

What Is Claimed Is:

1. A transport facility comprising:
 - a transport vehicle configured to travel along a travel route;
 - a guide rail along the travel route; and
 - a control system configured to control the transport vehicle,characterized in that,
 - with a travel direction being a direction along the travel route, a width direction being a direction orthogonal to the travel direction in a vertical view, a first side in the width direction being one side in the width direction, and a second side in the width direction being another side in the width direction,
 - the transport vehicle includes:
 - a guided section configured to be guided by the guide rail; and
 - a guide drive section configured to drive the guided section in the width direction to move the guided section to a first position on the first side in the width direction of the guide rail and to a second position on the second side in the width direction of the guide rail,
 - the travel route includes a guide zone in which the guide rail is disposed and a non-guide zone in which the guide rail is not disposed, and
 - in response to occurrence of a specific event in which the transport vehicle loses information on a travel position thereof, the control system (i) causes the guide drive section to execute a confirmation operation to drive the guided section in the width direction, (ii) determines that the transport vehicle is in the non-guide zone in response to the guided section moving from the first position to the second position or from the second position to the first position in the confirmation operation, and (iii) determines that the transport vehicle is in the guide zone in response to the guided section being prevented from moving from the first position to the second position or from the second position to the first position in the confirmation operation.

2. The transport facility according to claim 1,
wherein the transport vehicle further includes an obstacle sensor configured to detect an obstacle on a forward side in the travel direction,
the guide rail is in at least either a zone in which the travel route intersects another travel route or a zone in which the travel route is curved,
and
the control system sets a detection range of the obstacle sensor in the width direction wider in response to determining that the transport vehicle is in the guide zone than in response to determining that the transport vehicle is in the non-guide zone as a result of the confirmation operation.
3. The transport facility according to claim 1 or 2, further comprising:
an information holder holding positional information on a position thereof, at each of a plurality of points along the travel route,
wherein the transport vehicle further includes a reader configured to read the positional information of the plurality of information holders and recognize a travel position of the transport vehicle based on the information read by the reader,
the control system executes restoration processing to allow the transport vehicle to start traveling after the specific event is resolved, and
the transport vehicle in the restoration processing is caused to travel at or below a predetermined first speed limit for restoration from when the stopped transport vehicle starts traveling to when the transport vehicle reads the positional information of an information holder among the plurality of information holders.
4. The transport facility according to claim 3,
wherein, in the restoration processing, the control system (i) causes the

transport vehicle to travel at or below the first speed limit for restoration in response to determining that the transport vehicle is in the non-guide zone as a result of the confirmation operation, and (ii) causes the transport vehicle to travel at or below a second speed limit for restoration, which is lower than the first speed limit for restoration, in response to determining that the transport vehicle is in the guide zone as a result of the confirmation operation.

5. The transport facility according to claim 1 or 2, wherein in response to occurrence of the specific event on a plurality of transport vehicles on the travel route, the control system causes the plurality of transport vehicles to simultaneously execute the confirmation operation.

6. The transport facility according to claim 1 or 2,
wherein the transport vehicle includes a first guided section that is the guided section, and a second guided section on a rearward side of the first guided section in the travel direction,

the guide drive section drives the first guided section and the second guided section independently of each other in the width direction, and

in response to occurrence of the specific event, the control system (i) causes the confirmation operation to be executed for both the first guided section and the second guided section, (ii) determines that the transport vehicle is in the non-guide zone in response to both the first guided section and the second guided section moving from the first position to the second position or from the second position to the first position in the confirmation operation, and (iii) determines that the transport vehicle is in the guide zone in response to at least either the first guided section or the second guided section being prevented from moving from the first position to the second position or from the second position to the first position in the confirmation operation.

7. The transport facility according to claim 1,
wherein the transport vehicle further includes an obstacle sensor configured to detect an obstacle on a forward side in the travel direction,
the guide rail is in at least either a zone in which the travel route intersects another travel route or a zone in which the travel route is curved,
and
the control system sets a detection range of the obstacle sensor in a vertical direction or the travel direction wider in response to determining that the transport vehicle is in the guide zone than in response to determining that the transport vehicle is in the non-guide zone as a result of the confirmation operation.