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## TITLE OF THE INVENTION

CONNECTOR FOR FLEXIBLE PRINTED CIRCUIT BOARDS, HEAD  
ACTUATOR PROVIDED WITH THE SAME, AND DISK DRIVE

## BACKGROUND OF THE INVENTION

5           The present invention relates to a connector for  
connecting flexible printed circuit boards, a head  
actuator provided with the connector, and a disk drive.

          In general, a disk drive such as a hard disk drive  
(hereinafter referred to as HDD) comprises magnetic  
10       disks housed in a casing, a spindle motor for  
supporting and rotating the magnetic disks, a head  
actuator supporting magnetic heads, a voice coil motor  
for driving the head actuator, a substrate unit, etc.

          The head actuator includes a bearing portion  
15       attached to the casing and a plurality of arms  
extending from the bearing portion. A magnetic head is  
mounted on each arm by means of a suspension. The  
substrate unit includes a main flexible printed circuit  
board (hereinafter referred to as main FPC), the distal  
20       end portion of which extends close to the bearing  
portion. Each magnetic head is connected to one end of  
a relay flexible printed circuit board (hereinafter  
referred to as relay FPC) on each arm, and the other  
end portion of the relay FPC is connected to the main  
25       FPC. Thus, each magnetic head is connected  
electrically to the substrate unit through the relay  
and main FPC's and controlled by means of the substrate

unit.

In the case where the printed circuit boards are connected electrically to each other in this manner, each printed circuit board is provided with connecting  
5 pads, a pre-tinning layer is formed on each connecting pad, and the pads are opposed to one another. In this state, the pre-tinning layer is heated from the base-layer side of one of the printed circuit boards. By doing this, the pre-tinning layer is melted to  
10 connect the pads electrically and mechanically.

Possibly, the relay and main FPC's may be connected by contact bonding. In the magnetic disk drive, however, the connected portion between the relay and main FPC's moves as the head actuator rocks, and is  
15 subjected to vibration and shock. Accordingly, soldering is widely used to improve the reliability of connection.

In conventional assembly processes for a magnetic disk drive, soldering the FPC's is carried out in  
20 a clean room. However, the soldering operation includes a process for melting solder by means of a soldering iron. In this process, outgassing from a flux or the like in the solder may generate, possibly contaminating the atmosphere in the clean room and  
25 exerting a bad influence upon other components.

Further, soldering the relay and main FPC's involves operation for soldering very fine connecting

pads, so that the reliability of the soldering is easily influenced by workmanship.

Furthermore, repairing the head actuator requires resoldering after the solder on the connecting portions is removed. Thus, repairs are troublesome and their achievement level easily lowers.

#### BRIEF SUMMARY OF THE INVENTION

The present invention has been contrived in consideration of these circumstances, and its object is to provide a connector for flexible printed circuit boards, capable of easily securely connecting flexible printed circuit boards, a head actuator provided with the same, and a disk drive.

In order to achieve the above object, a connector for flexible printed circuit boards according to an aspect of the invention is a connector for electrically connecting a pair of first flexible printed circuit boards, fixed individually on the respective surfaces of two arms spaced and opposed to each other and each extending from a distal end portion of each arm to a proximal end portion thereof, and a second flexible printed circuit board extending from any other portion than the arms toward the proximal end portions.

The connector comprises: a female connector formed of the first flexible printed circuit boards; and a male connector provided at the second flexible printed circuit board. The female connector includes a pair of

connecting portions formed on respective proximal-side  
end portions of the first flexible printed circuit  
boards and opposed to each other across a given space,  
each of the connecting portions having a first contact  
5 formed by exposing a part of a conductor pattern of the  
first flexible printed circuit board. The male  
connector includes a projection configured to be fitted  
between the connecting portions of the female  
connector, and second contacts provided on the  
10 projection and connected to a conductor pattern of  
the second flexible printed circuit board, the second  
contacts being arranged so as to contact with the first  
contacts when the projection is fitted between the  
connecting portions.

15 A head actuator according to another aspect of the  
invention comprises: a bearing portion; two arms each  
having a proximal end portion attached to the bearing  
portion, and a distal end portion supporting a head,  
extending from the bearing portion, the arms being  
20 opposed to each other across a given space; first  
flexible printed circuit boards fixed individually on  
the respective arms, connected electrically to the  
respective heads, and extending from the heads to the  
proximal end portions of the arms; a second flexible  
25 printed circuit board connected to the first flexible  
printed circuit boards; and a male connector attached  
to the second flexible printed circuit board,

each of the first flexible printed circuit boards including a connecting portion provided at the proximal end portion of the arm and having a first contact formed by exposing a part of a conductor pattern of the first flexible printed circuit board,

the respective connecting portions on the two arms being opposed to each other across a given space to constitute a female connector,

the male connector including a projection configured to be fitted between the connecting portions of the female connector and second contacts provided on the projection and connected to a conductor pattern of the second flexible printed circuit board, the second contacts being arranged so as to contact with the respective first contacts when the projection is fitted between the connecting portions.

A disk drive according to still another aspect of the invention comprises a disk; a head configured to write and read in and retrieving information from the disk; a head actuator supporting the head for movement with respect to the disk; a substrate unit configured to input and output signals with respect to the head; a main flexible printed circuit board extending from the substrate unit and connected to the head actuator; and a male connector attached to the main flexible printed circuit board,

the head actuator including a bearing portion; two

arms each having a proximal end portion attached to the bearing portion, and a distal end portion supporting the head, extending from the bearing portion, the arms being opposed to each other across a given space; and  
5 relay flexible printed circuit boards fixed individually on the respective arms, connected electrically to the respective heads, and extending from the heads to the proximal end portions of the arms;

10 each of the relay flexible printed circuit boards including a connecting portion provided at the proximal end portion of the arm and having a first contact formed by exposing a part of a conductor pattern of the relay flexible printed circuit board, the connecting  
15 portions being opposed to each other across a given space to constitute a female connector,

the male connector including a projection configured to be fitted between the connecting portions of the female connector and second contacts provided on  
20 the projection and connected to a conductor pattern of the main flexible printed circuit board, the second contacts being arranged so as to contact with the respective first contacts when the projection is fitted between the connecting portions.

25 Additional objects and advantages of the invention will be set forth in the description which follows, and in part will be obvious from the description, or may be

learned by practice of the invention. The objects and advantages of the invention may be realized and obtained by means of the instrumentalities and combinations particularly pointed out hereinafter.

5 BRIEF DESCRIPTION OF THE SEVERAL VIEWS OF THE DRAWING

The accompanying drawings, which are incorporated in and constitute a part of the specification, illustrate an embodiment of the invention, and together with the general description given above and the  
10 detailed description of the embodiment given below, serve to explain the principles of the invention.

FIG. 1 is a perspective view showing the interior of an HDD according to an embodiment of the present invention;

15 FIG. 2 is an exploded perspective view of a head actuator attached to the HDD;

FIG. 3 is a perspective view of the head actuator;

FIG. 4 is a perspective view showing a male connector for the head actuator;

20 FIG. 5A is a sectional view of the male connector taken along line VA-VA in FIG. 4;

FIG. 5B is a sectional view of the male connector taken along line VB-VB in FIG. 4;

FIG. 5C is a sectional view of the male connector;

25 FIGS. 6A and 6B are sectional views schematically showing a process for connecting female connectors of the head actuator and the male connector;

FIG. 7 is a sectional view schematically showing the female connectors of the head actuator and the male connector connected to one another;

FIG. 8 is an exploded perspective view showing a head actuator of an HDD according to a second  
5 embodiment of the invention;

FIG. 9 is a perspective view showing a male connector for the head actuator of the HDD according to the second embodiment; and

10 FIGS. 10A and 10B are sectional views schematically showing a process for connecting female connectors of the head actuator and the male connector of FIG. 9.

#### DETAILED DESCRIPTION OF THE INVENTION

15 An HDD as a disk drive according to an embodiment of the present invention will now be described in detail with reference to the accompanying drawings.

As shown in FIG. 1, the HDD comprises a casing 10 in the form of an open-topped rectangular box and a top  
20 cover (not shown) that is fixed to the casing by means of screws and covers the top opening of the casing.

The casing 10 is stored with two magnetic disks 12a and 12b for use as magnetic recording media, a spindle motor 13 for supporting and rotating the  
25 magnetic disks, magnetic heads for writing in and reading information from the magnetic disks, a head actuator 14 that support the magnetic heads for

movement with respect to the magnetic disks 12a and 12b. The casing 10 is further stored with a VCM 16 for rocking and positioning the head actuator, a ramp load mechanism 18 that holds the magnetic heads in positions distant from the magnetic disks when the magnetic heads are moved to the outermost periphery of the magnetic disks, an inertia latch mechanism 20 for holding the head actuator in a refuge position, and a flexible printed circuit board unit (hereinafter referred to as FPC unit) 17 mounted with circuit components such as a preamplifier.

Further, a printed circuit board (not shown) for controlling the respective operations of the spindle motor 13, VCM 16, and magnetic heads by means of the FPC unit 17 is screwed to the outer surface of the casing 10 and opposed to the bottom wall of the casing.

Each of the magnetic disks 12a and 12b has a diameter of, for example, 65 mm (2.5 inches), and includes magnetic recording layers formed individually on its upper and lower surfaces. The two magnetic disks 12a and 12b are coaxially fitted on a hub (not shown) of the spindle motor 13, clamped by a clamp spring 21, and stacked in layers at a given space in the axial direction of the hub. The magnetic disks 12a and 12b are rotated at a given speed by means of the spindle motor 13.

As shown in FIGS. 1 to 3, the head actuator 14 is

provided with a bearing assembly 24 that is fixed on the bottom wall of the casing 10. The bearing assembly 24, which serves as a bearing portion, includes a pivot 23 set up on the bottom wall of the casing 10 and a  
5 cylindrical hub 26 that is rotatably supported on the pivot by means of a pair of bearings. An annular flange 29 is formed on the upper end of the hub 26, and a thread portion (not shown) around the lower end portion of the hub.

10 Further, the head actuator 14 includes four arms 27a, 27b, 27c and 27d and two spacer rings 28a and 28b, which are mounted on the hub 26, and four magnetic head assemblies 30 supported on the arms, individually.

Each of the arms 27a to 27b is a thin flat sheet  
15 of a stainless-steel-based material, such as SUS304, having a thickness of about 250  $\mu\text{m}$ . A circular aperture 31 is formed in one end or proximal end of each arm.

Each magnetic head assembly 30 includes  
20 an elongate suspension 32 and a magnetic head 33 fixed to the suspension. The suspension 32 is formed of a plate spring with a thickness of 60 to 70  $\mu\text{m}$ , and its proximal end is fixed to the distal end of each corresponding one of the arms 27a to 27d by spot  
25 welding or adhesive bonding and extends from the arm.

Each magnetic head 33 includes a substantially rectangular slider (not shown) and a writing/reading MR

(magnetic reluctance) head formed on the slider, and is fixed to a gimbal portion that is formed on the distal end portion of the suspension 32. Further, each magnetic head 33 has four electrodes (not shown).

5 The suspension 32 may be formed of the same material as and integrally with the arm. Each suspension 32 and its corresponding arm constitute an arm according to the present invention.

As shown in FIGS. 2 and 3, each magnetic head 33  
10 of the head actuator 14 is connected electrically to a main FPC 42 (mentioned later) through a relay FPC 62. The relay FPC 62, which serves as a first flexible printed circuit board, is fixedly stuck on the respective surfaces of each arm and each suspension 32  
15 of the head actuator 14, and extends from the distal end of the suspension to the proximal end of the arm.

The relay FPC 62 is in the form of an elongate belt as a whole, the distal end of which is connected electrically to the magnetic head 33, and the proximal  
20 end portion of which constitutes a connecting portion 64. The relay FPC 62 includes a base layer of an insulating material such as polyimide, a conductor pattern of a copper foil on the base layer, and a solder resist layer formed over the whole conductor  
25 pattern on the base layer except pad portions.

The electrodes of the magnetic head 33 are soldered to the pad portions (not shown) on the distal

end portion of the relay FPC 62. Further, the connecting portion 64 of the relay FPC 62 includes a plurality of first contacts 65 that are formed by exposing parts of the conductor pattern, and is located  
5 adjacent to a side edge of the arm at the proximal end portion of the arm. Each connecting portion 64 includes six elongate first contacts 65, which extend in a direction substantially perpendicular to the longitudinal direction of the arm or to the side edge  
10 of the arm, and are arranged at given spaces in the longitudinal direction of the arm.

The four arms 27a, 27b, 27c and 27d, thus fitted with the magnetic head assembly 30 and the relay FPC 62 each, are stacked on the flange 29 and mounted on the  
15 hub 26 in a manner such that the hub is passed through their respective apertures 31. Further, the spacer rings 28a and 28b are fitted on the hub 26 in a manner such that they are sandwiched between the arms 27a and 27b and between the arms 27c and 27d, respectively.

20 The four arms 27a to 27d and the two spacer rings 28a and 28b that are fitted on the hub 26 are interposed between the flange 29 and a nut (not shown) that is screwed on the thread portion of the hub 26, and are fixedly held on the hub 26. Thus, the four  
25 arms 27a to 27d extend parallel to one another in the same direction from the hub 26 with given spaces between them.

The magnetic head assemblies 30 and the magnetic heads 33 that are mounted on the arms 27a and 27b are opposed to one another. Likewise, the magnetic head assemblies 30 and the magnetic heads 33 that are  
5 mounted on the arms 27c and 27d are opposed to one another. The arms 27a to 27d and the magnetic head assemblies 30 fixed thereon can rock integrally with the hub 26.

As shown in FIGS. 2 and 3, moreover, the  
10 respective connecting portions 64 of the relay FPC's 62 that are attached individually to the arms 27a and 27b are opposed to each other at the respective proximal end portions of the arms with a given space between them, and constitute a female connector 66 for the  
15 connection of the main FPC (mentioned later). Likewise, the respective connecting portions 64 of the relay FPC's 62 that are attached individually to the arms 27c and 27d are opposed to each other at the respective proximal end portions of the arms with  
20 a given space between them, and constitute another female connector 66 for the connection of the main FPC.

As shown in FIG. 2, each of the spacer rings 28a and 28b has an extending portion 21 that extends toward a side edge of the proximal end portion of its  
25 corresponding arm and close to the connecting portion 64 of the relay FPC 62. The extending portion 21 is formed having a pair of abutting portions 25 that

project to the side edge of the arm. These abutting portions 25 are spaced in the extending direction of the arm and situated individually on the opposite sides of the connecting portion 64. When the arms 27a to 27d and the spacer rings 28a and 28b are mounted on the hub 26 of the bearing assembly 24, therefore, the extending portion 21 and the abutting portions 25 of each spacer ring are situated surrounding the whole periphery of each corresponding two adjacent or opposite connecting portions 64 except the side edge portion of the arm. A tapped hole 25a for a male connector 44 (mentioned later) is formed in one of the abutting portions 25 of each of the spacer rings 28a and 28b.

The spacer ring 28b has a support frame 34 that extends in the direction opposite from the extending direction of the arms 27a to 27d, and is integrally formed of a synthetic resin or the like. A voice coil 36 that constitutes a part of the VCM 16 is embedded in the frame 34. Two pin-shaped third contacts 35 protrude from the frame 34 and are situated side by side with the female connectors 66. The third contacts 35 are connected electrically to the voice coil 36 by means of wires (not shown) that are embedded in the support frame 34.

When the head actuator 14 constructed in this manner is set in the casing 10, as seen from FIG. 1, the magnetic disk 12a is situated between the arms 27a

and 27b, while the disk 12b is situated between the arms 27c and 27d.

When the HDD is actuated, the magnetic heads 33 that are attached to the arms 27a and 27b are opposed  
5 individually to the upper and lower surfaces of the magnetic disk 12a, and hold the disk 12a from both sides. Likewise, the magnetic heads 33 that are attached to the arms 27c and 27d are opposed  
individually to the upper and lower surfaces of the  
10 magnetic disk 12b, and hold the disk 12 from both sides.

When the head actuator 14 is set in the casing 10, moreover, the voice coil 36 that is fixed to the support frame 34 is situated between a pair of yokes 38  
15 that are fixed on the casing 10. The yokes 38 and a magnet (not shown) that is fixed to one of the yokes constitute the VCM 16. When the voice coil 36 is energized, the head actuator 14 rocks, whereupon the magnetic heads 33 are moved to and positioned on  
20 desired tracks of the magnetic disks 12a and 12b.

As shown in FIGS. 1 to 4, the FPC unit 17 has a rectangular board body 40 that is fixed on the bottom wall of the casing 10, and a plurality of electronic components, connectors, etc. are mounted on the board  
25 body. Further, the FPC unit 17 includes the belt-shaped main flexible printed circuit board (referred to as main FPC) 42 that electrically connects

the board body 40 and the head actuator 14. The main FPC 42, which serves as a second flexible printed circuit board, extends from the board body 40. A male connector 44 for electrically connecting the main FPC 42 and the head actuator 14 is stuck on the rear surface of the extending end portion of the main FPC 42. The main FPC 42 is formed integrally with the board body 40.

The main FPC 42 includes a base film of an insulating material such as polyimide, a conductor pattern that is formed by patterning a copper foil formed on the base film, and a solder resist layer formed of an insulating material that covers the whole area of the conductor pattern and the base film except pad portions of the conductor pattern that are situated on the extending end portion the main FPC.

As shown in FIGS. 3 and 4, the conductor pattern of the main FPC 42 includes a number of conducting wires 45 that extend parallel to one another in the axial direction of the FPC. Further, the extending end portion of the main FPC 42 is formed having four connecting pad groups 46 corresponding to the magnetic heads 33 in number and two pad portions 47 that are to be connected to the voice coil 36. The pad groups 46 and the pad portions 47 connected to the board body 40 by means of the conducting wires 45, individually. Each connecting pad group 46 includes six connecting

pads corresponding to the electrodes of the magnetic head 33 and the poles of a head IC in number.

The connecting pads are spaced and arranged side by side in a straight line in the axial direction of the main FPC 42. Further, the extending end portion of the main FPC 42 is formed having a through hole 48, which is used in screwing the distal end portion of the FPC to the bearing assembly 24 of the head actuator 14.

As shown in FIGS. 3 to 5C, the male connector 44 that is attached to the extending end portion of the main FPC 42 includes a base 50 in the form of a rectangular plate and a pair of rectangular projections 52 that protrude from one surface of the base at right angles to it. The male connector 44 is integrally formed of an insulating material such as a synthetic resin. The base 50 has a thickness of about 0.5 mm, and is formed of a synthetic resin that contains glass in order to maintain its strength. The extending end portion of the main FPC 42 is stuck on the other surface of the base 50.

The paired projections 52 are formed having a size and shape such that they can be fitted individually into the female connectors 66 of the head actuator 14. They are arranged parallel to each other with a given space between them, and extend in the longitudinal direction of the main FPC 42. Each projection 52 has a pair of connecting surfaces 54 that extend

perpendicularly from the base 50 in the longitudinal direction of the main FPC 42. The connecting surfaces 54 are opposed to each other across a given space. Each connecting surface 54 is formed having six  
5 engaging grooves 55 that extend at right angles to the base 50 and are arranged at given spaces in the longitudinal direction of the main FPC 42.

Each engaging groove 55 is fitted with a second contact 56 in the form of an elongate rod for  
10 electrical connection with the relay FPC 62 of the head actuator 14. The second contacts 56 extend along the grooves 55 and slightly project from their corresponding connecting surfaces 54. Further, the second contacts 56 penetrate the base 50 and the main  
15 FPC 42 and project from the main FPC, and are soldered individually to their corresponding pad portions of the pad groups 46 of the main FPC. Thus, the second contacts 56, twelve in total number, on each projection 52 are connected electrically to the conductor pattern  
20 of the main FPC 42.

Furthermore, the male connector 44 is provided with fourth contacts 60 for current supply to the voice coil 36 and hybridized. More specifically, a pair of through holes 58 are formed in the base 50, and the  
25 fourth contacts 60 are arranged individually in the through holes so as to extend along their respective inner peripheral surfaces. The fourth contacts 60

penetrate the main FPC 42 and project from it, and are soldered individually to their corresponding pad portions 47 of the main FPC. Thus, the two fourth contacts 60 are connected electrically to the conductor pattern of the main FPC 42.

The base 50 of the male connector 44 is formed having a through hole 61 through which the male connector, along with the main FPC 42, is screwed to the head actuator 14. The through hole 61 is aligned with the through hole 48 of the main FPC.

In connecting the main FPC 42, fitted with the male connector 44 constructed in this manner, to the head actuator 14, the projections 52 are fitted into their corresponding female connectors 66, as shown in FIGS. 3, 6A, 6B and 7. The abutting portions 25 on the spacer rings 28a and 28b serve as guides for the insertion of the projections 52. Thereupon, each projection 52 is fitted in a manner such that it is situated in a predetermined position with respect to its corresponding female connector 66 or that it is positioned in the longitudinal direction of the arms by means of each pair of abutting portions 25. Thus, the second contacts 56 on each projection 52 are pressed against the opposite first contacts 65 of the female connector 66 to make electrical conduction, whereupon the relay FPC 62 and the main FPC 42 are connected electrically to each other.

As the male connector 44 is connected to the female connectors 66 of the head actuator 14, moreover, the two third contacts 35 that protrude from the support frame 34 are inserted and fitted into their corresponding through holes 58 of the male connector. Thus, the third contacts 35 are pressed against their corresponding fourth contacts 60 in the holes 58 to make electrical conduction, whereupon the voice coil 36 and the main FPC 42 are connected electrically to each other.

After the male connector 44 is connected to the head actuator 14, a screw 70 is driven into the tapped hole 25a in the one abutting portion 25 of the spacer ring 28b through the through hole 48 of the main FPC 42 and the through hole 61 of the male connector, whereby the male connector 44 is screwed to the bearing assembly 24. Thereupon, connecting the main FPC 42 to the head actuator 14 is finished.

According to the HDD constructed in this manner, the relay FPC 62 and the main FPC 42 can be connected electrically to each other by only inserting and fitting the projections 52 of the male connector 44 that is attached to the main FPC 42 into the spaces between the connecting portions 64 of the female connectors 66 that are attached to the head actuator 14. Thus, connecting these FPC's requires no soldering, and therefore, never contaminates the

atmosphere in a clean room. Further, no veteran skill is needed, and variation in workmanship can be lowered. In consequence, the assembly time can be shortened to improve the manufacturing efficiency and lower the manufacturing cost, and the reliability of connection can be improved.

Since the female connectors 66 are constructed by opposing the connecting portions 64 of the relay FPC's 62 that are attached individually to the arms, moreover, they can be automatically formed by attaching the arms to the bearing assembly 24. Since the abutting portions 25 of the spacer rings 28a and 28b can double as the respective housings of the female connectors 66, furthermore, no dedicated housings for the connectors are needed, so that the construction can be simplified.

The first and second contacts 65 and 56 can be accurately connected to one another by positioning the male connector 44 with respect to the female connectors 66 by means of the abutting portions 25 of the spacer rings 28a and 28b. Thus, the pitches of the contacts can be narrowed, so that the connectors can be miniaturized. Further, screwing can improve the reliability of prevention of disengagement that is attributable to vibration, shock, and rotation of the head actuator.

Furthermore, the female connectors 66 are provided

on the respective proximal end portions of the arms for rocking motion, and the male connector 44 is connected to the female connectors. Therefore, the center of gravity of the connectors can be situated close to the center of rotation of the head actuator 14, so that the moment of inertia can be lowered, and the accessing speed can be improved.

According to the embodiment described above, the male connector 44 is provided with the fourth contacts 60 for the connection between the voice coil 36 and the main FPC 42. Therefore, male connector 44 can be hybridized, and the relay FPC's 62 and the voice coil 36 can be connected to the main FPC 42 by means of only one connector. Thus, the main FPC 42 can be connected to the head actuator 14 entirely by connector-connection, so that the connecting operation can be made easier.

The following is a description of a head actuator 14 of an HDD according to a second embodiment of the invention and its structure for connection. Like reference numerals are used to designate like portions of the first and second embodiments, and a detailed description of those portions is omitted. Thus, only differences between the two embodiments will be described in detail below.

According to the second embodiment, as shown in FIGS. 8 to 10B, a support frame 34 of the head

actuator 14 is provided with a flexible printed circuit board for connection (hereinafter referred to as connecting FPC) 72 that is connected electrically to a voice coil 36. The connecting FPC 72 extends close to female connectors 66. A connecting portion having a third contact 35 is formed by exposing pad portions of a conductor pattern.

A male connector 44 has a pair of engaging projections 74 that protrude perpendicularly from a base 50 and are opposed to each other across a given space. A fourth contact 60 is fixed to the inner surface of each engaging projection 74. Each fourth contact 60 penetrates the base 50 and a main FPC 42 and projects from the main FPC. It is soldered to its corresponding pad portion of the main FPC. Thus, the two fourth contacts 60 are connected electrically to the conductor pattern of the main FPC 42.

When the male connector 44 constructed in this manner is connected to the female connectors 66 of the head actuator 14, a side edge portion of the support frame 34 of the support frame 34 on which the third contact 35 is provided is fitted in a fitting recess that is defined between the engaging projections 74. Thus, the fourth contacts 60 on the respective inner surfaces of the projections 74 are pressed against the third contact 35 on the support frame 34 to make electrical conduction, whereupon the voice coil 36 and

the main FPC 42 are connected electrically to each other.

The second embodiment arranged in this manner can enjoy the same functions and effects of the foregoing embodiment. If the male connector 44 is hybridized  
5 according to the second embodiment, moreover, it is necessary only that the contacts be redirected, so that the cost of the connectors can be lowered.

Additional advantages and modifications will  
10 readily occur to those skilled in the art. Therefore, the invention in its broader aspects is not limited to the specific details and representative embodiments shown and described herein. Accordingly, various modifications may be made without departing from the  
15 spirit or scope of the general inventive concept as defined by the appended claims and their equivalents.

According to the foregoing embodiments, for example, the arms are four in number. However, the number of the arms according to the invention is  
20 expected only be an even number, and may be two or six or more.



WHAT IS CLAIMED IS:

1. A connector for electrically connecting a pair of first flexible printed circuit boards, fixed individually on the respective surfaces of two arms spaced and opposed to each other and each extending from a distal end portion of each arm to a proximal end portion thereof, and a second flexible printed circuit board extending from any other portion than the arms toward the proximal end portions, the connector comprising:
  - a female connector formed of the first flexible printed circuit boards; and
  - a male connector provided at the second flexible printed circuit board,
  - the female connector including a pair of connecting portions formed on respective proximal-side end portions of the first flexible printed circuit boards and opposed to each other across a given space, each of the connecting portions having a first contact formed by exposing a part of a conductor pattern of the first flexible printed circuit board,
  - the male connector including a projection configured to be fitted between the connecting portions of the female connector, and second contacts provided on the projection and connected to a conductor pattern of the second flexible printed circuit board, the second contacts being arranged so as to contact with



the first contacts when the projection is fitted between the connecting portions.

2. A connector according to claim 1, wherein the male connector comprises a base in the formed of a  
5 plate of an insulating material having first and second surfaces opposite to each other, the extending end portion of the second flexible printed circuit board is fixed on the first surface of the base, the projection protrudes from the second surface of the base and has  
10 a pair of connecting surfaces opposed individually to the connecting portions of the female connector, and the second contact is provided on each connecting surface of the projection and connected to the conductor pattern of the second flexible printed  
15 circuit board through the base.

3. A connector according to claim 1, wherein each of the connecting portions of the female connector has a plurality of the first contacts extending across the extending direction of the arms and arranged at given  
20 spaces in the extending direction of the arms, the projection has a pair of connecting surfaces opposed individually to the connecting portions of the female connector, and the second contacts are provided individually on the connecting surfaces of the  
25 projection, corresponding to the first contacts.

4. A head actuator comprising:  
a bearing portion;



two arms each having a proximal end portion  
attached to the bearing portion, and a distal end  
portion supporting a head, extending from the bearing  
portion, the arms being opposed to each other across a  
5 given space;

first flexible printed circuit boards fixed  
individually on the respective arms, connected  
electrically to the respective heads, and extending  
from the heads to the proximal end portions of the  
10 arms;

a second flexible printed circuit board connected  
to the first flexible printed circuit boards; and

a male connector attached to the second flexible  
printed circuit board,

15 each of the first flexible printed circuit boards  
including a connecting portion provided at the proximal  
end portion of the arm and having a first contact  
formed by exposing a part of a conductor pattern of the  
first flexible printed circuit board,

20 the respective connecting portions on the two arms  
being opposed to each other across a given space to  
constitute a female connector,

the male connector including a projection  
configured to be fitted between the connecting portions  
25 of the female connector and second contacts provided on  
the projection and connected to a conductor pattern of  
the second flexible printed circuit board, the second



contacts being arranged so as to contact with the respective first contacts when the projection is fitted between the connecting portions.

5        5. A head actuator according to claim 4, wherein  
the male connector comprises a base in the formed of a  
plate of an insulating material having first and second  
surfaces opposite to each other, the extending end  
portion of the second flexible printed circuit board is  
fixed on the first surface of the base, the projection  
10 protrudes from the second surface of the base and has  
a pair of connecting surfaces opposed individually to  
the connecting portions of the female connector, and  
the second contact is provided on each connecting  
surface of the projection and connected to the  
15 conductor pattern of the second flexible printed  
circuit board through the base.

6. A head actuator according to claim 4, wherein  
each of the connecting portions of the female connector  
has a plurality of the first contacts extending across  
20 the extending direction of the arms and arranged at  
given spaces in the extending direction of the arms,  
the projection has a pair of connecting surfaces  
opposed individually to the connecting portions of the  
female connector, and the second contacts are provided  
25 individually on the connecting surfaces of the  
projection, corresponding to the first contacts.

7. A head actuator according to claim 4, wherein



the base is screwed to the bearing portion.

8. A head actuator according to claim 4, wherein the bearing portion includes a spacer held between the two arms, the spacer having an abutting portion  
5 configured to abut against the projection fitted in the female connector and to position the projection in the extending direction of the arms with respect to the female connector.

9. A head actuator according to claim 4, which  
10 further comprises a support frame extending from the bearing portion and mounted with a driving coil for rocking motion, and a third contact provided on the support frame and connected electrically to the coil, and wherein the male connector comprises a fourth  
15 contact connected to the conductor pattern of the second flexible printed circuit board and pressed against the third contact to connect the second flexible printed circuit board and the coil electrically to each other.

20 10. A head actuator according to claim 9, wherein the third contact is in the form of a pin protruding outward from the support frame, and the male connector has a hole in which the fourth contact is located and the third contact is fitted.

25 11. A head actuator according to claim 9, wherein the support frame has a second connecting portion, which further comprises a third flexible printed



circuit board connected electrically to the driving coil and extending to the second connecting portion of the support frame, and wherein the third contact is formed by exposing a part of the conductor pattern of the third flexible printed circuit board, and the male connector has a fitting recess in which the fourth contact is located and the second connecting portion of the support frame is fitted.

12. A disk drive comprising:

- 10 a disk;
- a head configured to write and read in and retrieving information from the disk;
- a head actuator supporting the head for movement with respect to the disk;
- 15 a substrate unit configured to input and output signals with respect to the head;
- a main flexible printed circuit board extending from the substrate unit and connected to the head actuator; and
- 20 a male connector attached to the main flexible printed circuit board,
- the head actuator including a bearing portion; two arms each having a proximal end portion attached to the bearing portion, and a distal end portion supporting
- 25 the head, extending from the bearing portion, the arms being opposed to each other across a given space; and relay flexible printed circuit boards fixed



individually on the respective arms, connected electrically to the respective heads, and extending from the heads to the proximal end portions of the arms;

5           each of the relay flexible printed circuit boards including a connecting portion provided at the proximal end portion of the arm and having a first contact formed by exposing a part of a conductor pattern of the relay flexible printed circuit board, the connecting  
10           portions being opposed to each other across a given space to constitute a female connector,

            the male connector including a projection configured to be fitted between the connecting portions of the female connector and second contacts provided on  
15           the projection and connected to a conductor pattern of the main flexible printed circuit board, the second contacts being arranged so as to contact with the respective first contacts when the projection is fitted between the connecting portions.

20           13. A disk drive according to claim 12, wherein the male connector comprises a base in the formed of a plate of an insulating material having first and second surfaces opposite to each other, the extending end portion of the main flexible printed circuit board is  
25           fixed on the first surface of the base, the projection protrudes from the second surface of the base and has a pair of connecting surfaces opposed individually to



the connecting portions of the female connector, and the second contact is provided on each connecting surface of the projection and connected to the conductor pattern of the main flexible printed circuit board through the base.

14. A disk drive according to claim 13, wherein each of the connecting portions of the female connector has a plurality of the first contacts extending across the extending direction of the arms and arranged at given spaces in the extending direction of the arms, the projection has a pair of connecting surfaces opposed individually to the connecting portions of the female connector, and the second contacts are provided individually on the connecting surfaces of the projection, corresponding to the first contacts.

15. A disk drive according to claim 12, which further comprises a support frame extending from the bearing portion and mounted with a driving coil for rocking motion, and a third contact provided on the support frame and connected electrically to the coil, and wherein the male connector comprises a fourth contact connected to the conductor pattern of the main flexible printed circuit board and pressed against the third contact to connect the main flexible printed circuit board and the coil electrically to each other.

16. A disk drive according to claim 15, wherein the third contact is in the form of a pin protruding



outward from the support frame, and the male connector has a hole in which the fourth contact is located and the third contact is fitted.

17. A disk drive according to claim 15, wherein  
5 the support frame has a second connecting portion,  
which further comprises a third flexible printed  
circuit board connected electrically to the driving  
coil and extending to the second connecting portion of  
the support frame, and wherein the third contact is  
10 formed by exposing a part of the conductor pattern of  
the third flexible printed circuit board, and the male  
connector has a fitting recess in which the fourth  
contact is located and the second connecting portion of  
the support frame is fitted.