

ABSTRACT

Provided in the present application are a control method and apparatus for a virtual robot, and a device, a storage medium and a program product. The control method for a virtual robot comprises: starting a plurality of virtual robots which are constructed by using a finite state automaton, wherein the virtual robots are used for cyclically simulating a user to operate an application program several times; in each cycle, determining a view where the virtual robots are located in the application program, and taking the view as a state; in each cycle, simulating the user to select services in the view, and taking the selected service as events; and in each cycle, driving the virtual robots to execute, in the view, user operations for triggering the service, and taking the user operations as actions.

Fig. 1