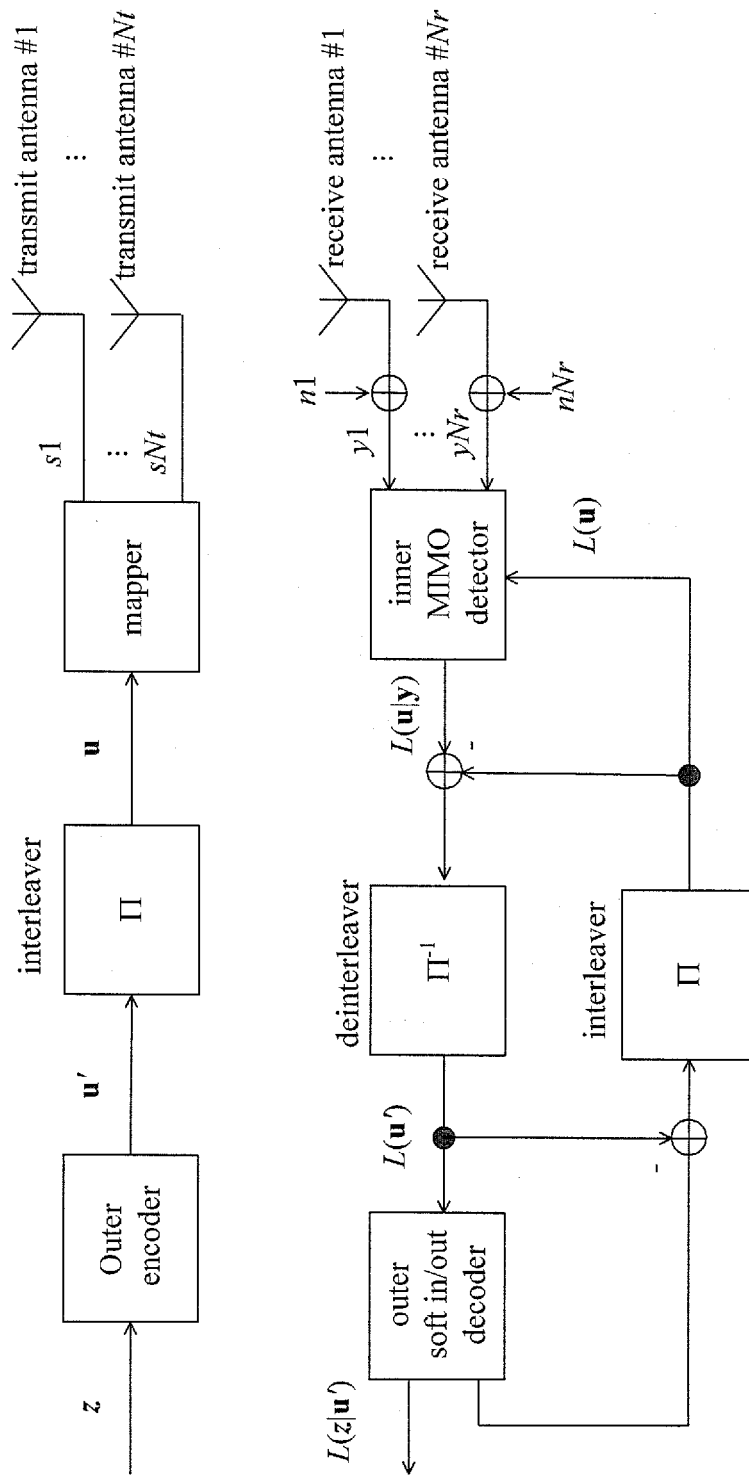
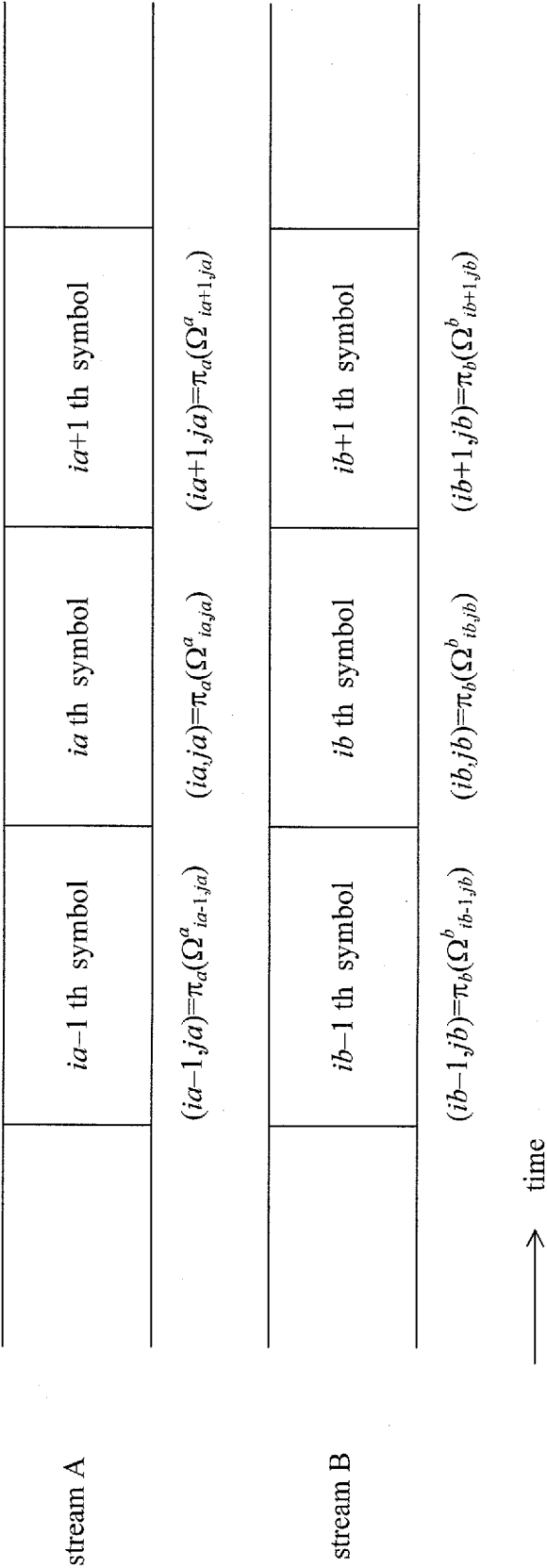


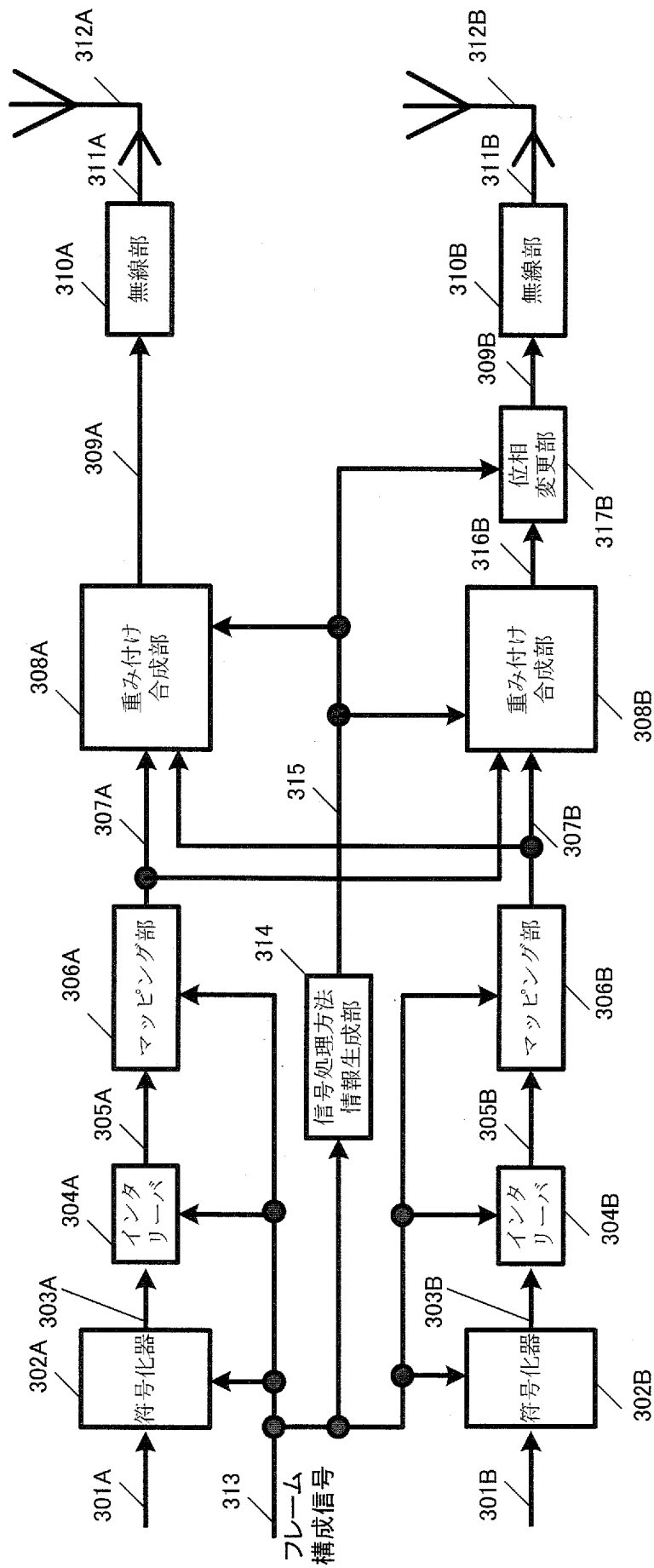
[図1]



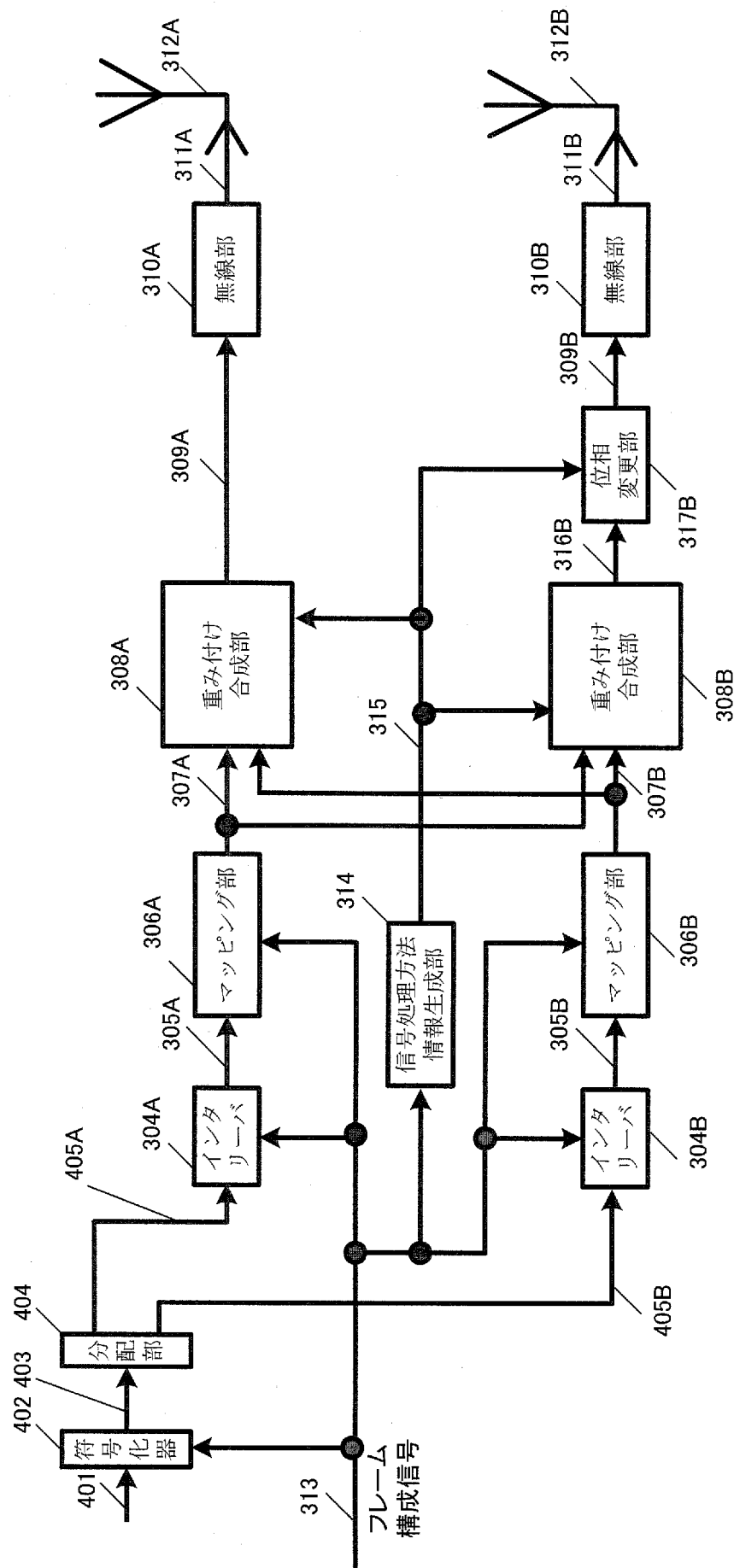
[図2]



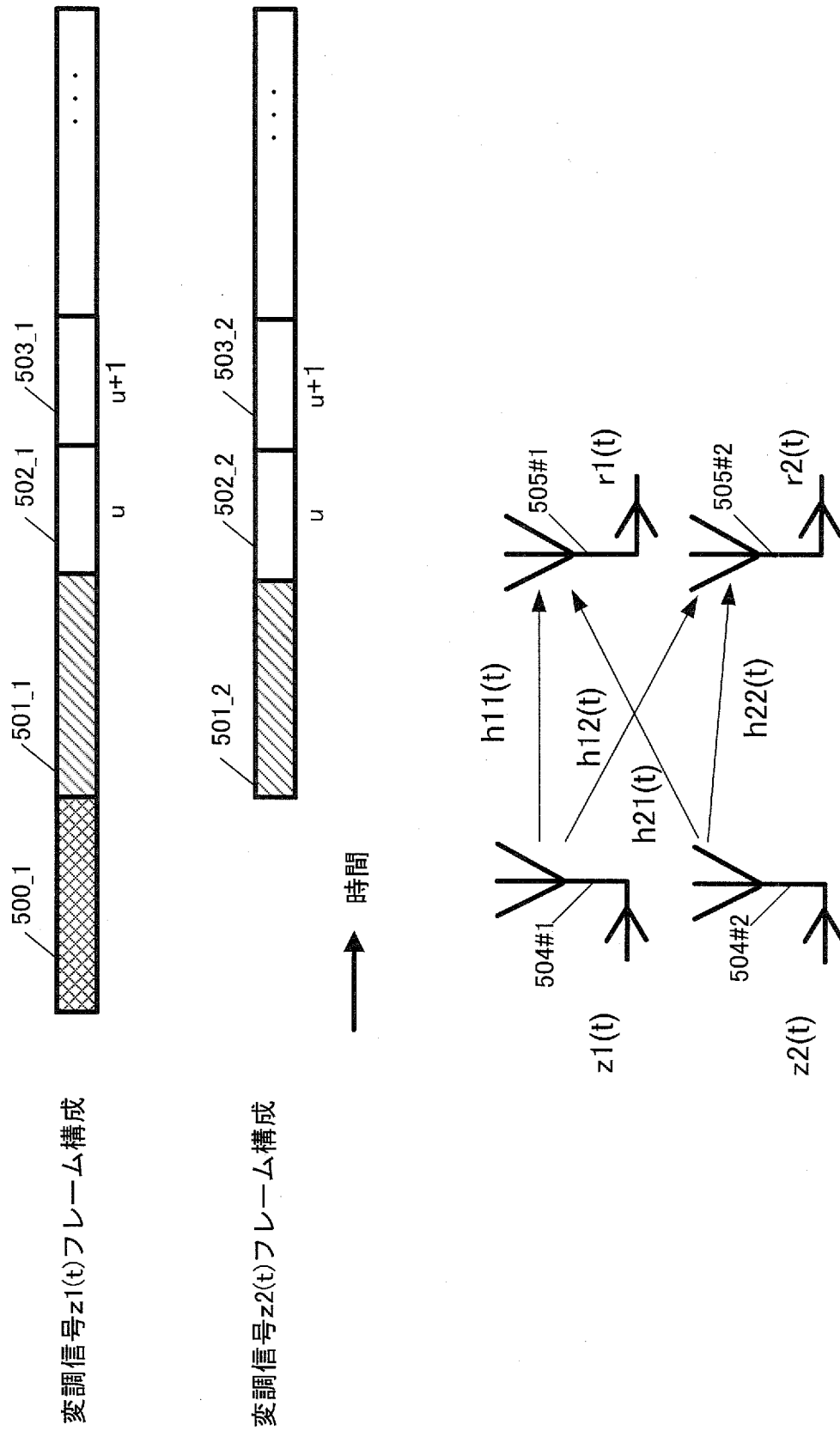
[図3]



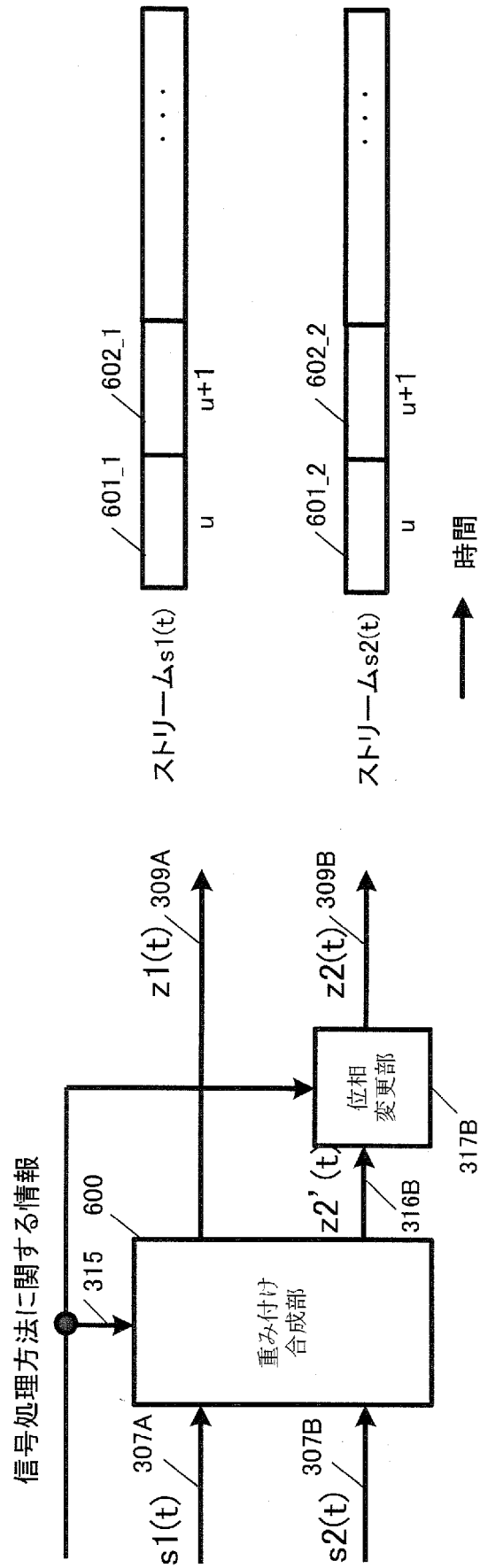
[図4]



[図5]



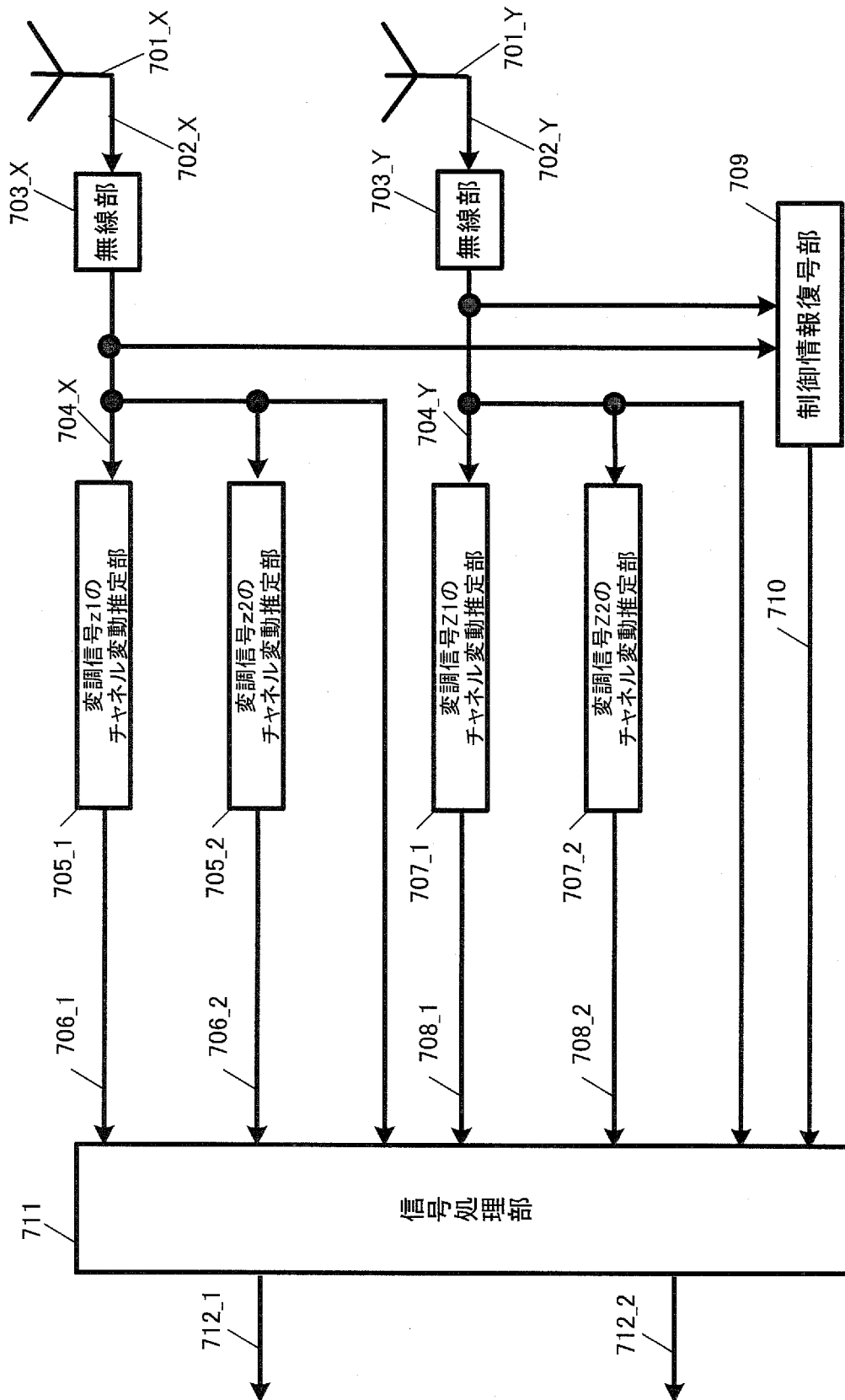
[図6]



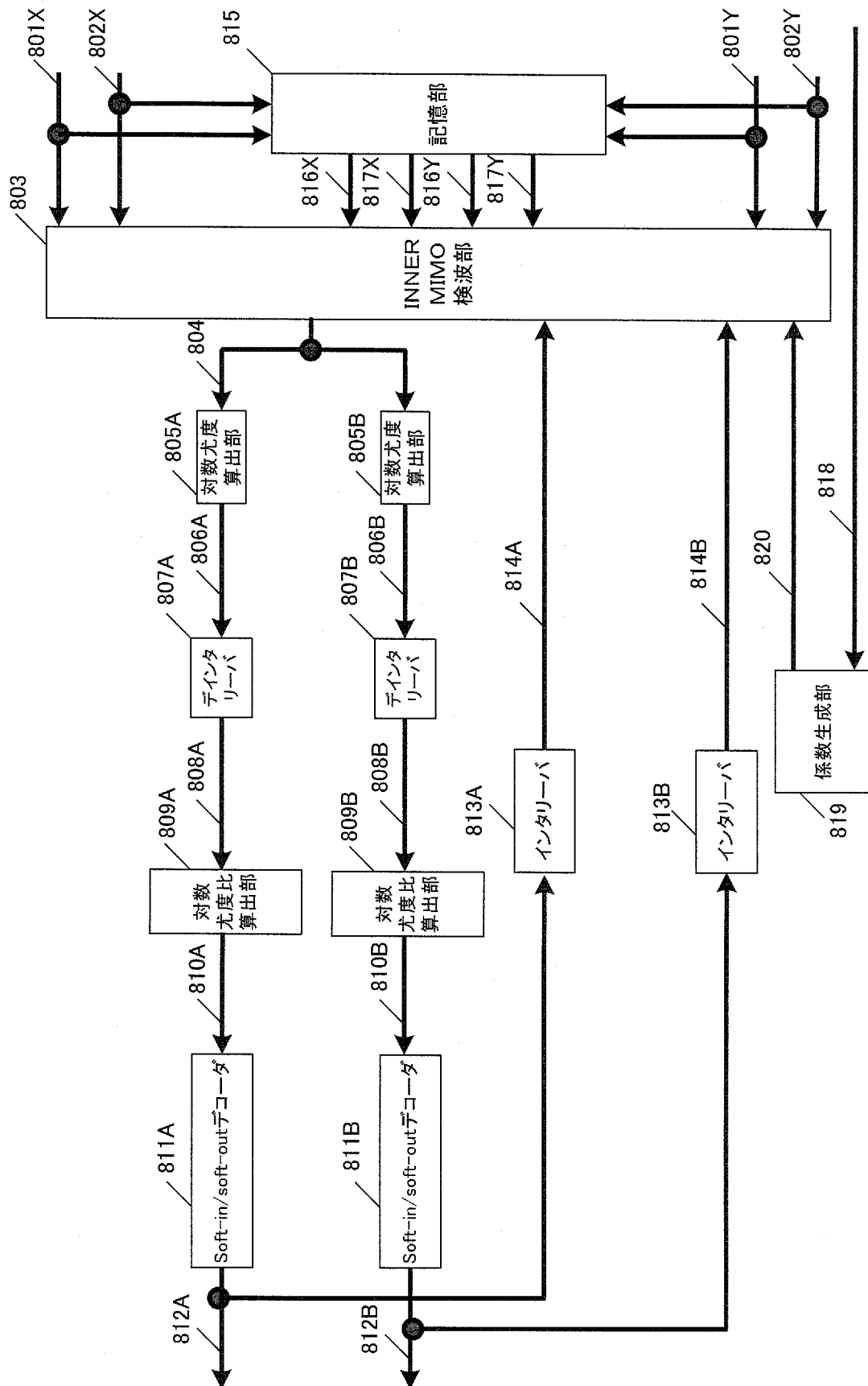
位相変更部の位相変更式 $y(t)$ の変更例

時刻 u	時刻 $u+1$	時刻 $u+2$	時刻 $u+3$	時刻 $u+k$
$y(u) = e^{j0}$	$y(u+1) = e^{j\frac{\pi}{2}}$	$y(u+2) = e^{j\pi}$	$y(u+3) = e^{j\frac{3\pi}{2}}$	$y(u+k) = e^{j\frac{k\pi}{2}}$

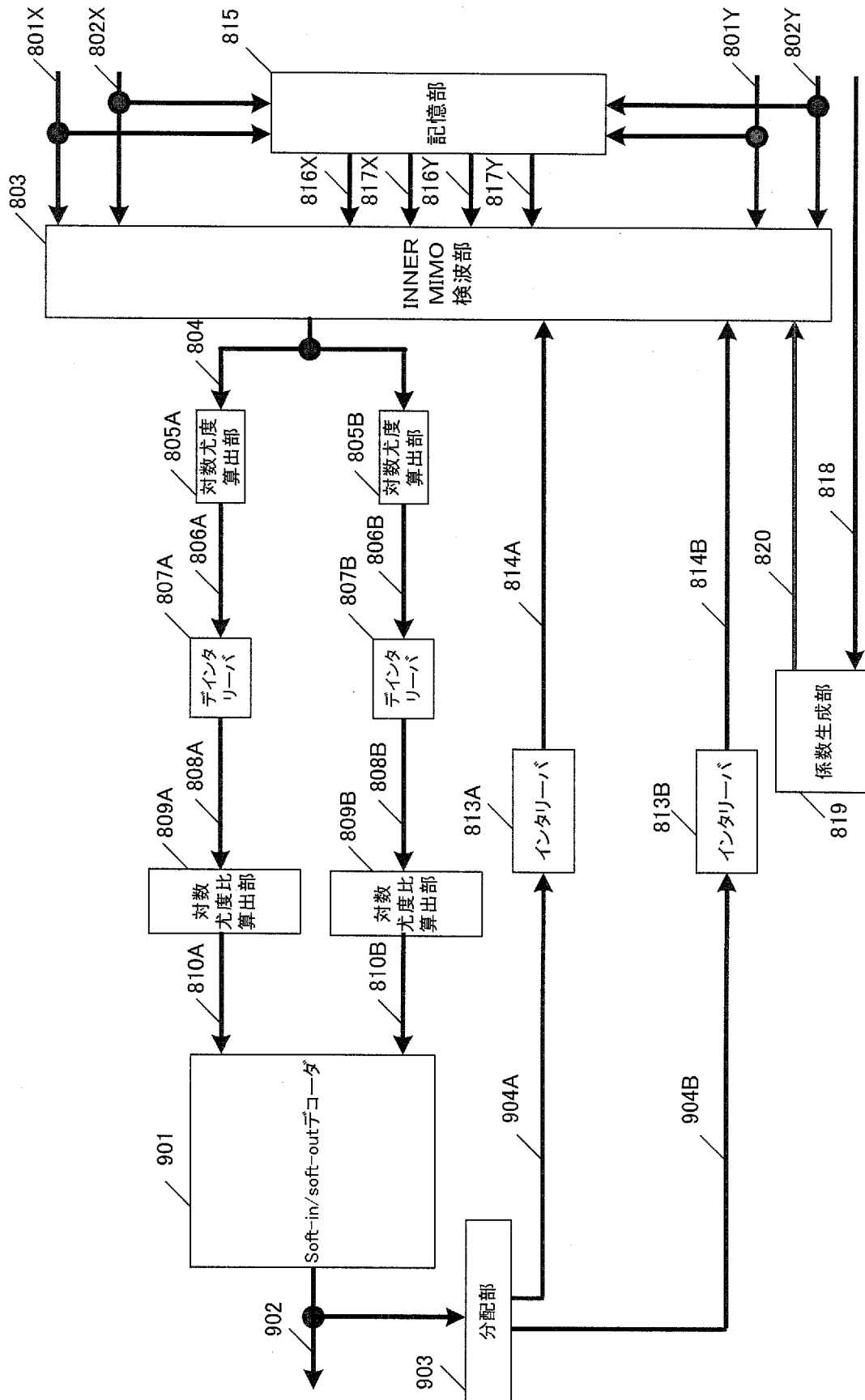
[図7]



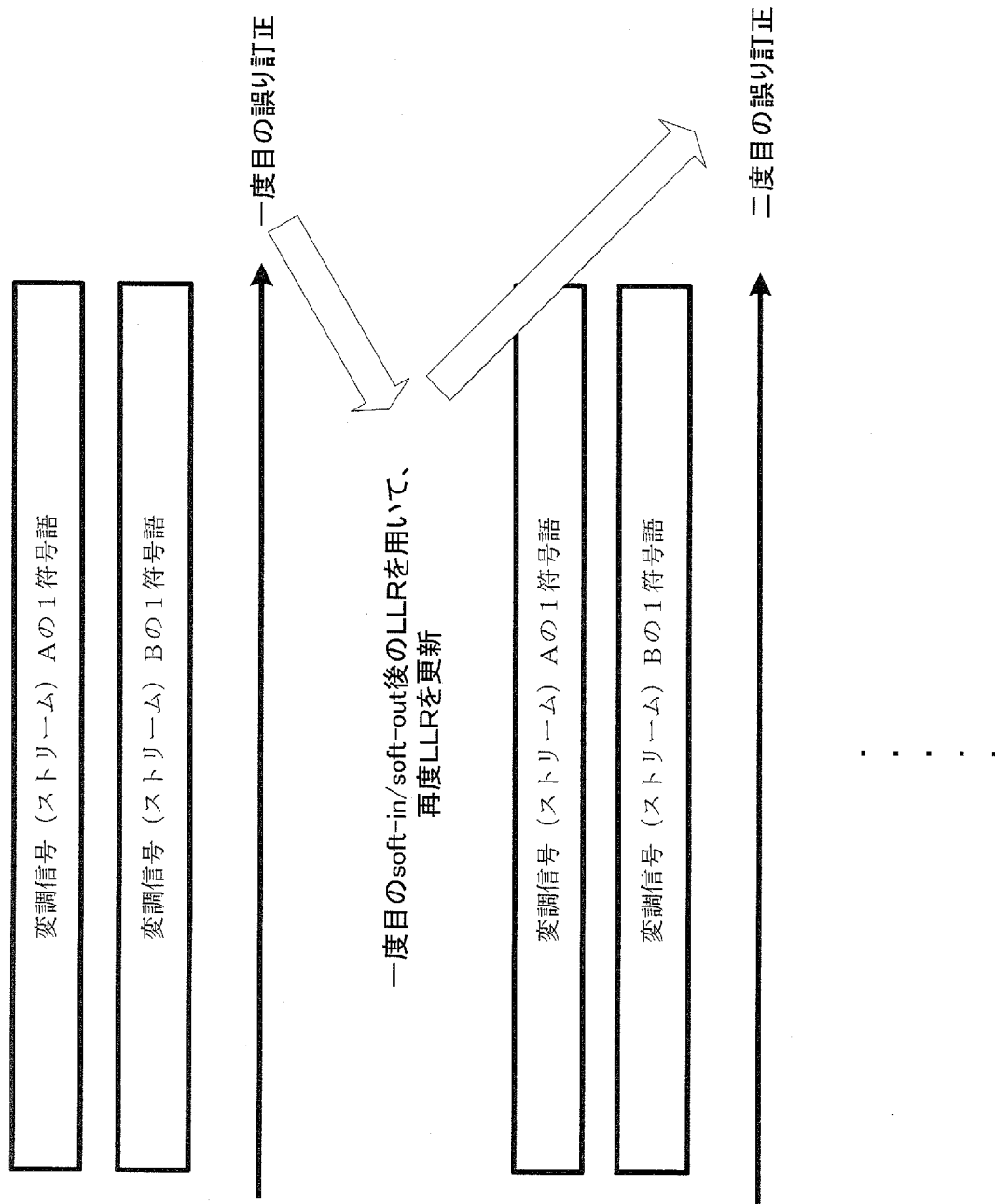
[図8]



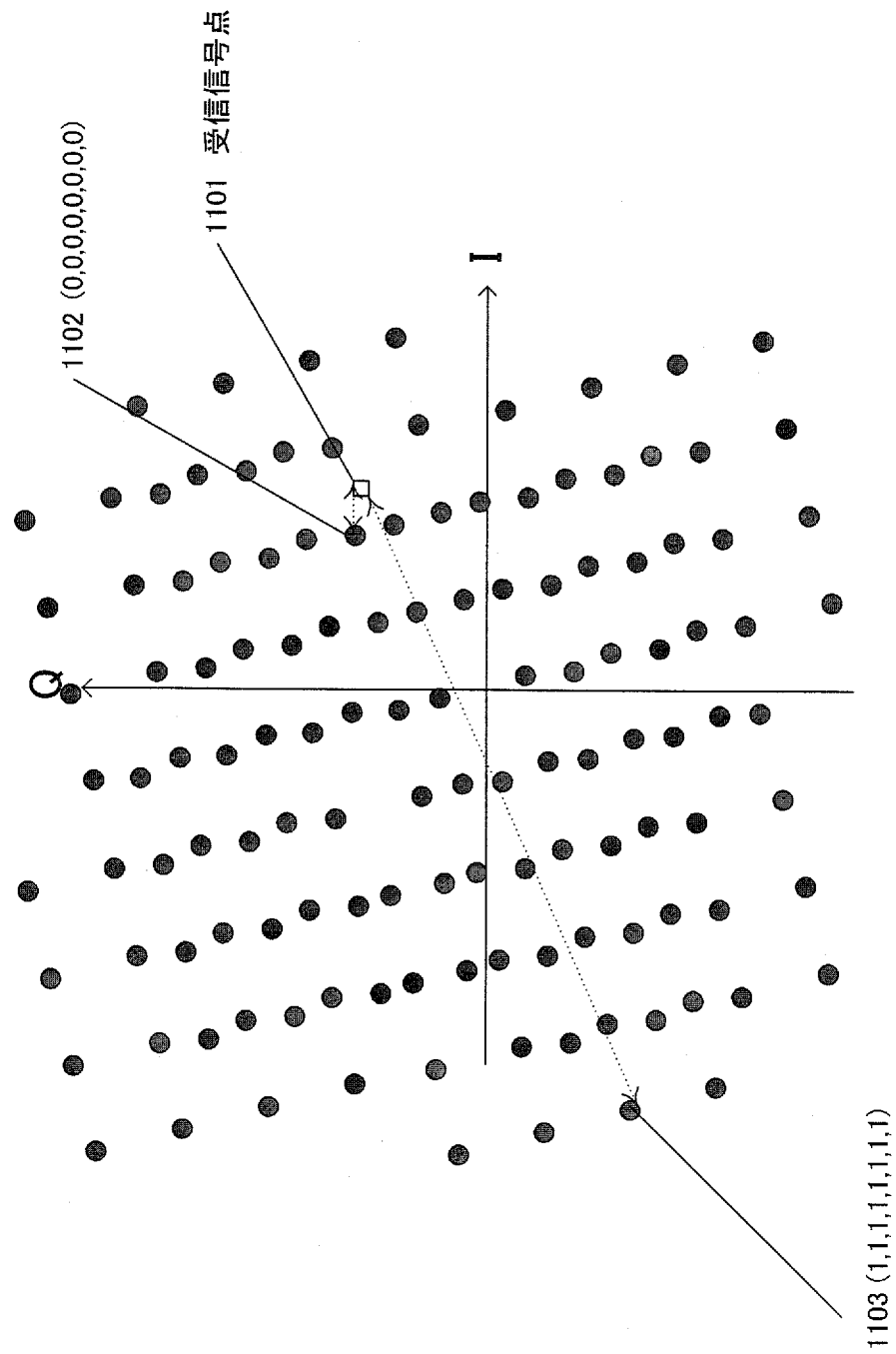
[図9]



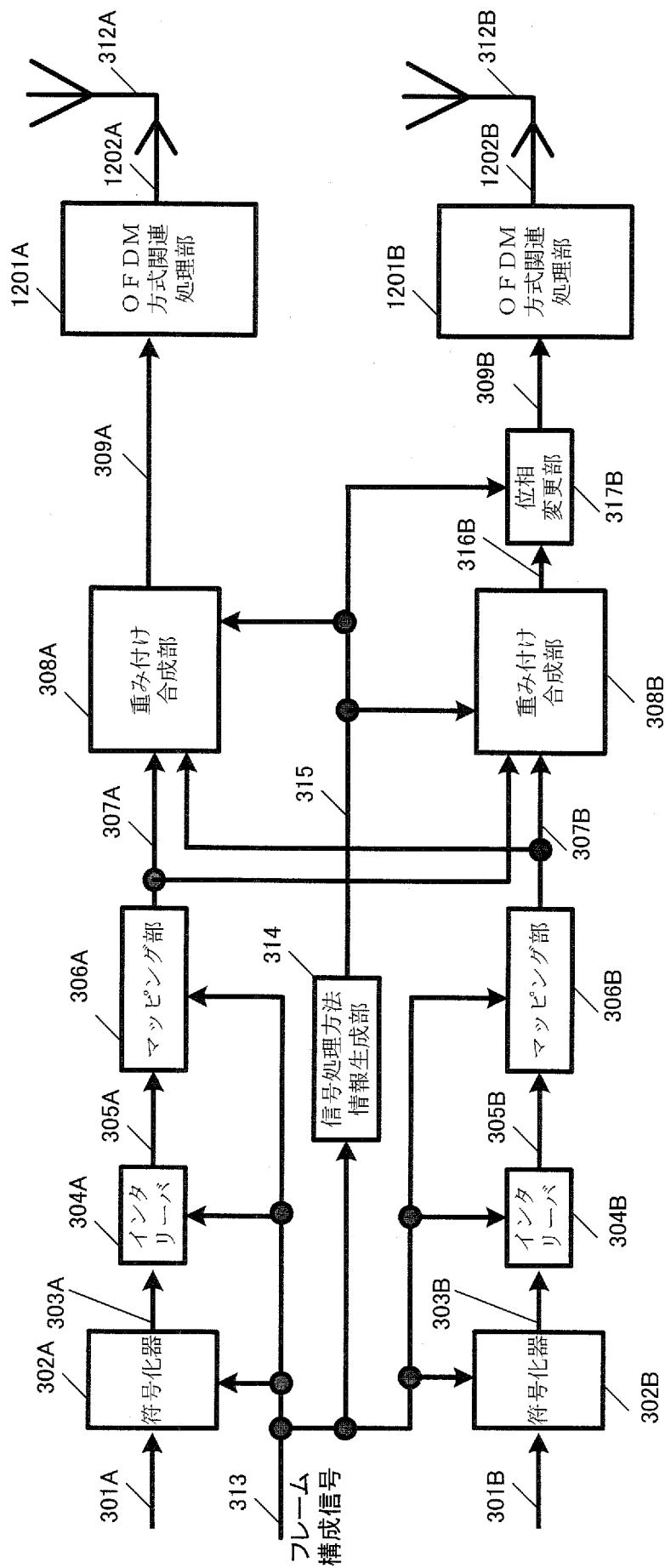
[図10]



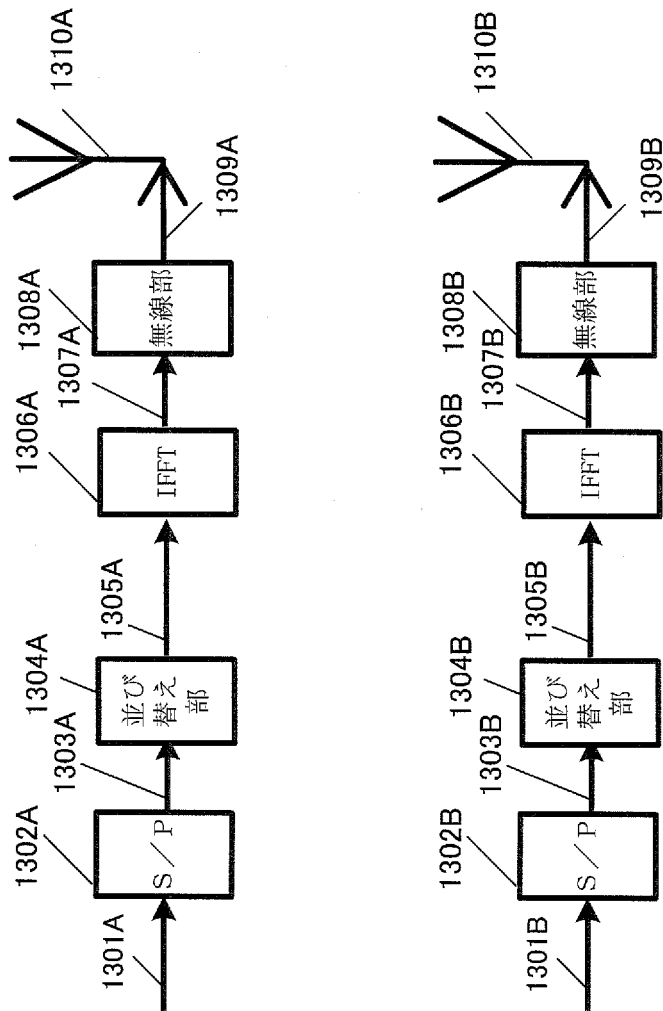
[図11]



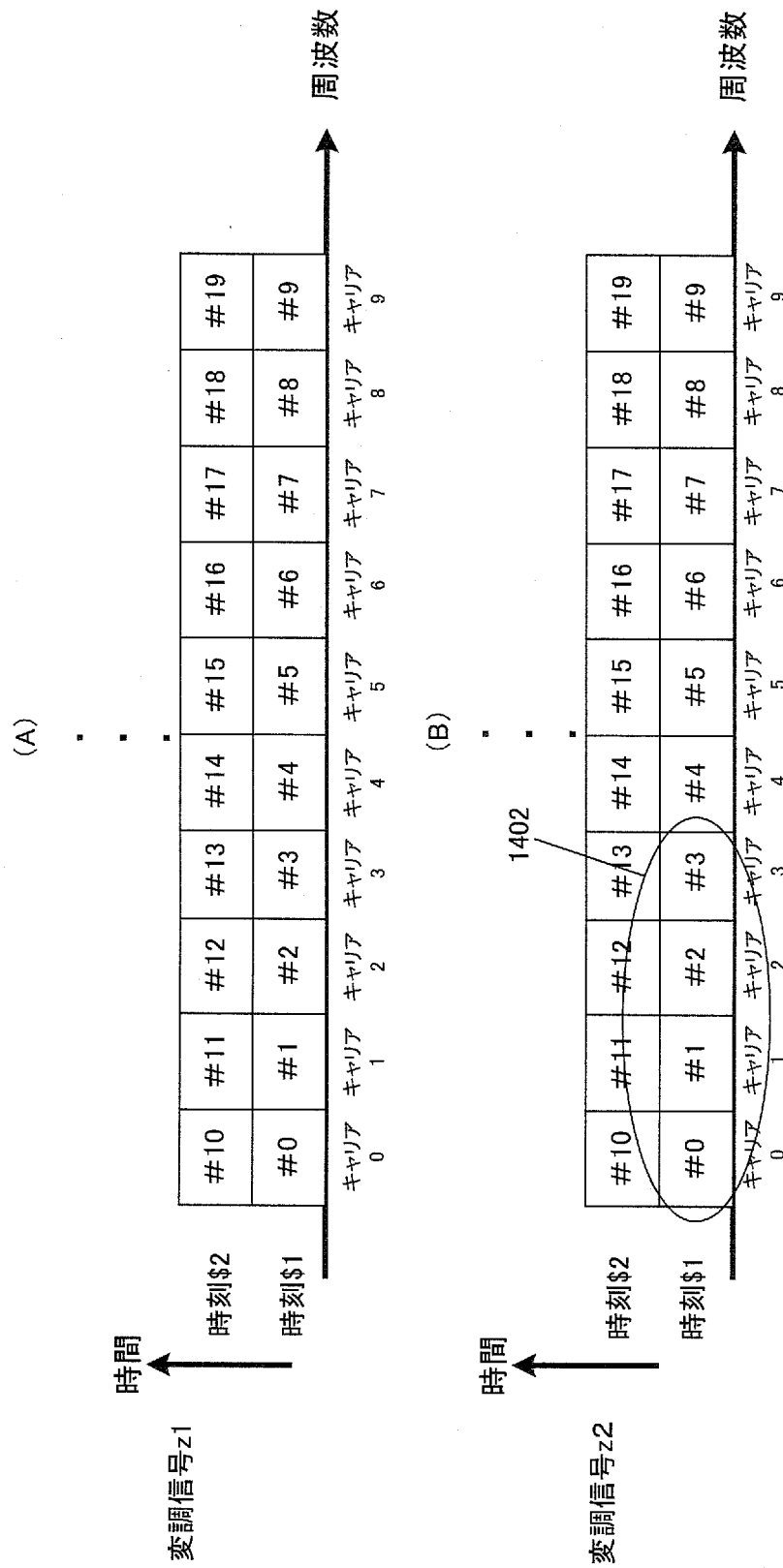
[図12]



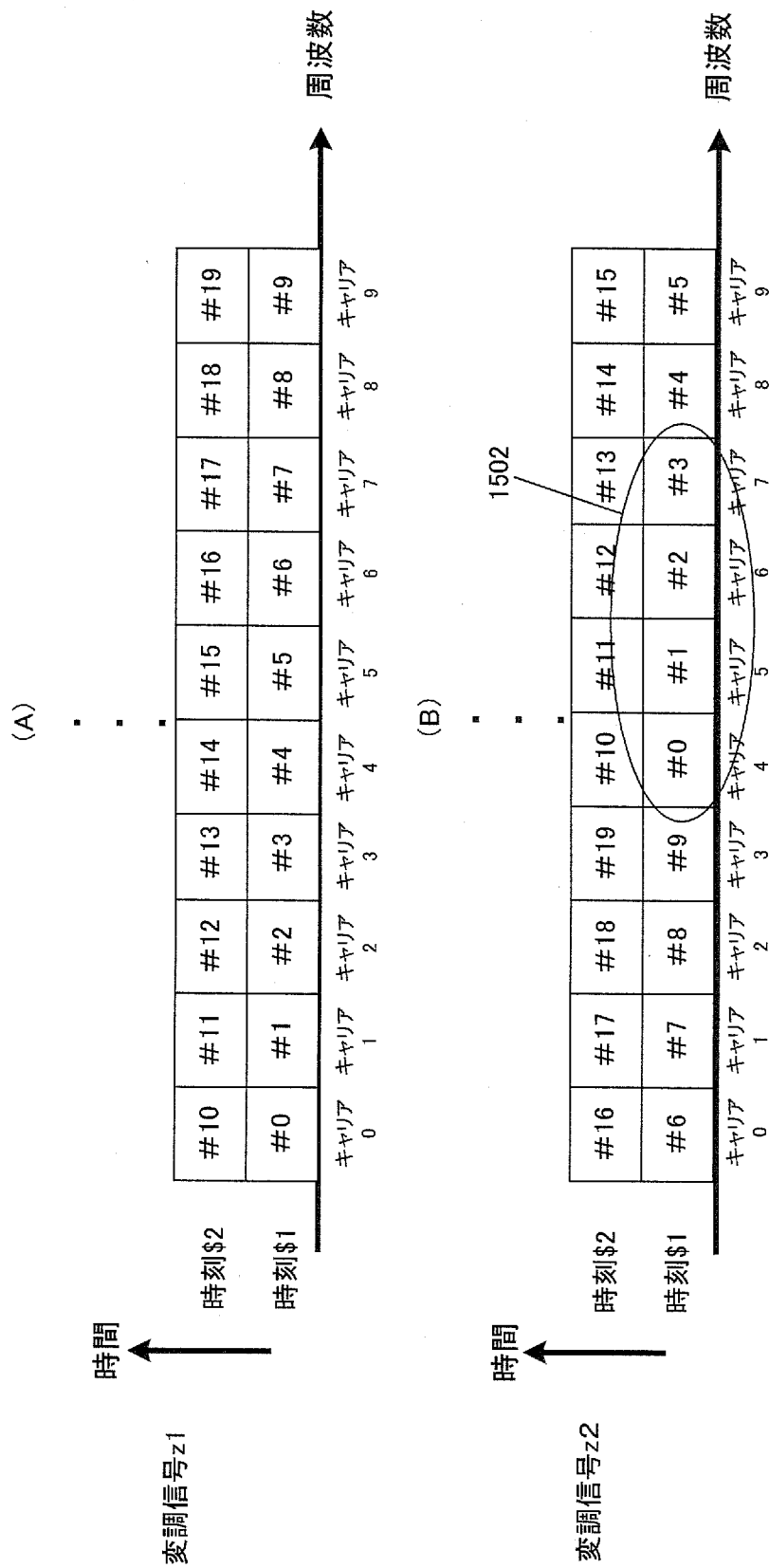
[図13]



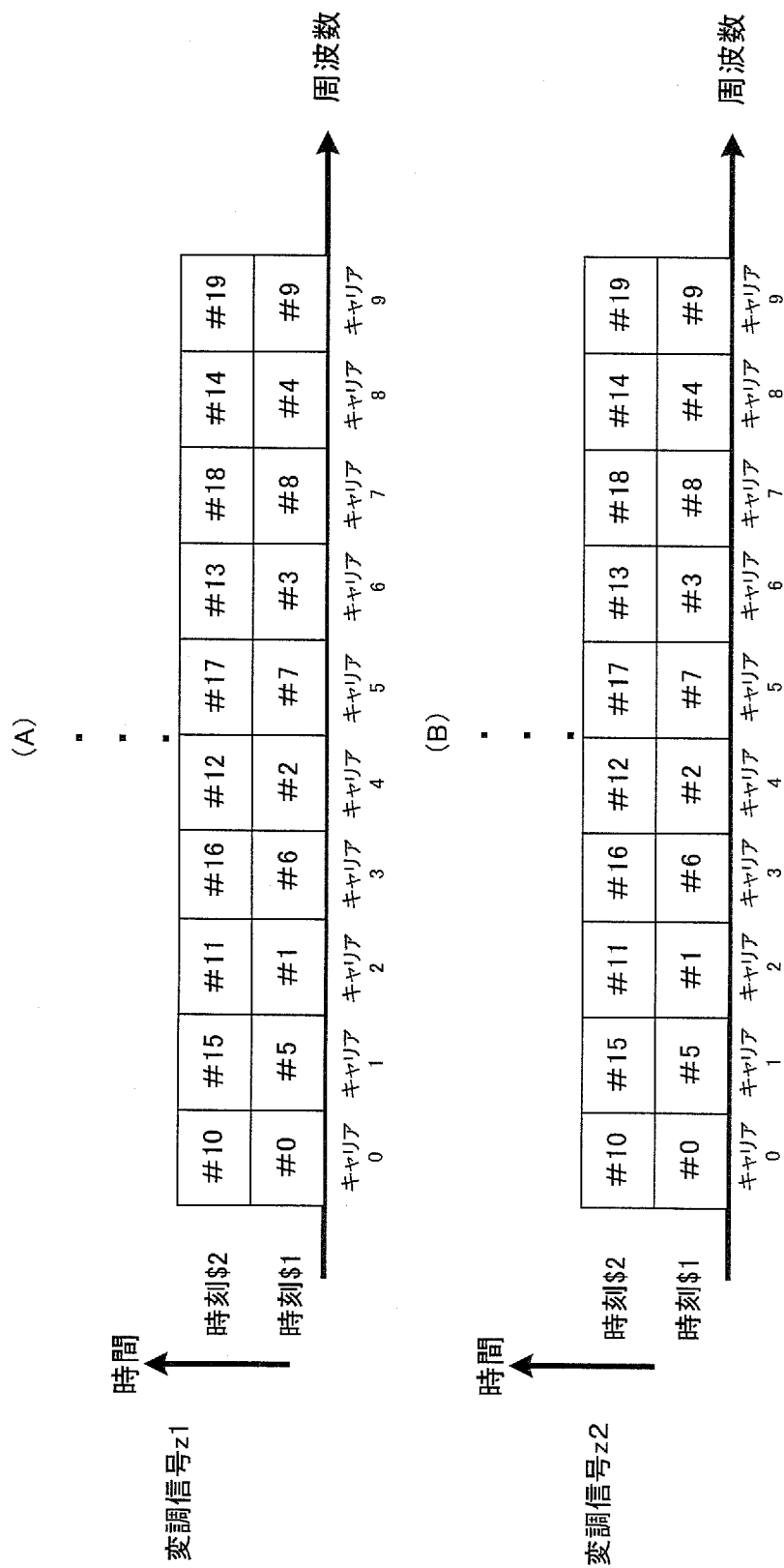
[図14]



[図15]

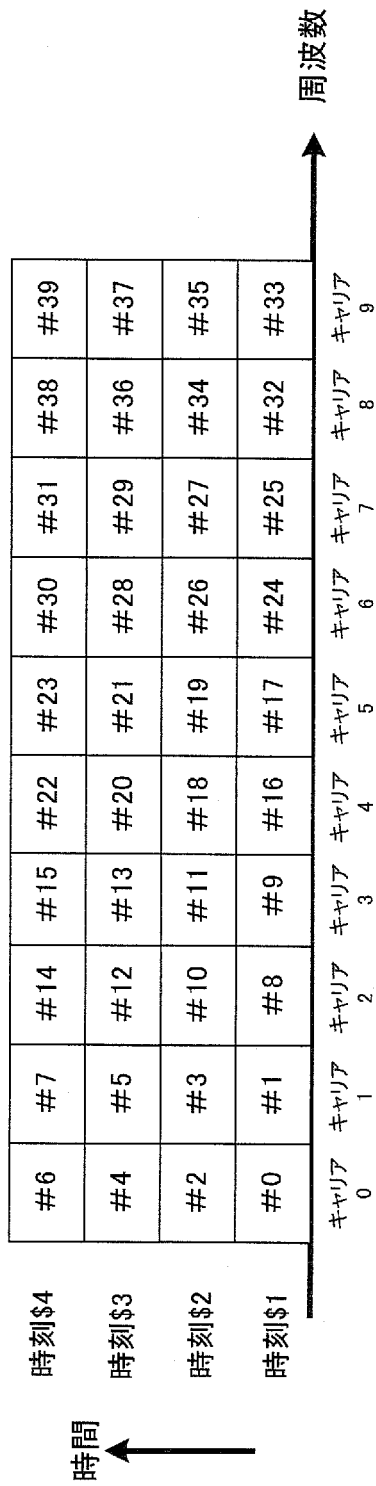


[図16]



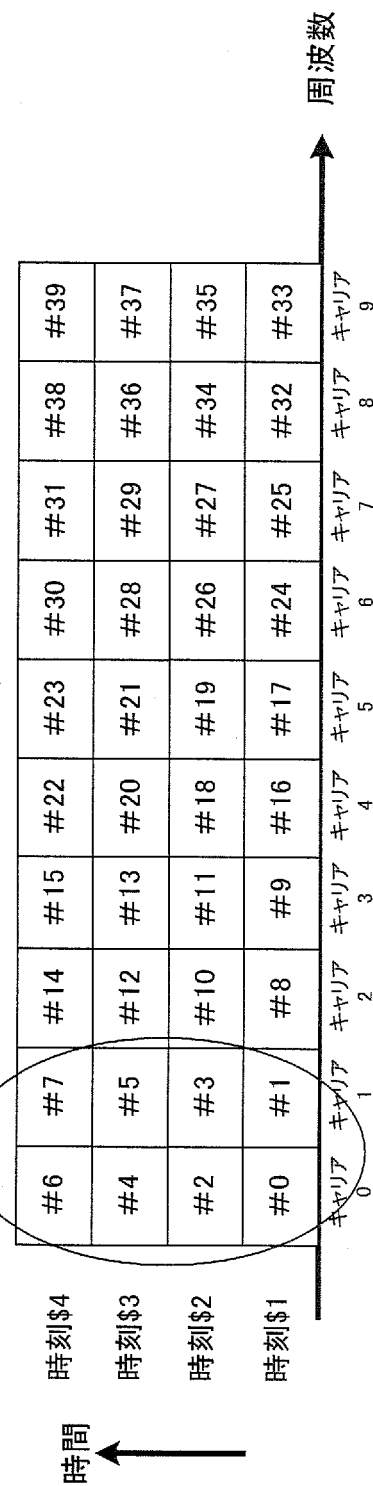
[図17]

(A)

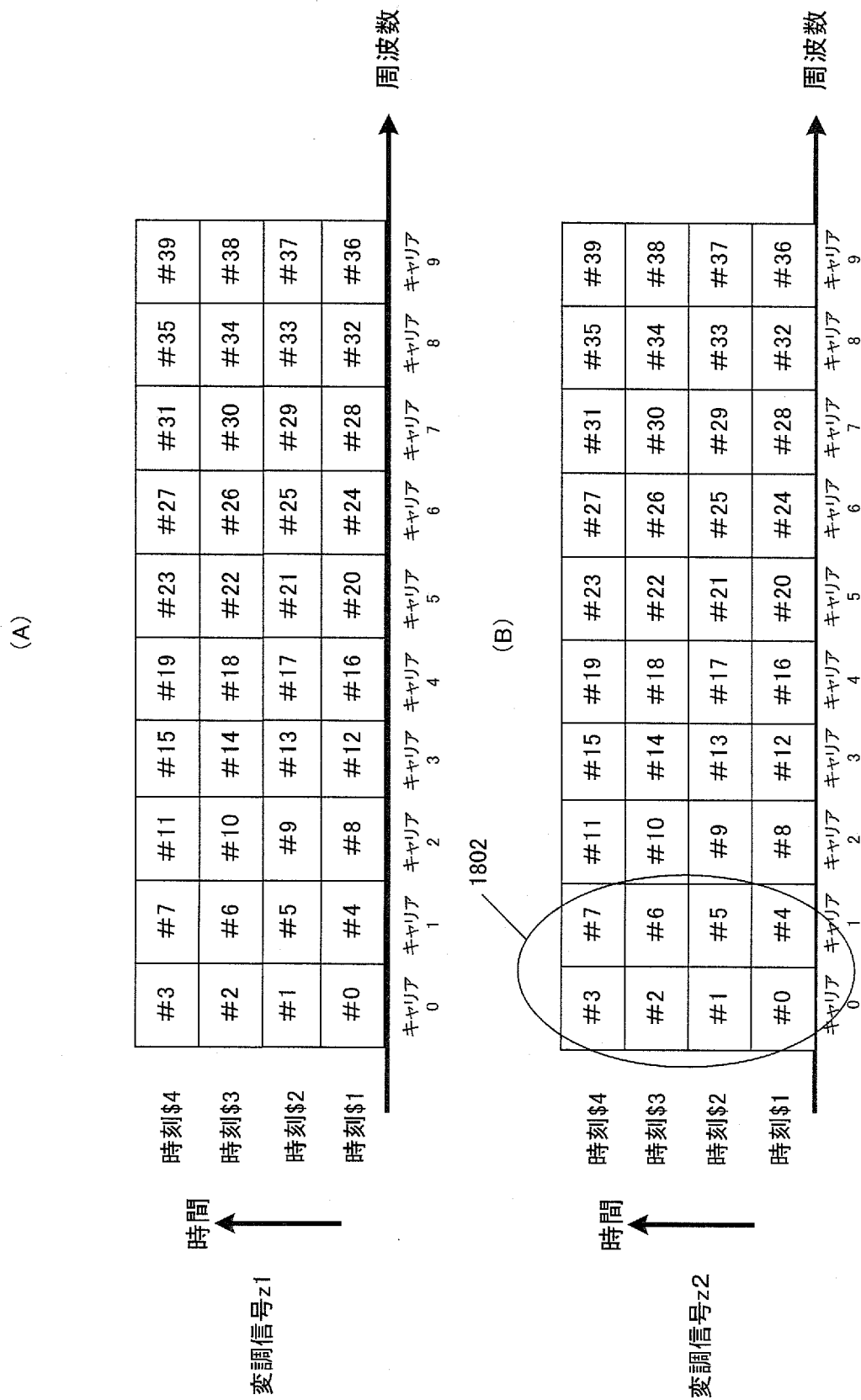


(B)

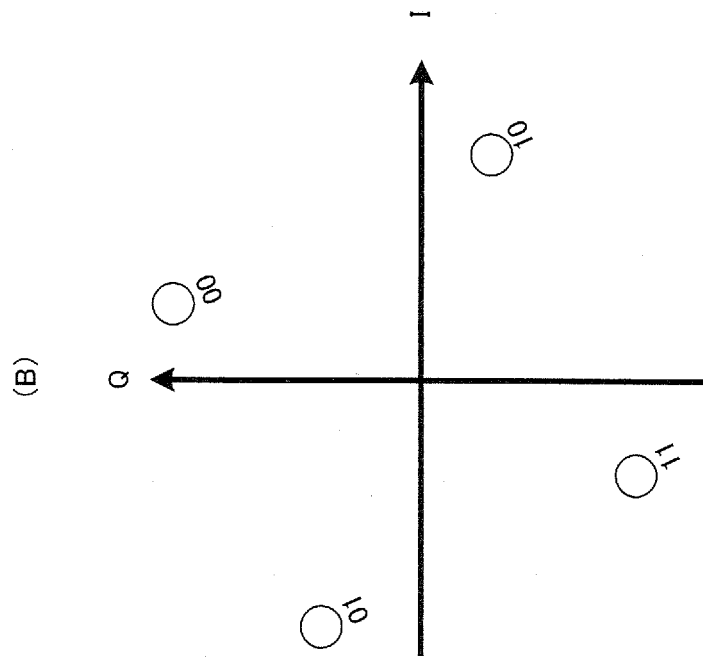
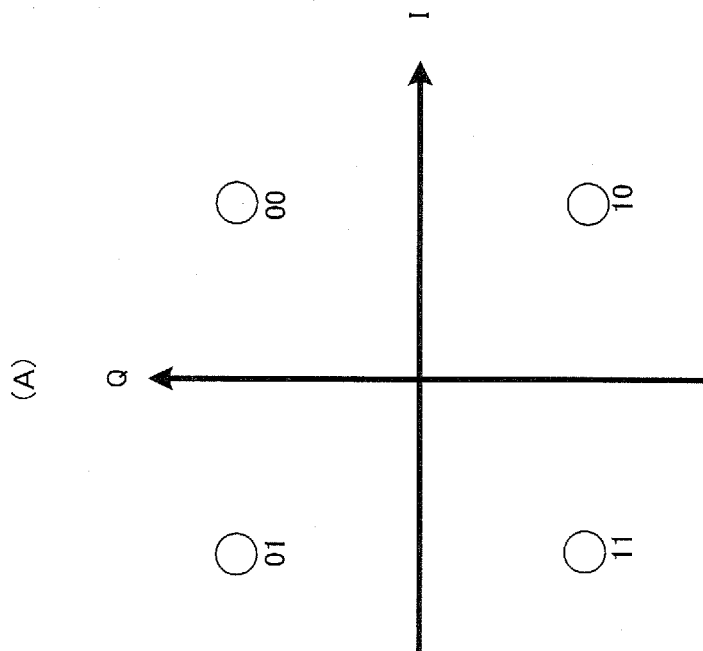
1702



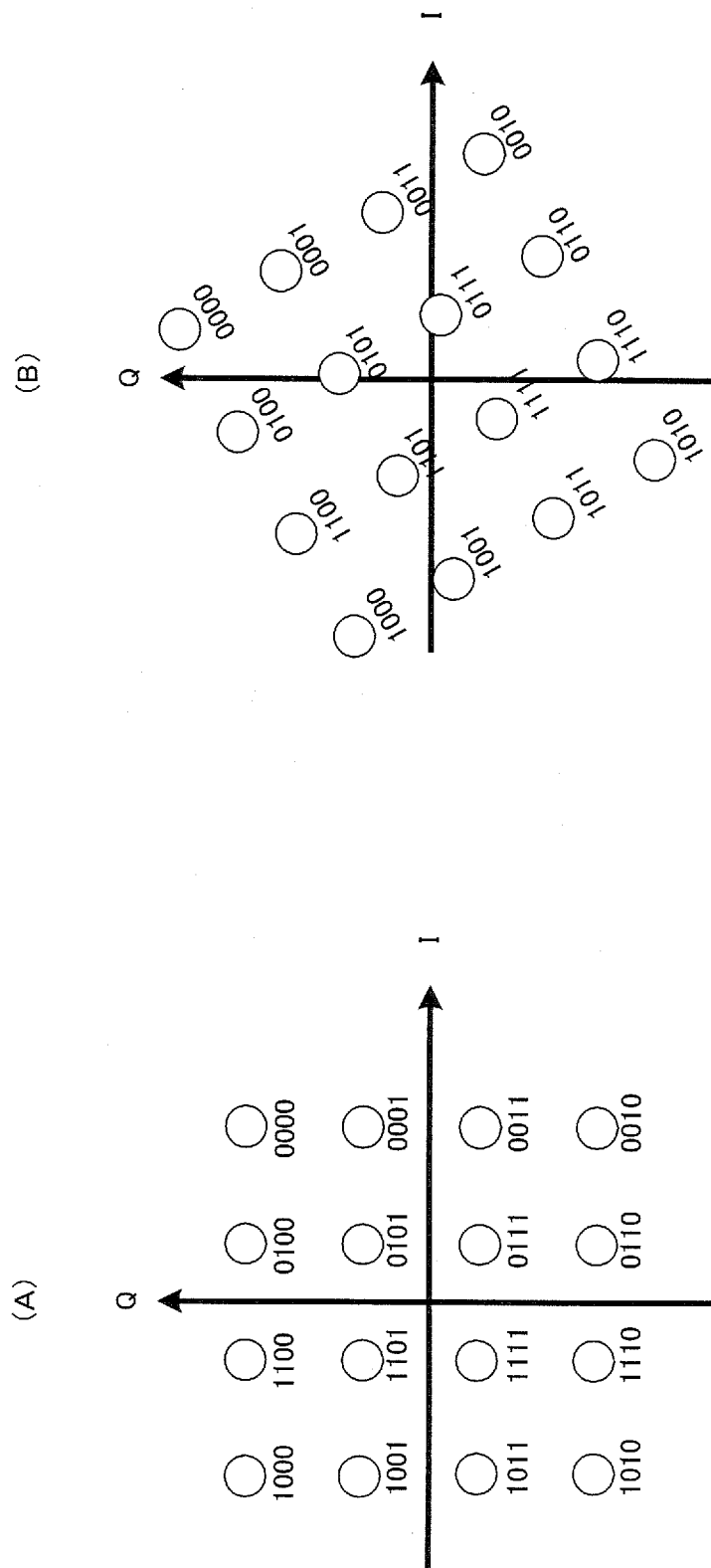
[図18]



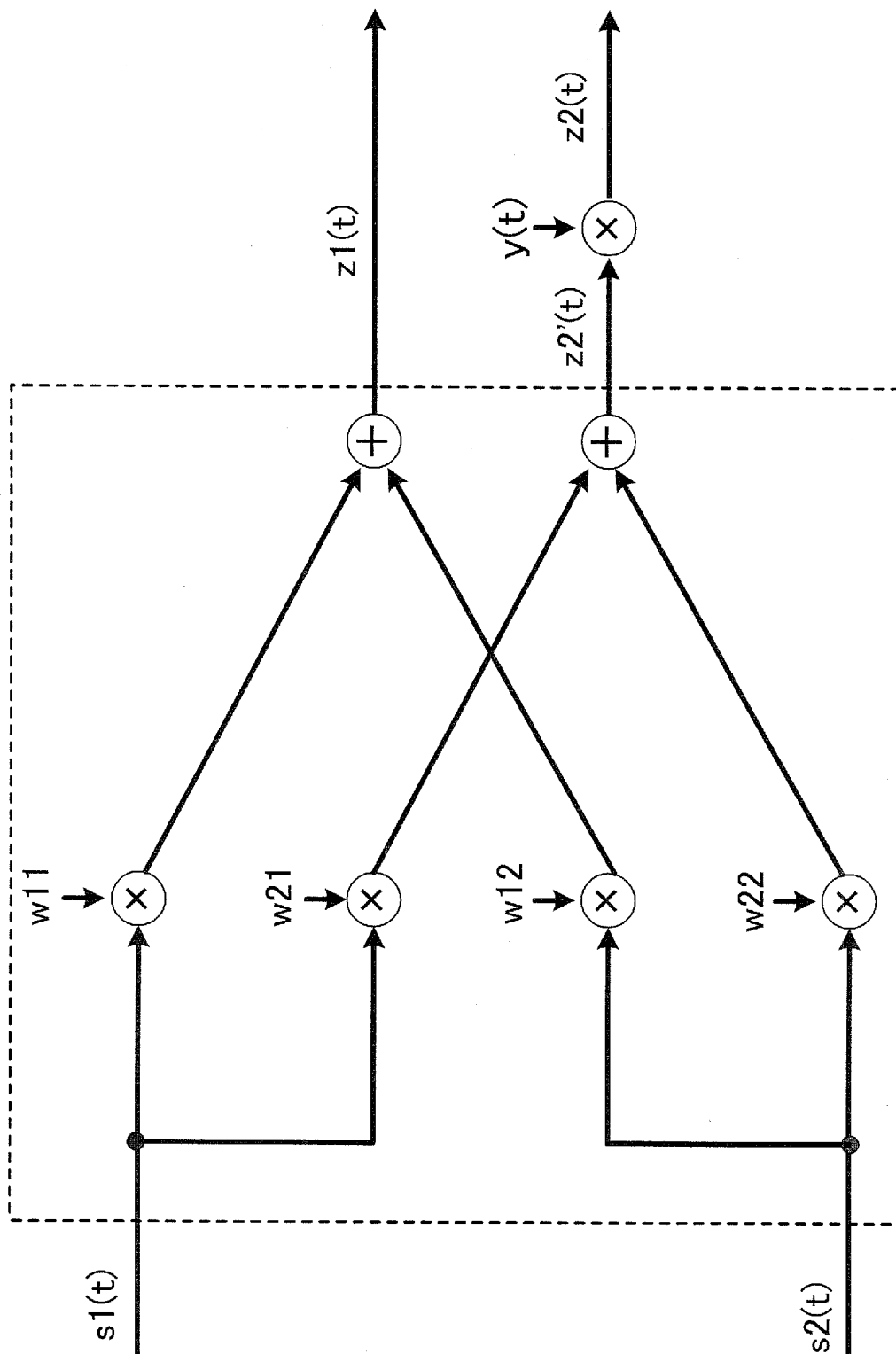
[図19]

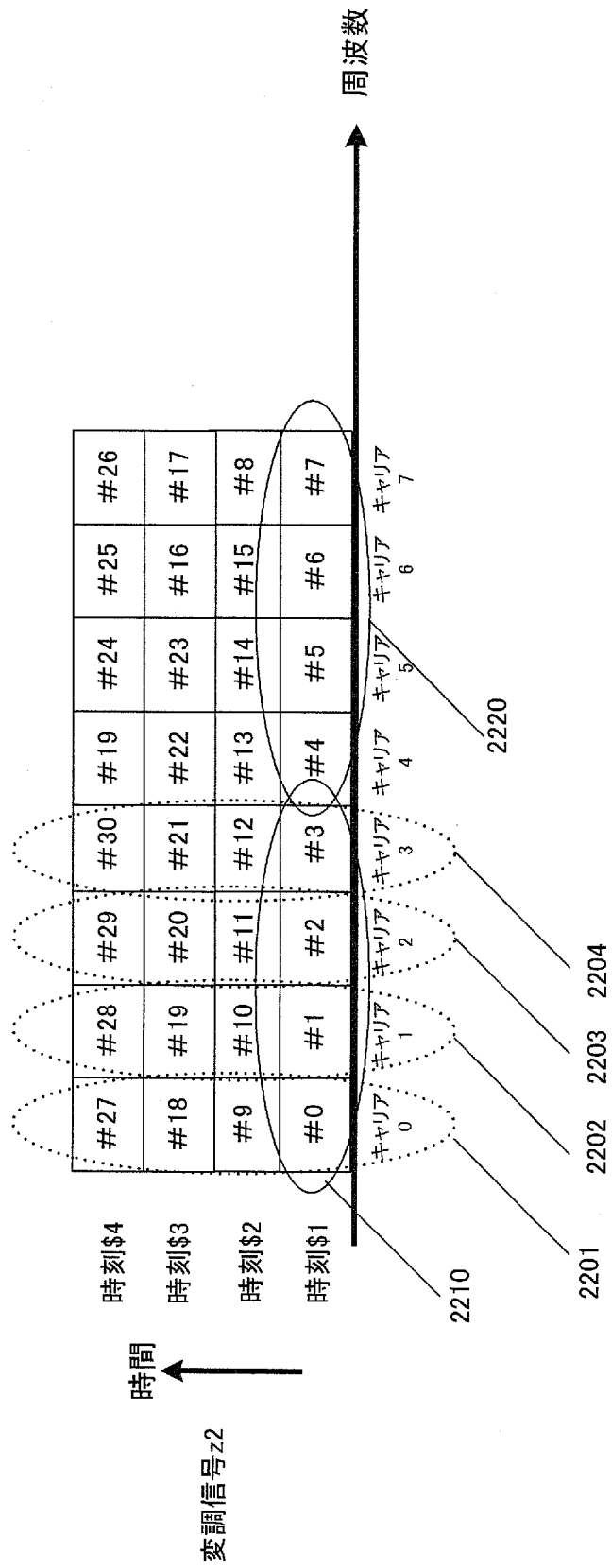


[図20]

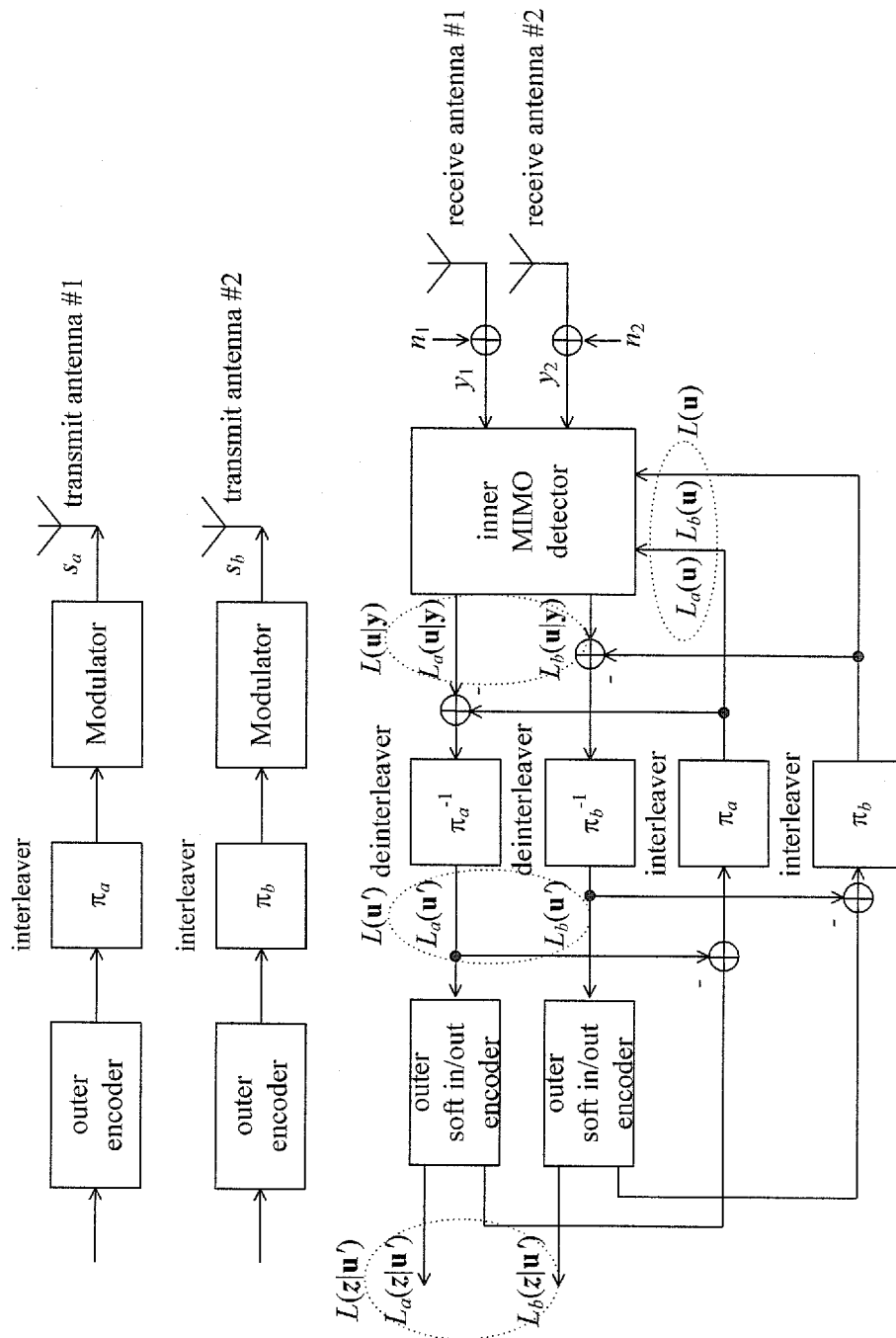


[図21]

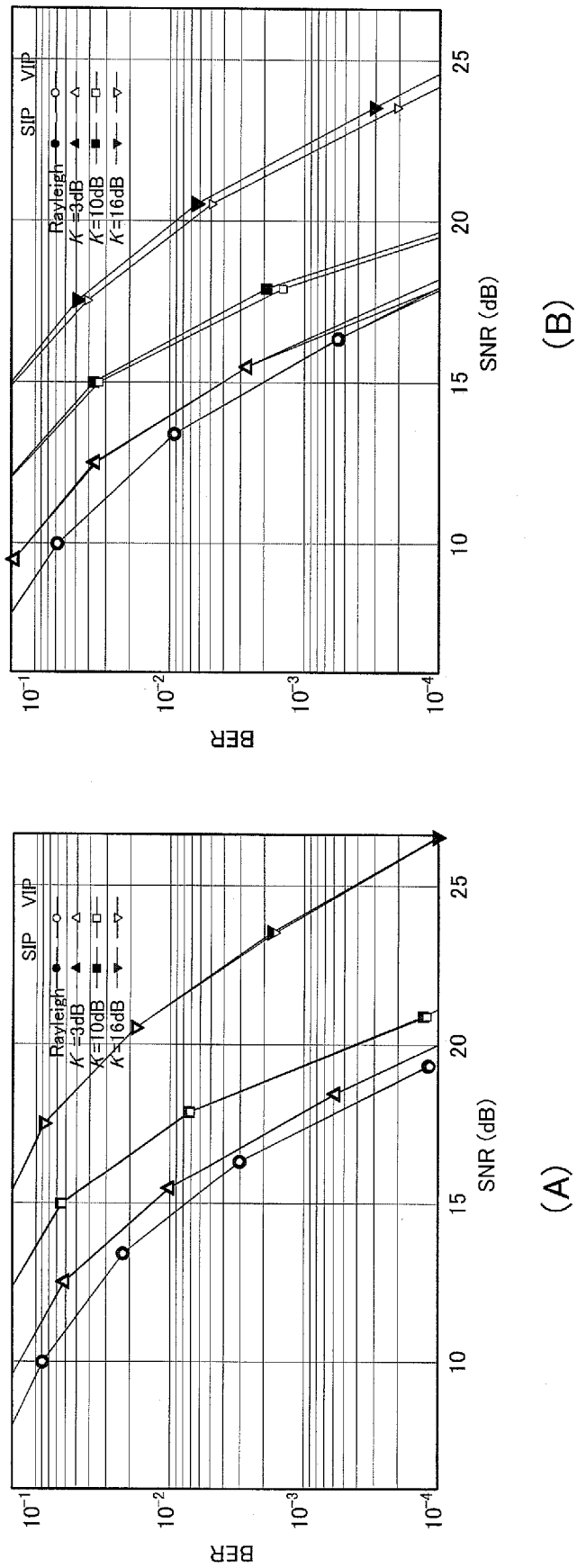




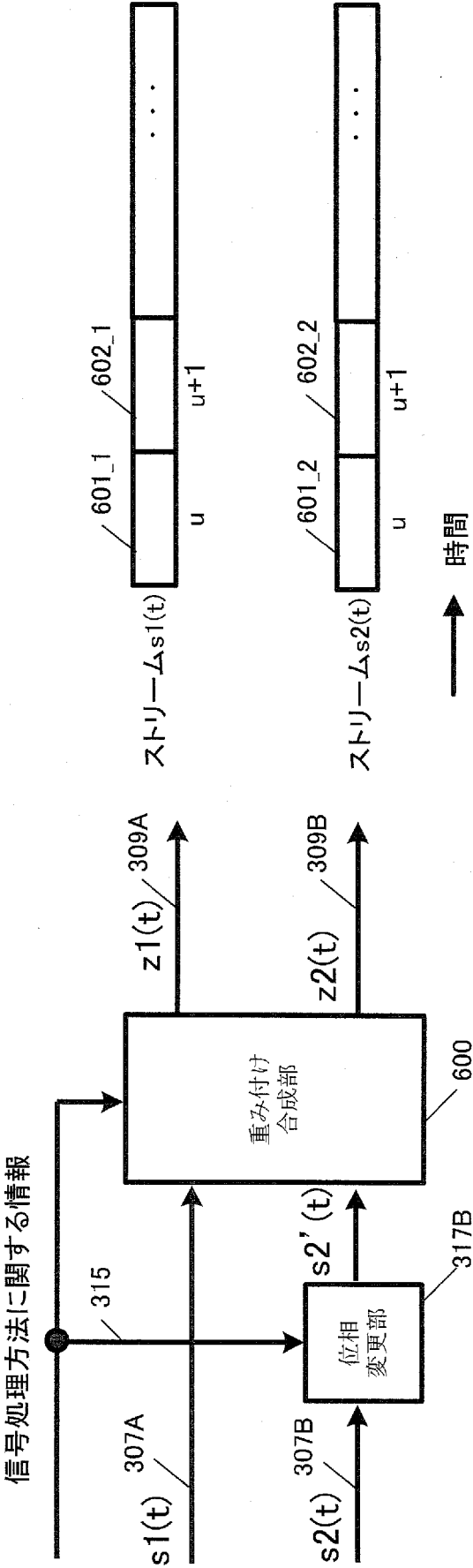
[図23]



[図24]



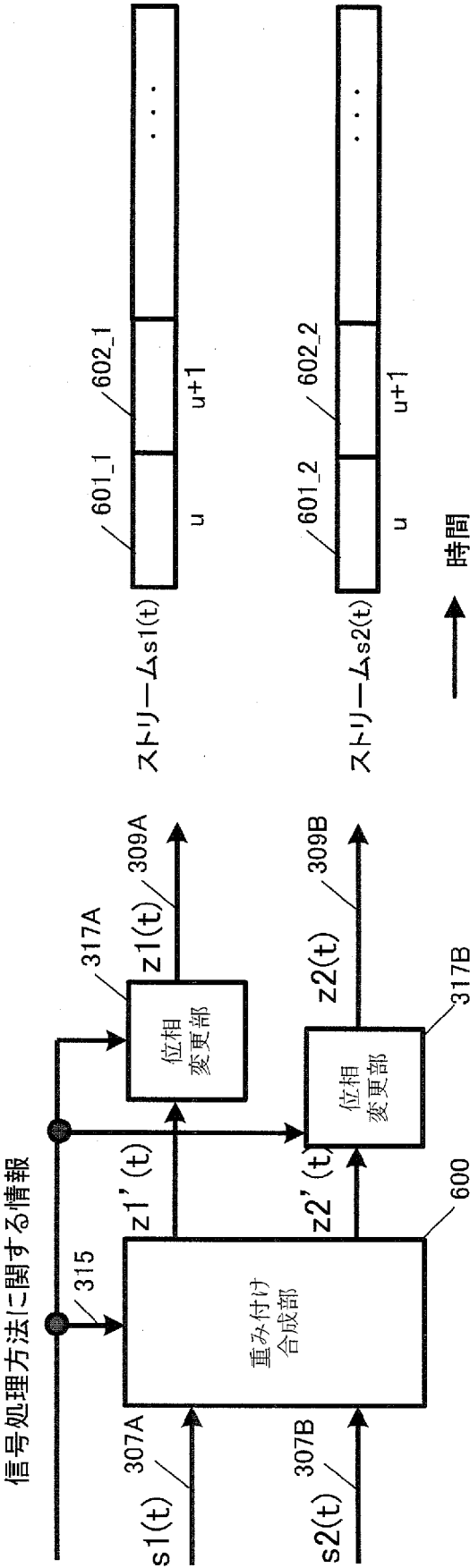
[図25]



位相変更部の位相変更式 $y(t)$ の変更例

時刻 u	時刻 $u+1$	時刻 $u+2$	時刻 $u+3$	時刻 $u+k$
$y(u) = e^{j0}$	$y(u+1) = e^{j\frac{\pi}{2}}$	$y(u+2) = e^{j\pi}$	$y(u+3) = e^{j\frac{3\pi}{2}}$	$y(u+k) = e^{j\frac{k\pi}{2}}$

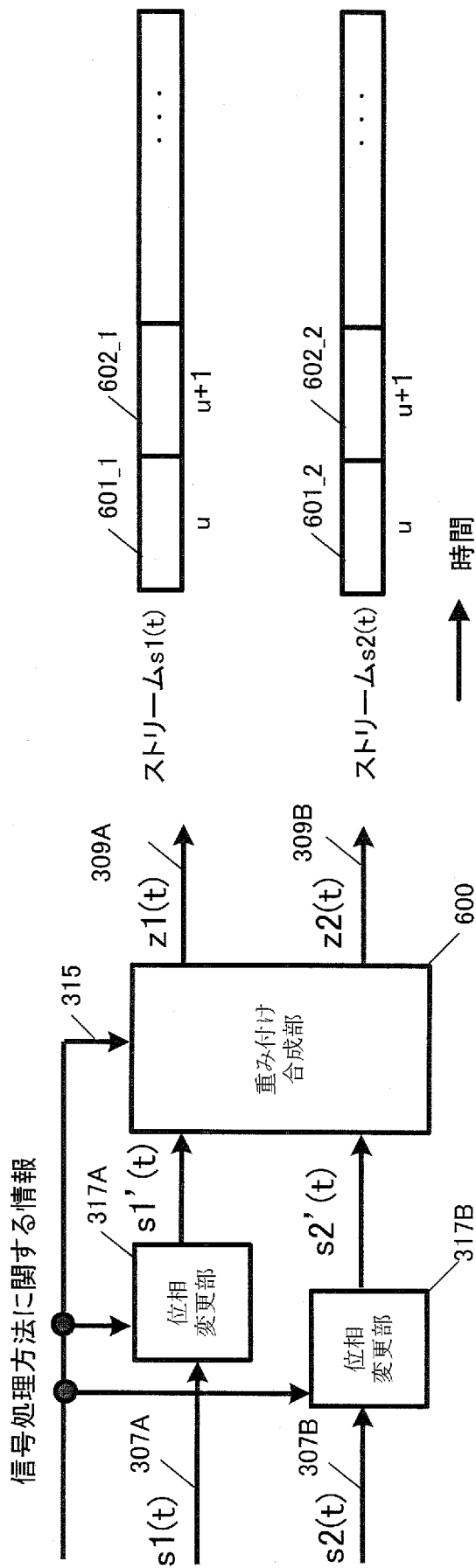
[図26]



位相変更部の位相変更式 $y_1(t)$ 、 $y_2(t)$ の変更例

時刻 u	時刻 $u+1$	時刻 $u+2$	時刻 $u+3$	時刻 $u+k$
$y_1(u) = e^{j0}$	$y_1(u+1) = e^{j\frac{\pi}{4}}$	$y_1(u+2) = e^{j\frac{\pi}{2}}$	$y_1(u+3) = e^{j\frac{3\pi}{4}}$	$y_1(u+k) = e^{j\frac{k\pi}{4}}$
$y_2(u) = e^{-j\frac{\pi}{2}}$	$y_2(u+1) = e^{-j\frac{3\pi}{4}}$	$y_2(u+2) = e^{-j\pi}$	$y_2(u+3) = e^{-j\frac{5\pi}{4}}$	$y_2(u+k) = e^{j\left(-\frac{k\pi}{4} - \frac{\pi}{2}\right)}$

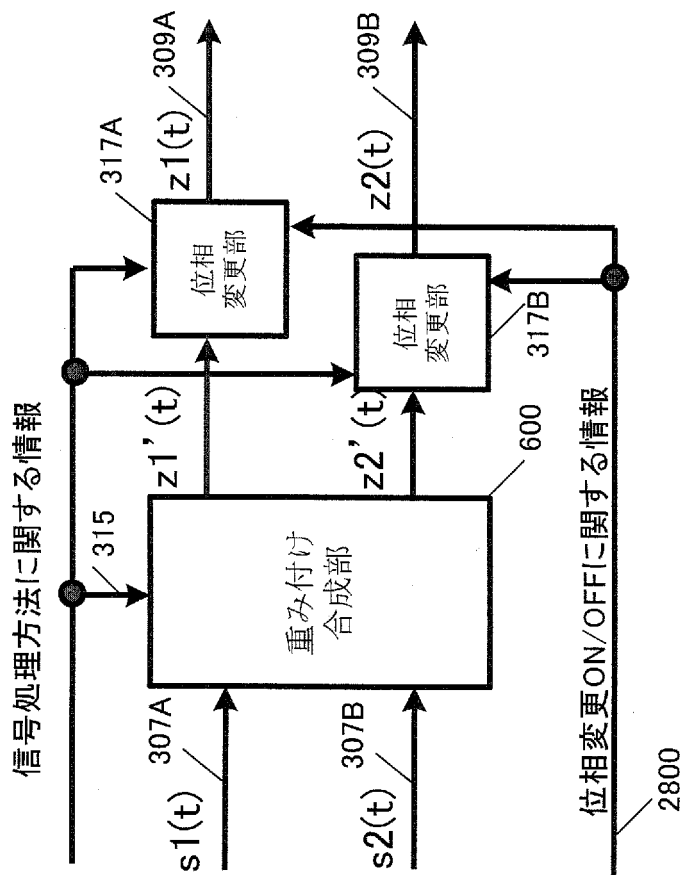
[図27]



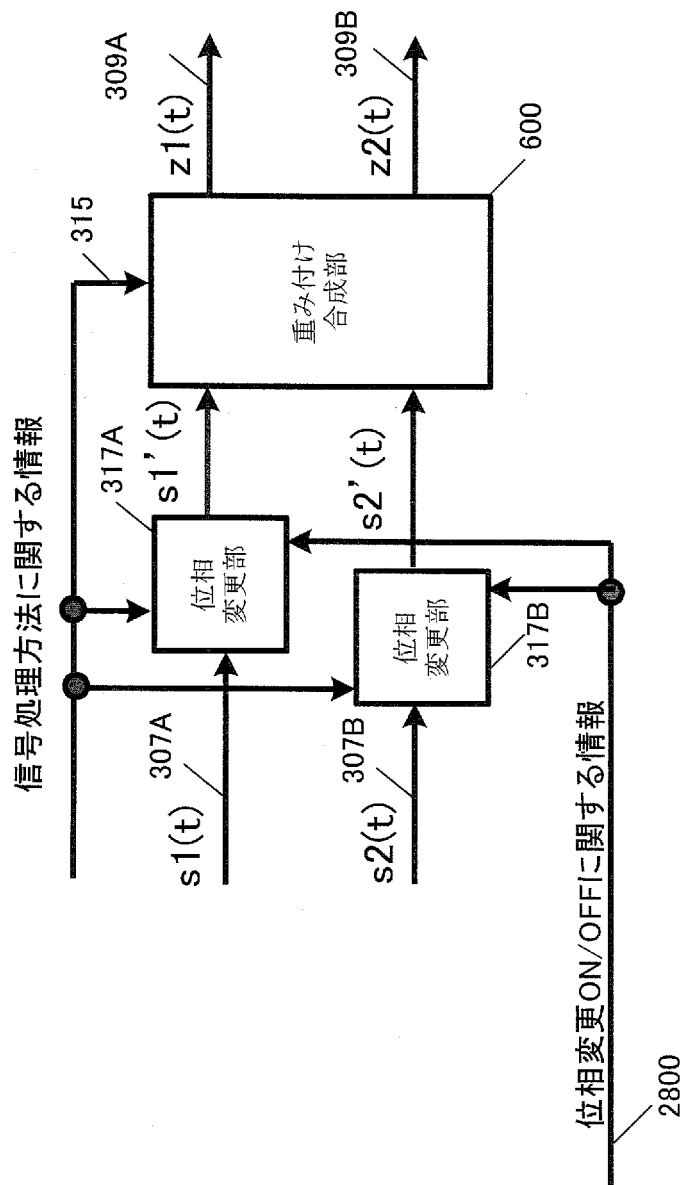
位相変更部の位相変更式 $y_1(t)$ 、 $y_2(t)$ の変更例

時刻 u	時刻 $u+1$	時刻 $u+2$	時刻 $u+3$	時刻 $u+k$
$y_1(u) = e^{j0}$	$y_1(u+1) = e^{j\frac{\pi}{4}}$	$y_1(u+2) = e^{j\frac{\pi}{2}}$	$y_1(u+3) = e^{j\frac{3\pi}{4}}$	$y_1(u+k) = e^{j\frac{k\pi}{4}}$
$y_2(u) = e^{-j\frac{\pi}{2}}$	$y_2(u+1) = e^{-j\frac{3\pi}{4}}$	$y_2(u+2) = e^{-j\pi}$	$y_2(u+3) = e^{-j\frac{5\pi}{4}}$	$y_2(u+k) = e^{j\left(-\frac{k\pi}{4} + \frac{\pi}{2}\right)}$

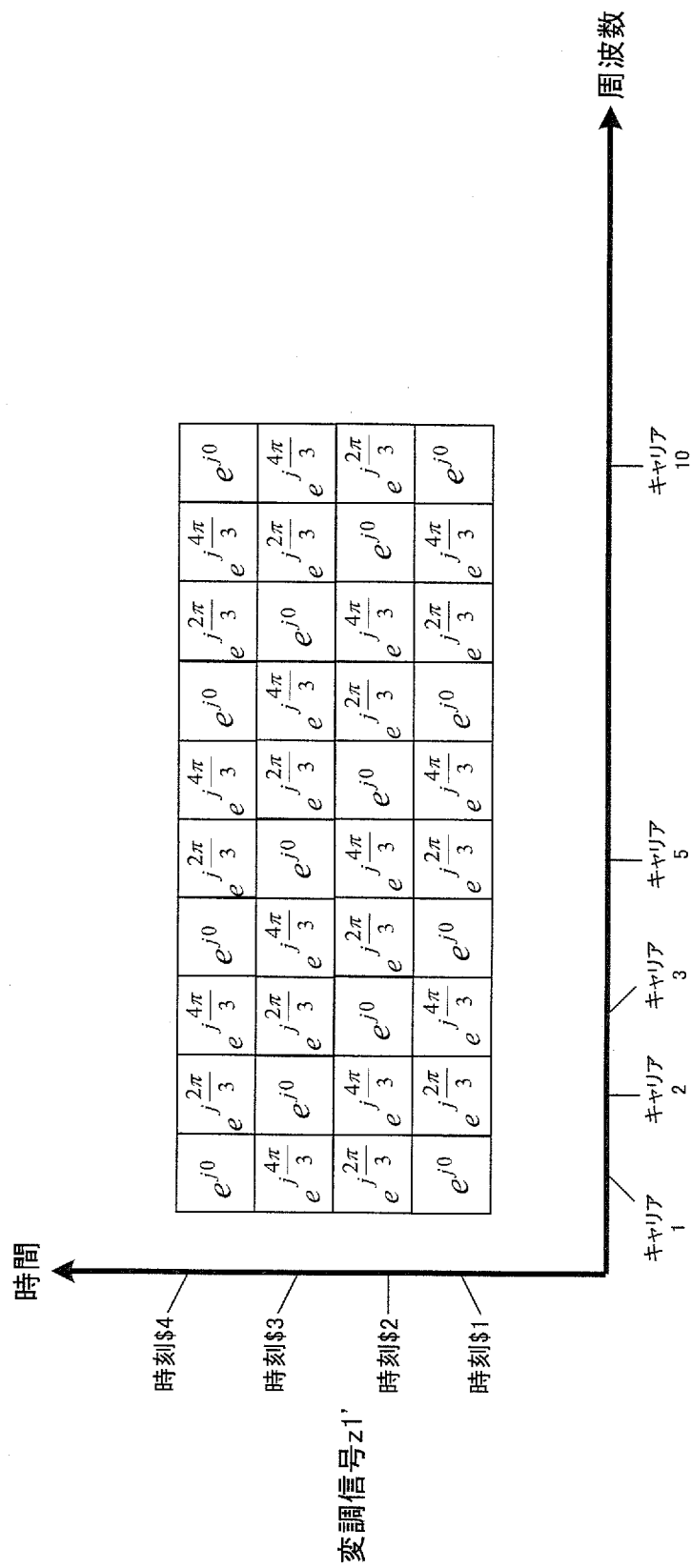
[図28]



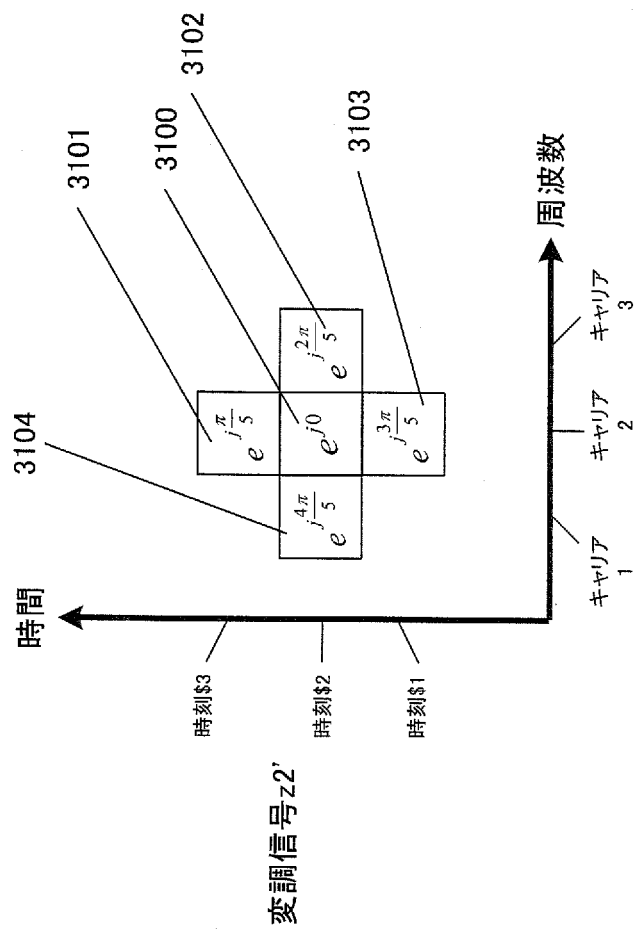
[図29]



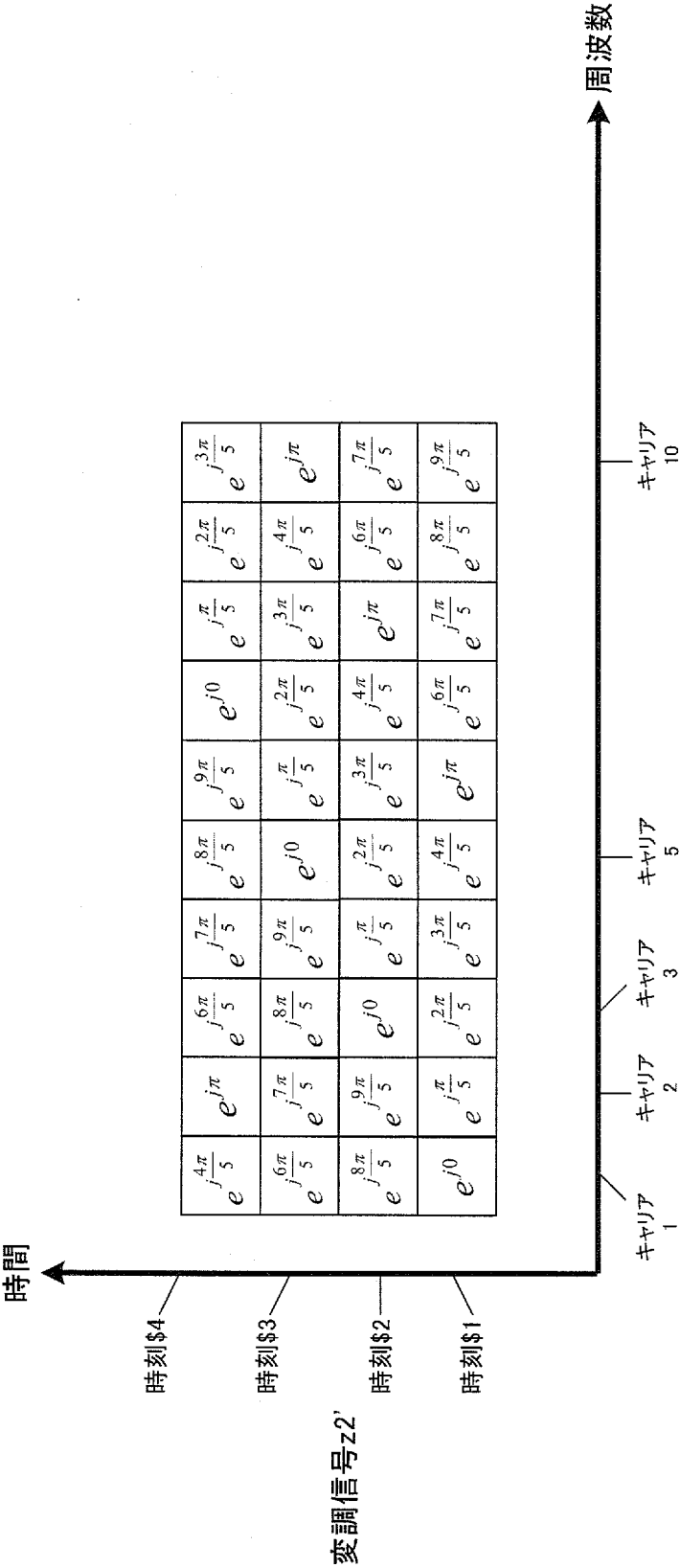
[図30]



[図31]



[図32]

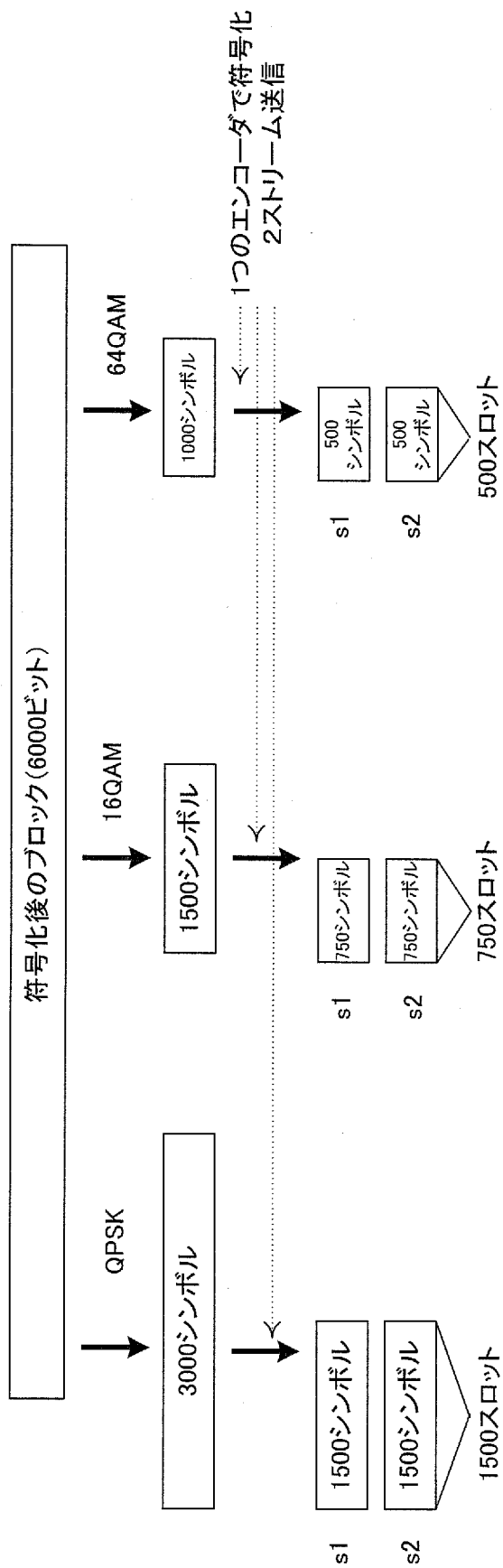


変調信号 z_1

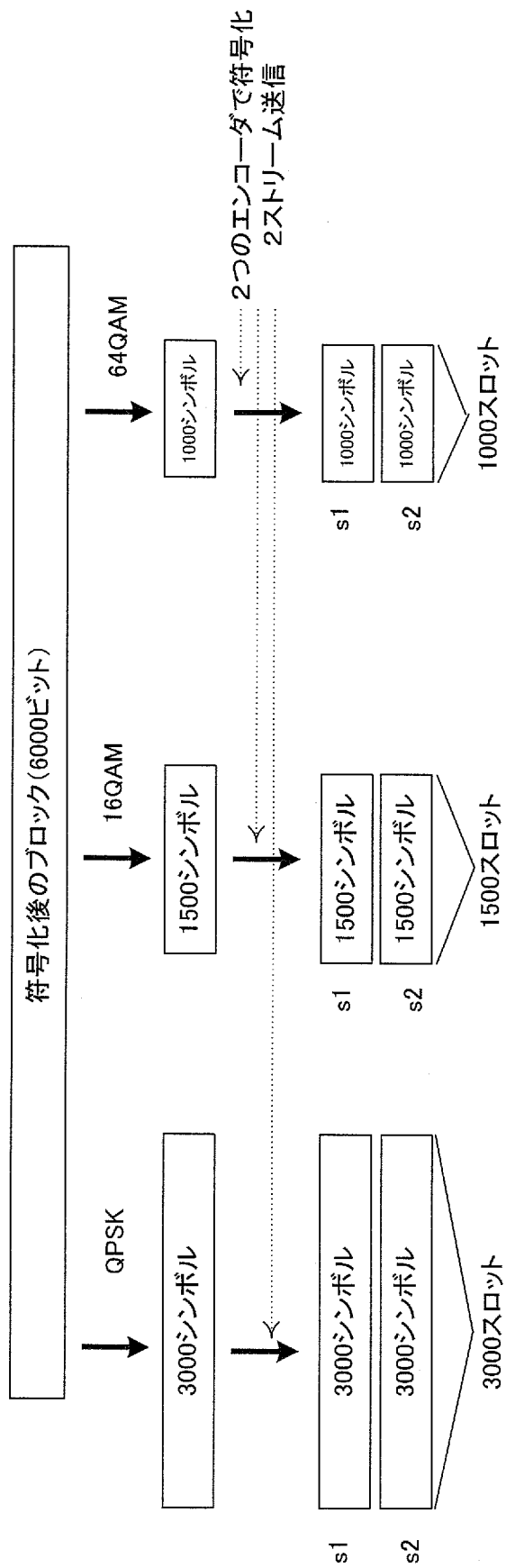
時刻\$4	時刻\$3	時刻\$2	時刻\$1
$e^{j\frac{\pi}{3}}$	$e^{j\frac{\pi}{3}}$	$e^{j\frac{\pi}{9}}$	e^{j0}
$e^{j\frac{2\pi}{9}}$	$e^{j\frac{2\pi}{9}}$	$e^{j\frac{\pi}{9}}$	e^{j0}
$e^{j\frac{\pi}{3}}$	$e^{j\frac{\pi}{3}}$	$e^{j\frac{\pi}{9}}$	e^{j0}
$e^{j\frac{2\pi}{9}}$	$e^{j\frac{2\pi}{9}}$	$e^{j\frac{\pi}{9}}$	e^{j0}

周波数

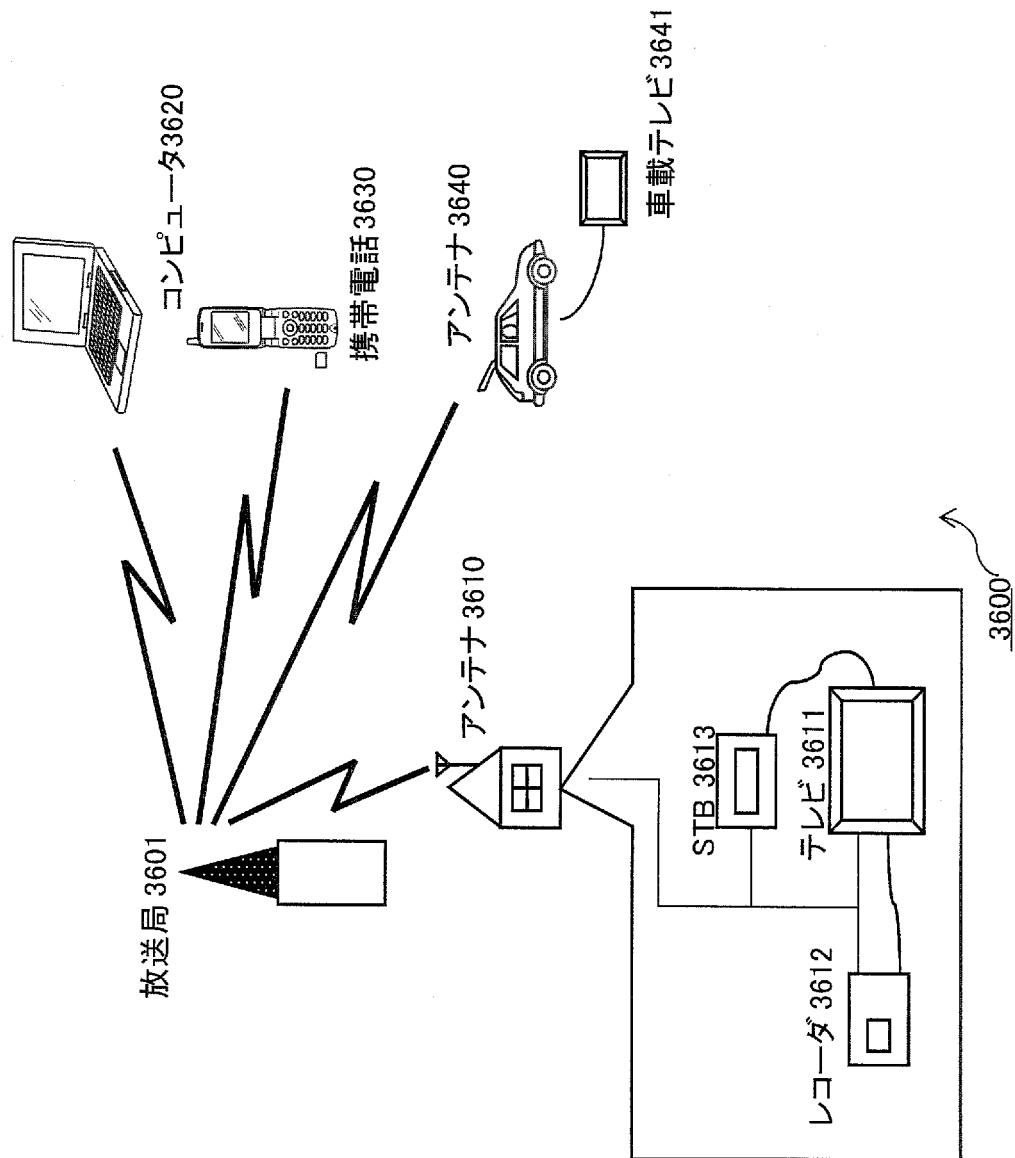
[図34]



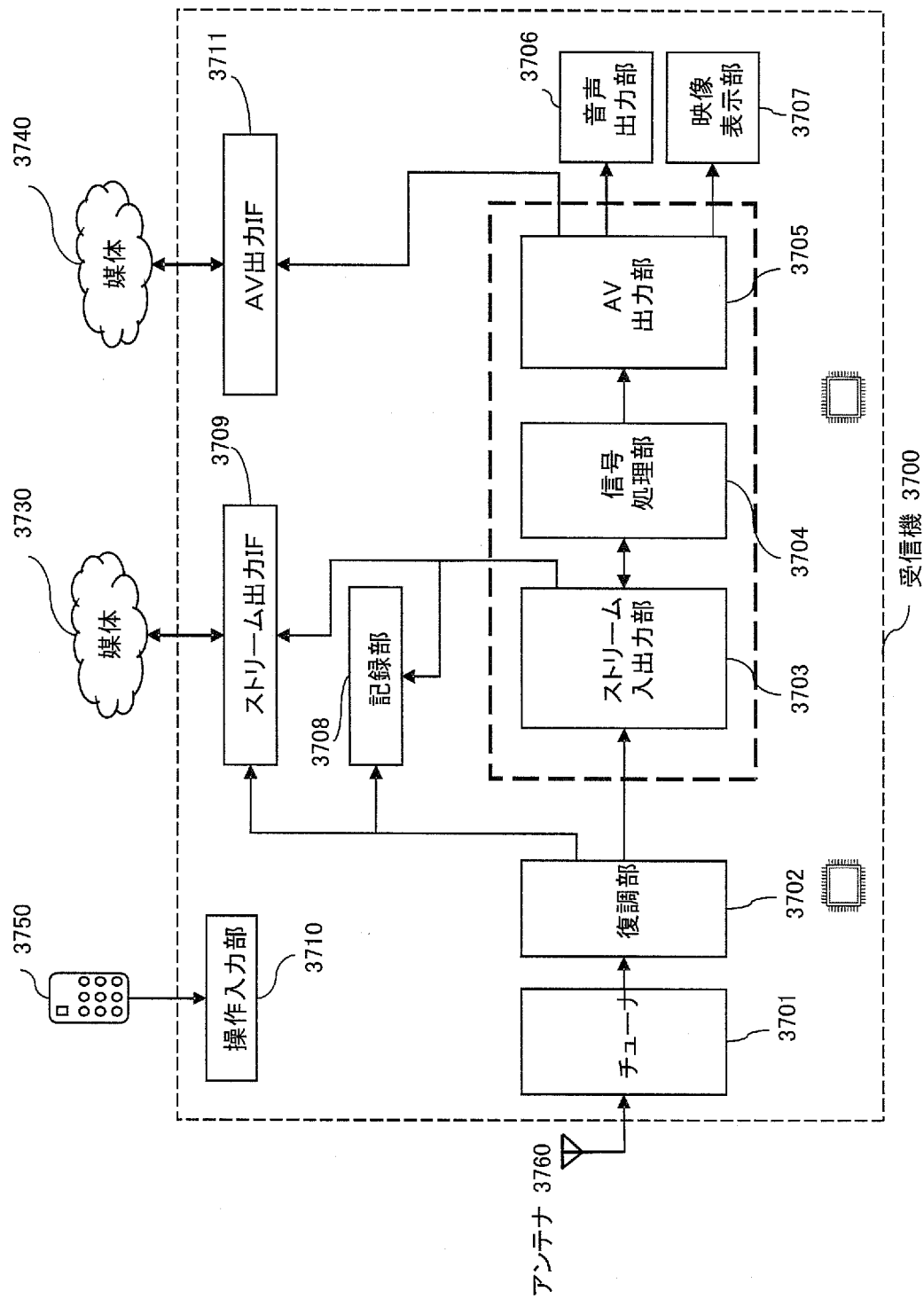
[図35]



[図36]



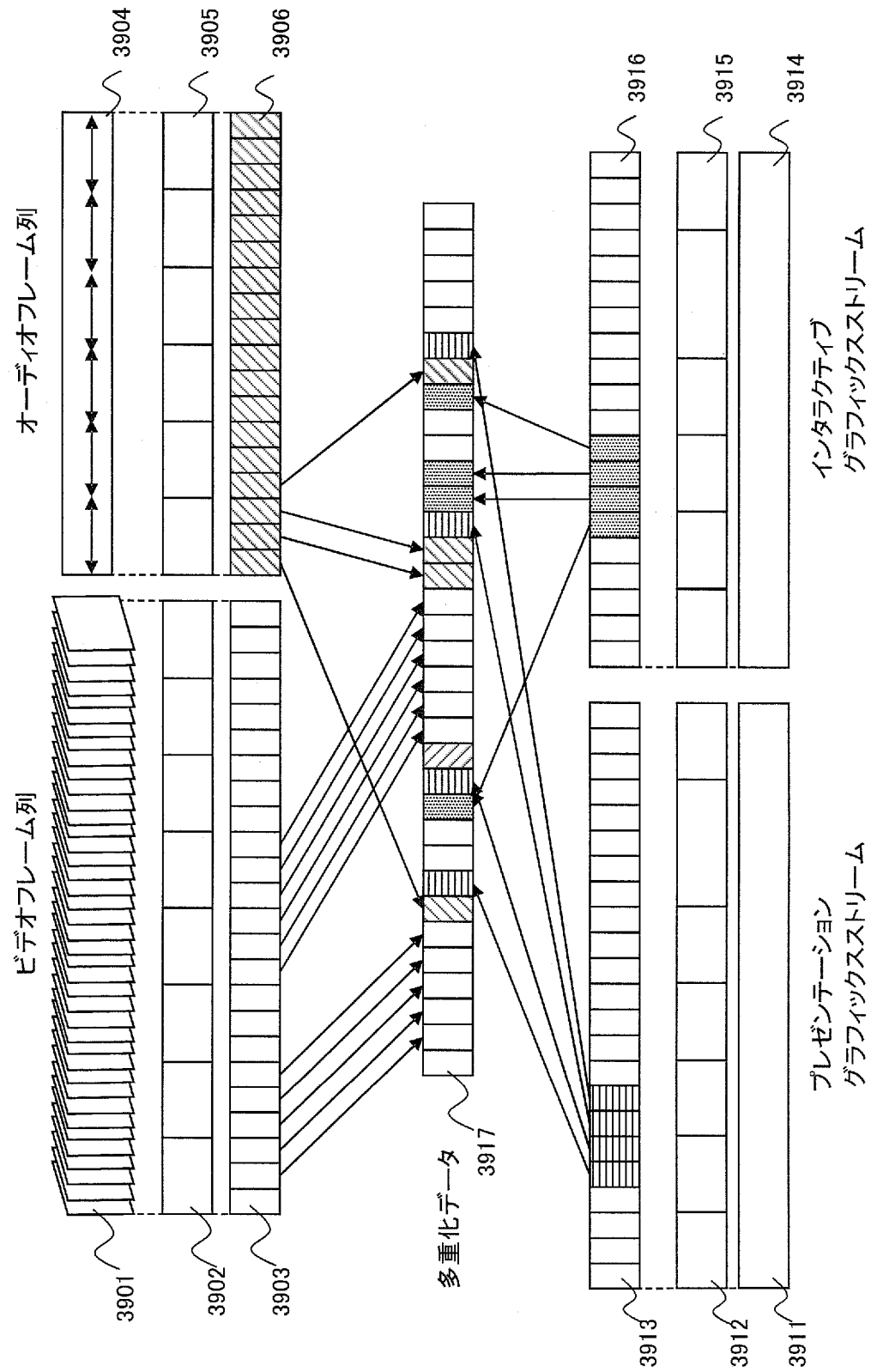
[図37]



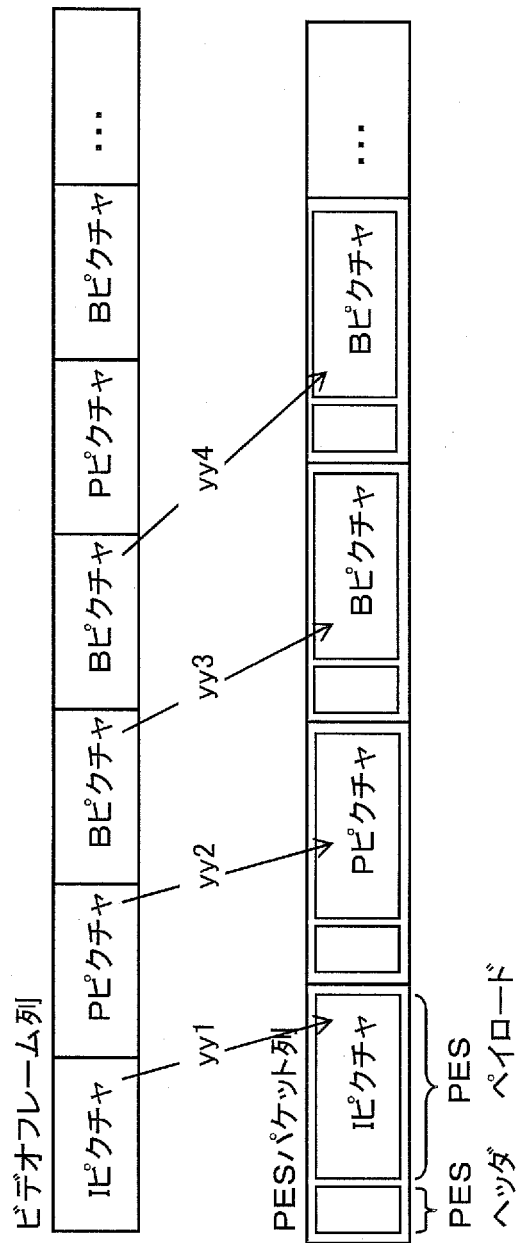
[図38]

ビデオストリーム (PID=0x1011 主映像)
オーディオストリーム (PID=0x1100)
オーディオストリーム (PID=0x1101)
プレゼンテーショングラフィックスストリーム (PID=0x1200)
プレゼンテーショングラフィックスストリーム (PID=0x1201)
インタラクティブグラフィックスストリーム (PID=0x1400)
ビデオストリーム (PID=0x1B00 副映像)
ビデオストリーム (PID=0x1B01 副映像)

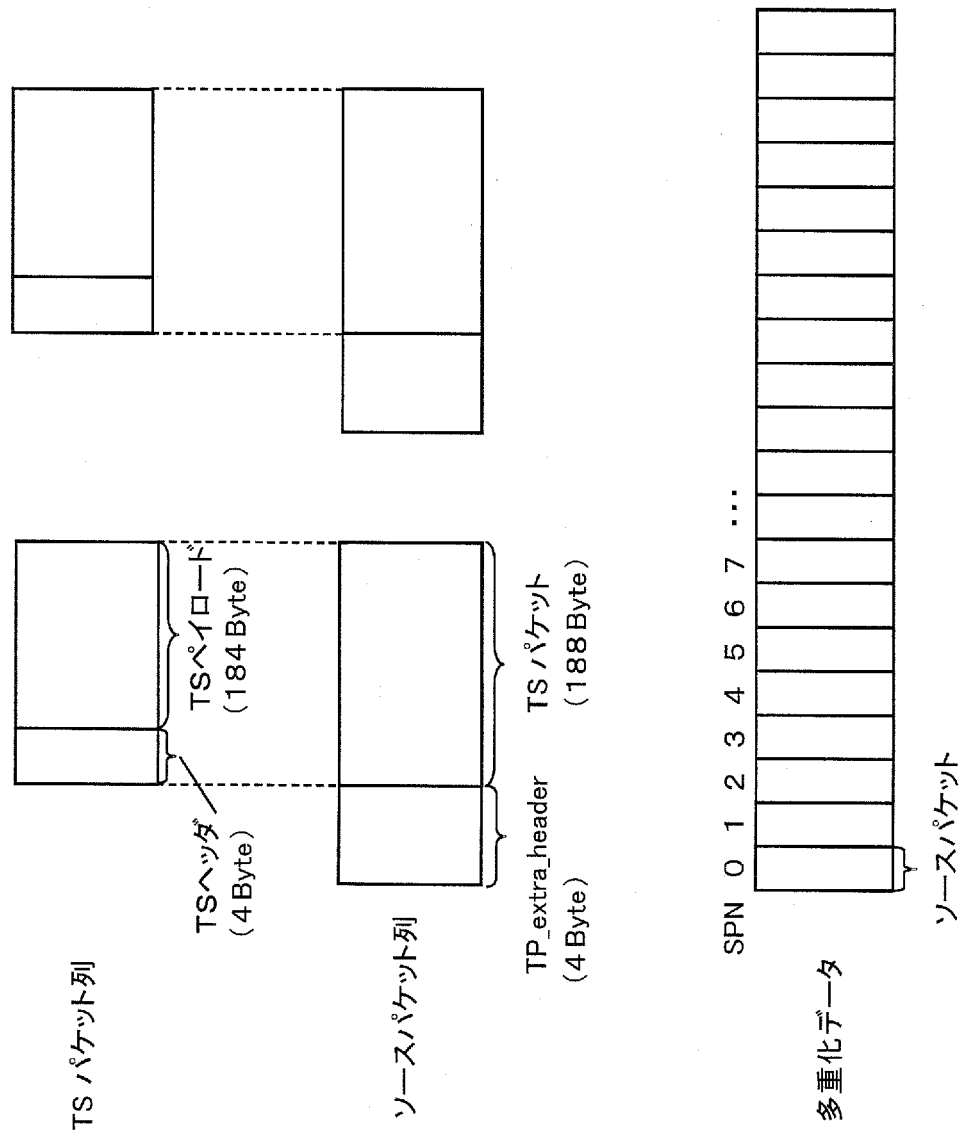
[図39]



[図40]

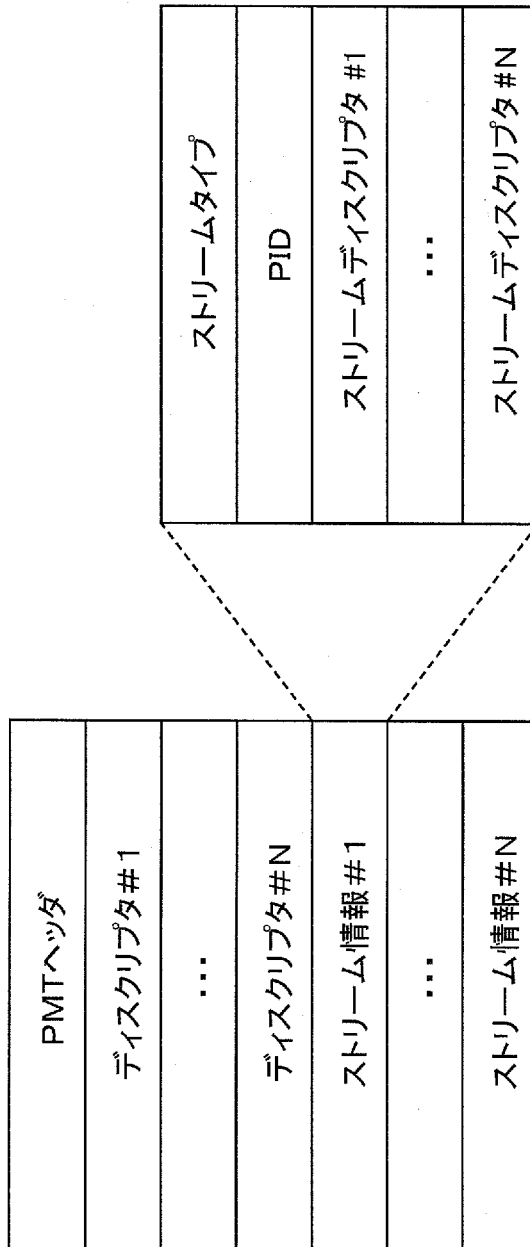


[図41]

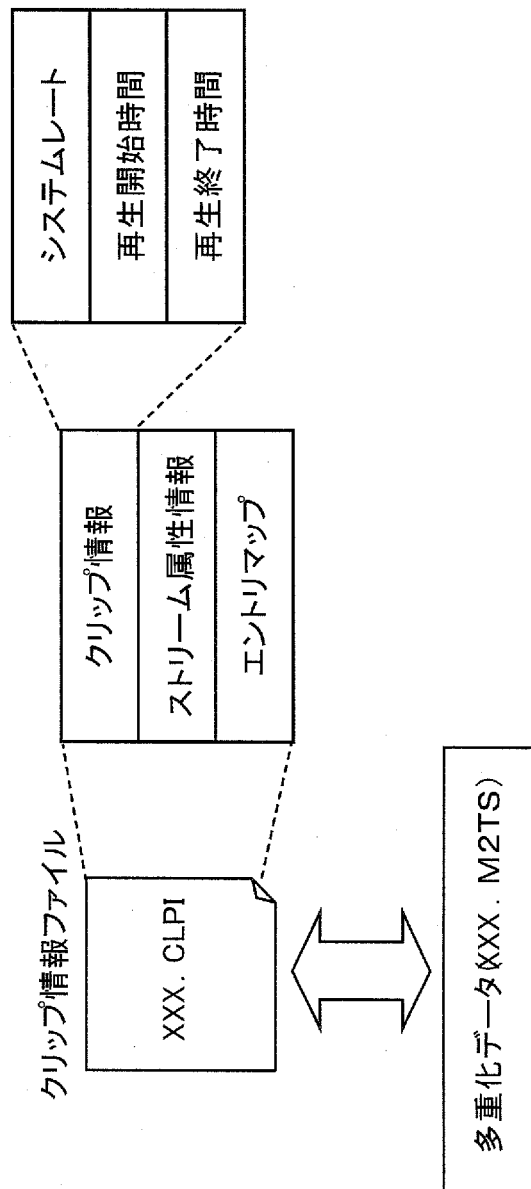


[図42]

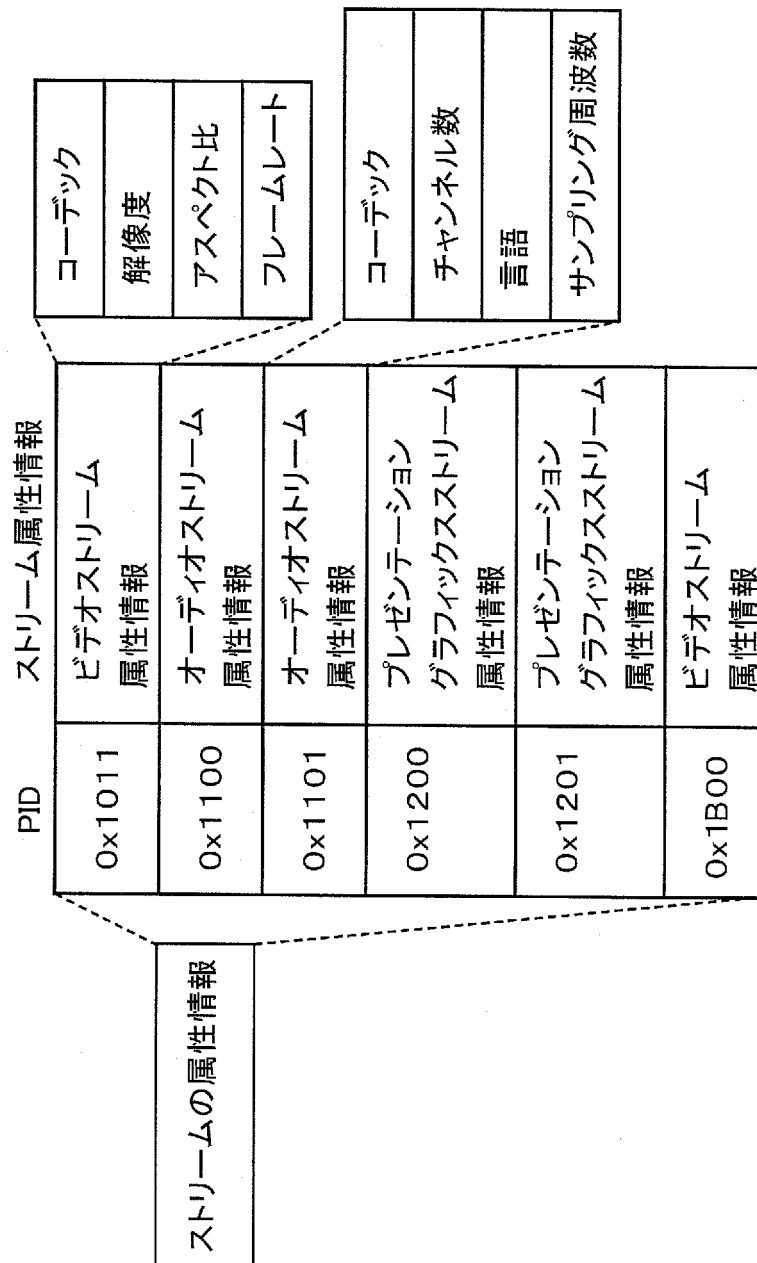
PMTのデータ構造



[図43]



[図44]



4500

4501

4502 映像

4503 World Wide Web
(WWW: ワールド ワイド ウェブ)
(ハイパーテキストシステム)

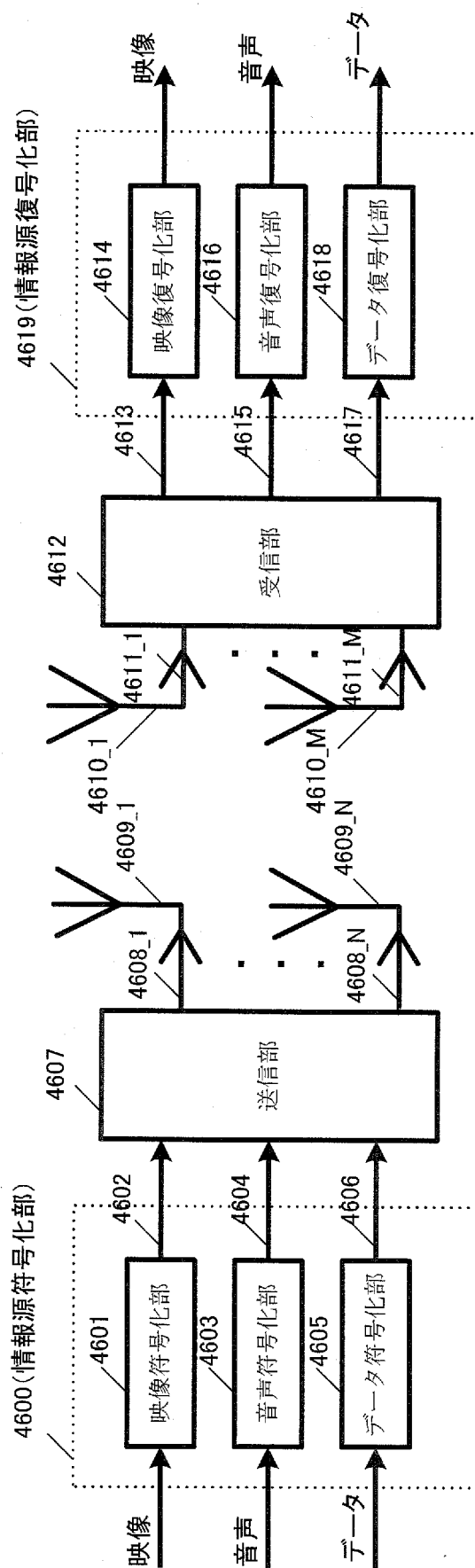
4504 受信装置

4505 IF

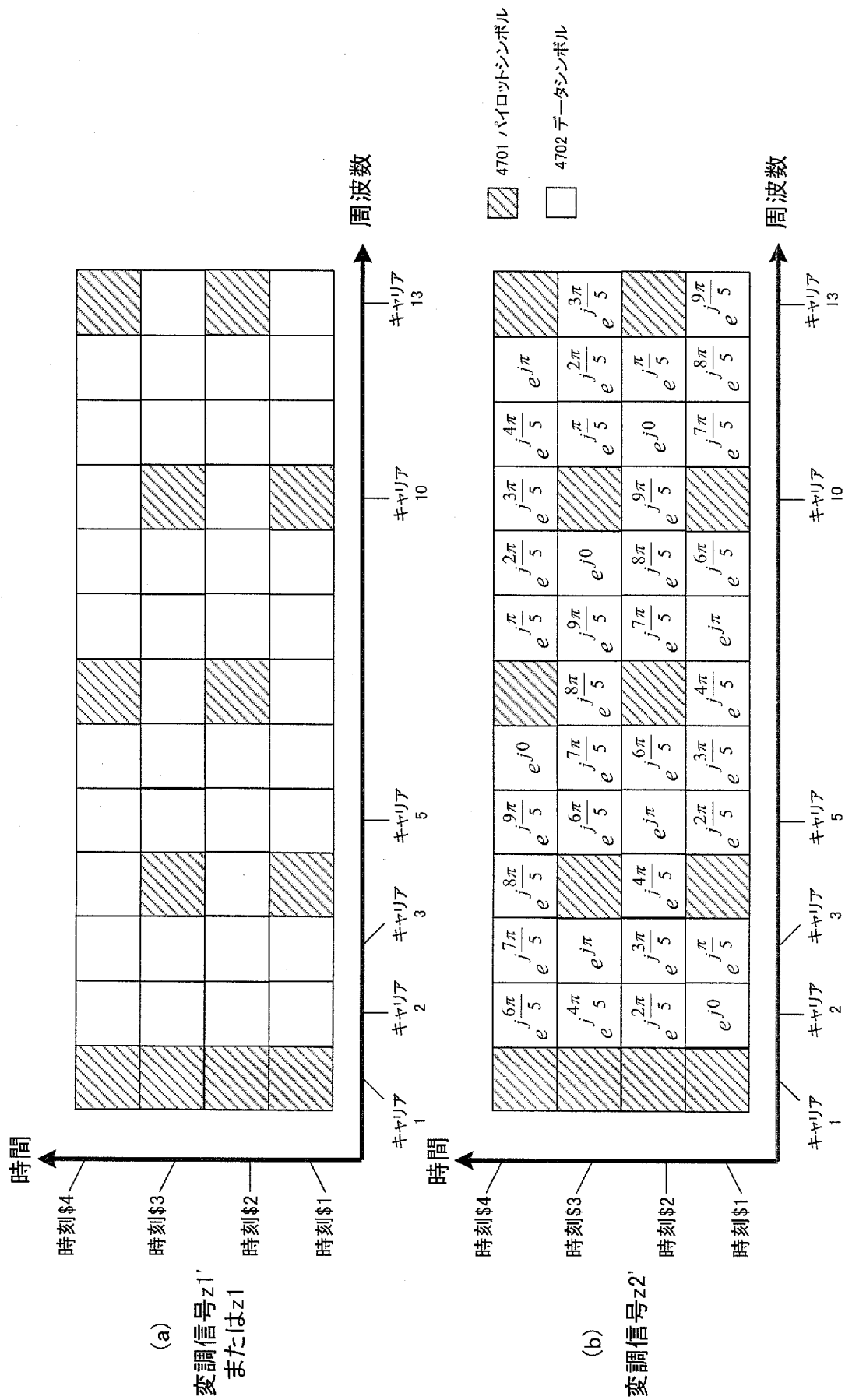
4506 送信装置

4507

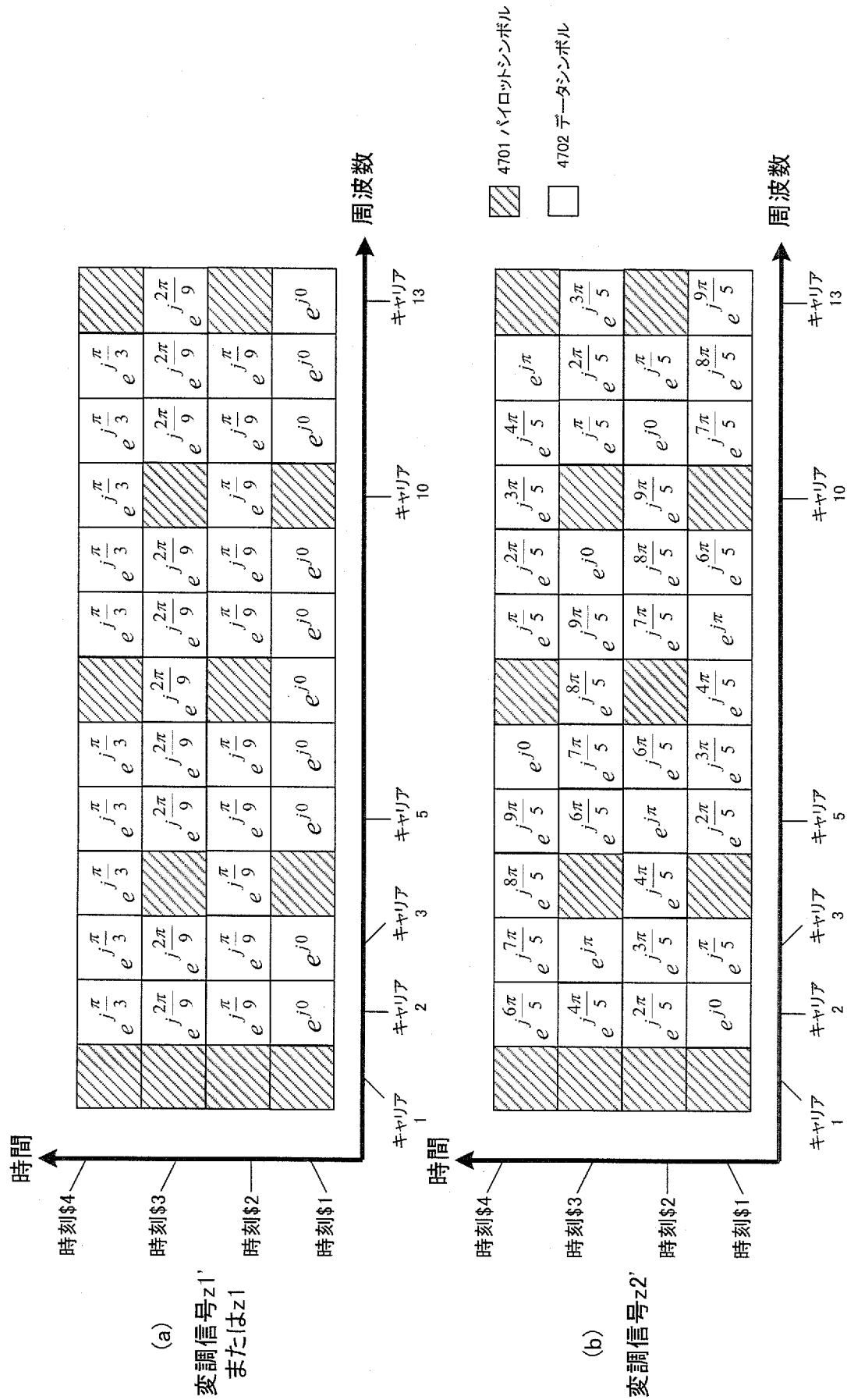
[図46]



[図47]



[図48]



(a) 変調信号 z_1 または z_1

(b) 変調信号 z_2

時刻\$4
時刻\$3
時刻\$2
時刻\$1

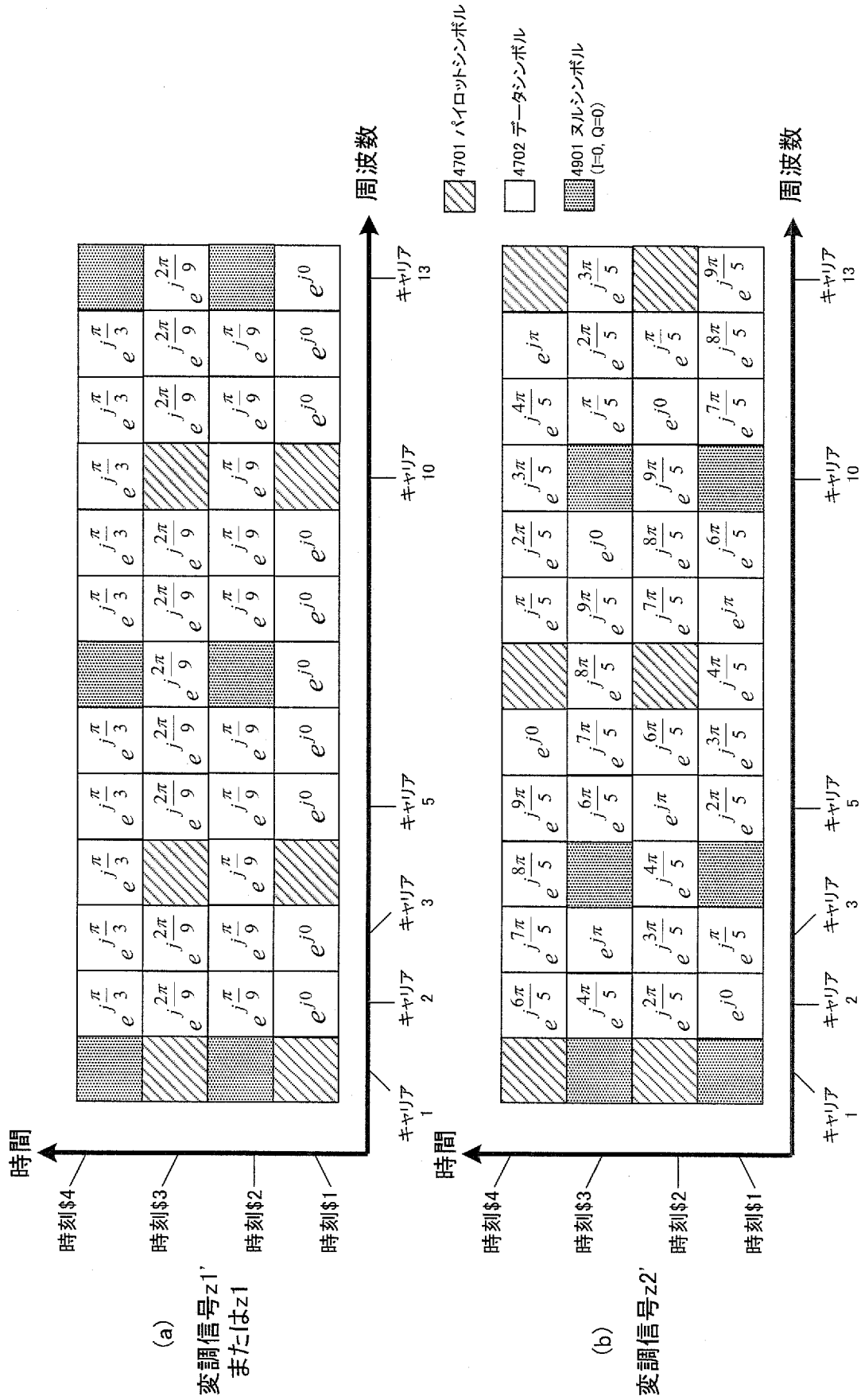
時間

キャリア 1 キャリア 2 キャリア 3 キャリア 5 キャリア 10 キャリア 13

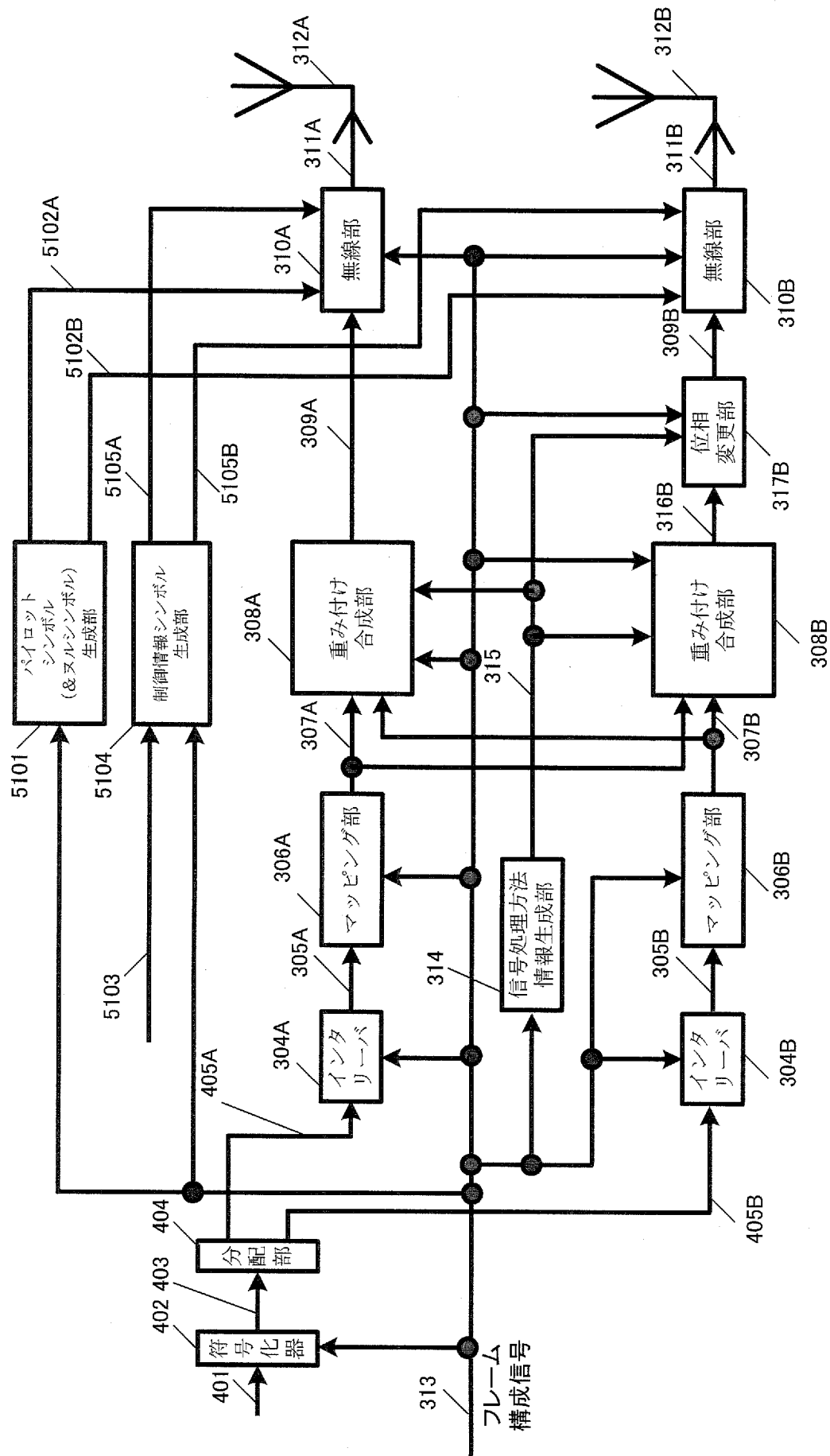
周波数

4701 パイロットシンボル
4702 データシンボル
4901 ヌルシンボル (I=0, Q=0)

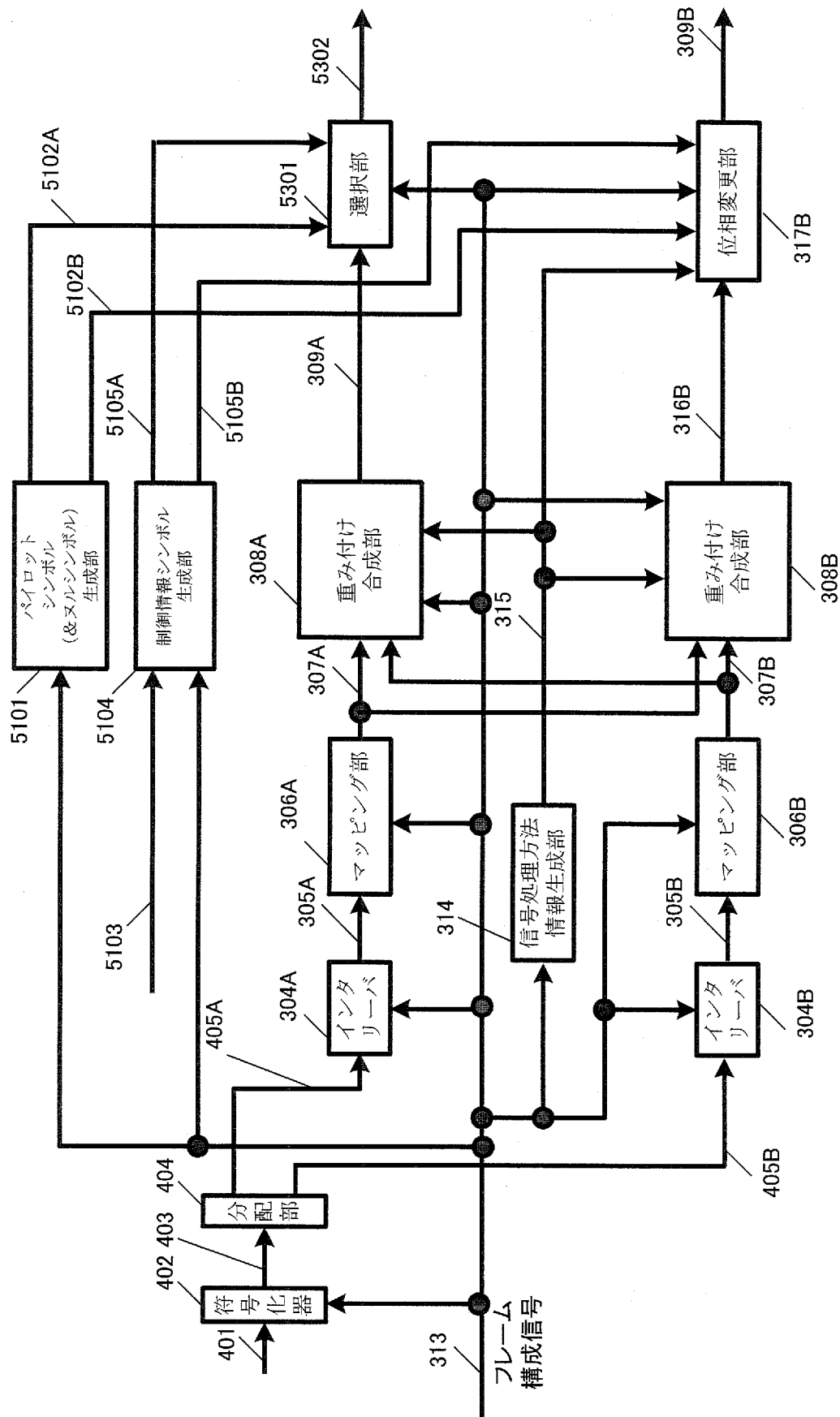
[図50]



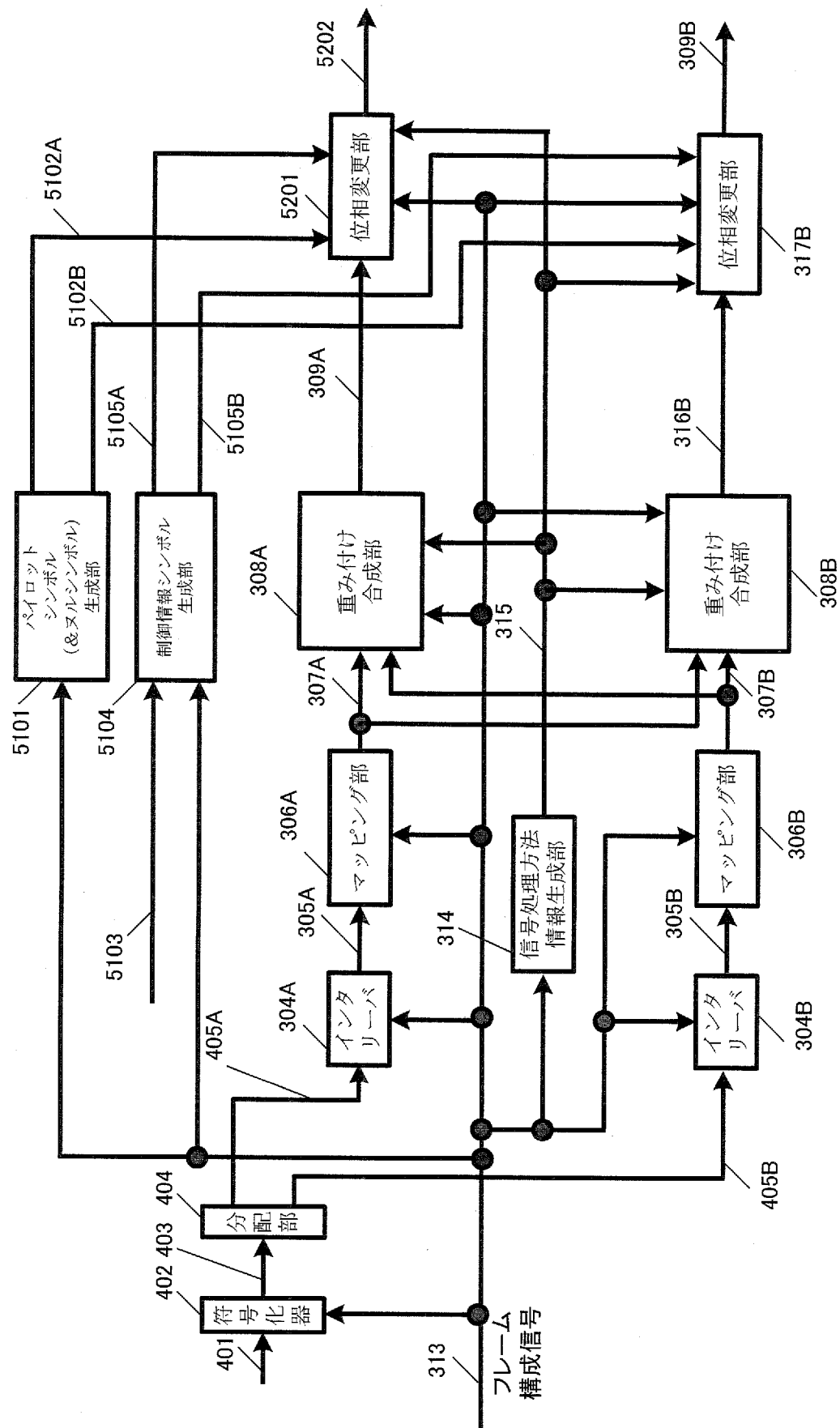
[図51]



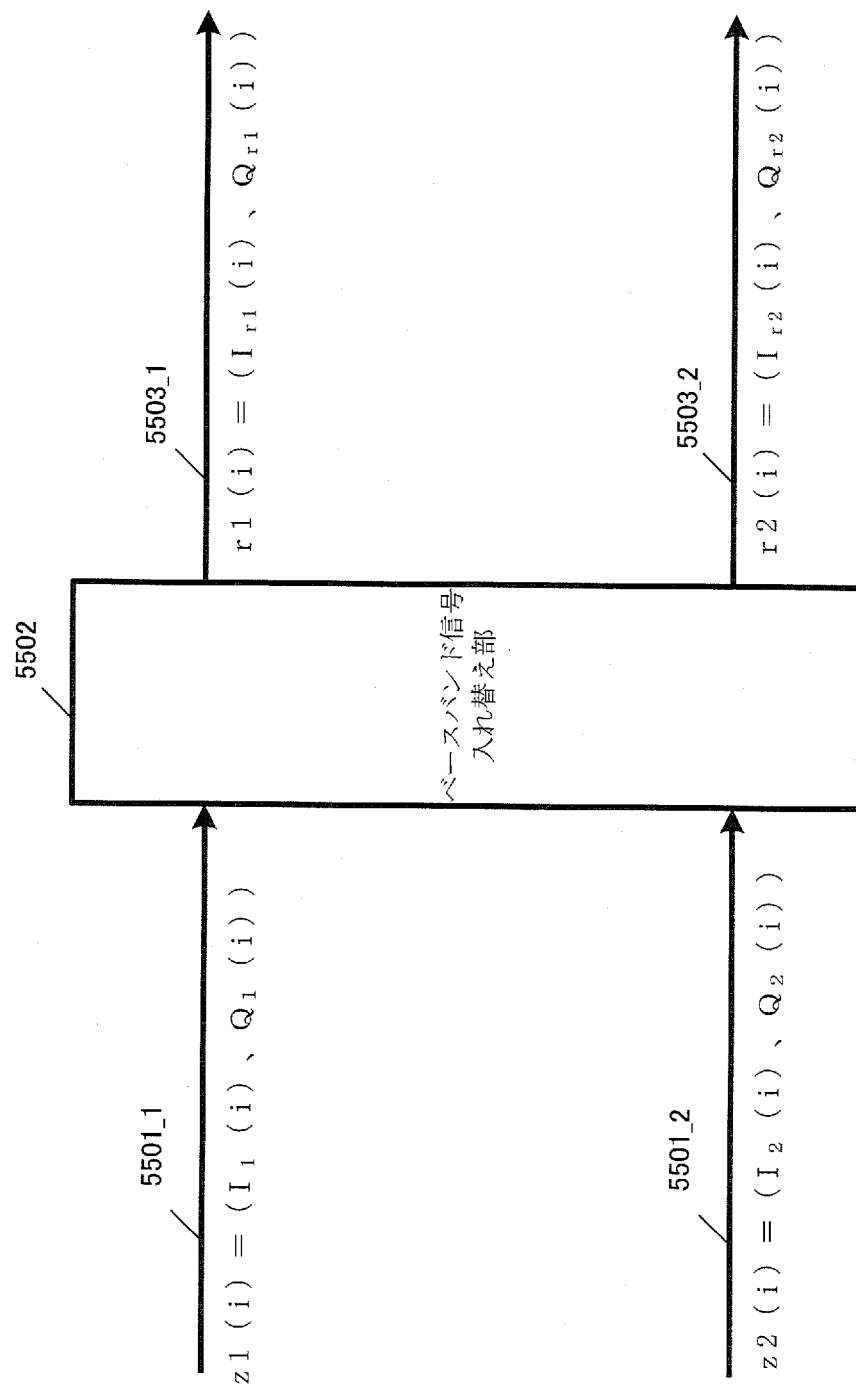
[図53]



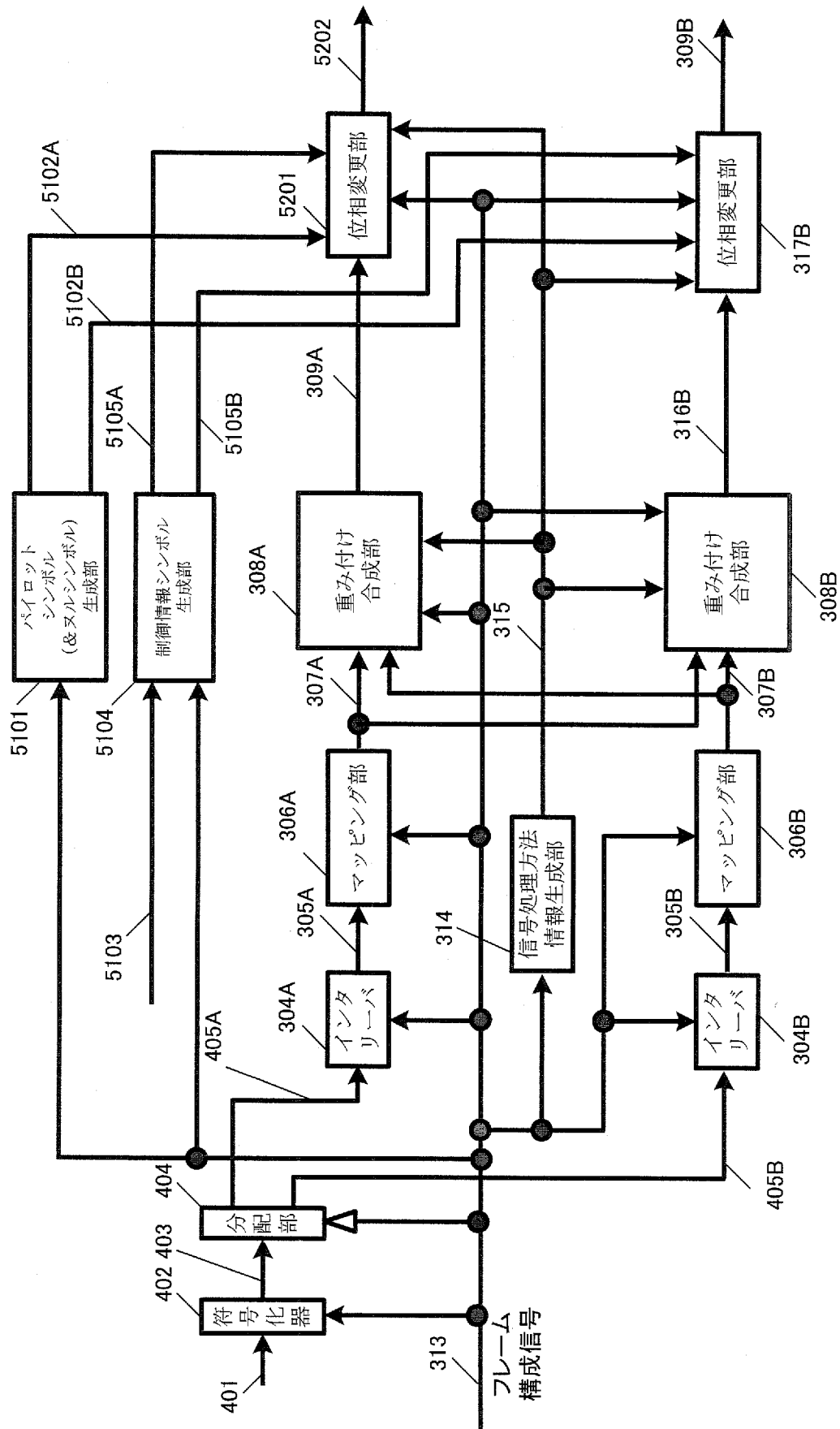
[図54]



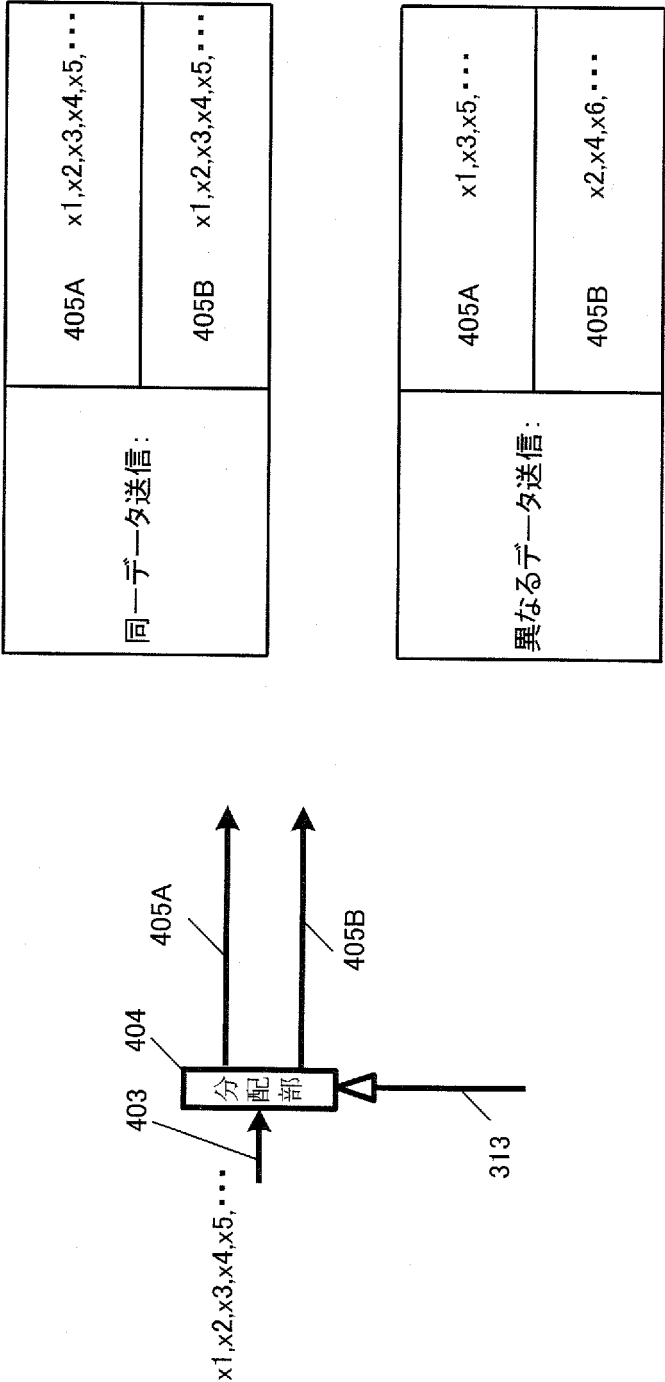
[図55]



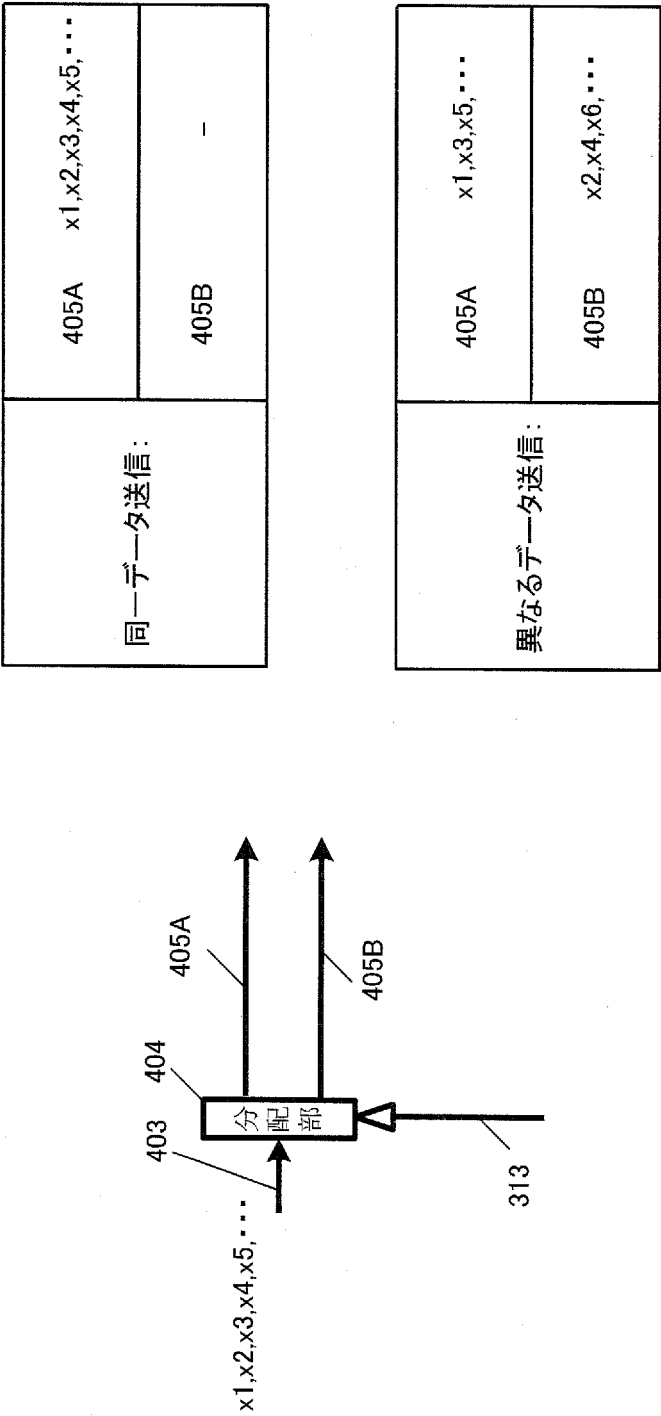
[図56]



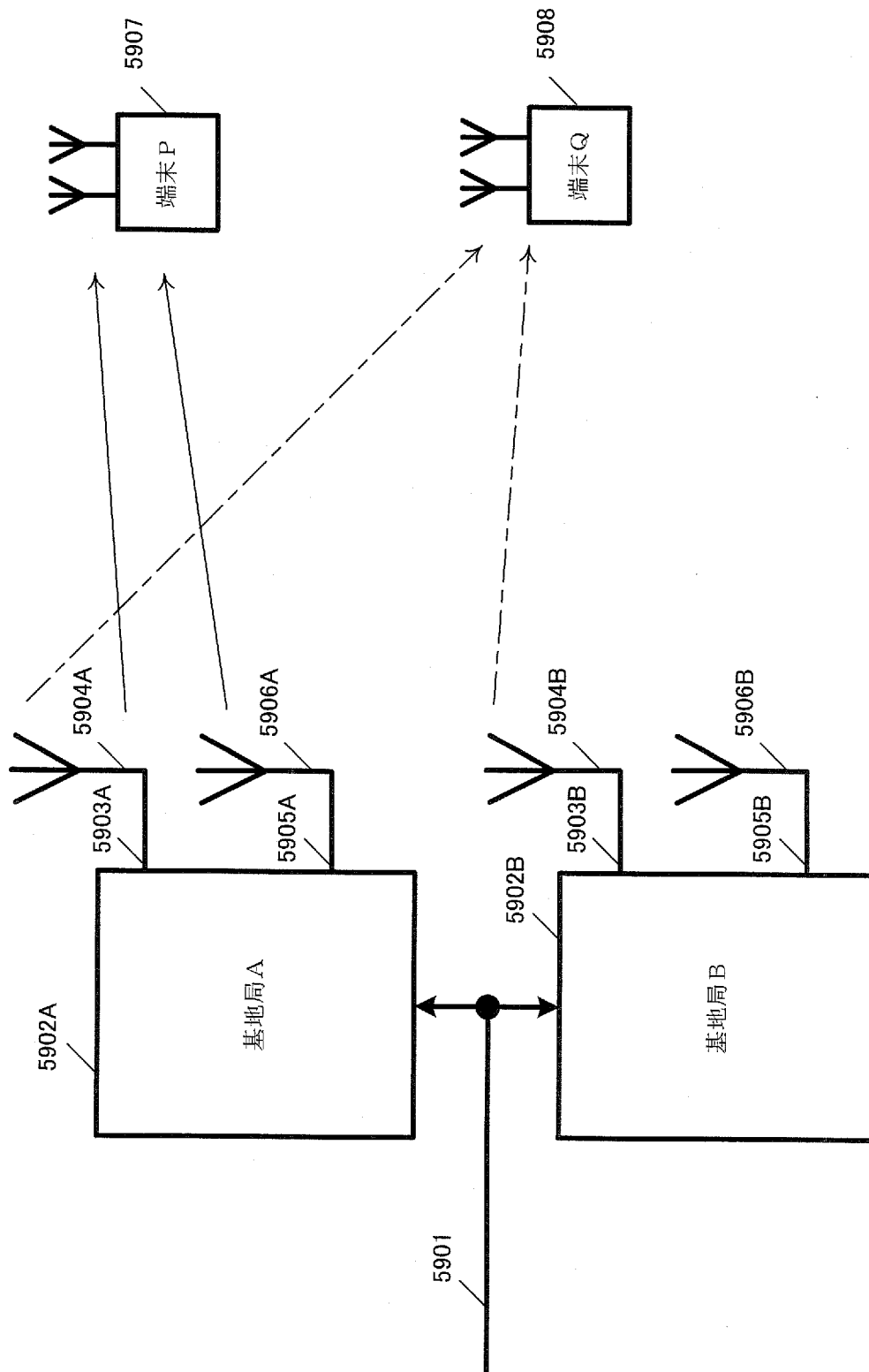
[図57]



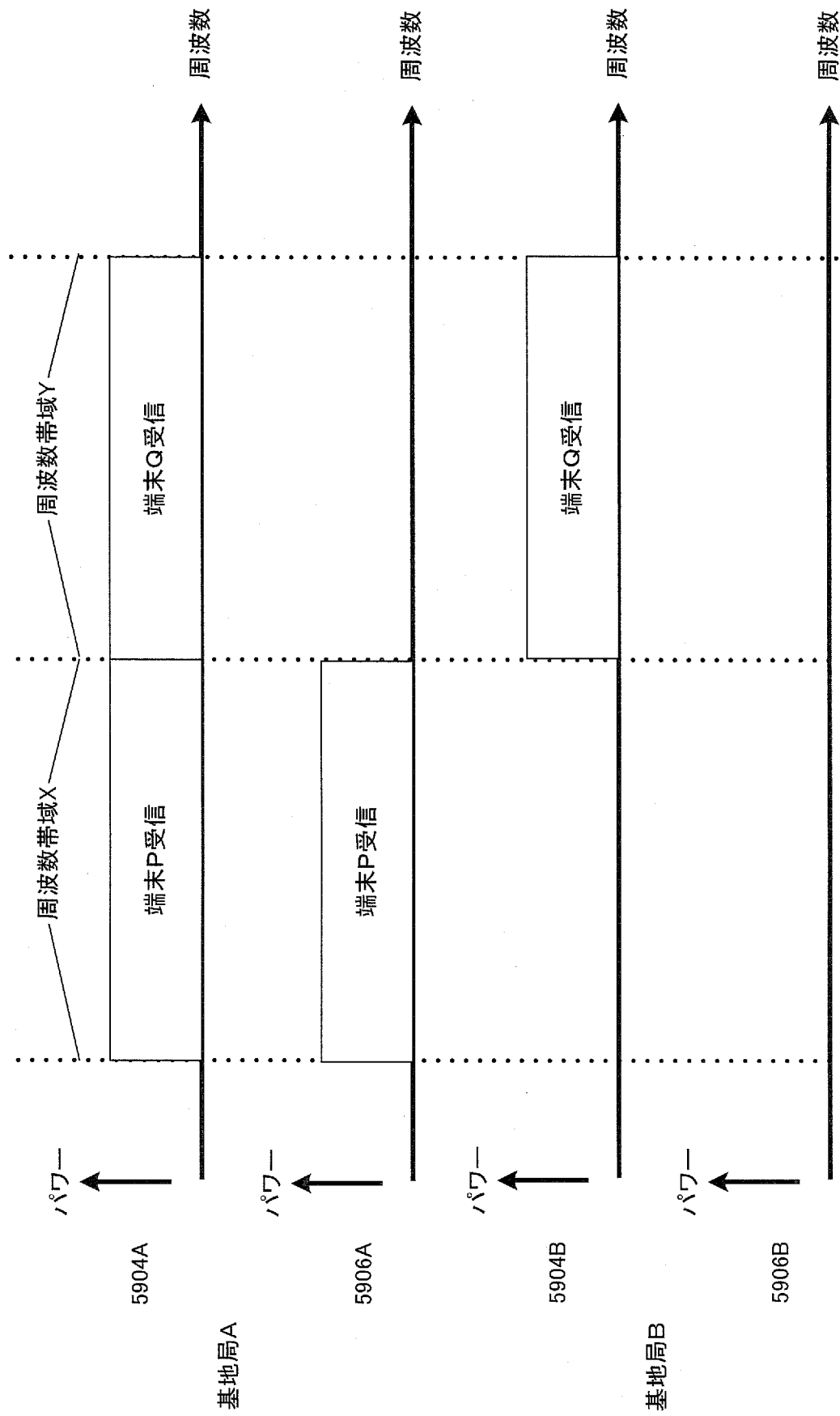
[図58]



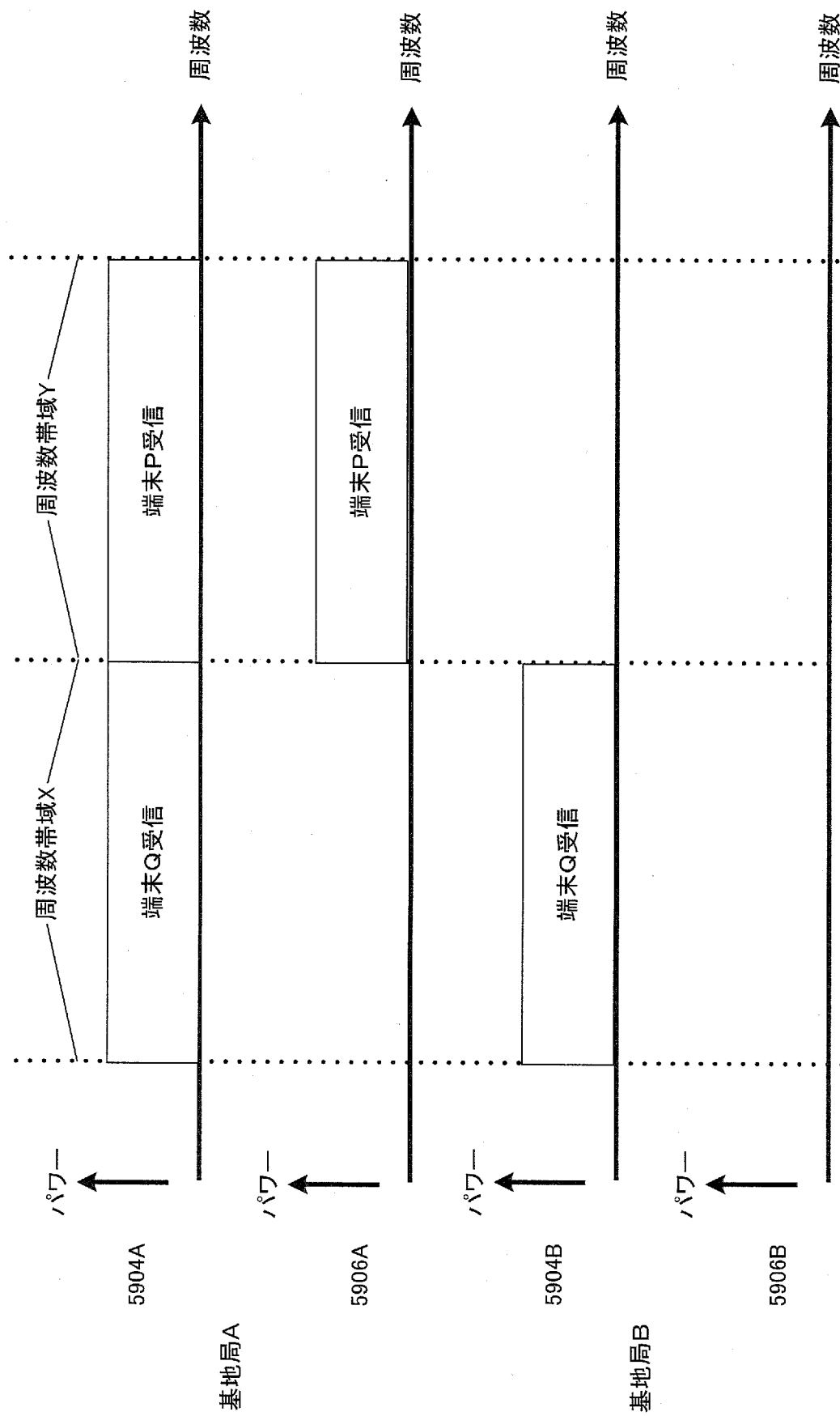
[図59]



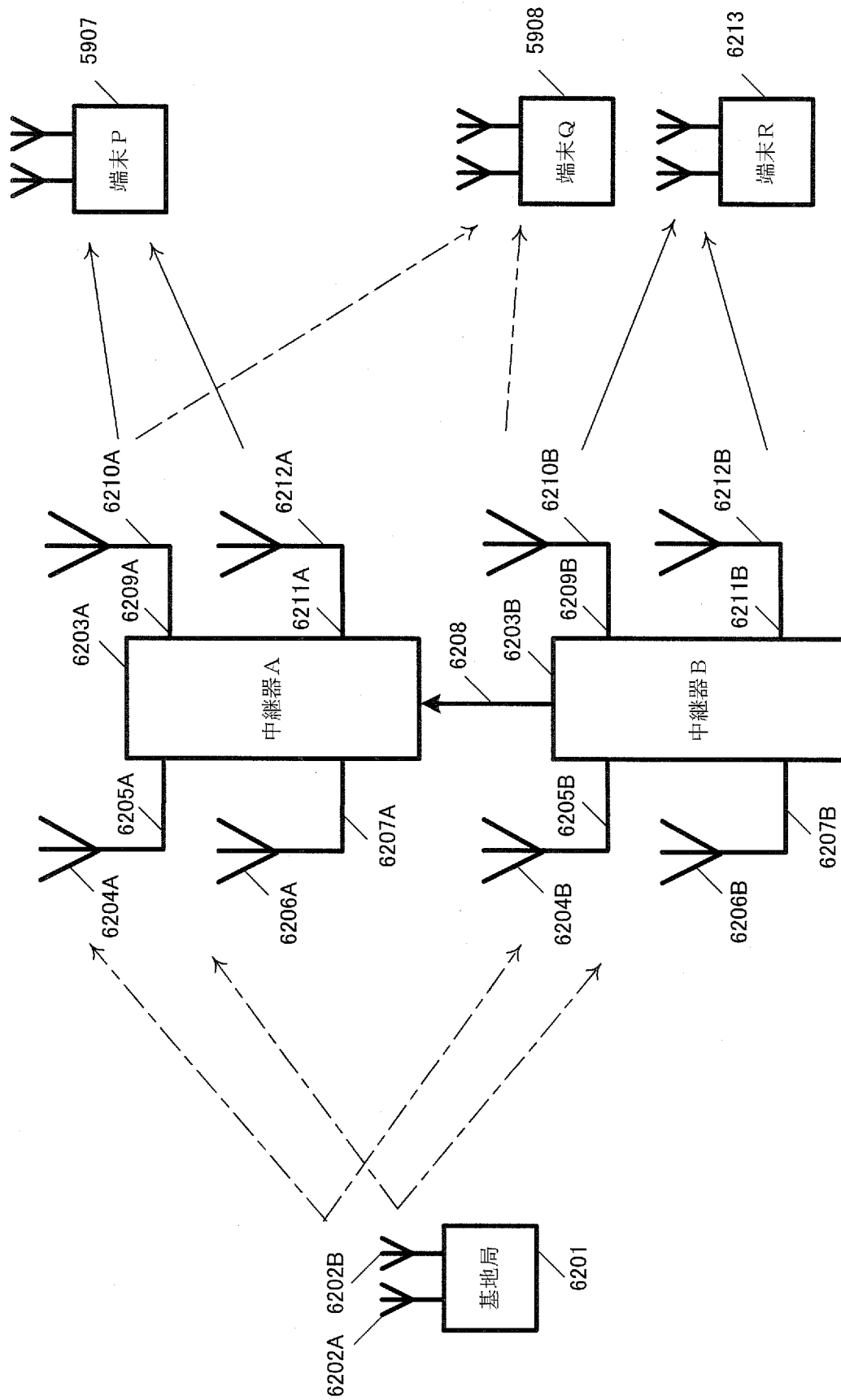
[図60]



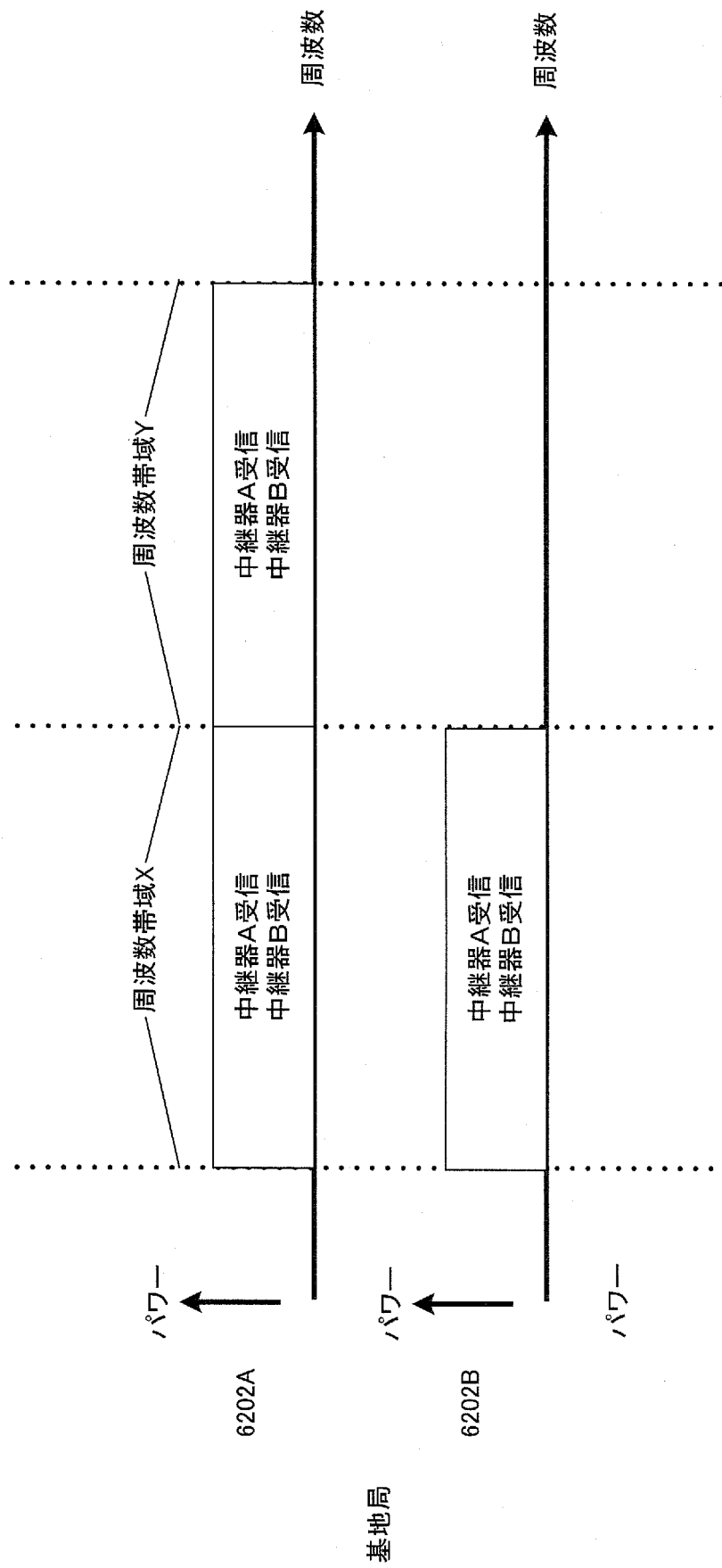
[図61]



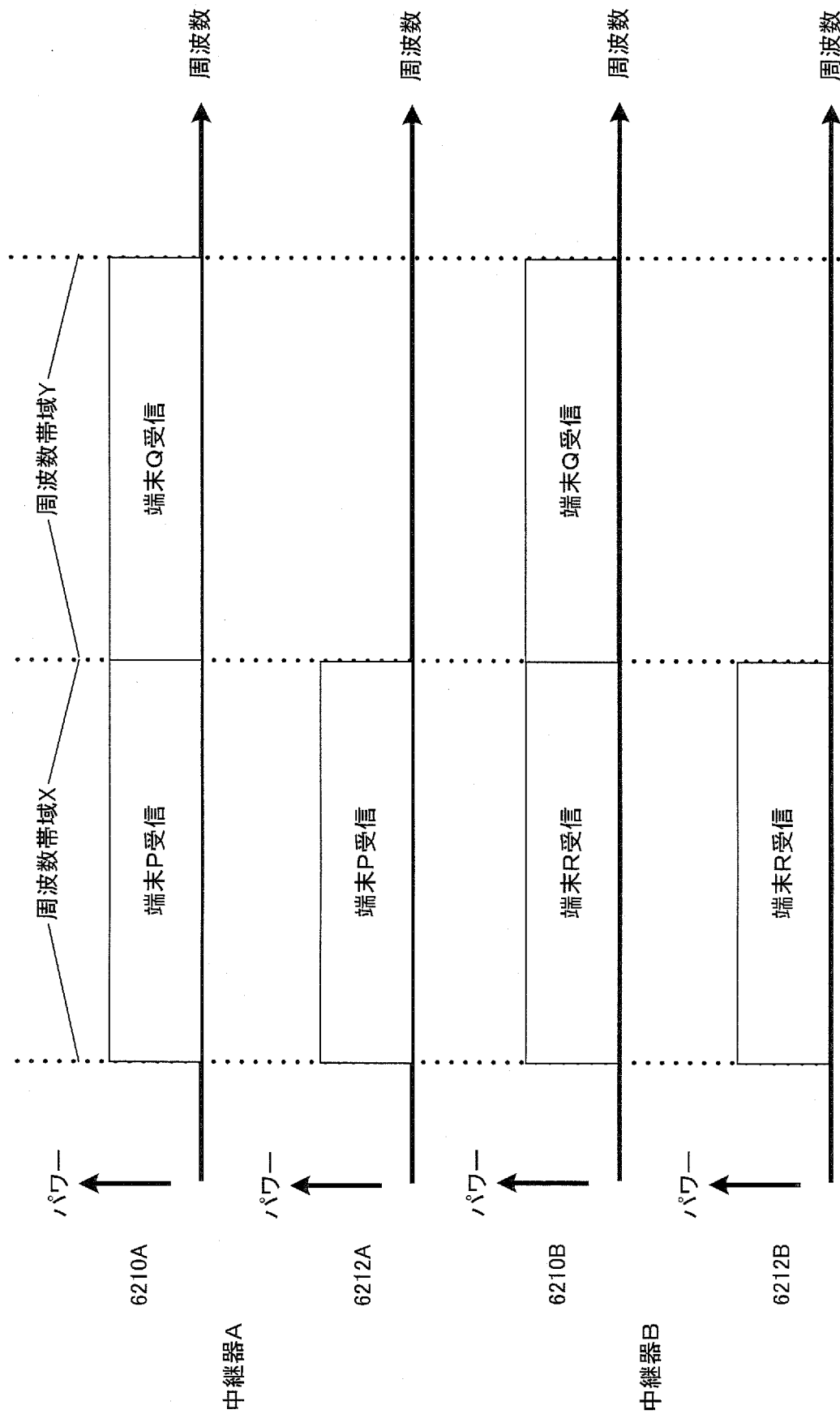
[図62]



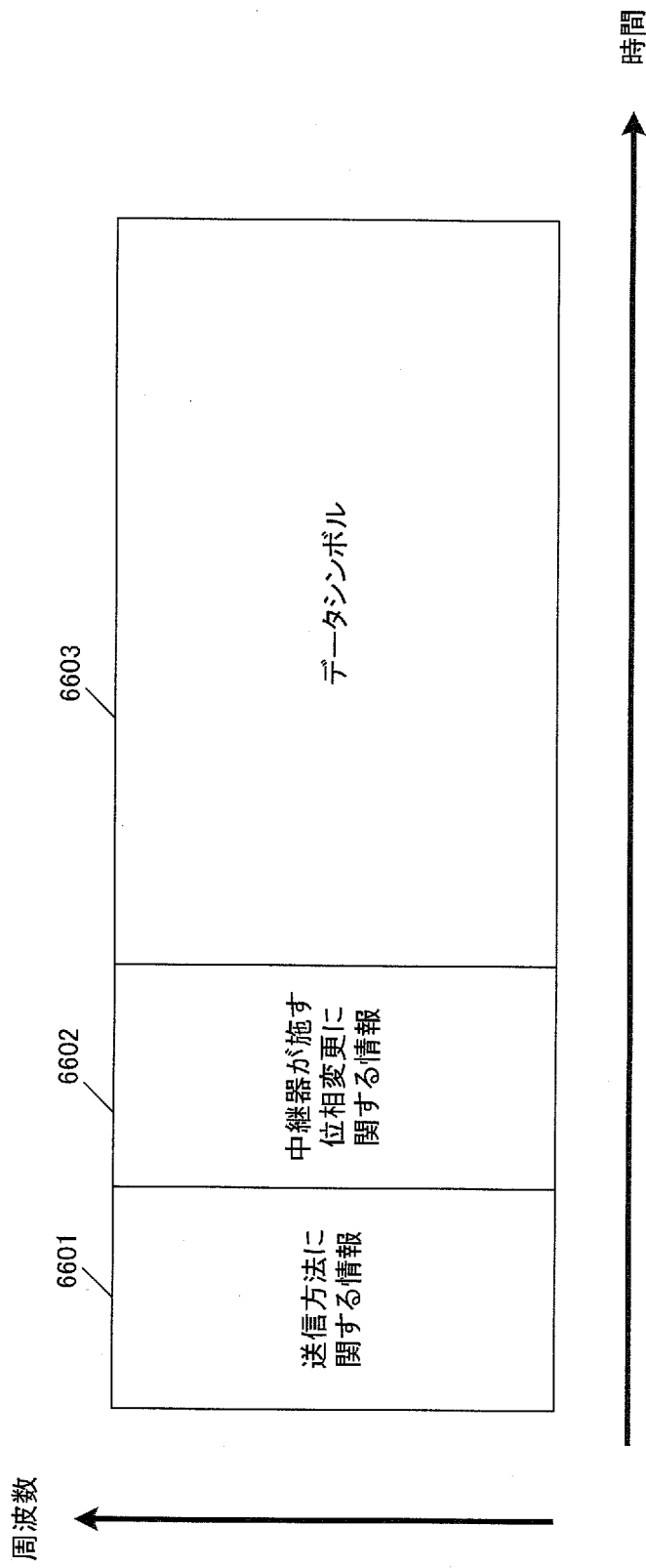
[図63]



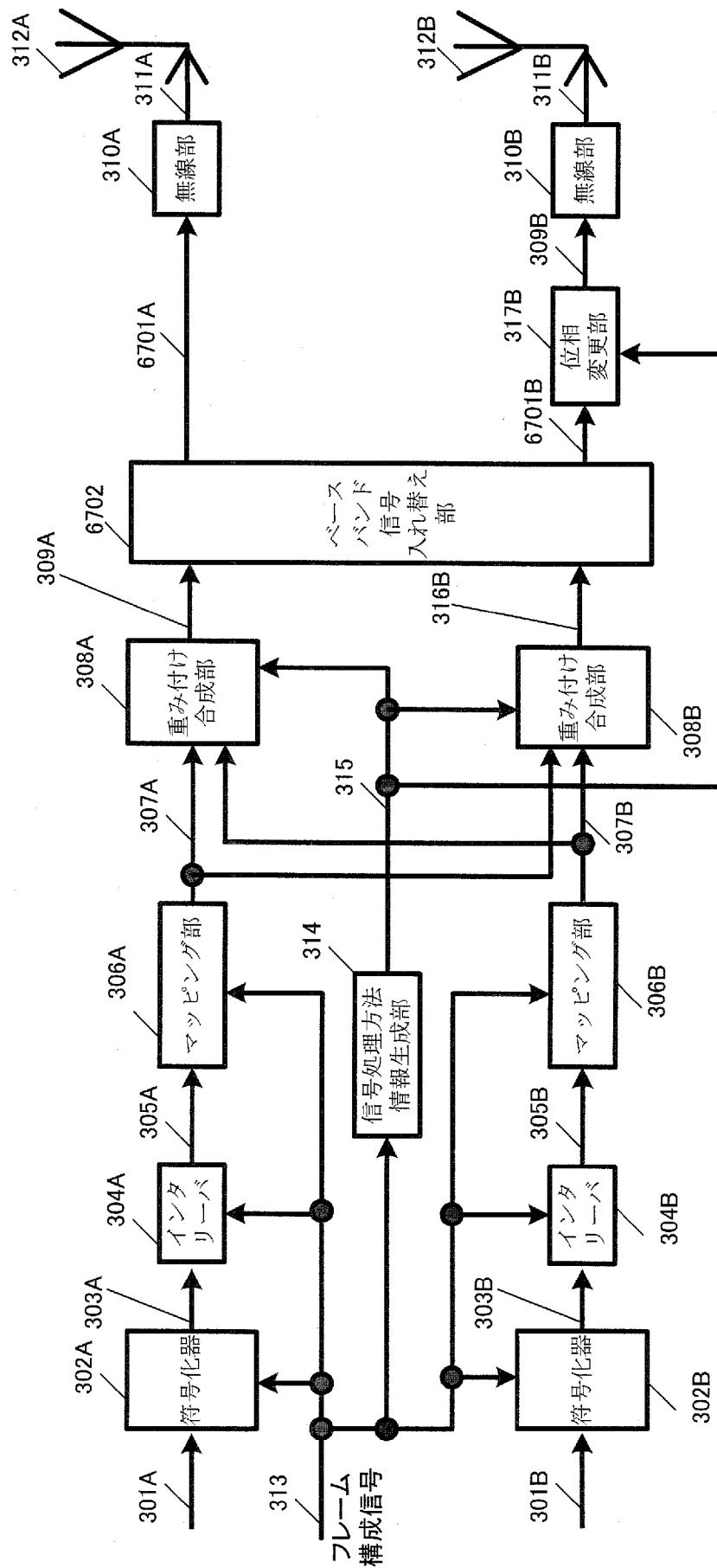
[図64]



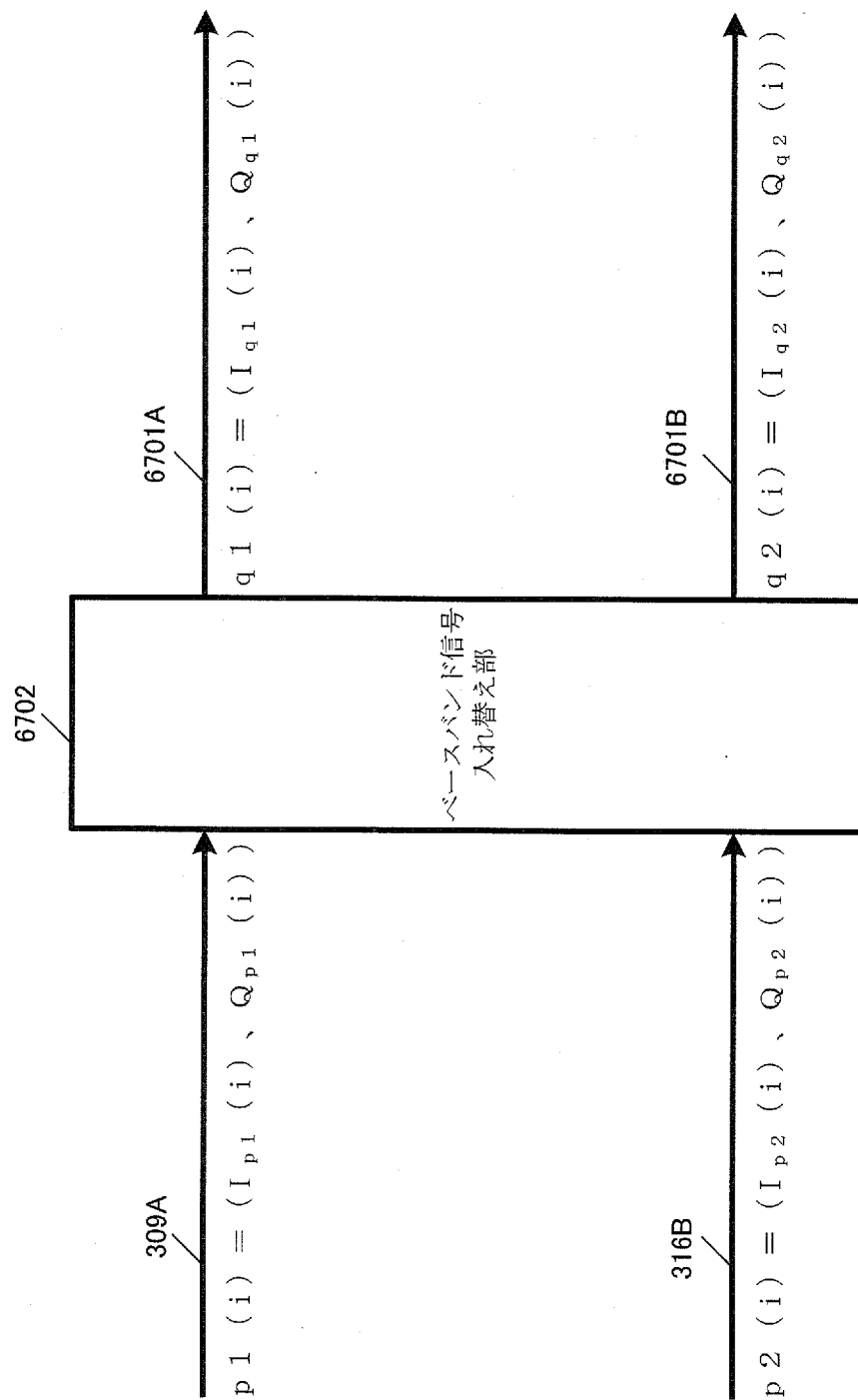
[図66]



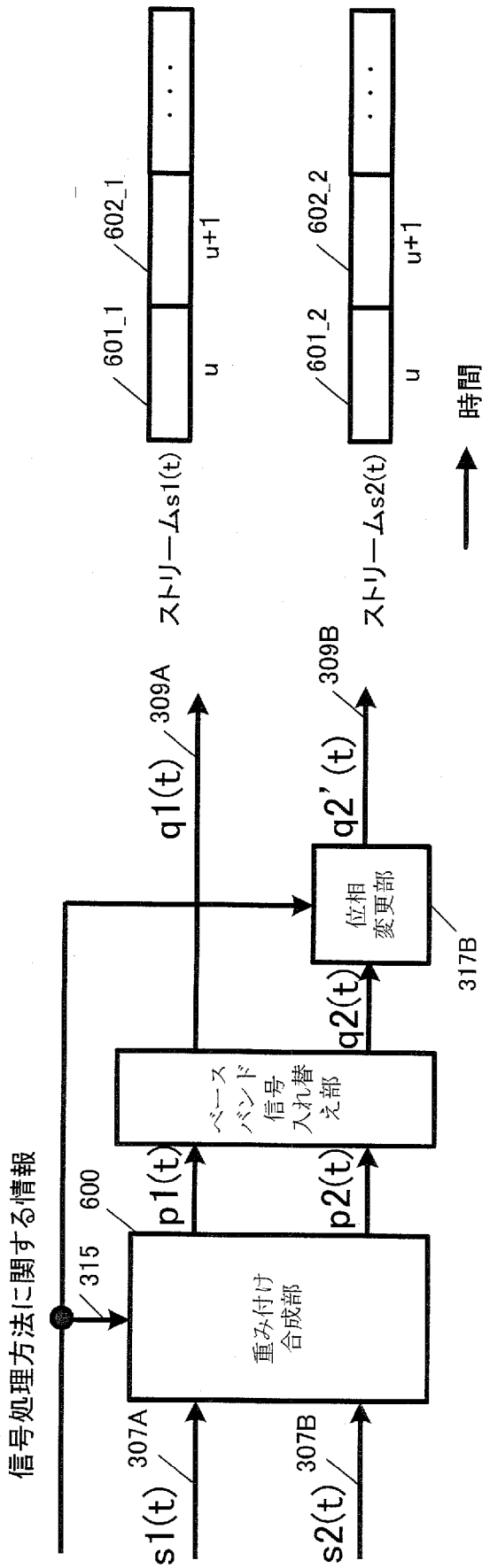
[図67]



[図68]



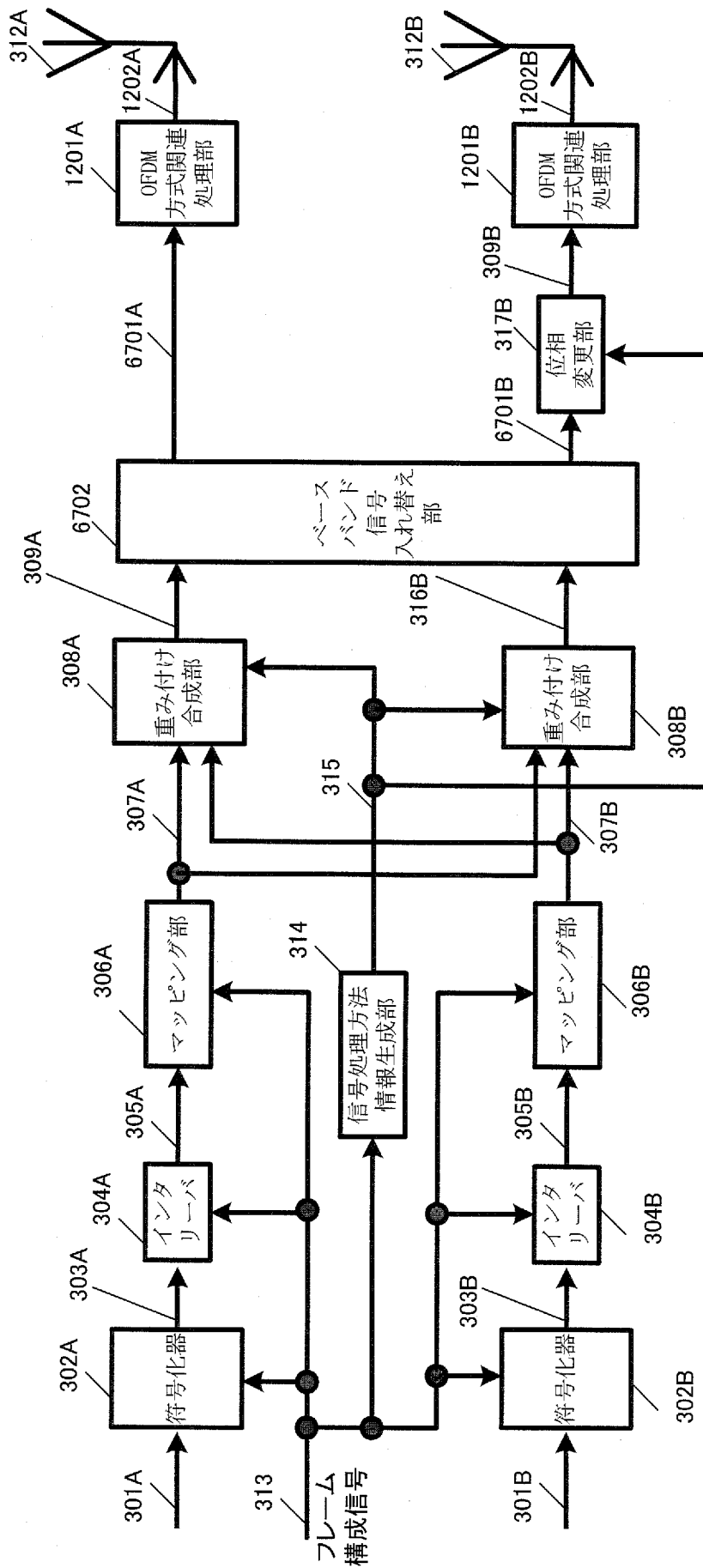
[図69]



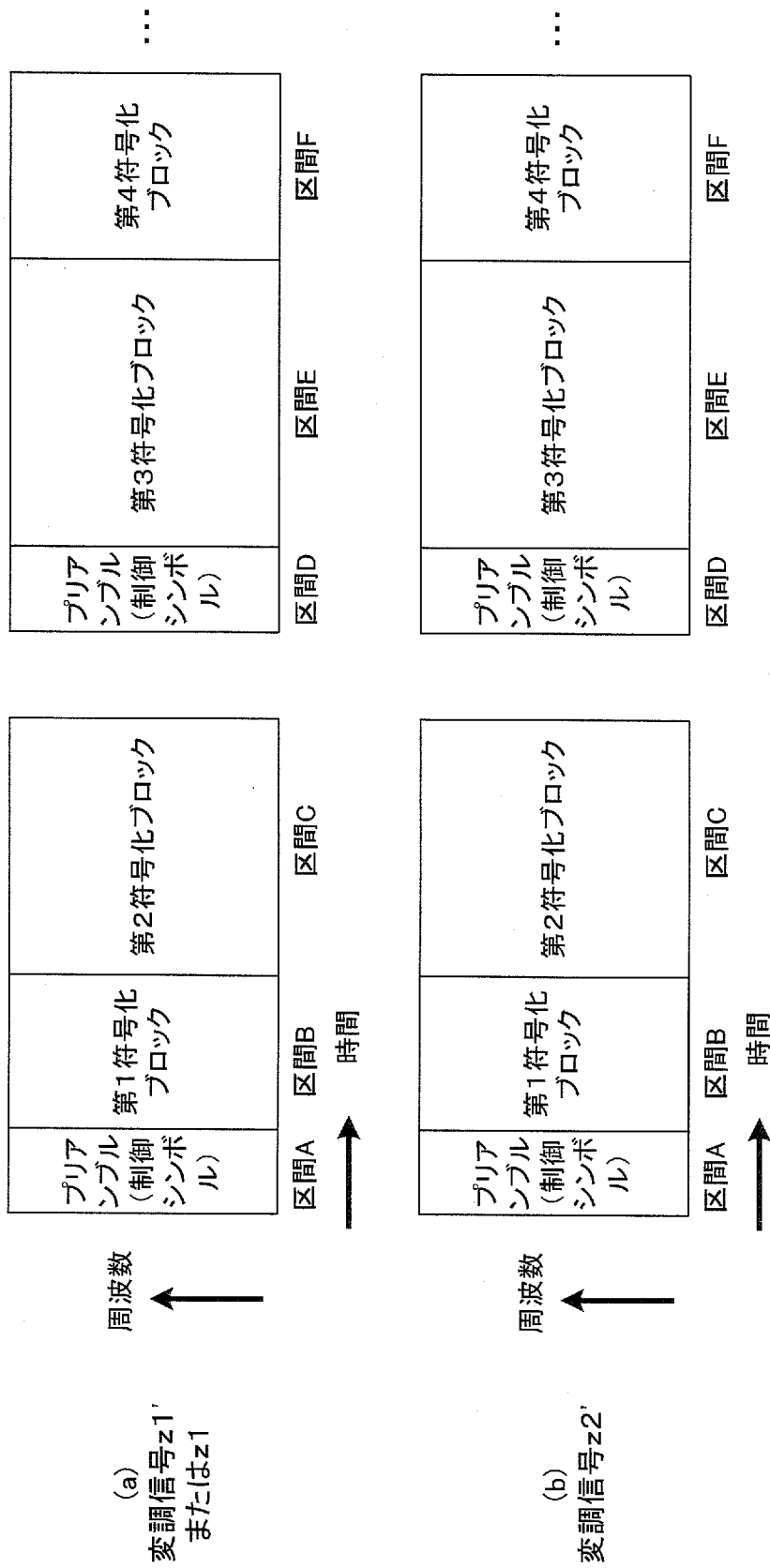
位相変更部の位相変更式 $y(t)$ の変更例

時刻 u	時刻 $u+1$	時刻 $u+2$	時刻 $u+3$	時刻 $u+k$
$y(u) = e^{j0}$	$y(u+1) = e^{j\frac{\pi}{2}}$	$y(u+2) = e^{j\pi}$	$y(u+3) = e^{j\frac{3\pi}{2}}$	$y(u+k) = e^{j\frac{k\pi}{2}}$

[図70]

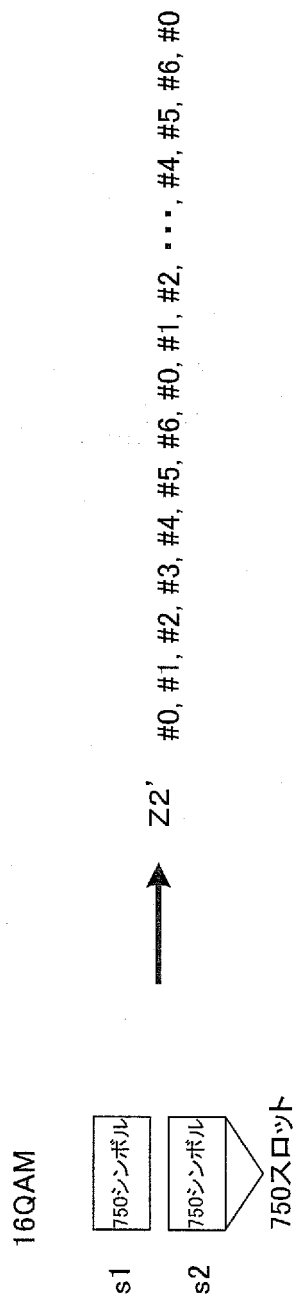


[図71]

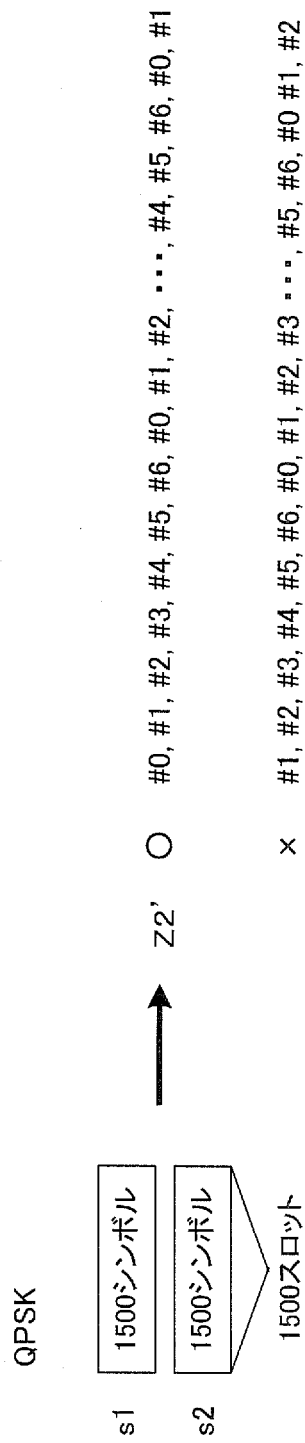


[図72]

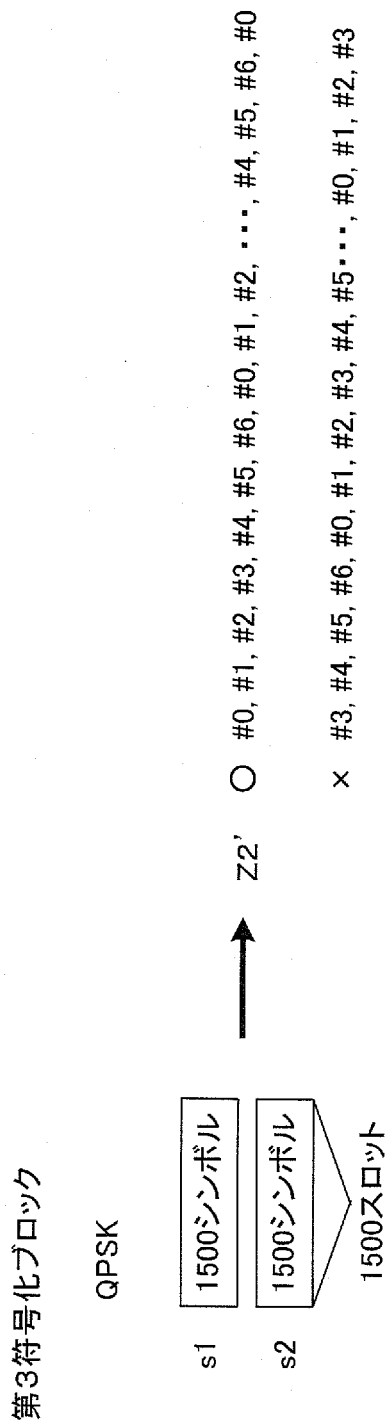
第1符号化ブロック



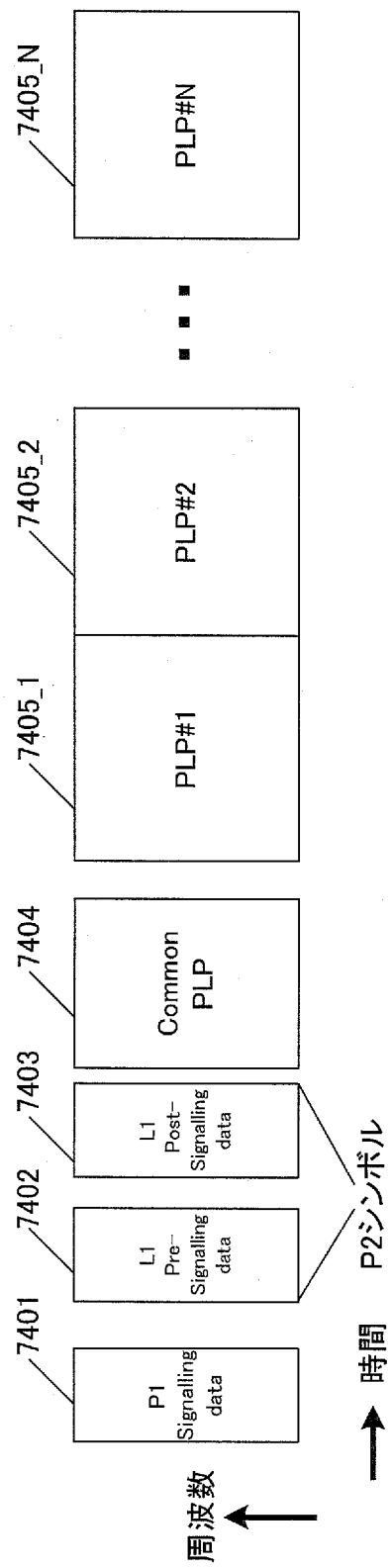
第2符号化ブロック



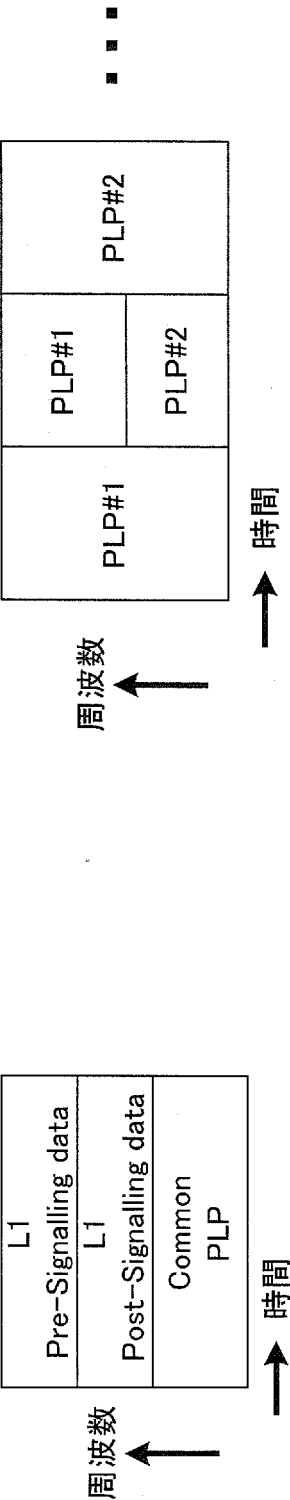
[図73]



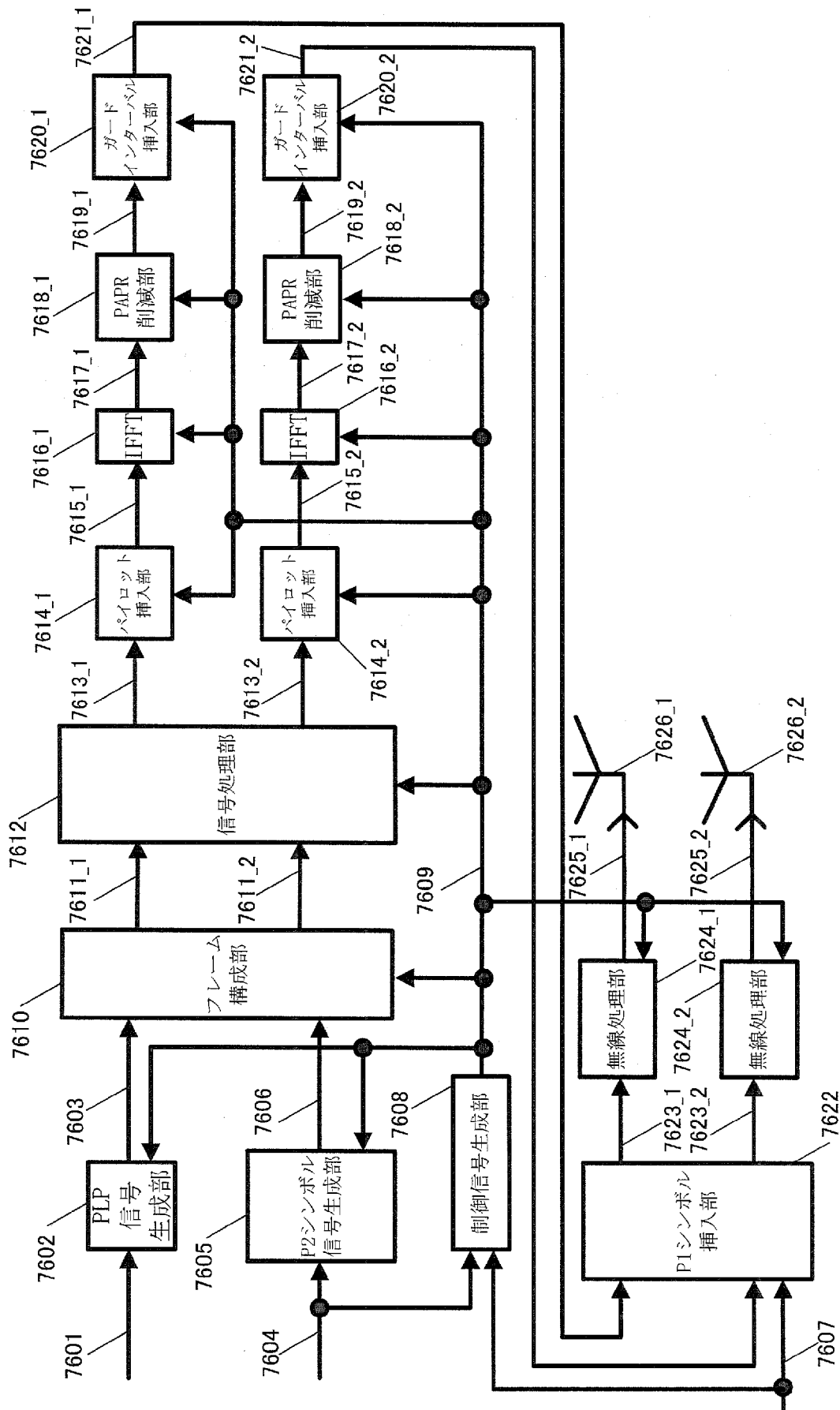
[図74]



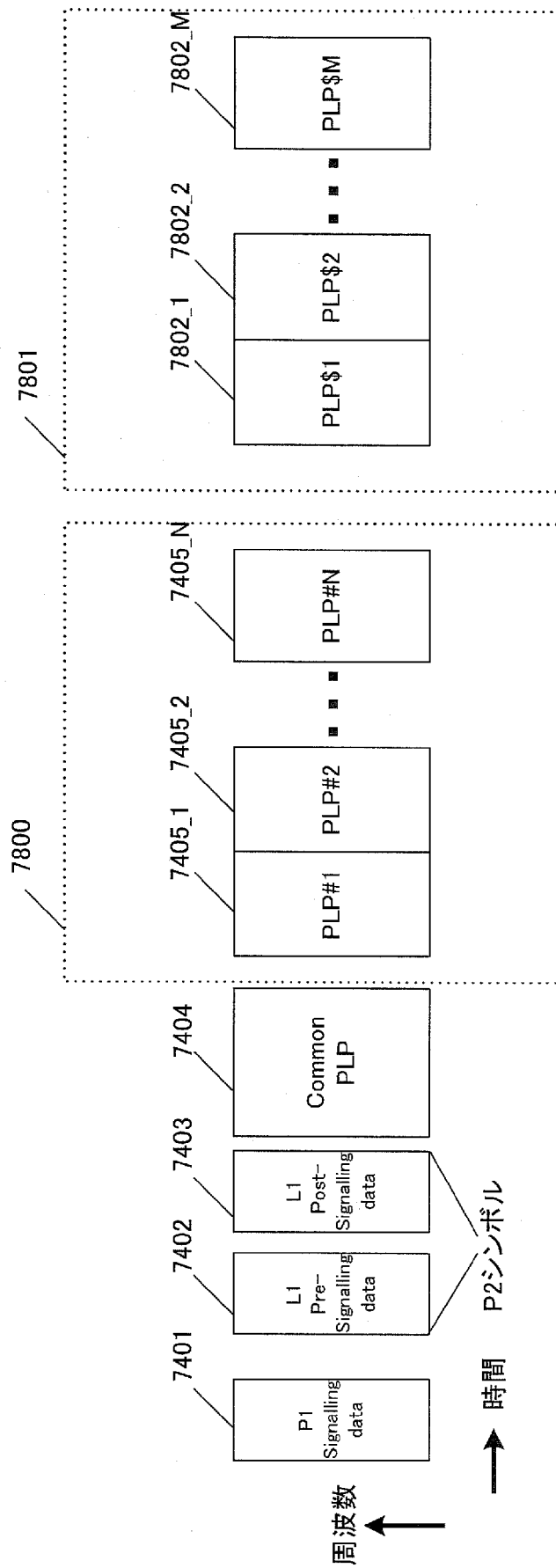
[図75]



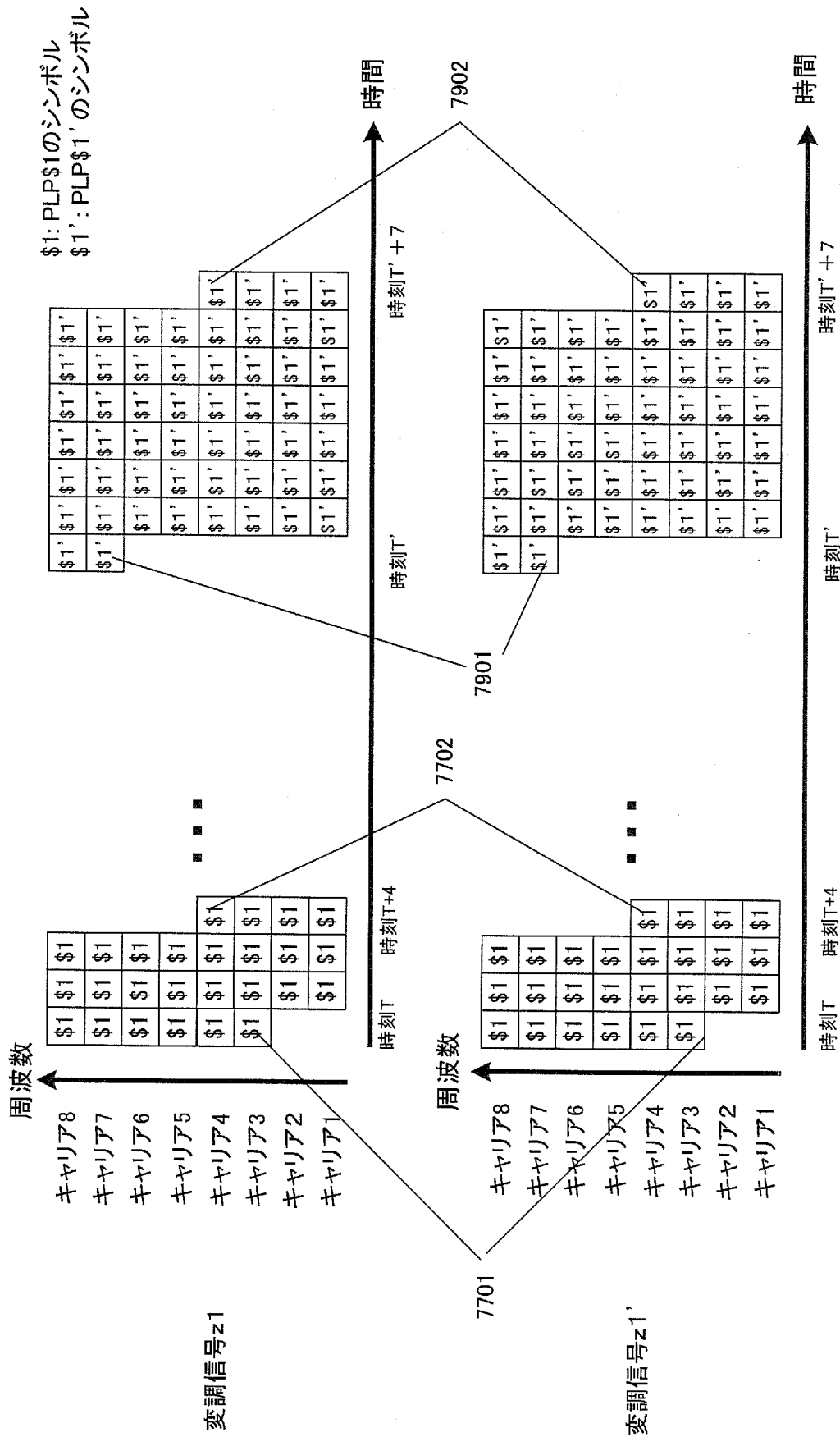
[図76]



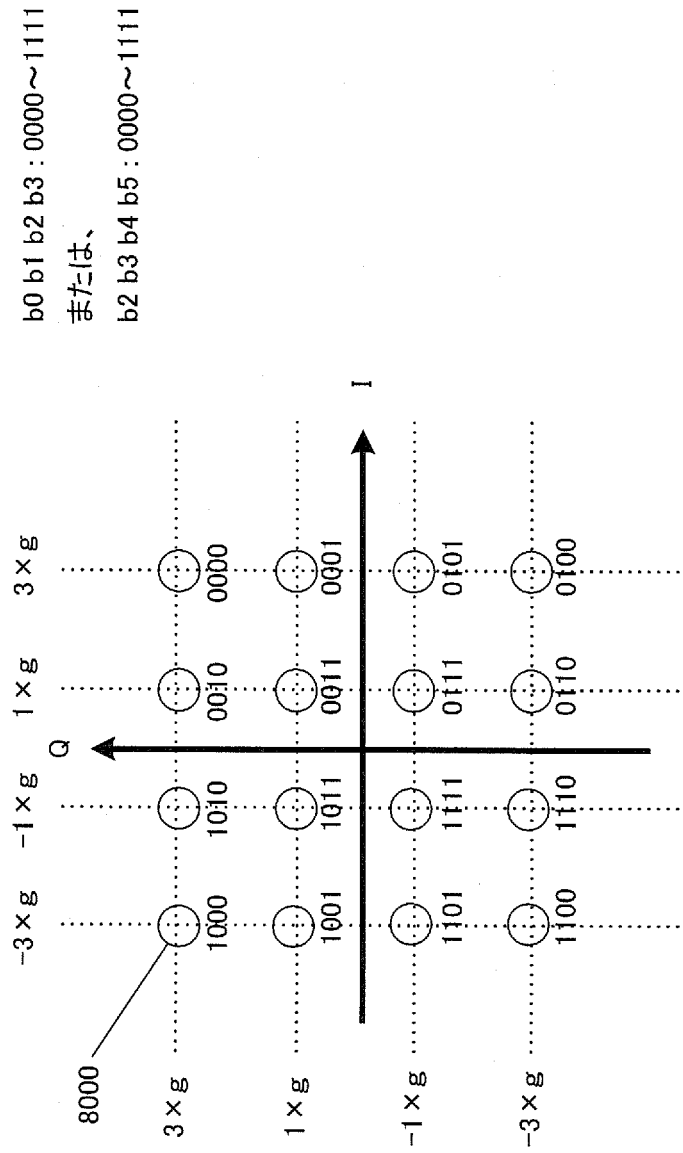
[図78]



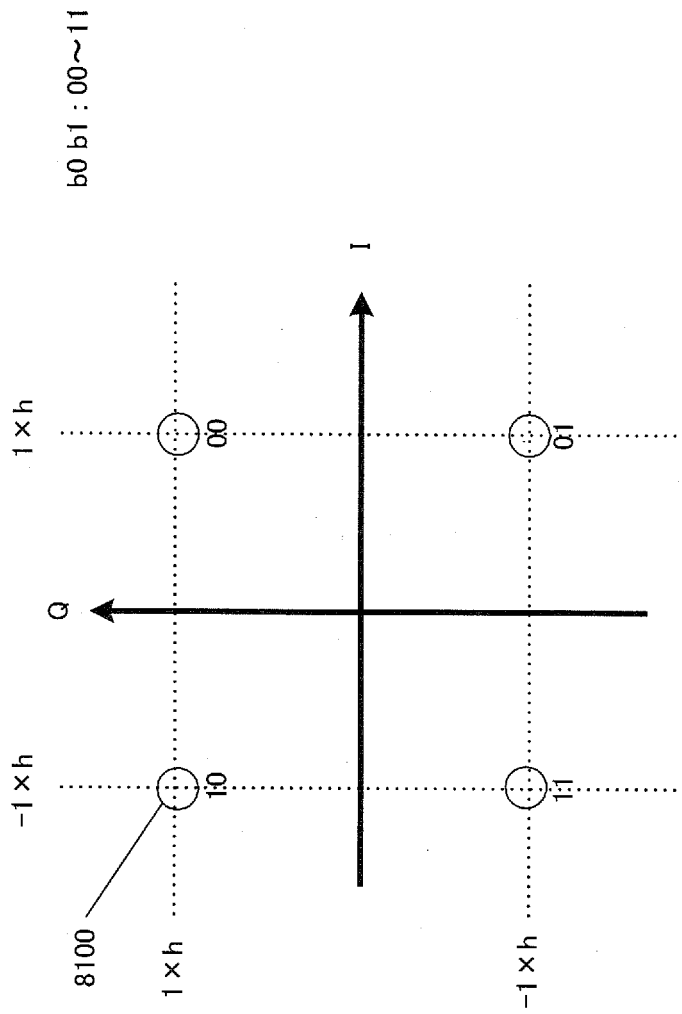
[図79]



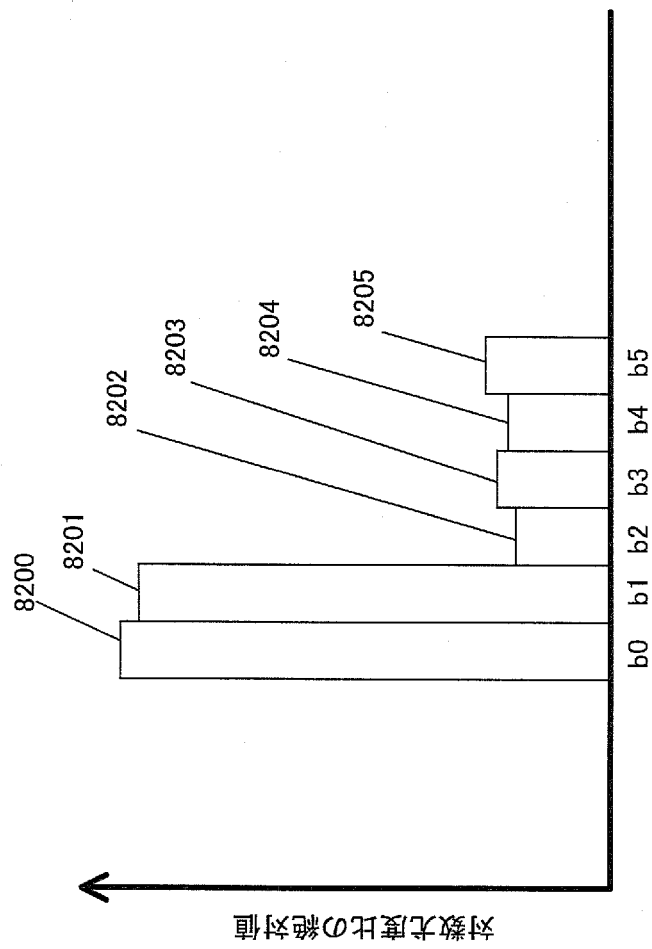
[図80]



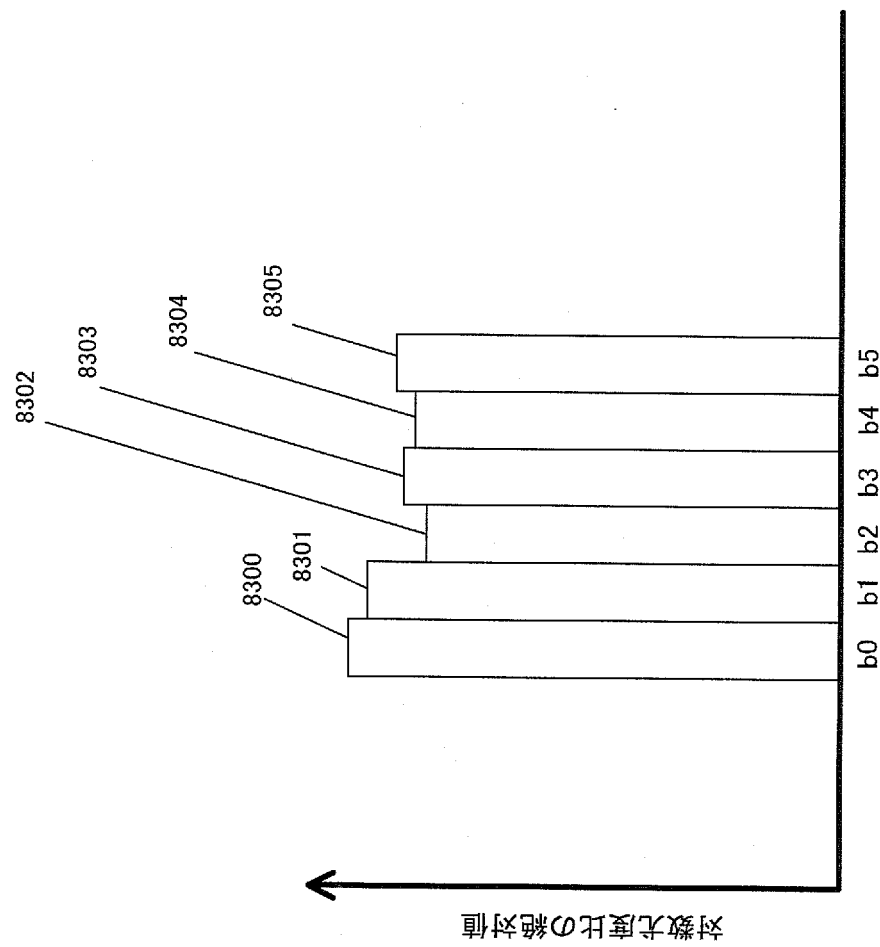
[図81]

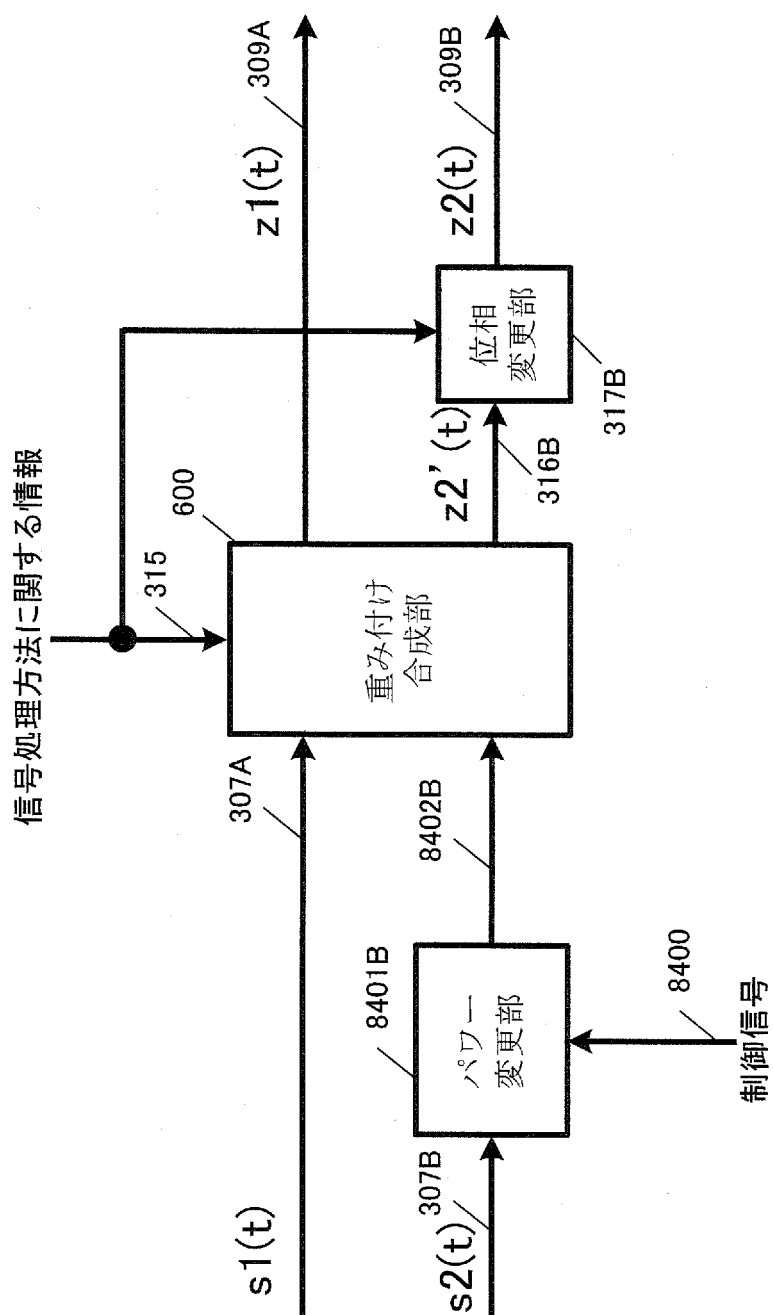


[図82]

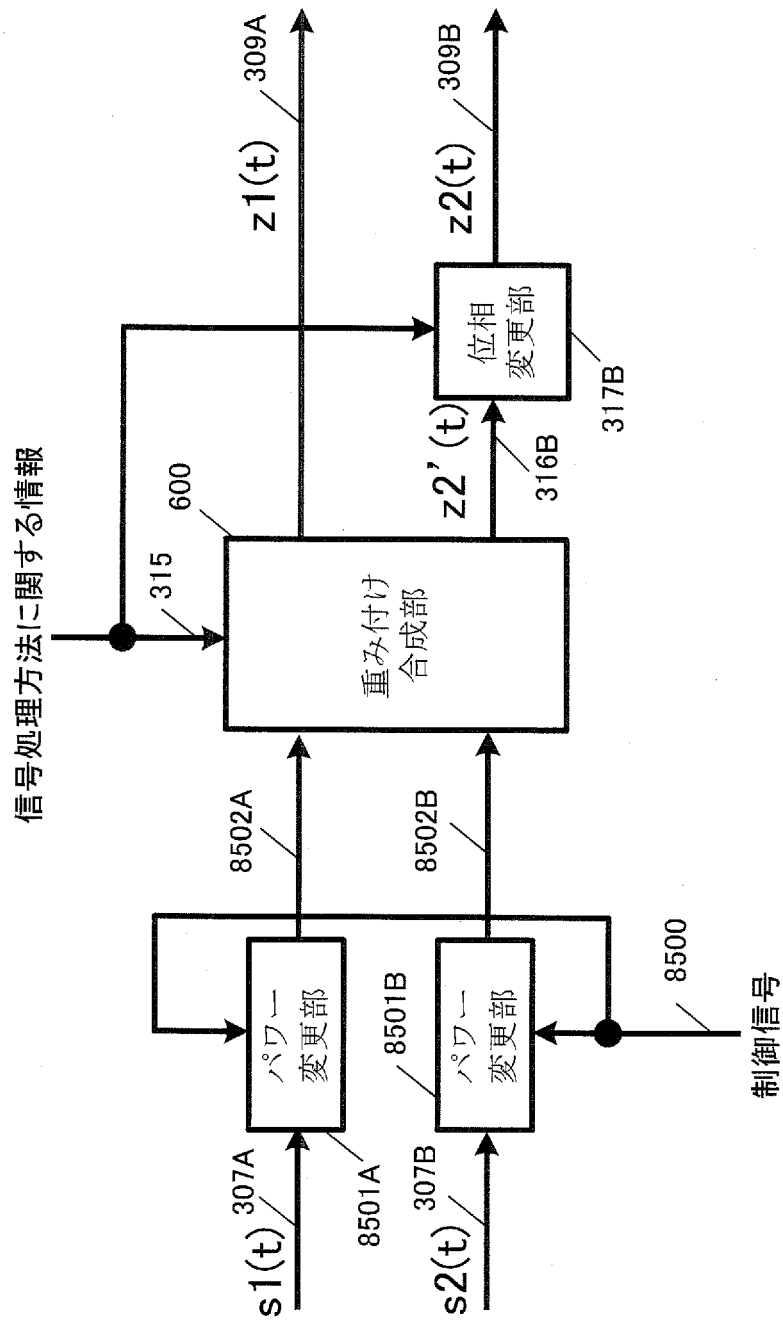


[図83]





[図85]



[illegible]

[図87]

$s1(t)$	QPSK	QPSK	QPSK	16QAM	16QAM	16QAM	QPSK	QPSK	QPSK	16QAM	16QAM	16QAM	16QAM	16QAM	16QAM	...
$s2(t)$	16QAM	16QAM	16QAM	QPSK	QPSK	QPSK	16QAM	16QAM	16QAM	QPSK	QPSK	QPSK	QPSK	QPSK	QPSK	...
パワー変更部 (8501A)	$v=a$	$v=a$	$v=a$	$v=b$	$v=b$	$v=b$	$v=a$	$v=a$	$v=a$	$v=b$	$v=b$	$v=b$	$v=b$	$v=b$	$v=b$	...
パワー変更部 (8501B)	$u=b$	$u=b$	$u=b$	$u=a$	$u=a$	$u=a$	$u=b$	$u=b$	$u=b$	$u=a$	$u=a$	$u=a$	$u=a$	$u=a$	$u=a$	...
位相変更値	$y[0]$	$y[1]$	$y[2]$	$y[0]$	$y[1]$	$y[2]$	$y[0]$	$y[1]$	$y[2]$	$y[0]$	$y[1]$	$y[2]$	$y[0]$	$y[1]$	$y[2]$	...
時間 (周波数)	$t=0$ ($f=f_0$)	$t=1$ ($f=f_1$)	$t=2$ ($f=f_2$)	$t=3$ ($f=f_3$)	$t=4$ ($f=f_4$)	$t=5$ ($f=f_5$)	$t=6$ ($f=f_6$)	$t=7$ ($f=f_7$)	$t=8$ ($f=f_8$)	$t=9$ ($f=f_9$)	$t=10$ ($f=f_{10}$)	$t=11$ ($f=f_{11}$)	$t=11$ ($f=f_{11}$)	$t=11$ ($f=f_{11}$)	$t=11$ ($f=f_{11}$)	...

位相変更の周期: 3

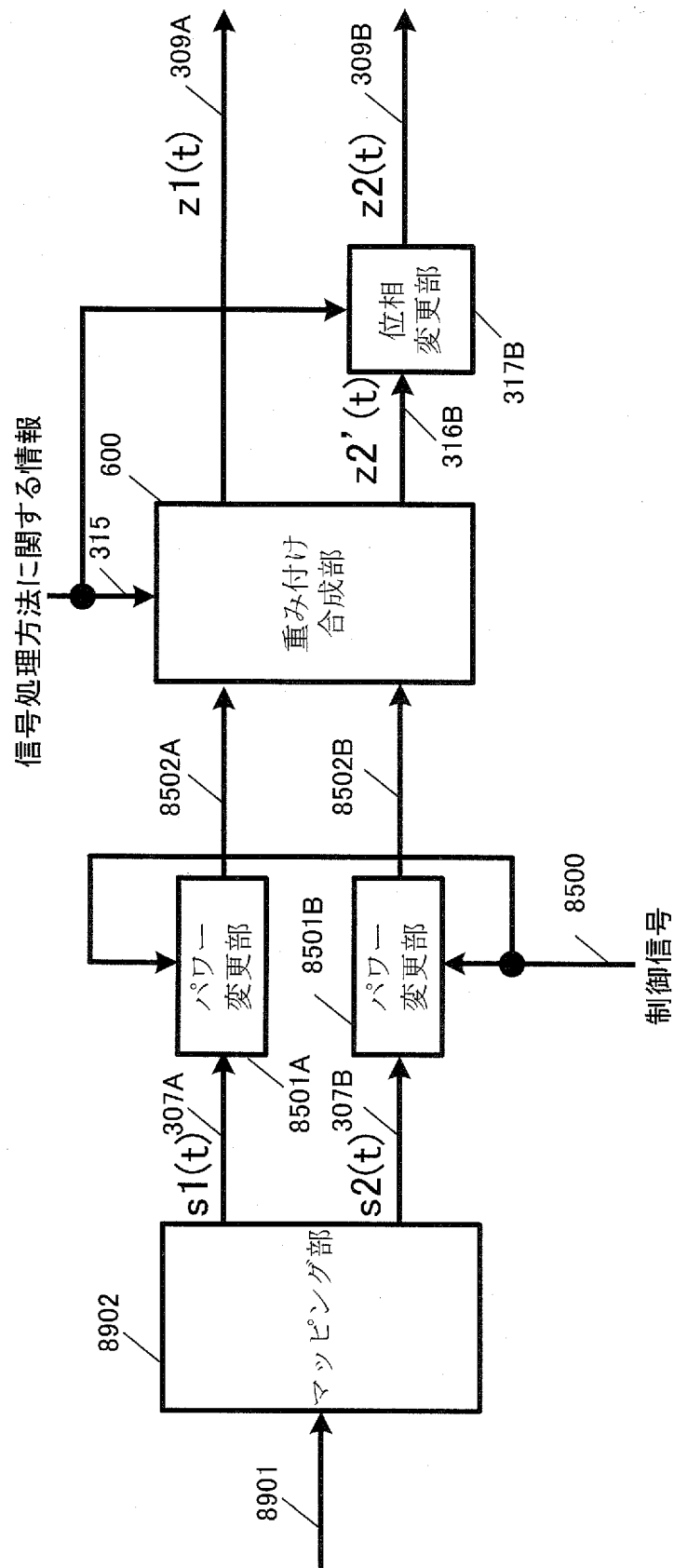
位相変更と変調方式
切り替えを考慮した時の周期: $6=3 \times 2$

位相変更の周期:3

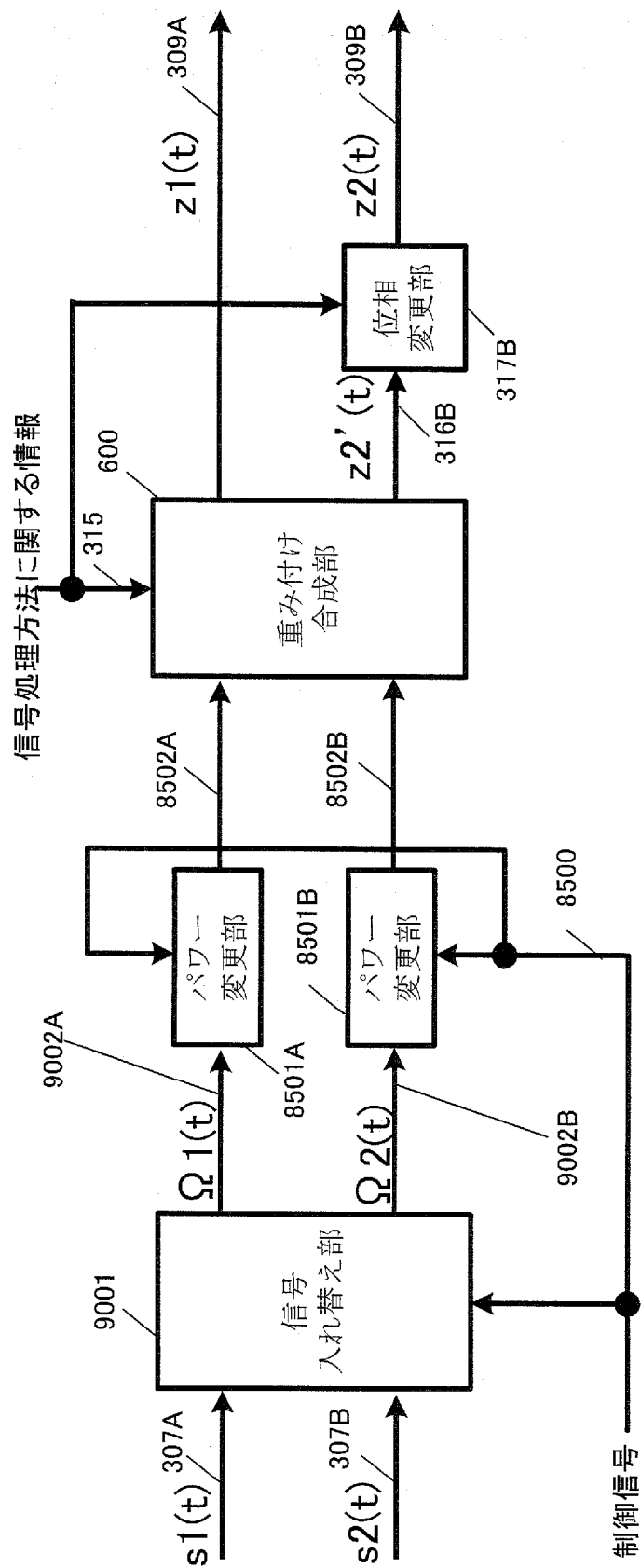
s1(t)	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	...
	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	...
パワ一變更部 (8501A)	v=a	v=b	v=a	v=b	v=a	v=b	v=a	v=b	v=a	v=b	v=a	v=b	...
	u=b	u=a	u=b	u=a	u=b	u=a	u=b	u=a	u=b	u=a	u=b	u=a	...
位相變更値	v[0]	v[1]	v[2]	v[0]	v[1]	v[2]	v[0]	v[1]	v[2]	v[0]	v[1]	v[2]	...
	t=0 (f=f0)	t=1 (f=f1)	t=2 (f=f2)	t=3 (f=f3)	t=4 (f=f4)	t=5 (f=f5)	t=6 (f=f6)	t=7 (f=f7)	t=8 (f=f8)	t=9 (f=f9)	t=10 (f=f10)	t=11 (f=f11)	...

↑
位相変更と変調方式
切り替えを考慮した時の周期: $6=3 \times 2$

[図89]



[図90]



位相変更の周期:3

s1(t)	QPSK												...
s2(t)	16QAM												...
$\Omega 1(t)$	QPSK	QPSK	QPSK	16QAM	16QAM	16QAM	16QAM	QPSK	QPSK	16QAM	16QAM	16QAM	...
$\Omega 2(t)$	16QAM	16QAM	16QAM	QPSK	QPSK	QPSK	16QAM	16QAM	16QAM	QPSK	QPSK	QPSK	...
パワ一変更部 (8501A)	v=a	v=a	v=a	v=b	v=b	v=b	v=a	v=a	v=a	v=b	v=b	v=b	...
パワ一変更部 (8501B)	u=b	u=b	u=b	u=a	u=a	u=a	u=b	u=b	u=b	u=a	u=a	u=a	...
位相変更値	y[0]	y[1]	y[2]	y[0]	y[1]	y[2]	y[0]	y[1]	y[2]	y[0]	y[1]	y[2]	...
時間 (周波数)	t=0 (f=f0)	t=1 (f=f1)	t=2 (f=f2)	t=3 (f=f3)	t=4 (f=f4)	t=5 (f=f5)	t=6 (f=f6)	t=7 (f=f7)	t=8 (f=f8)	t=9 (f=f9)	t=10 (f=f10)	t=11 (f=f11)	...

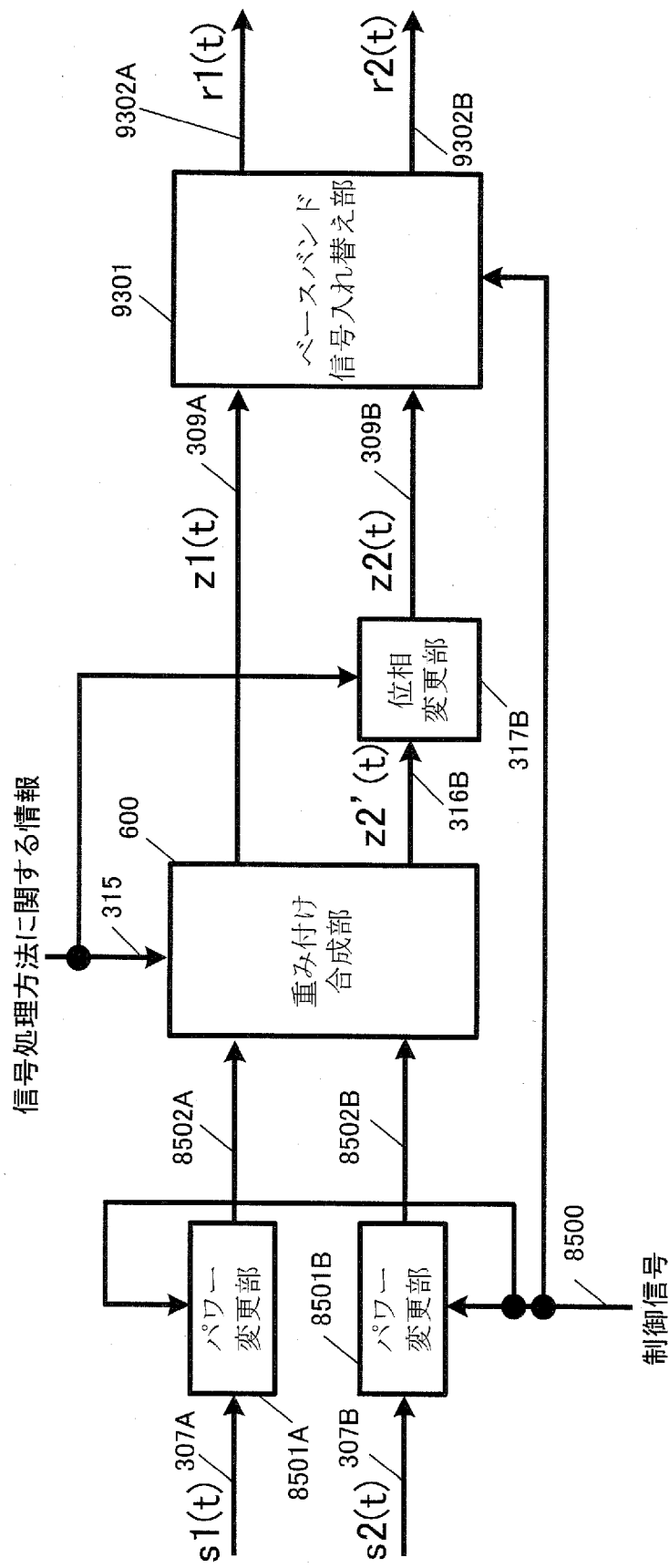
位相変更と変調方式
切り替えを考慮した時の周期: $6=3 \times 2$

位相変更の周期:3

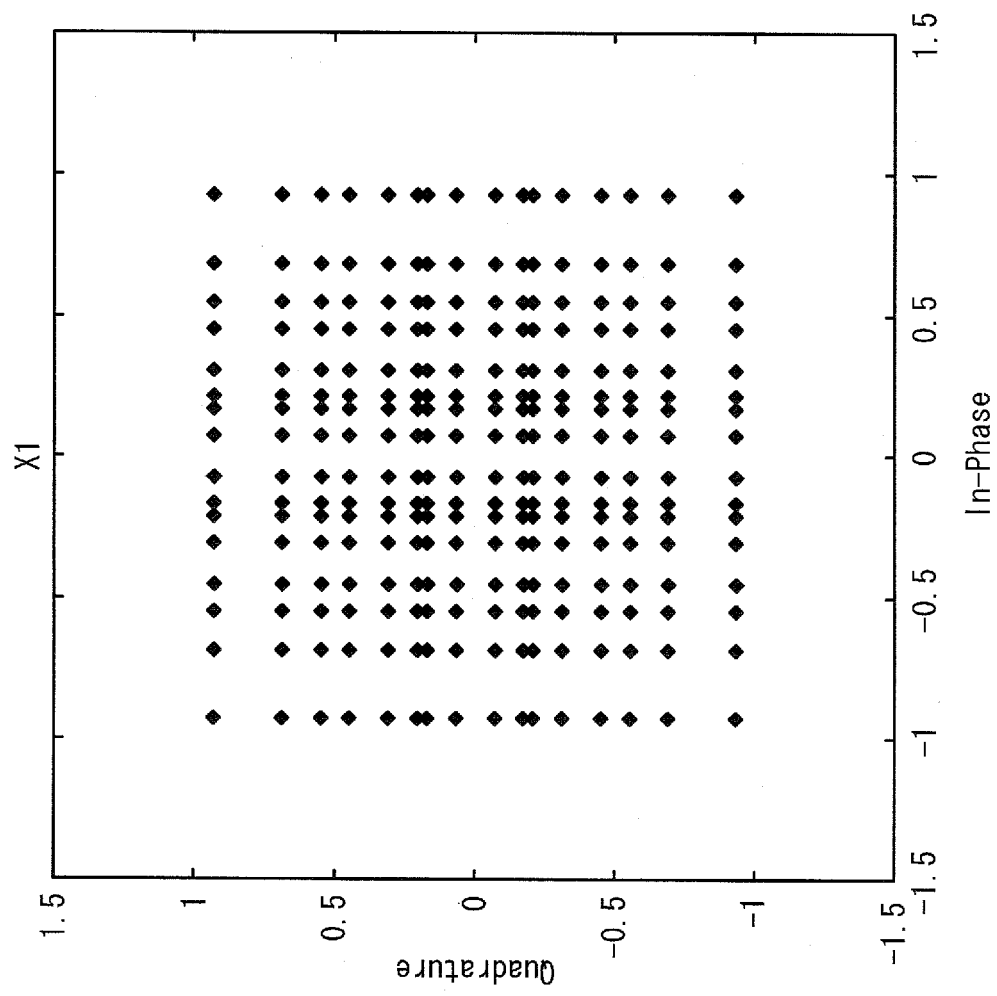
$s1(t)$	QPSK												...
$s2(t)$	16QAM												...
$\Omega 1(t)$	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	...
$\Omega 2(t)$	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	16QAM	QPSK	...
パワー変調部 (8501A)	$v=a$	$v=b$	$v=a$	$v=b$	$v=a$	$v=b$	$v=a$	$v=b$	$v=a$	$v=b$	$v=a$	$v=b$	...
パワー変調部 (8501B)	$u=b$	$u=a$	$u=b$	$u=a$	$u=b$	$u=a$	$u=b$	$u=a$	$u=b$	$u=a$	$u=b$	$u=a$	...
位相変調部	$y[0]$	$y[1]$	$y[2]$	$y[0]$	$y[1]$	$y[2]$	$y[0]$	$y[1]$	$y[2]$	$y[0]$	$y[1]$	$y[2]$	...
時間 (周波数)	$t=0$ ($f=f_0$)	$t=1$ ($f=f_1$)	$t=2$ ($f=f_2$)	$t=3$ ($f=f_3$)	$t=4$ ($f=f_4$)	$t=5$ ($f=f_5$)	$t=6$ ($f=f_6$)	$t=7$ ($f=f_7$)	$t=8$ ($f=f_8$)	$t=9$ ($f=f_9$)	$t=10$ ($f=f_{10}$)	$t=11$ ($f=f_{11}$)	...

位相変更と変調方式
切り替えを考慮した時の周期: $6=3 \times 2$

[図93]



[図94]



[図95]

