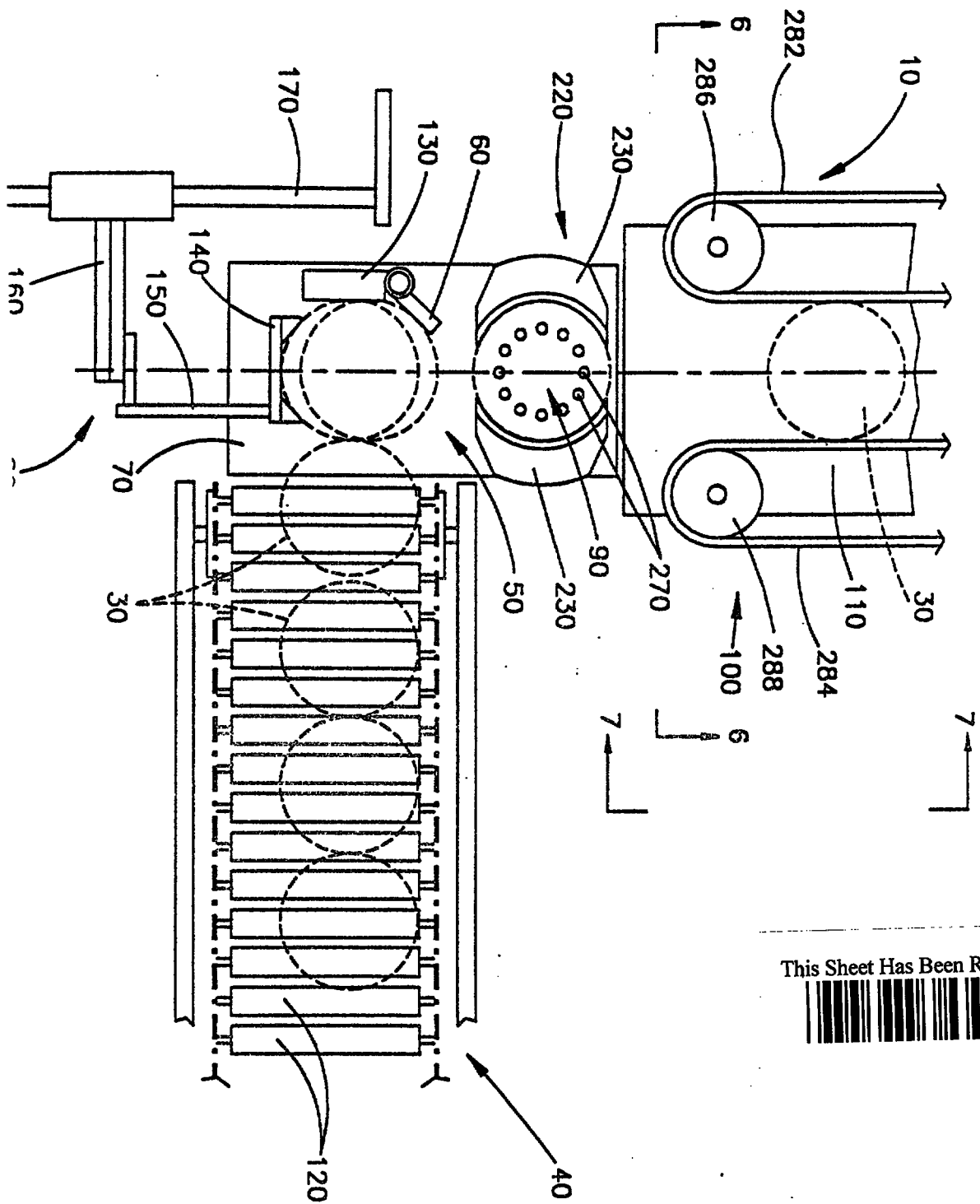


Fig. 1

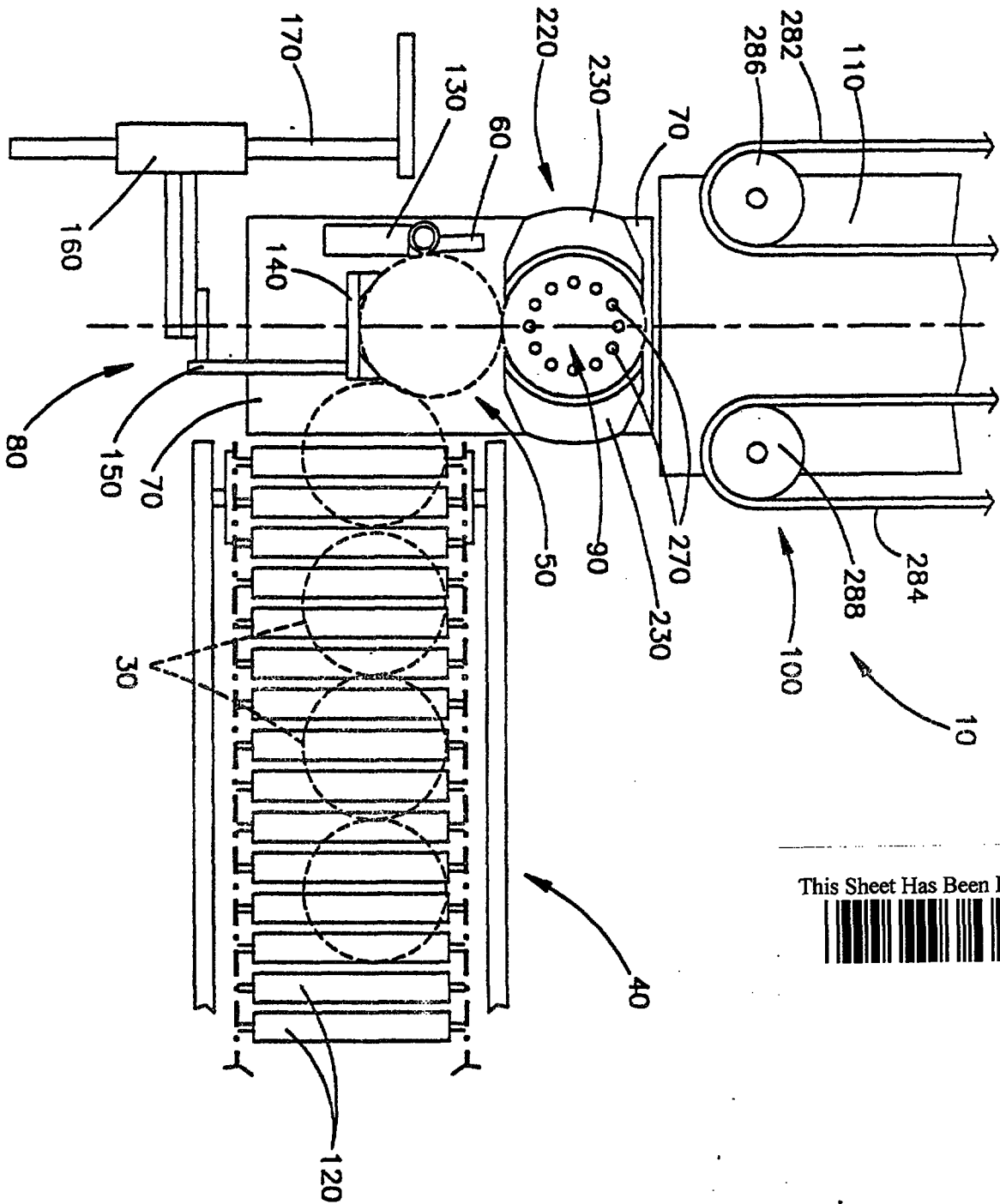
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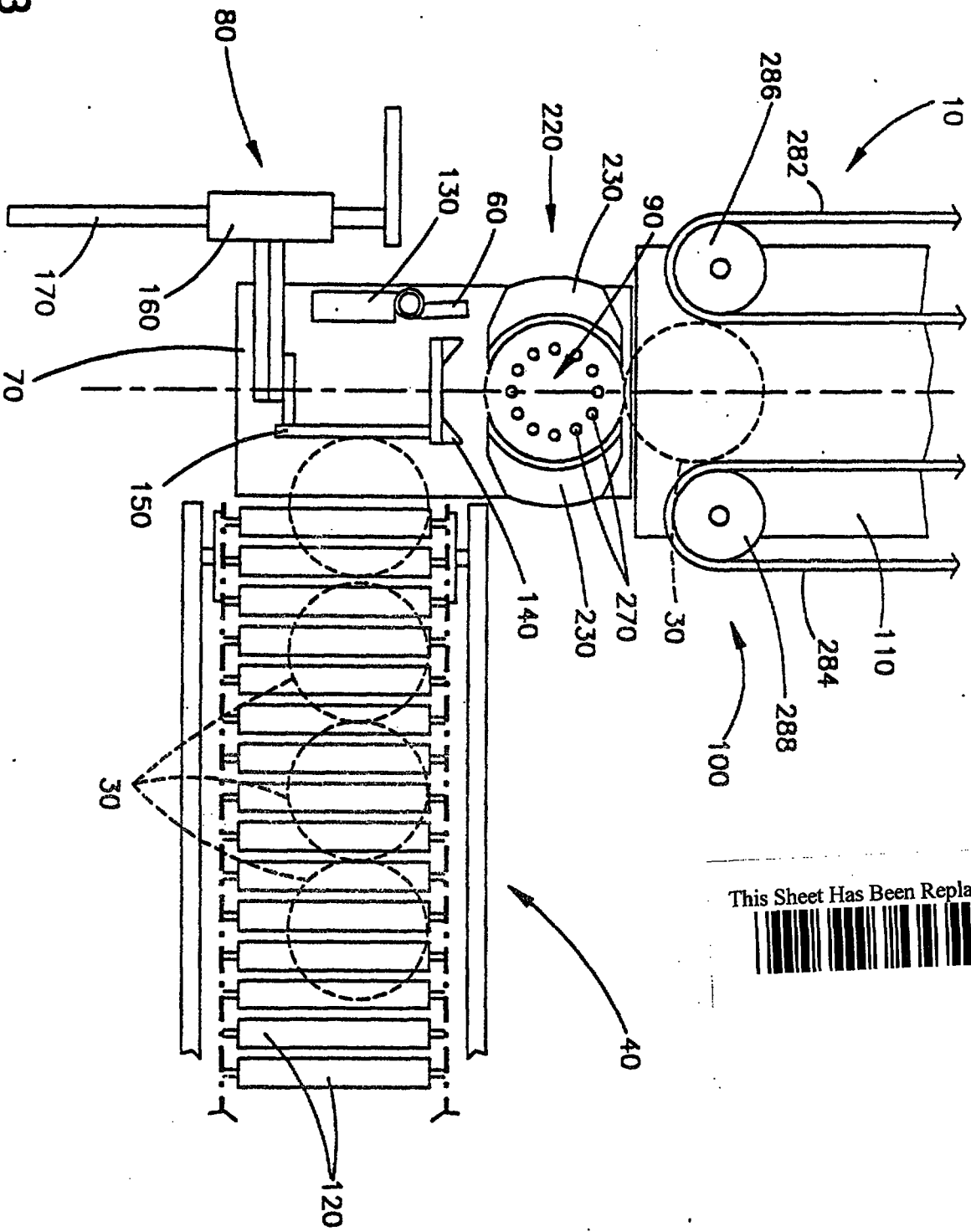
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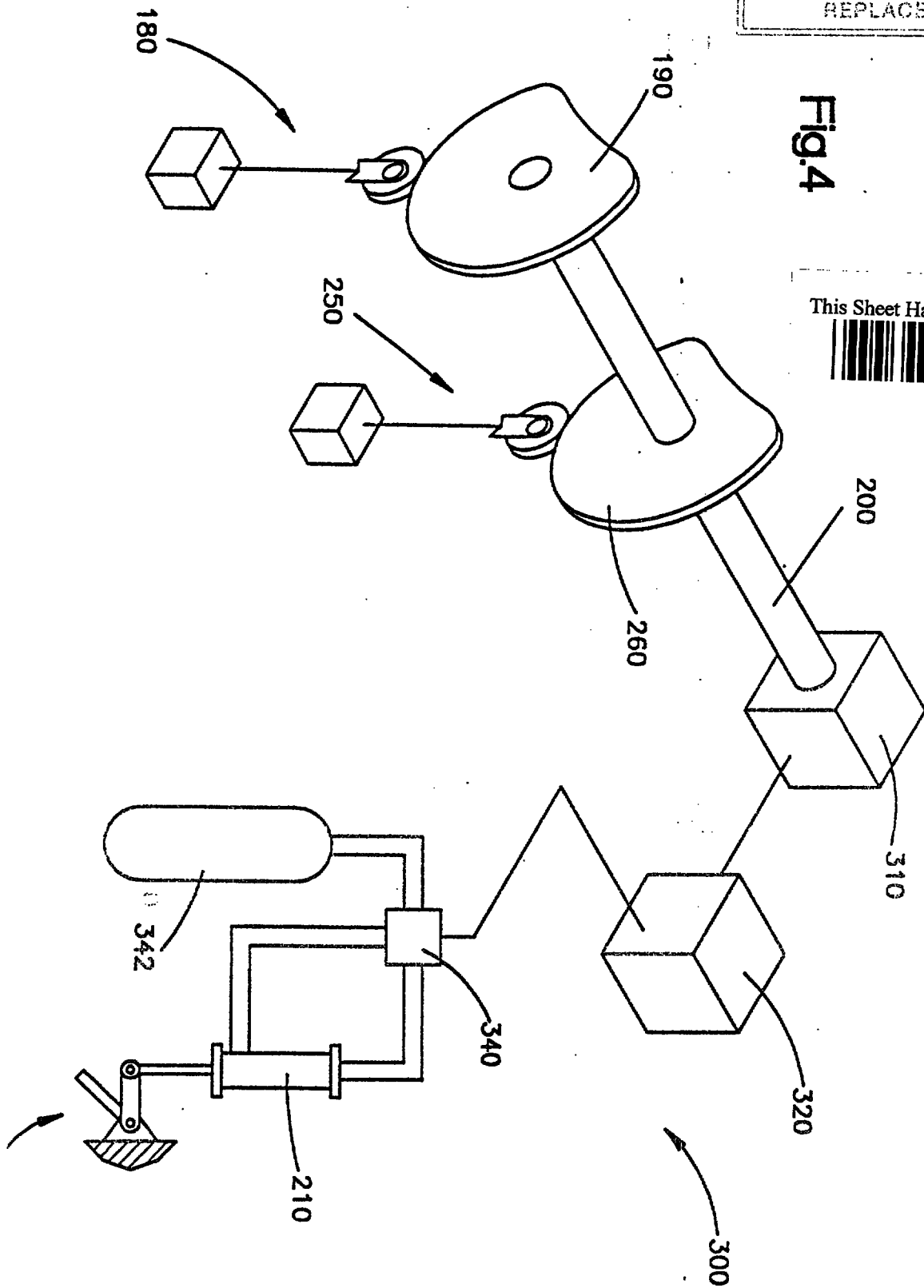


Fig.3

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Fig.4

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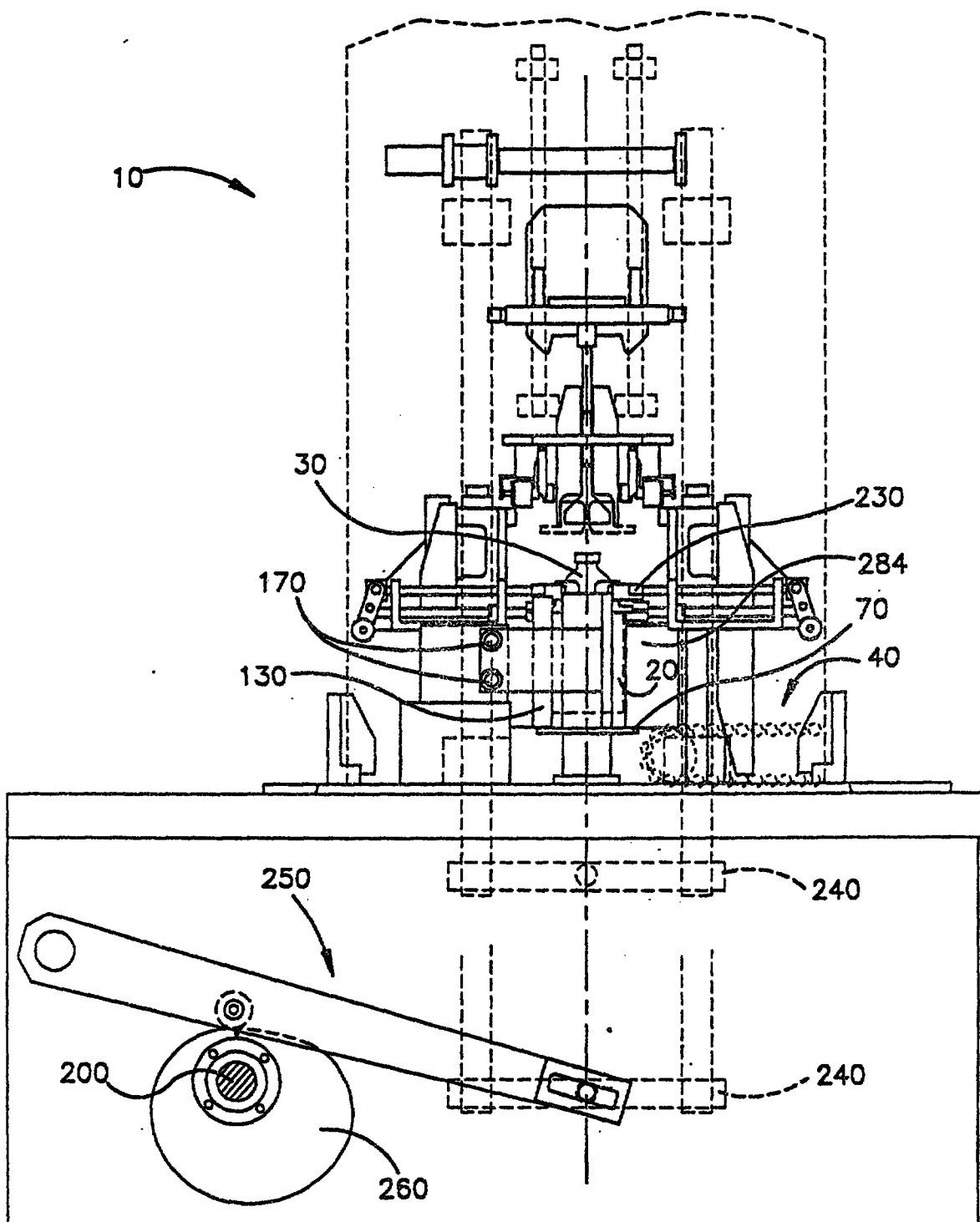
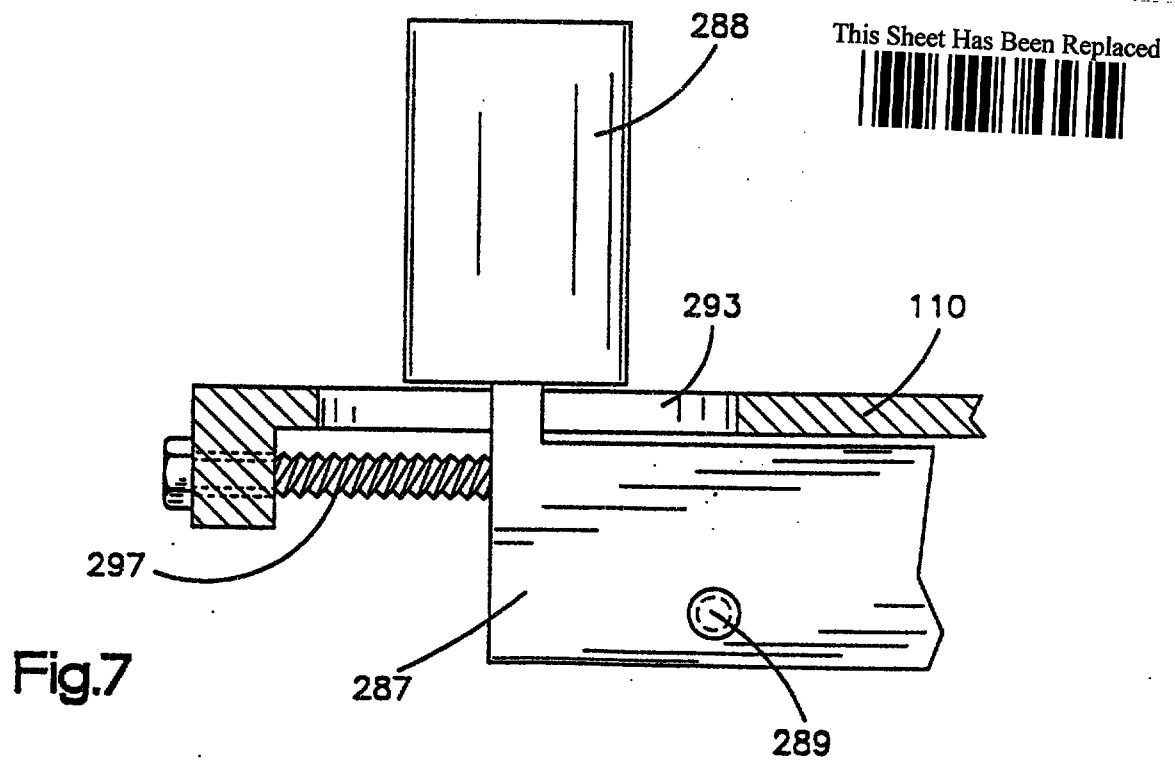
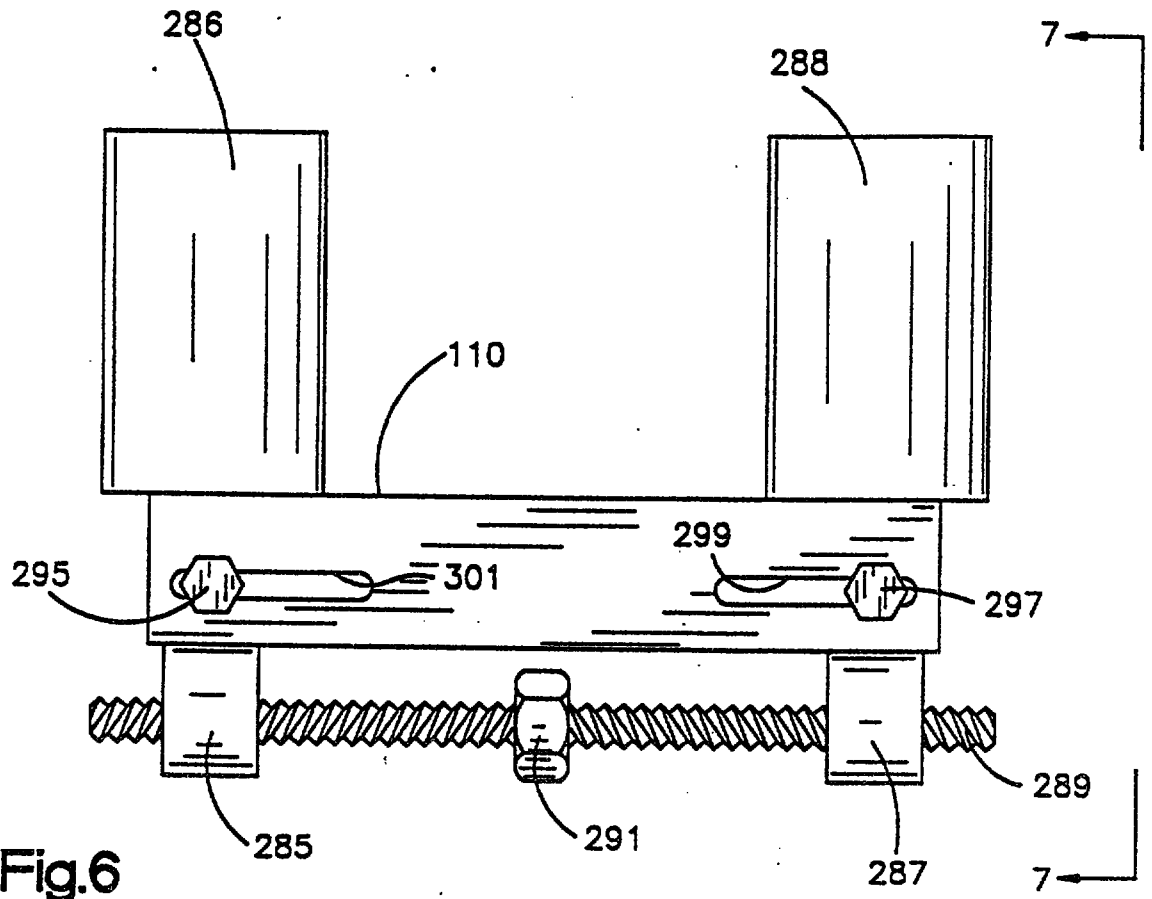


Fig.5

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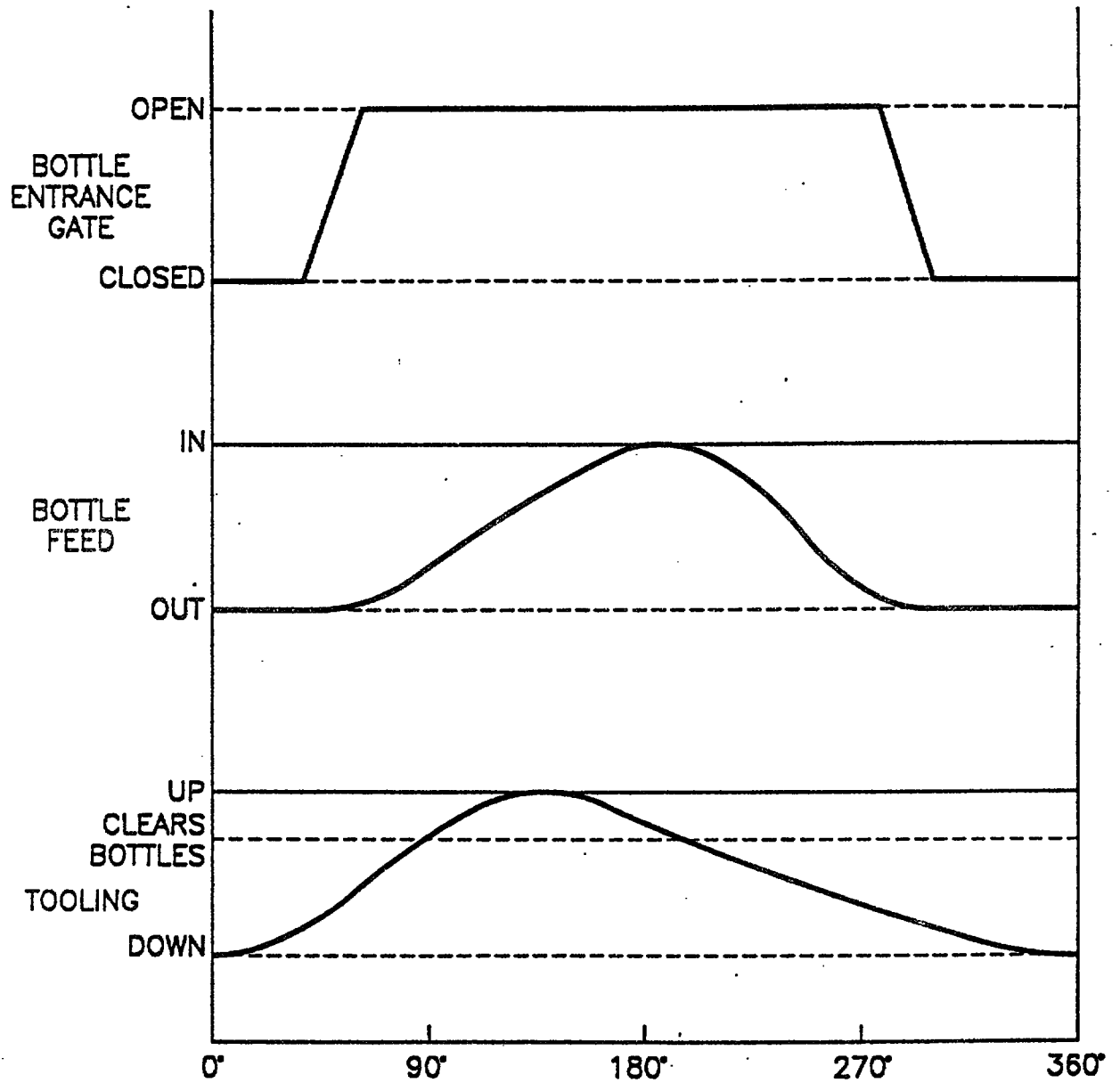
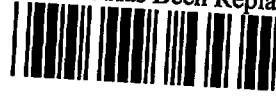


Fig.8

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paratus requires costly specialized parts, does not adapt well to variations in bottle shapes and will occasionally jam and damage bottles. Fluid-filled bottles create greater problems when damaged in a labeling operation because the contents spill over the machinery and other bottles. Therefore, a need has arisen for a filled bottle labeler which can be manufactured at low cost, which accepts variations in the shapes of bottles to be labeled, and which reduces jams and down time.

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In the preferred and illustrated embodiment, the labeling apparatus further includes an entrance gate for preventing products in the presenting station from approaching the labeling position until the appropriate time.

A new method is also provided for applying labels to products. The method includes advancing a product to be labeled to a product presenting position using a conveyor. A product is engaged at the presenting position with an advancing conveyor and driven toward a labeling station. The driven product pushes a predecessor product out of the labeling station and into a slowing conveyor. The driven product is then registered by abutting against a slowed downstream product. The slowed downstream product is conveyed further downstream. As a label is applied to the registered product.

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Figure 1, the apparatus includes an input conveyor 40, a presenting station 50, an entrance gate 60, a slide plate 70, an advancing conveyor 80, a work station 90, a slowing conveyor 100, and an exit support 110. The labeling apparatus 10 isolates and registers individual bottles 30 in a stream of bottles. The bottles 30 are isolated and registered at the work station 90 where a labeling applying tool 220 applies a label 20 to each bottle 30.

The stream of bottles is brought to the presenting station 50 by the input conveyor 40. The preferred input conveyor 40 is a continuously running roller chain conveyor of the type disclosed in Figures 10 and 11 of the Filled Bottle. The bottles 30 on the input conveyor 40 are continuously urged in the downstream direction toward the presenting station 50. If a bottle occupies the presenting station 50, as illustrated in Figure 1, each bottle 30 on the input conveyor 40 is obstructed from moving forward by its neighboring downstream bottle. The bottles 30 on the input conveyor 40 may remain stationary while the input conveyor 40 continues to move beneath them by virtue of free-wheeling rollers 120. With this arrangement, bottles are continuously urged toward the presenting station 50 and a bottle 30 will only be pushed into the presenting station 50 when it is unoccupied.

Underlying the presenting station 50 is the slide plate 70, which is simply a smooth flat plate. Bottles 30 leaving the input conveyor 40 are pushed onto the slide plate 70 until the lead bottle abuts a stop 130. The slide plate 70 extends in the downstream direction from the presenting station 50 to the exit conveyor 110 as illustrated in Figures 1-3.

The advancing conveyor 80 is proximate the presenting station 50 and includes a pusher 140, a barrier arm 150, and a slider arm 160. The pusher 140 engages individual bottles 30 to push them along the slide plate 70 toward the work station 90 and then returns. The movement of the pusher 140 is repeated in continuous cyclic fashion. The barrier arm 150 blocks the downstream bottle on the input conveyor 60 from entering

the presenting station 50 until the pusher 140 has fully returned as illustrated in Figure 3. The slider arm 160 slides on a pair of parallel guide bars 170 for guiding the advancing conveyor's reciprocating motion. A pusher cam follower mechanism 180 is connected to the slider arm 160 for driving the slider arm 160 in a predetermined synchronized motion. Preferably, the pusher cam follower mechanism 180 is driven by a pusher cam 190 connected to a main drive shaft 200 as illustrated in Figure 4.

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Figure 6 shows schematically a device for adjusting the distance between the pulleys 286, 288 so that the conveyor 100 may accommodate bottles of different diameters. The adjusting device includes a pair of pulley supports 285, 287 and a threaded shaft 289. The shaft 289

includes a hexagonal turning head 291. The threads on one side of the turning head 291 are opposite handed from those on the other side like a turn buckle. Each pulley support 285, 287 has a threaded opening for receiving the shaft 289. Rotation of the head 291 causes the pulleys 286, 288 either to move closer together or further apart depending on the direction of rotation. Other pulleys (not shown) on the conveyor 100 are similarly adjusted. Slots 293, Figure 7, may be formed in the support plate 110 to allow for the movement of the pulley supports 285, 287.

Figure 7 shows schematically a device for adjusting the distance between the work station 90 and the pulleys 286, 288. The device includes a pair of bolts 295, 297 which are threaded to the pulley supports 285, 287. Rotation of the bolts 295, 297 causes the pulleys 286, 288 to move further from or closer to the work station 90 depending on the direction of rotation. A pair of slots 299, 301 permit lateral movement of the bolts. Numerous other mechanisms for adjusting the positions of the pulleys are readily available to one of ordinary mechanical skill.

As an alternate to the disclosed two belt system, a fixed flat vertical element and an opposed conveyor as taught and claimed in the DeDenter Application may be employed as the slowing conveyor. This alternate slowing conveyor serves the multiple functions of 1) arresting the motion of a just labeled bottle to locate a succeeding bottle in the work station, 2) transport to a downstream conveyor and 3) at least partial rerounding of the labeled bottles that may have become dented during earlier processing.

A timing apparatus 300 is provided for synchronizing the pusher conveyor 140, the entrance gate 60, and the labeling tooling 230. As illustrated in Figure 4, the main drive shaft 200 drives the pusher and labeling cams 190, 260. The pusher cam 190 is connected to the pusher cam follower mechanism 180 for operating the advancing conveyor 80. Reciprocating motion from the pusher cam follower mechanism 180 is transferred to the slider arm 160 in a manner well understood by those

with ordinary mechanical skill. The labeling cam 260 is connected to the labeling cam follower mechanism 250 for driving the label appliers 230 cyclically up and down:

The timing apparatus 300 further includes an encoder device 310 for producing digital signals corresponding to discrete rotational positions of the main drive shaft 200. For example, an encoder sold under the name BEI model H25D-CCW-8CG-7406-EM20-S may be used. The signals from the encoder device 310 are sent to a microprocessor 320 which is programmed to send operating signals to the entrance-gate valve 340, which controls the operation of the entrance gate pneumatic cylinder 210. The valve 340 is operable to connect or disconnect opposite ends of the pneumatic cylinder 210 with a pressurized air supply 342. Thus, at the appropriate times in the labeling cycle, as determined by the rotational position of the main drive shaft 200, the entrance gate 60 is either opened or closed with air pressure.

Figure 8 illustrates a timing diagram showing the rotational position of the main drive shaft 200 on the horizontal axis. The various positions of the entrance gate 60, pusher 140, and label appliers (tooling) 230 are designated on the vertical axis. The bottle entrance gate positions are designated as open or closed on the vertical axis of Figure 6. The "closed" position is the position where the path of the bottles is blocked. The position of the pusher 140 is designated as "bottle feed." The position labeled "in" is the pusher position away from the presenting station 50 and toward the work station 90. The position of the label appliers 230 is labeled as "tooling." A horizontal broken line labeled "clears bottle" indicates the point in the cycle at which the label appliers 230 are clear of the bottle 30. During the portion of the tooling cycle which is above the broken line, the bottle 30 may move in or out of the work station 90 without interference.

As shown in Figure 8, the pusher 140 pushes a bottle to be labeled toward the work station 90 only when the entrance gate 60 is open. The

predecessor (labeled) bottle is driven out of the work station 90 at a relatively fast speed and into the slowing conveyor 100 where it is slowed but not stopped. The bottle to be labeled, which is moving relatively fast, then abuts the slowed predecessor bottle and is caused to stop. The relative speeds of the pusher 140 and the slowing conveyor 100 are adjusted such that the bottle to be labeled is properly registered at the work station by its impact with the predecessor bottle. The slowing conveyor 100 carries the slowed bottle downstream thus isolating the bottle being labeled. Since the bottle being labeled is isolated from the stream, there is ample clearance around it for operation of the label appliers 230.

Operation

To be labeled bottles 30 are advanced to the presenting station 50 using the input conveyor 40. The bottles 30 are then sequentially engaged by the pusher 140 and driven toward the work station 90. A downstream labeled bottle 30, in the work station is pushed out of the work station 90 by the bottle to be labeled being driven by the pusher 140. The labeled bottle is pushed into position to be gripped and slowed by the slowing conveyor 100 to serve as a registration abutment to locate the bottle to be labeled in the work station. The just labeled bottle is conveyed downstream by the slowing conveyor to isolate the bottle now registered in the work station 90 as a label 20 is applied to the registered bottle. The process is then repeated.

Although the invention has been described in its preferred form with a certain degree of particularity, it is understood that the present disclosure of the preferred form has been made only by way of example and that numerous changes in the details of construction and the combination and arrangement of parts may be resorted to without departing from the spirit and the scope of the invention as hereinafter claimed.

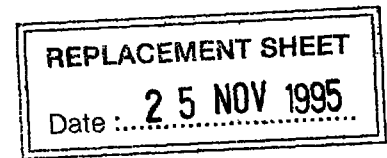


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CLAIMS

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1. In a labeling apparatus having a labeling assembly for applying sleeve labels to individual products in a stream of products, a product advancing mechanism comprising:
 - (a) an advancing conveyor for advancing an unlabeled product from a product presenting position to a label applying position; and
 - (b) a slowing conveyor located a predetermined distance in a downstream direction from said label applying position for slowing the speed of a second and labeled product downstream from said unlabeled product, thereby registering said unlabeled product with respect to said label applying position by abutting against a slowed downstream product, and wherein said slowing conveyor carries said second product in the downstream direction
2. The labeling apparatus of claim 1 further comprising a slide plate for supporting products conveyed by said advancing conveyor, wherein said slide plate comprises a vacuum port for stabilizing products at said labeling position.
3. The labeling apparatus of claim 1, wherein said slowing conveyor comprises a pair of opposed belt conveyors which are spaced apart a predetermined distance to permit each product to be engaged on opposite sides.
4. The labeling apparatus of claim 1, wherein said slowing conveyor comprises a vertical stationary element and an opposed con-



veyor which element and conveyor are spaced apart a predetermined distance to permit each product to be engaged on opposite sides.

5. A conveyor system for a stream of discrete objects for temporarily registering individual ones of said objects, said system comprising:

a supply conveyor for conveying said stream;

a work station located along said flow path where an operation is performed on each object in said stream;

an entrance gate located upstream of said work station, said entrance gate comprising a first movable blocking mechanism for alternately moving into and out of said flow path to block passage of an object when moved into said flow path and to permit passage of a object when moved out of said flow path; and

a slowing conveyor located downstream of said work station, said slowing conveyor comprising a conveyor nip located a predetermined distance downstream from said work station such that each object is gripped by said slowing conveyor and slowed wherein each slowed object serves as a registration abutment for registering a subsequent object in said stream.

6. A conveyor system according to claim 5 further comprising a pusher for pushing objects from an entrance gate location towards said work station.



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7. A conveyor system according to claim 5 wherein said station includes a vacuum hold-down device for stabilizing objects at work station.

8. A bottle registration system for registering individual bottles in a stream of bottles, said system comprising:
an entry conveyor defining a portion of a flow path;
a slide plate adjacent to said entry conveyor for receiving bottles delivered by said entry conveyor;
a work station located on said slide plate;
a pusher for pushing bottles along said slide plate toward said work station; a slowing conveyor located downstream from said work station whereby such said pusher being operable to drive a bottle from said conveyor to said work station;
said slowing conveyor being adapted to slow a bottle exiting the work station and whereby such driven bottle abuts and is stopped by a slowed downstream bottle; and,
said slowing conveyor being located a predetermined distance downstream of said work station such that each such driven bottle is properly registered at said work station when stopped by one such slowed bottle.

9. A bottle registration system according to claim 8 where said slide plate comprises a vacuum port for stabilizing bottles stopped at said work station.

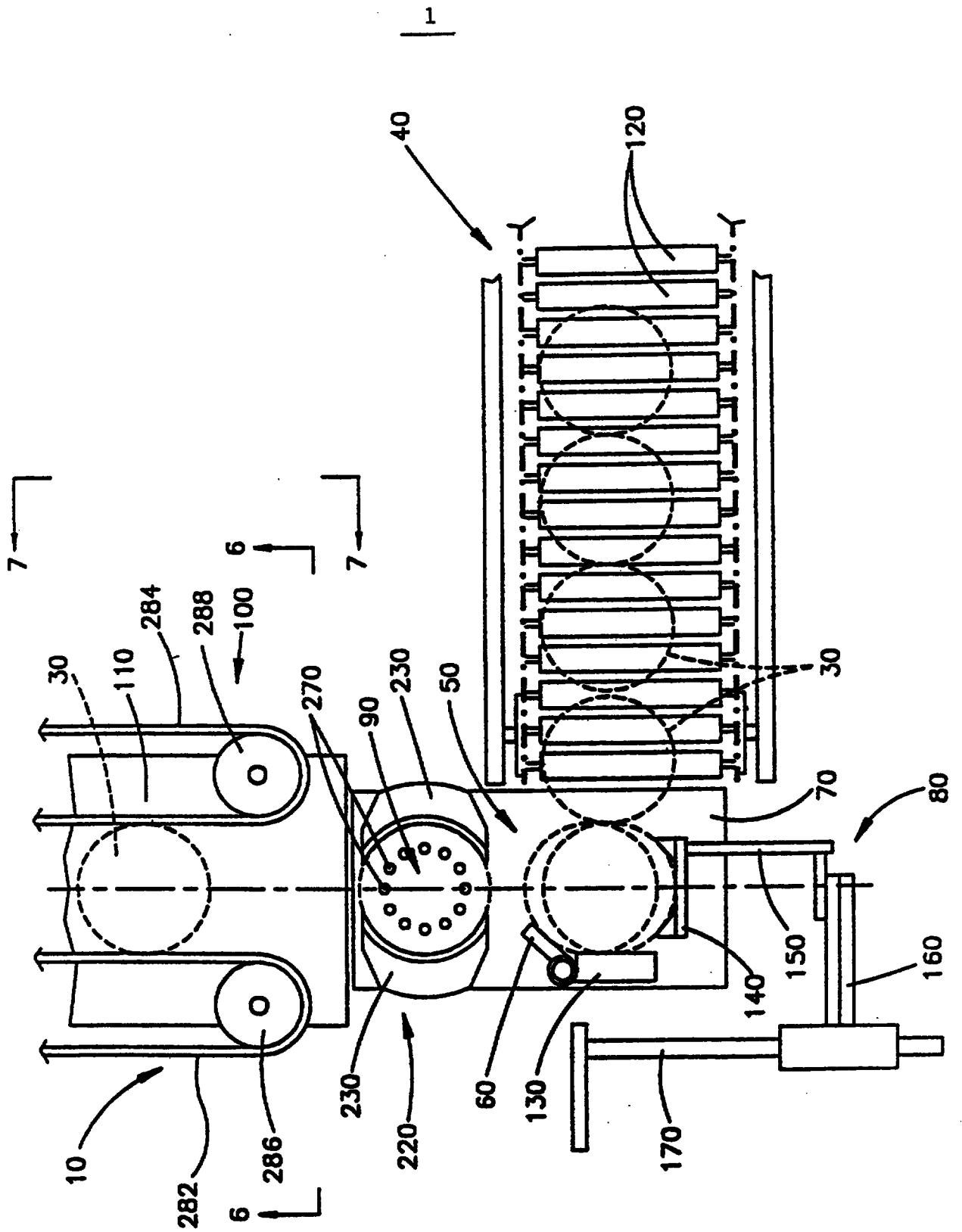


Fig.1

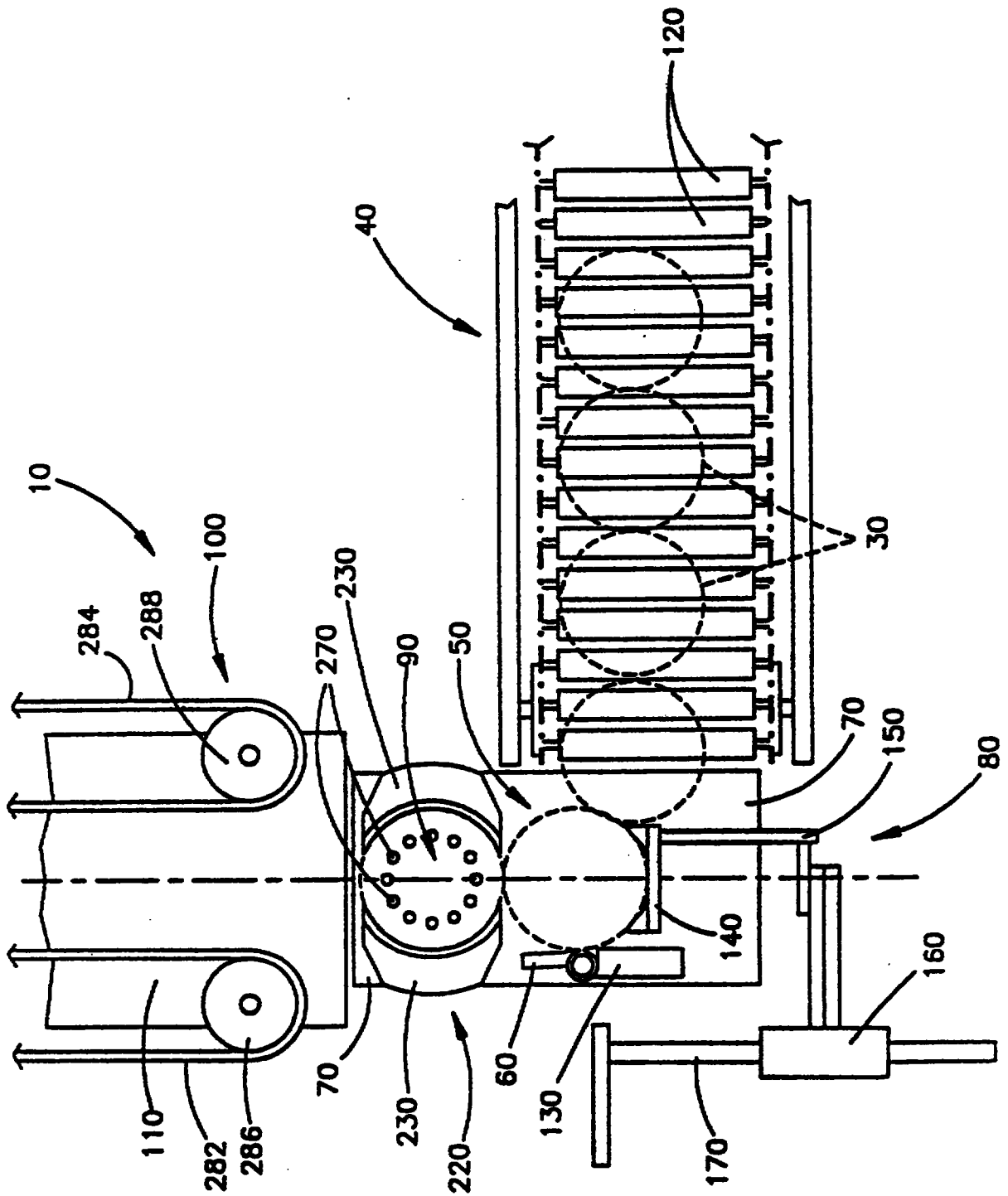


Fig.2

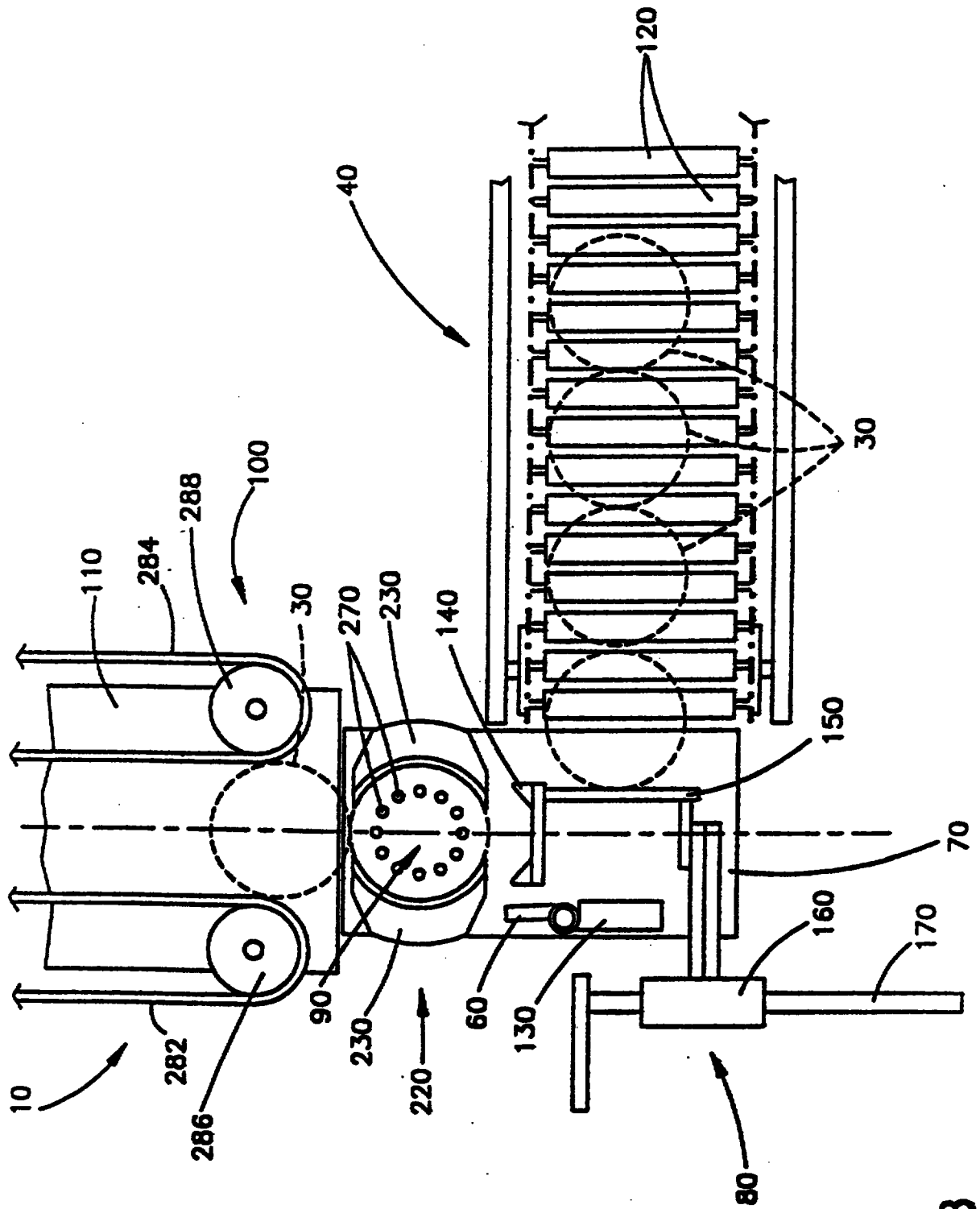


Fig.3

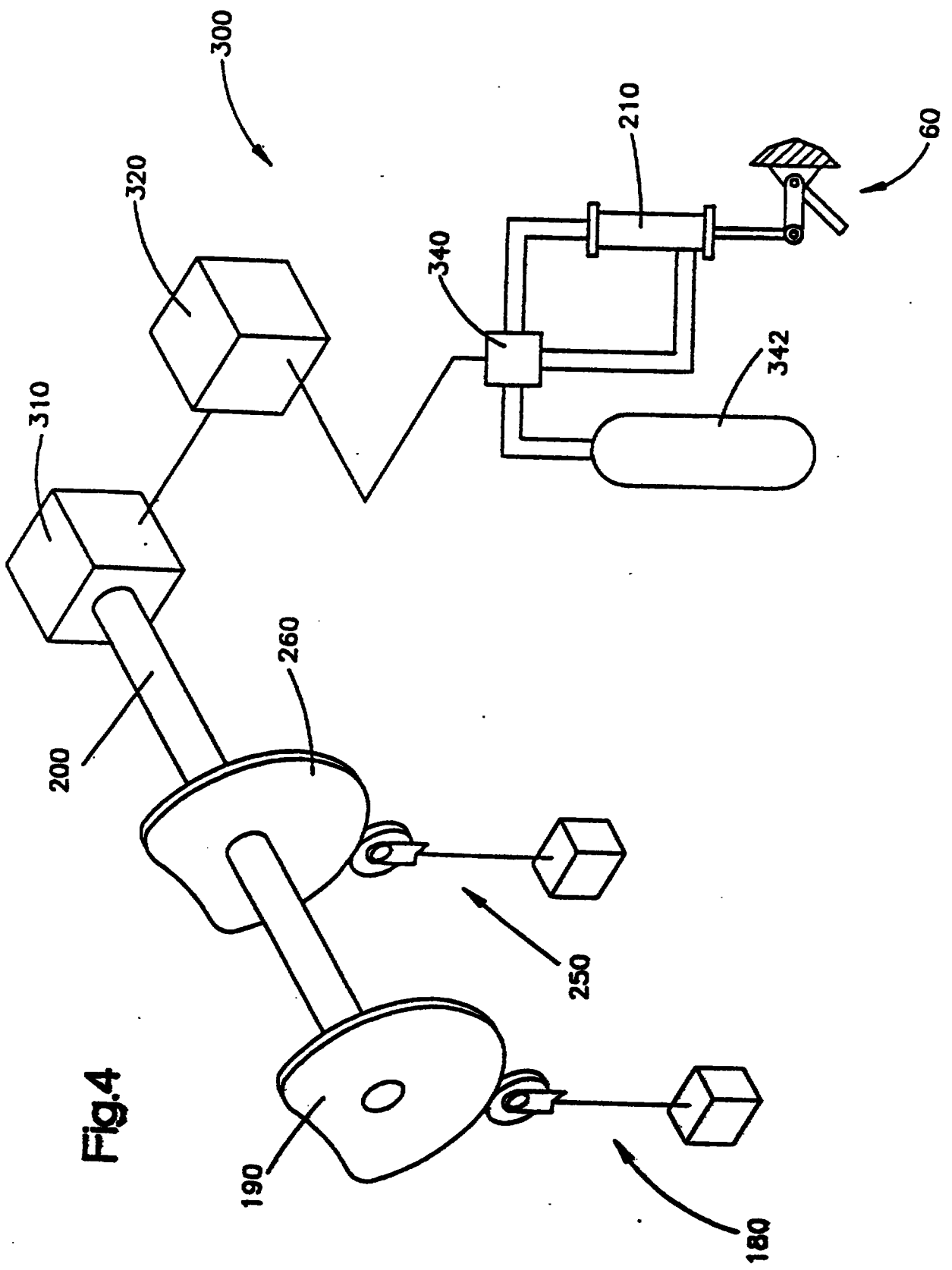


Fig.4

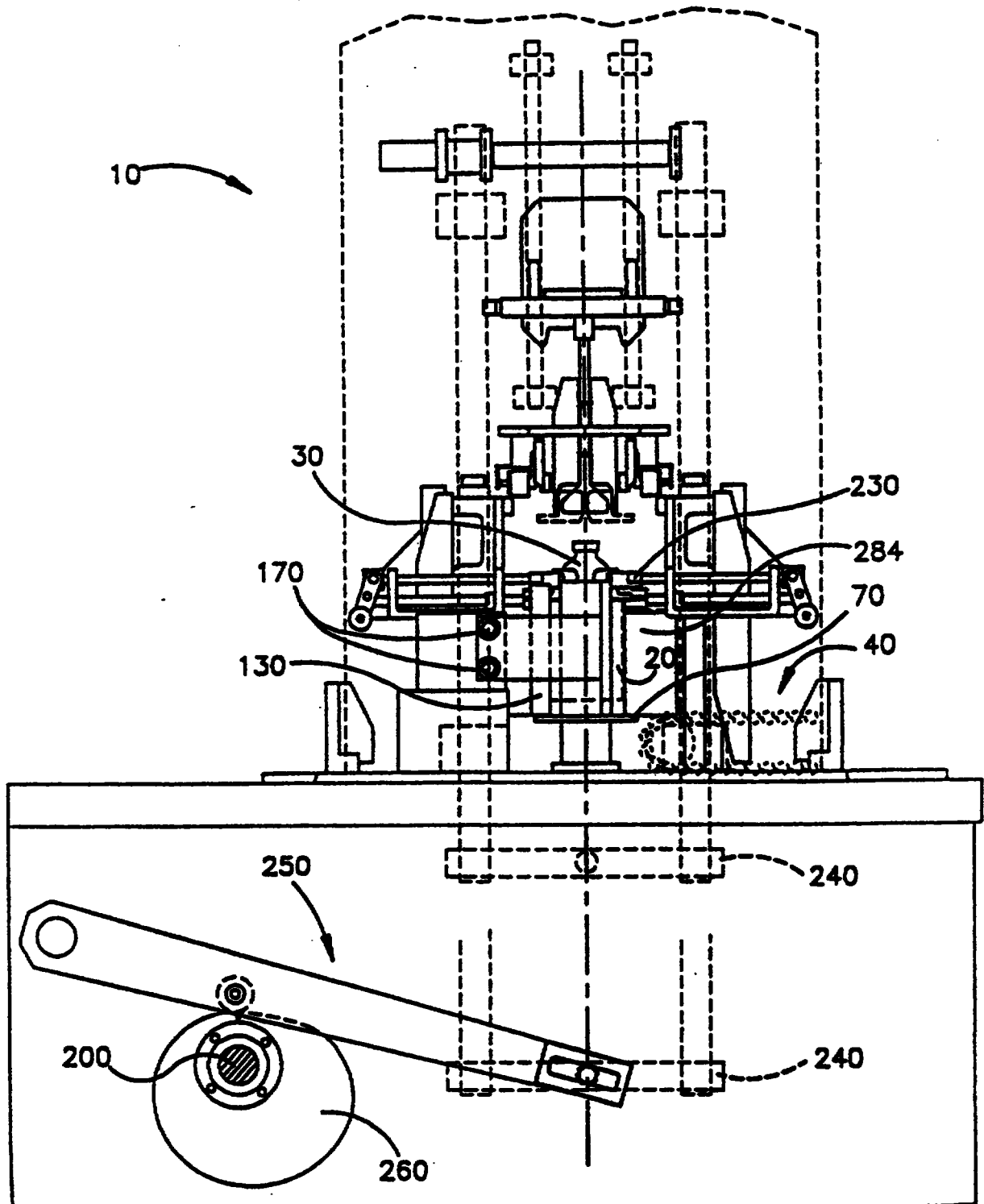
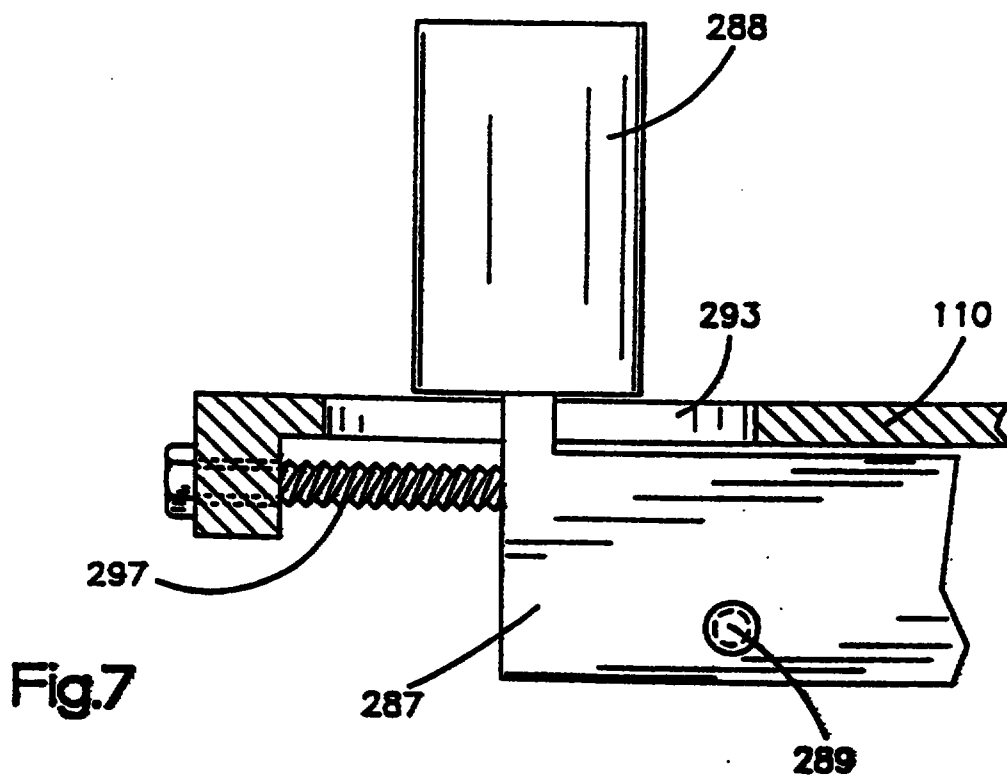
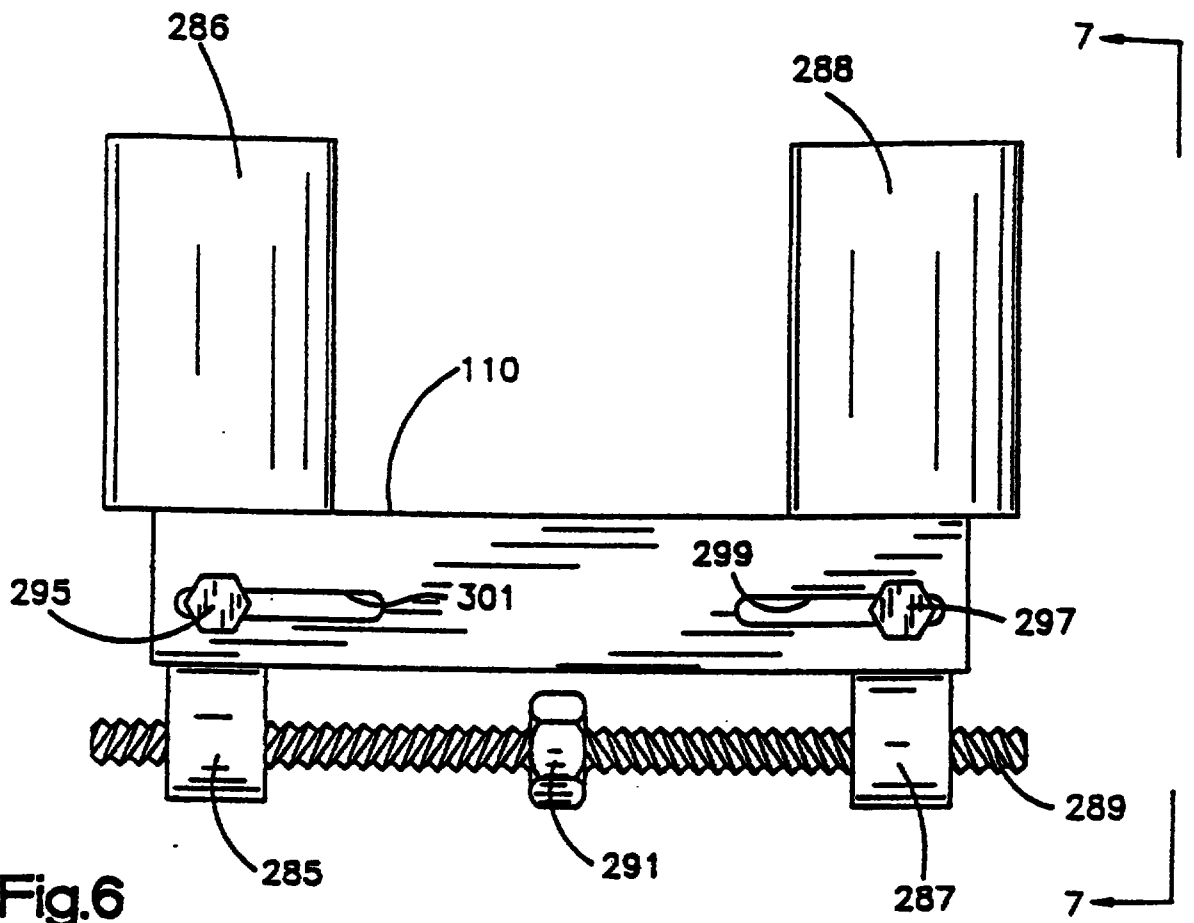


Fig.5



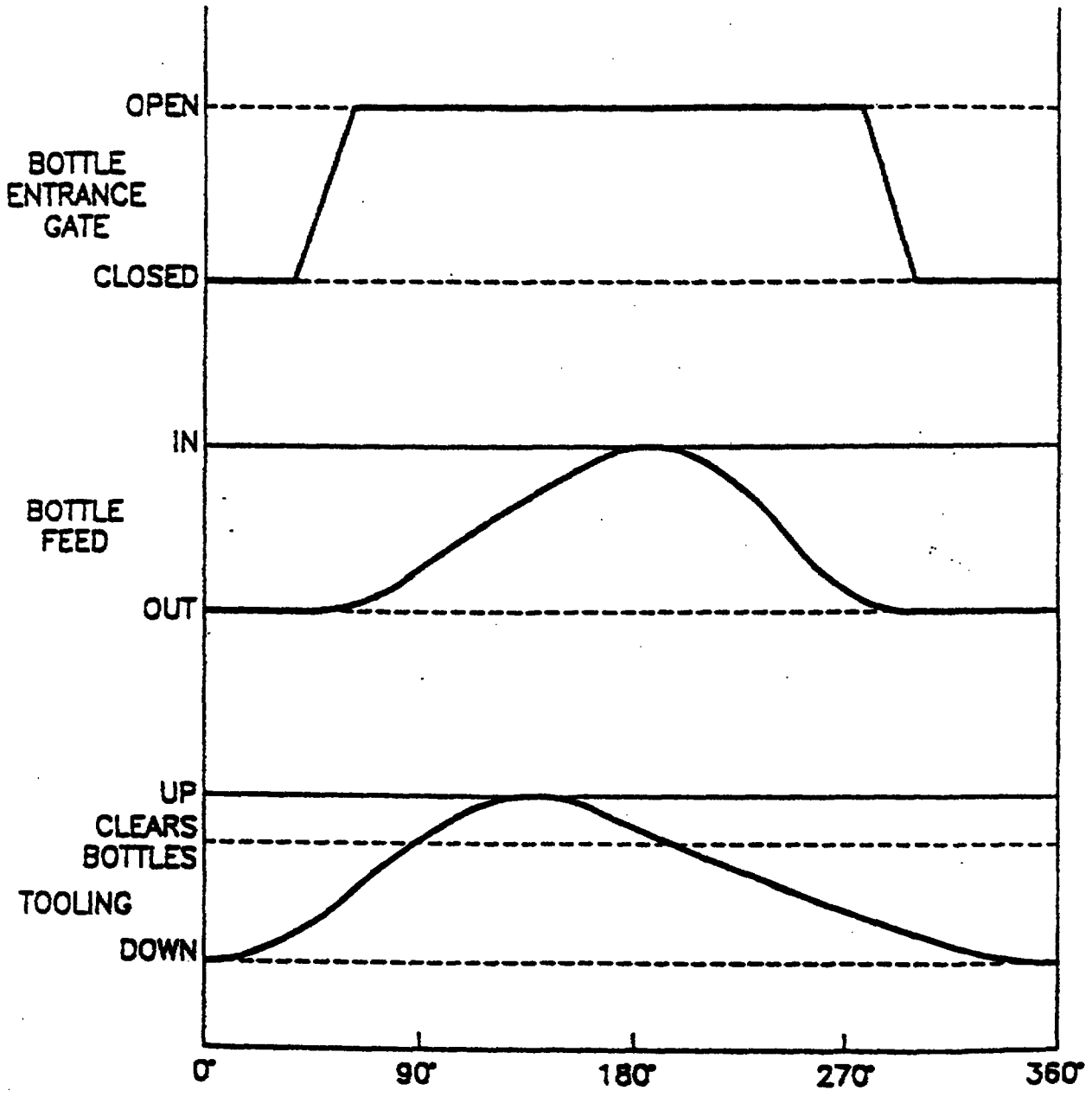


Fig.8

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METHOD AND APPARATUS FOR REGISTERING BOTTLES

ABSTRACT OF THE DISCLOSURE

An apparatus and method are shown and described for labeling bottles in a stream. An input conveyor is provided for supplying bottles to a presenting station. Bottles are restrained at the presenting station until the appropriate time by an entrance gate. Bottles are conveyed from the presenting station to a work station by an advancing conveyor. Bottles entering the work station drive the predecessor bottle out of the work station to a slowing conveyor. Slowed bottles are abutted by subsequent relatively faster moving bottles to be labeled. Abutment with a slowed labeled bottle serves to register each bottle to be labeled at the labeling station.

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METHOD AND APPARATUS FOR REGISTERING BOTTLES**ABSTRACT OF THE DISCLOSURE**

An apparatus and method are shown and described for labeling bottles in a stream. An input conveyor (40) is provided for supplying bottles (30) to a presenting station (50). Bottles are restrained at the presenting station (50) until the appropriate time by an entrance gate (60). Bottles are conveyed from the presenting station (50) to a work station (90) by an advancing conveyor (80). Bottles (30) entering the work station (90) drive the predecessor bottle out of the work station to a slowing conveyor (100). Slowed bottles are abutted by subsequent relatively faster moving bottles to be labeled. Abutment with a slowed labeled bottle serves to register each bottle to be labeled at the labeling station (10).

Fig. 1.

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