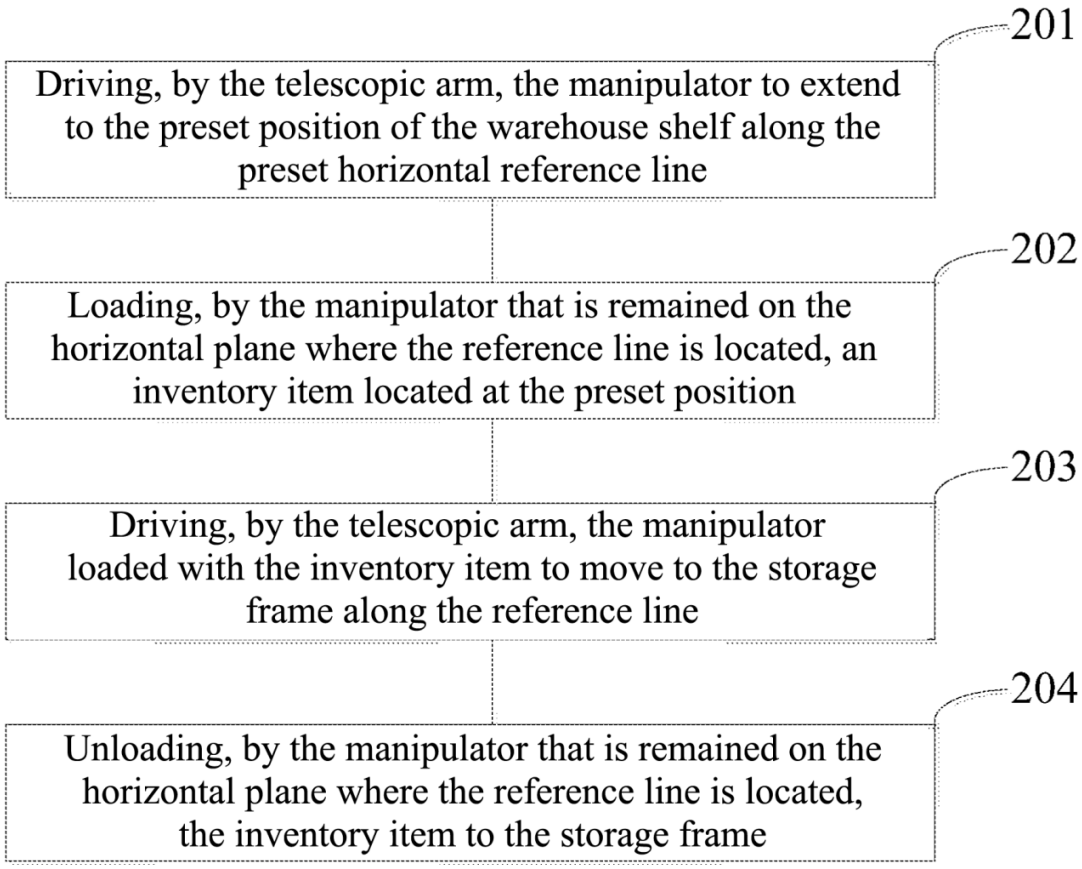

201
Driving, by the telescopic arm, the manipulator to extend to the preset position of the warehouse shelf along the preset horizontal reference line
202
Loading, by the manipulator that is remained on the horizontal plane where the reference line is located, an inventory item located at the preset position
203
Driving, by the telescopic arm, the manipulator loaded with the inventory item to move to the storage frame along the reference line
204
Unloading, by the manipulator that is remained on the horizontal plane where the reference line is located, the inventory item to the storage frame

FIG. 11