

TITLE OF THE INVENTION
TIGHTENING DEVICE

BACKGROUND OF THE INVENTION

The present invention relates to tightening
5 devices for tightening up or loosening threaded members
such as hexagon socket head bolts, hexagon head bolts
and nuts, and more particularly to tightening devices
suitable for use in tightening up or loosening threaded
members for installing, for example, massflow
10 controllers which are to be provided in gas control
apparatus for fabricating semiconductors and which must
be held highly gastight.

Controllers such as massflow controllers which
are provided in such gas control apparatus for
15 fabricating semiconductors and which need to be given
high air- or gas-tightness include a member fastened to
a base plate with four bolts having a hexagon socket
head and arranged on one side of the member, usually
with a gasket or like seal disposed between the butting
20 faces. If the bolt tightening torque is too weak, a
faulty seal will result, whereas excessive torque
deforms the gasket to entail an improper seal, so that
each bolt needs to be tightened up with proper torque.
Further if one bolt only is tightened with a greater

force than the other bolts to result in uneven fastening, the gasket will be deformed to produce a faulty seal. The bolts must therefore be tightened up equivalently. It is also required that the bolts be loosened equivalently so that the gasket will not be deformed greatly to ensure reuse. In installing the massflow controller, accordingly, the bolts are first tightened manually, and one of the four bolts is then tightened with a wrench by a fraction of the required or specified amount of tightening. Next, the second bolt, which is positioned diagonally of the first bolt, is tightened by the same amount, the third bolt adjacent to the second bolt is subsequently tightened by the same amount, the fourth bolt positioned diagonally of the third bolt is tightened by the same amount, and the first bolt is thereafter tightened to repeat the same procedure as above. Thus, the bolts are tightened equivalently by a small amount at a time and eventually screwed up by the specified amount.

When to be loosened, the bolts are loosened in a specified order by a small amount at a time.

The following problems are encountered in tightening up or loosening threaded members by the conventional procedure using a wrench for hexagon head bolts.

1. The work of turning the bolts individually by a small amount at a time is cumbersome.

2. The amount the bolt is tightened at a time, if increased, facilitates the tightening work but
5 increases the possibility of deforming the gasket by uneven fastening, hence increased likelihood of making the seal faulty.

3. Although the angle through which the bolt is to be rotated by the wrench after manual tightening is
10 predetermined, the accuracy of the angle of rotation is insufficient because of the manual work involved. This entails the likelihood that the bolt will not be tightened up by the proper amount to cause a fault in the seal.

15 SUMMARY OF THE INVENTION

An object of the present invention is to provide a tightening device, for example, for use in installing or removing a massflow controller which is provided for a gas control apparatus for producing semiconductors
20 and which needs to be held highly gastight, the device being adapted to tighten up threaded members with proper torque without necessitating the cumbersome procedure of rotating the threaded members one by one through a specified small angle at a time and free of
25 the likelihood of producing a faulty seal.

The present invention provides a tightening device for tightening up a plurality of threaded members at the same time, the tightening device comprising a plurality of rotary shafts each provided at a forward end thereof with a wrench portion fittable to the threaded member, drive means for individually driving the rotary shafts, and control means for detecting the amount of tightening of each threaded member and the tightening torque thereof and controlling the drive means based on the values detected, the control means comprising drive stop means for discontinuing the drive upon the amount of tightening of each threaded member reaching a specified value based on the time when the tightening torque reaches a predetermined value, and judging means for judging each threaded member to be properly tightened in the case where the tightening torque of the threaded member is within a predetermined range, with the difference in tightening torque between the threaded members within a predetermined range, when the drive is discontinued.

With the tightening device of the invention, the judging means judges that the tightening torque of each threaded member is within a predetermined range upon the amount of tightening (e.g., the number of revolutions) of the threaded member reaching a

specified value to thereby assure that the threaded member as tightened is at a proper absolute level. Furthermore, the judging means judges whether the difference in tightening torque between the threaded members is within a predetermined range to thereby ensure that the threaded members are equivalently tightened. Consequently, only when the absolute level of each threaded member is within the specified limits without giving rise to unequivalent tightening or uneven fastening, the threaded members are judged to be properly tightened and can therefore be tightened up at the same time. Accordingly, the threaded members can be tightened up with proper tightening torque without necessitating the cumbersome procedure of rotating the threaded members one by one by a small amount at a time, with uneven fastening precluded.

The specified value for the amount of tightening is smaller than a proper value for the final amount of tightening. Preferably, the control means further comprises main tightening means for finally tightening up each threaded member to the proper value when the threaded member is judged to be properly tightened. Faults in tightening can then be detected early to discontinue the tightening operation before the seal member, for example, is broken.

The present invention provides a tightening device for tightening up a plurality of threaded members at the same time, the tightening device comprising a plurality of rotary shafts each provided at a forward
5 end thereof with a wrench portion fittable to the threaded member, drive means for individually driving the rotary shafts, and control means for detecting the amount of tightening of each threaded member and the tightening torque thereof and controlling the drive
10 means based on the values detected, the control means comprising drive stop means for discontinuing the drive upon the tightening torque of each threaded member reaching a predetermined value with the tightening amount within a specified range, and judging means for
15 judging each threaded member to be properly tightened in the case where the difference in tightening amount between the threaded members is within a predetermined range when the drive is discontinued.

With the tightening device of the invention,
20 tightening is completed upon the tightening torque of each threaded member reaching a predetermined value with the amount of tightening within a specified range to thereby assure that the threaded member as tightened is at a proper absolute level. Furthermore, the
25 judging means judges whether the difference in

tightening amount between the threaded members is within a specified range to thereby ensure that the threaded members are tightened equivalently.

Consequently, only when the absolute level of each threaded member is within the specified limits without giving rise to unequivalent tightening or uneven fastening, the threaded members are judged to be properly tightened and can therefore be tightened up at the same time. Accordingly, the threaded members can be tightened up with proper tightening torque without necessitating the cumbersome procedure of rotating the threaded members one by one by a small amount at a time, with uneven fastening precluded.

The predetermined value for the tightening torque is smaller than a proper value for final tightening torque. Preferably, the control means further comprises main tightening means for tightening up each threaded member until the proper final torque value is reached when the threaded member is judged to be properly tightened. Faults in tightening can then be detected early to discontinue the tightening operation before the seal member, for example, is broken.

Preferably, the control means further comprises excessive torque abnormality indicating means for discontinuing tightening and indicating abnormal

tightening upon the tightening torque of one of the threaded members reaching the predetermined value before the amount of tightening of the threaded member reaches a specified lower limit. Further preferably, 5 the control means comprises deficient torque abnormality indicating means for discontinuing tightening and indicating abnormal tightening when the tightening torque of one of the threaded members is below the predetermined value even if the amount of 10 tightening of the threaded member reaches a specified upper limit. Thus, when the torque is either excessive or deficient relative to the amount of tightening, an abnormality in tightening is indicated to discontinue tightening.

15 The drive means comprises motors for driving the respective rotary shafts. Each of the motors has a spur gear attached to a forward end of its drive shaft, and each of the rotary shafts has a pinion attached to a base end thereof and meshing with the spur gear. 20 Preferably, in this case, the spur gear is attached to the forward end of the motor drive shaft by a joint, with play provided between the joint and the motor drive shaft for permitting the spur gear to rotate slightly about the axis of the motor shaft relative to 25 the shaft. When the wrench portions are to be fitted

to the respective threaded members at the same time, the wrench portions are then rotatable and thereby made fittable with greater ease. The rotary shaft drive means may alternatively comprise a single motor which
5 is connected to the rotary shafts by respective clutches to drive all the rotary shaft or to stop one of the rotary shafts.

For example, two or four rotary shafts are provided. Two bolts which are positioned diagonally
10 can be tightened at the same time by the two rotary shafts. Four bolts as arranged at four corners can be tightened at the same time by the four shafts.

Each wrench portion has a forward end in the form of a hexagonal prism for hexagon socket head bolts.
15 The forward end is formed with a hexagon socket for hexagon nuts or hexagon head bolts.

Preferably, each wrench portion is connected to the rotary shaft movably axially thereof. When the wrench portions are to be fitted to the respective
20 threaded members at the same time, the wrench portions are then axially movable and thereby made fittable with greater ease.

Preferably, a coiled compression spring is provided for biasing the wrench portion so as to move
25 the wrench portion forward relative to the rotary

shaft. As the threaded member moves forward by being
screwed by the rotation of the wrench portion, the
compression spring expands to move the wrench portion
forward, so that the screw member can be tightened up
5 without pushing the body of the device forward.

The angle of rotation or displacement of the
threaded member is used as the amount of tightening
thereof. The angle of rotation of the threaded member
can be determined, for example, by an encoder. The
10 displacement of the threaded member can be determined
by a potentiometer, eddy current sensor or laser
displacement sensor. The tightening torque can be
determined, for example, by a strain gauge affixed to
the rotary shaft and a tightening torque detector for
15 converting the strain of the rotary shaft into torque.
Alternatively, the tightening torque can be determined
by a magnetostrictive torque sensor. The amount of
tightening of the threaded member can be determined
also from the number of revolutions of the motor. The
20 tightening torque can be calculated from the current
for driving the motor utilizing the fact that the
current exhibits the same tendency as the tightening
torque on a graph.

BRIEF DESCRIPTION OF THE DRAWINGS

25 FIG. 1 is a perspective view partly broken away

and showing a tightening device embodying the invention;

FIG. 2 is an enlarged exploded fragmentary perspective view of the same;

5 FIG. 3 is a view in vertical section showing the device and taken along a line in the middle of its width;

FIG. 4 is a view in section taken along the line 4-4 in FIG. 3;

10 FIG. 5 is a flow chart showing the primary routine of tightening up bolts in a bolt revolution number control mode using the device of the invention;

FIG. 6 is a flow chart of a pretightening routine in the same mode;

15 FIG. 7 is a flow chart of a main tightening routine in the same mode;

FIG. 8 is a graph of the relationship between the bolt revolution number and the bolt torque to show an overall checking procedure in the same mode;

20 FIG. 9 is a flow chart of the primary routine of tightening up bolts in a bolt tightening torque control mode using the device of the invention;

FIG. 10 is a is a flow chart of a pretightening routine in the same mode;

25 FIG. 11 is a flow chart of a main tightening

routine in the same mode; and

FIG. 12 is a graph of the relationship between the bolt revolution number and the bolt torque to show an overall checking procedure in the same mode.

5 DESCRIPTION OF THE PREFERRED EMBODIMENTS

Embodiments of the invention will be described below with reference to the drawings. In the following description, the term "forward end" refers to an end closer to the threaded member to be tightened up, and
10 the term "base end" to the other end. The terms "right" and "left" are used based on FIG. 3; the front side of the plane of the drawing will be referred to as "left," and the rear side thereof as "right."

FIGS. 1 to 4 show a tightening device 1 embodying
15 the invention. The device 1 is used for tightening up and loosening threaded members such as hexagon socket head bolts 44 for installing a massflow controller 42 for use in a gas control apparatus 41 shown in FIG. 1. The massflow controller 42 has a seal comprising a
20 gasket 43. Flanges 42a provided respectively at opposite sides of the controller 42 are each formed with four tapped bores 45, in which four hexagon socket head bolts 44 are screwed. The tightening device 1 is adapted to simultaneously tighten up two of the four
25 bolts 44 which are positioned diagonally.

The device 1 comprises a body 2, right and left motors 3 disposed inside the body 2, a spur gear 4 attached by a joint 5 to the forward end of the drive shaft 3a of each motor 3, right and left rotary shafts 6 each carrying at its base end a pinion 7 in mesh with the spur gear 4, right and left wrench portions 8 provided at the forward ends of the respective shafts 6, and a control unit 9 disposed inside the body 2 for controlling the motors 3.

10 The body is rectangular parallelepipedal and has a base end wall 2a, which is provided with a handle 23, connector 24, forward-reverse change-over switch 25 and on-off button switch 26.

 The joint 5 comprises a shaft portion 13 fixedly
15 fitted in a shaft hole of the spur gear 4, and a hollow cylindrical portion 14 integral with the shaft portion 13 coaxially therewith and having loosely fitted therein the drive shaft 3a of the motor 3. The shaft portion 13 extends through the spur gear 4 and has a
20 forward end rotatably supported by a forward end wall 2b of the body 2. The peripheral wall of the cylindrical portion 14 has opposed two U-shaped cutouts 15 extending from the base end thereof to a position close to the forward end thereof. The motor shaft 3a
25 has a parallel pin 16 fixedly extending through a

forward end portion of the shaft diametrically thereof and engaged in the cutouts 15 for transmitting the rotation of the motor 3 to the joint 5. The cutouts 15 have a width greater than the diameter of the parallel pin 16. Play is provided between the spur gear 4 and the shaft 3a of the motor 3 for permitting the gear 4 to idly rotate slightly relative to the motor shaft 3a.

The right and left rotary shafts 6 extend through the forward end wall 2b of the body 2 and are each rotatably supported at a portion thereof close to its based end by the forward end wall 2b of the body 2. A bearing portion 10 accommodating the opposite shafts 6 is joined to the forward end wall 2b of the body 2. Each rotary shaft 6 has at its forward end a small-diameter portion 11 coaxial with the shaft 6. A major part of the small-diameter portion 11 is projected out from the bearing portion 10. The portion 11 has two opposed guide grooves 12 extending longitudinally thereof and positioned close to the forward end thereof. Since the spur gear 4 plays relative to the drive shaft 3a of the motor 3, the rotary shaft 6 starts to rotate a short period of time after the start of rotation of the motor shaft 3a, following the rotation of the motor shaft 3a.

25. The wrench portion 8 comprises a hollow cylinder

17 having fitted therein approximately half forward part of the small-diameter portion 11 of the rotary shaft 6, and a hexagonal prism 18 joined to the forward end of the cylinder 17 and shaped in cross section in conformity with the hexagon socket of the bolt 44. The cylinder 17 has at its base end a large-diameter part 17a having a larger outside diameter than the other part of the cylinder 17. The peripheral wall of the large-diameter part 17a has two opposed tapped bores 20. With the tapped bores 20 opposed to the respective two guide grooves 12 in the small-diameter portion 11 of the rotary shaft 6, a stepped bolt 21 is screwed in each tapped bore 20. The stepped bolt 21 is formed by removing a distal end portion of a hexagon socket head bolt to provide a short solid cylindrical portion 21a with a diameter equal to the width of the guide groove 12. The short cylindrical portion 21a projects inward from the inner periphery of the large-diameter part 17a and is inserted in the groove 12. The wrench portion 8 is connected to the rotary shaft 6 by the stepped bolts 21 axially movably by an amount corresponding to the length of the guide grooves 12.

A coiled compression spring 19 is fitted in the hollow cylinder 17. The spring 19 is held between the forward end of the small-diameter portion 11 of the

rotary shaft 6 and the base end of the hexagonal prism 18, biasing the prism 18 into forward movement relative to the rotary shaft 6.

5 The hexagonal prism 18 of the wrench portion 8 is provided with a bolt holder 22 comprising three plate springs 22a. The portion of each spring 22a from the lengthwise middle thereof to its forward end is bent outward. The base ends of the springs 22a are each
10 brazed to one side face of the hexagonal prism 18 and are spaced apart by the intervening side face thereof. The forward ends of the three springs 22a are projected downward beyond the forward end of the hexagonal prism 18 and adapted to hold the hexagon socket head of the bolt 44.

15 The control unit 9 comprises, for example, a microcomputer and controls the motors 3 while judging whether each bolt 44 as tightened is at a proper level and also checking the bolts 44 for relative level to judge whether the bolts are equivalently tightened.

20 The judgment of whether each bolt 44 is properly tightened is made by judging whether the tightening torque of the bolt 44 has reached a predetermined value. The judgment of whether the bolts 44 are equivalently tightened is made by judging whether the
25 difference in the amount of tightening between the

bolts 44 is within a specified range when the tightening torque of each of the bolts 44 has reached the predetermined value. Conversely, the judgment of whether each bolt 44 is properly tightened is made by
5 judging whether the amount of tightening of the bolt 44 has reached a specified value, and the judgment of whether the bolts 44 are equivalently tightened is made by judging whether the difference in tightening torque between the bolts 44 is within a predetermined range
10 when the amount of tightening of each bolt 44 has reached the specified value.

The angle of rotation of the bolt 44 or the displacement thereof is used as the amount of tightening of the threaded member. The angle of
15 rotation of the bolt 44 can be determined, for example, by an encoder. The rotational angle of the bolt 44 can of course be determined from the angle of rotation of the rotary shaft 6. Alternatively, the angle of rotation can be detected by using a potentiometer and
20 converting an analog signal to an angle. The displacement of the bolt 44 can be determined by measuring the distance between the bolt 44 and the massflow controller 42 with a potentiometer, eddy current displacement sensor, laser displacement sensor
25 or the like.

The tightening torque can be determined by using a strain gauge affixed to the rotary shaft 6 and converting the strain of the shaft 6 by a tightening torque detector. Alternatively, the tightening torque can be determined by a magnetostrictive torque sensor. Further alternatively, the tightening torque can be calculated from the current for driving the motor 3 utilizing the fact that the current exhibits the same tendency as the tightening torque on a graph.

With the tightening device 1 described, the spur gear 4 is slightly rotatable relative to the drive shaft 3a of the motor 3, so that while the motor shaft 3a is at rest, the wrench portion 8 can be rotated manually by an amount corresponding to the play. The wrench portion 8 is movable also toward the base end against the compression spring 19. If the hexagonal prisms 18 of the wrench portions 8 are out of register with the respective hexagon sockets of the right and left bolts 44 already screwed in when the prisms 18 are to be fitted into the sockets, the wrench portion prisms 18 are simultaneously fittable into the respective bolts 44 by manually moving the wrench portions 8 toward the base ends against the compression springs 19 and manually rotating the prisms 18 slightly.

Two of the hexagon socket head bolts 44 can be tightened up at the same time by the tightening device 1 in the following manner.

First, the hexagonal prisms 18 of the right and
5 left wrench portions 8 are fitted into the hexagon sockets of the respective bolts 14, with each spring holder 22 caused to hold the bolt 14. Next, the bolts 44 are positioned in register with the respective tapped bores 45, with the handle 23 gripped by hand.
10 When the body 2 is pushed forward at this time, the springs 19 are compressed, permitting the base ends of the wrench portions 8 to come into striking contact with the forward end of the bearing portion 10, whereby the body 2 is halted. Subsequently, each motor 3 is
15 rotated by pressing the button switch 26, whereupon the wrench portion 8 rotates, screwing the bolt 44 into the tapped bore 45. As the bolt moves forward, the wrench portion 8 moves forward with the expansion of the compression spring 19, so that the body 2 need not be
20 pushed forward. The control unit 3 checks each bolt 44 for absolute level, that is, the unit 3 judges whether the tightening torque of each bolt 44 is within a predetermined range relative to the amount of
25 tightening, and also checks the bolts 44 for relative level, that is, the unit 3 judges whether the

difference in the amount of tightening between the bolts 44 and the difference in the tightening torque between the bolts 44 are within a specified range and predetermined range, respectively. Thus, the two bolts
5 44 are tightened up with equivalent and proper torque by driving the respective motors 3.

Two of the hexagon socket head bolts 44 as tightened up are removed at the same time in the following manner by the tightening device 1 after the
10 change-over switch 25 is actuated for reverse rotation.

First, the hexagonal prisms 18 of the right and left wrench portions 8 are fitted respectively into the hexagon sockets of the bolts 44, with the heads of the bolts 44 held by the respective bolt holders 22. At
15 this time, the wrench portion prisms 18 can be fitted into the sockets of the bolts 44 by holding the cylinder 17 of each wrench portion 8 by hand, moving the wrench portion 8 toward the base end against the spring 19 and, when required, rotating the wrench
20 portion 8 about its axis. The body 2 is moved not to a full extent but to such an extent as to leave a clearance between the base end of the wrench portion 8 and the forward end of the bearing portion 10. Next, the button switch 26 is pressed to rotate the motors 3,
25 whereupon the wrench portions 8 rotate to unscrew the

bolts 44 from the tapped bores 45. At this time, the body 2 need not be pushed toward the base end since each wrench portion 8 moves toward the base end as the bolt 44 moves toward the base end. When rotated at the same time, the motors 3 loosen the two bolts 44 through substantially the same angle of rotation without the likelihood that a great force will act only on one of the bolts 44 or locally on the gasket 43. This eliminates the likelihood that the bolt 44 or the gasket 43 will become unusable again owing to deformation.

In the tightening procedure, the bolts 44 may be manually screwed into the tapped bores 45 first, followed by tightening with the tightening device 1. At this time, the prisms 18 of the wrench portions 8 can be fitted into the sockets of the respective bolts 44 by holding the cylinder 17 of each wrench portion 8 by hand, moving the wrench portion 8 toward the base end against the spring 19 and, when required, rotating the wrench portion 8. After the wrench portion prisms 18 have been fitted respectively into the sockets of the two bolts 44, the body 2 is pushed forward and the button switch 26 is then pressed to rotate the motors 3. The control unit 9 checks the two bolts 44 not only for absolute level but also for relative level, causing

the motors 3 to tighten up the bolts 4 equivalently with proper torques.

In replacing the massflow controller 42 as installed in the gas control apparatus for producing
5 semiconductors as seen in FIG. 1, the wrench is interfered with by adjacent components, is not turnable freely in a sufficient space and encounters difficulty in loosening or tightening up the bolts, whereas the device 1 of the invention is usable if a space
10 permitting the insertion of the portion of the device forward from the body 2 is available, ensuring greatly facilitated work in loosening or tightening the bolts 44 in limited spaces.

While the device 1 described is adapted to tighten
15 up two bolts 44 at the same time, a device for simultaneously tightening up four bolts is readily available by using four sets of rotary shafts 6, wrench portions 8 and motors 3. In this case, the device tightens the four bolts while judging whether each
20 bolt as tightened is at a proper absolute level, and also judging for six combinations of bolts whether the difference in the amount of tightening or tightening torque between the bolts is in a specified or predetermined range. The tightening device 1 can be
25 adapted to tighten hexagon nuts or hexagon head bolts

by replacing each hexagonal prism 18 by a socket having a hexagon cavity. Although the embodiment described has two motors 3 for the respective two rotary shafts 6, a single motor may be usable as connected to the
5 rotary shafts by respective clutches for rotating both the rotary shafts and for holding one of the shafts out of rotation.

FIGS. 5 to 7 are flow charts showing one mode of practicing the method of tightening up four bolts
10 arranged at four corners of the member to be fastened using the tightening device 1 (bolt revolution number control mode). FIG. 8 shows the relationship between the bolt revolution number and the bolt torque, as established for two bolts positioned diagonally and
15 each provided with a spring washer when the bolts were tightened up normally.

With reference to FIG. 8, the bolt is tightened with constant small torque after the bolt starts to rotate and until the bolt comes into contact with the
20 spring washer. Upon the bolt coming into contact with the spring washer, the torque increases with an approximately constant gradient until the bolt intimately contacts the surface of the member to be fastened (flange). Upon the bolt coming into intimate
25 contact with the flange, the gradient of torque

increases, and the torque thereafter increases with the same gradient. Suppose the proper tightening torque upon the bolt coming into intimate contact with the flange is 10 kgf·cm, and the proper tightening torque
5 at the time of complete tightening is 30 kgf·cm.

With reference to FIG. 5, the primary routine of the tightening method in the bolt revolution number control mode will be described first.

First, the hardware of the microcomputer is
10 initialized to set the parameters, ports and memory for the start of operation (step 1). The start key is then pressed (step 2) to pretighten two of the four bolts which are positioned diagonally (step 3). In step 3, a bolt pretightening revolution number and start-point
15 torque are set first (step 4). Specified as the start point torque is a torque value immediately after the tightening torque starts to increase upon the bolt coming into contact with the spring washer. The predetermined bolt pretightening revolution number is
20 based on, and counted from, the revolution number giving this torque value and is a revolution number that brings the bolt into intimate contact with the flange (see FIG. 5). Subsequently based on the pretightening routine to be described below, the bolts
25 in the diagonal position are checked as to whether they

are pretightened properly (step 5).

When the bolts positioned diagonally (diagonal bolts) are judged to be pretightened properly, the tightening device 1 is removed from the diagonal bolts and then fitted to the other bolts positioned along the other or reverse diagonal line (reverse diagonal bolts). When the start key is then pressed (step 6), the reverse diagonal bolts are pretightened (step 7). Step 7 is similar to step 3; a bolt pretightening revolution number and start-point torque are set first (step 8). According to the pretightening routine, the reverse diagonal bolts are checked as to whether they are pretightened properly (step 9). Since the reverse diagonal bolts differ from the first diagonal bolts in tightening torque curve, the bolt pretightening revolution number and the start-point torque set are values determined for reverse diagonal bolts by actual tightening.

When the reverse diagonal bolts are completely pretightened, the device 1 is removed from these bolts and fitted to the first diagonal bolts. Depression of the start key (step 10) is followed by the main tightening of the diagonal bolts in accordance with the main tightening routine to be described below (step 11). The device 1 is then removed from the first

diagonal bolts and set on the reverse diagonal bolts. Depression of the start key (step 12) is followed by the main tightening of the reverse diagonal bolts according to the main tightening routine, whereby a
5 sequence of tightening operations is completed for the four bolts (step 13). Step 2 follows again to repeat the foregoing steps when another set of four bolts are to be tightened up.

In the foregoing process, the bolt is rotated at a
10 high speed for pretightening and at a low speed for main tightening. In the pretightening operation, the first half of the operation may be effected at a high speed, and the second half thereof at a low speed. Although the torque value at a time immediately after
15 the tightening torque starts to increase following the contact of the bolt with the spring washer is selected as the predetermined start-point torque, the predetermined torque may be the value at the time when the bolt is engaged in the tapped bore or the value
20 given when the bolt has been rotated by one turn or two turns.

Next, the pretightening routine of the tightening method will be described with reference to FIG. 6.

First, bolt (1) and bolt (2) are rotated at a high
25 speed for the start of tightening, and flags for torque

(1), torque (2), revolution number (1) and revolution number (2) are reset (step 21). The flags for torque (1) and torque (2) are set when the torque of bolt (1) and bolt (2) reaches a value not smaller than the
5 predetermined start-point torque. The flags for revolution number (1) and revolution number (2) are set when bolt (1) and bolt (2) are rotated at least to the predetermined pretightening revolution number.

Next, the flag for torque (1) is checked as to
10 whether it is set (step 22). When the flag is found to be set, whether the flag for torque (2) is set is checked (step 23). If the flag for torque (2) is found to be on, this is interpreted as indicating that bolt (1) and bolt (2) are both at the start point, and the
15 sequence proceeds to step 30. If the flag for torque (1) is not found to be on in step 22, the torque of bolt (1) is read (step 27) and checked as to whether it is not smaller than the predetermined start-point torque (step 28). When the torque is found to be not
20 smaller than the start-point torque in step 28, the flag for torque (1) is set, and tightening of bolt (1) is discontinued (step 29), followed by step 23. If the torque of bolt (1) is found to be smaller than the start-point value in step 28, step 23 directly follows.
25 If the flag for torque (2) is not found to be set in

step 23, the torque of bolt (2) is read (step 24) and checked as to whether it is not smaller than the start-point value (step 25). If the torque of bolt (2) is found to be at least the start-point value in step 25, the flag for torque (2) is set, and tightening of bolt (2) is discontinued (step 26), followed by step 22. If the torque of bolt (2) is found to be smaller than the start-point value in step 25, step 22 directly follows.

Upon the torque of one of the bolts reaching the predetermined value in the foregoing steps 22 to 29, tightening of that bolt is discontinued, and the other bolt is continuously tightened until the predetermined torque value is reached. With the two bolts thus tightened with the predetermined torque, the sequence proceeds to step 30 and the following for pretightening on the basis of the bolt revolution number.

In step 30 et seq., an inquiry is made as to whether the flag for revolution number (1) is set (step 30). If the answer is negative, tightening of bolt (1) is started (step 31), and the number of revolutions of bolt (1) is read (step 32). An inquiry is made as to whether the number is at least the predetermined pretightening revolution number (step 33). When the answer to the inquiry is affirmative, bolt (1) is judged to be pretightened normally, the flag for

revolution number (1) is set, and the tightening of bolt (1) is discontinued (step 34), followed by step 35. When the flag for revolution number (2) is not found to be set in step 35, step 36 starts to tighten
5 bolt (2), and the number of revolutions of bolt (2) is read (step 37). An inquiry is made as to whether the number is at least the predetermined pretightening revolution number (step 38). When the answer is affirmative, bolt (2) is judged to be pretightened
10 normally, the flag for revolution number (2) is set, and tightening of bolt (2) is discontinued (step 39), followed by step 30. If the flag for revolution number (2) is found on in step 35, this is interpreted as indicating that the pretightening revolution number
15 (absolute level) of each of bolts (1), (2) is within a predetermined range, followed by checking as to whether the bolts are tightened normally. First, an inquiry is made as to whether torque (1) is within a predetermined range (step 40). If the answer is negative, torque
20 abnormality is indicated (step 42), and the routine is changed over to a manual mode routine (step 49). If the answer is affirmative, an inquiry is made as to whether torque (2) is within the predetermined range (step 41). When the answer is negative, torque
25 abnormality is indicated (step 42), followed by a

change-over to the manual mode routine (step 49). When torque (1) and torque (2) are both within the predetermined range, torque (1) is compared with torque (2) (step 43). In the case where torque (1) is greater, torque (2) is subtracted from torque (1) to calculate the torque difference ΔT (step 44). If torque (1) is not greater than torque (2), torque (1) is subtracted from torque (2) to calculate the torque difference ΔT (step 45). An inquiry is then made as to whether the torque difference ΔT is within a predetermined range (step 46). When the answer is affirmative, this is interpreted as indicating that the bolts are tightened properly, and the sequence comes to an end (step 47). If the answer is negative, the bolts are judged to be tightened unequivalently, and an unequivalent tightening error is indicated (step 48), followed by a change-over to the manual mode routine (step 49).

Upon the torque of one of the bolts reaching the predetermined revolution number first in the foregoing steps 30 to 39, tightening of that bolt is discontinued, and the other bolt is continuously tightened until the predetermined revolution number is reached. With the two bolts thus tightened at least to the predetermined revolution number, the sequence

proceeds to step 40 and the following.

Next, the main tightening routine of the present tightening method will be described with reference to FIG. 7.

5 First, bolt (1) and bolt (2) are rotated at a low speed for the start of tightening, and flags for revolution number (1) and revolution number (2) are reset (step 51). The flags for revolution number (1) and revolution number (2) are set when bolt (1) and
10 bolt (2) are rotated at least to the predetermined main tightening revolution number. This number is an eventual bolt tightening revolution number based on and counted from the bolt pretightening revolution number. The flag for revolution number (1) is checked as to
15 whether it is set (step 52). If the flag for revolution number (1) is found to be on in step 52, the flag for revolution number (2) is checked as to whether it is on (step 53). If it is found to be on in step 53, the bolts are judged to be tightened properly to
20 terminate the routine.

In the case where the flag for revolution number (1) is not found to be on in step 52, revolution number (1) of bolt (1) is read, and an inquiry is made as to whether the number is at least the main tightening
25 revolution number (step 58). If the answer is

affirmative, main tightening of bolt (1) is judged to be effected normally, tightening of bolt (1) is discontinued (step 59), the flag for revolution number (1) is set (step 60), and step 53 follows to check whether the flag for revolution number (2) is set. If the revolution number (1) is smaller than the main tightening revolution number, bolt (1) is continuously tightened, followed by step 53 to check whether the flag for revolution number (2) is set. If the flag is not found to be on in step 53, revolution number (2) of bolt (2) is read, and an inquiry is made as to whether this number is at least the main tightening revolution number (step 55). If the answer is affirmative, main tightening of bolt (2) is judged to be effected normally, tightening of bolt (2) is discontinued (step 56), the flag for revolution number (2) is set (step 57), and the sequence returns to step 52 to check whether the flag for revolution number (1) is on. In this way, the flags for revolution numbers (1), (2) are eventually set, and the sequence proceeds to step 54 to terminate the routine.

Thus, the four bolts can be tightened up equivalently with proper torque using the device 1 for tightening two bolts at the same time.

Since the tightening torque is checked in the

pretightening routine as to whether the torque is within the predetermined range, it is not necessary to check in the main tightening torque whether the tightening torque is within a predetermined range, and
5 the program can be simplified by a corresponding amount. Whether the eventual torque is within the predetermined torque may of course be checked, or the main tightening routine may be performed in exactly the same manner as the pretightening routine.

10 FIGS. 9 to 11 are flow charts showing another mode (bolt tightening torque control mode) of the method of tightening four bolts at four corners of the member to be fastened by the tightening device. FIG. 12 shows a graph corresponding to the graph of FIG. 8 which shows
15 the relationship between the bolt revolution number and the bolt torque and in which the scales of abscissa and ordinate are altered in conformity with the present mode of tightening method. It is seen that when rotated n turns, the bolt comes into intimate contact
20 with the flange, and the proper tightening torque (pretightening torque) at this time is 10 kgf·cm.

With reference to FIG. 9, a description will be given first of the primary routine of the tightening method in the bolt tightening torque control mode.

25 First, the hardware of the microcomputer is

initialized to set the parameters, ports and memory for the start of operation (step 1). The start key is then pressed (step 2) to pretighten two of the four bolts which are positioned diagonally (step 3). In step 3, a
5 predetermined bolt pretightening revolution number and predetermined diagonal bolt torque are set (step 4). In connection with the predetermined revolution number which is based on one revolution of the bolt, a required range is added to obtain a predetermined upper
10 limit of revolution numbers and a predetermined lower limit thereof for use as reference values. The predetermined torque is the tightening torque resulting from exactly one revolution of the bolt. According to the pretightening routine to be described below, an
15 inquiry is then made as to whether the tightening torque for the first revolution of the bolt is within the range of predetermined torque (step 5). If the answer is affirmative, an inquiry is made as to whether the tightening torque has reached the pretightening
20 torque (10 kgf·cm) (step 6). When the pretightening torque is not reached, the next predetermined bolt revolution number and predetermined diagonal bolt torque are set (step 7), followed by step 5. The predetermined bolt revolution number is based on one
25 revolution of the bolt, predetermined torque is set for

each revolution of the bolt. The pretightening routine of step 5 is repeated until the bolt is rotated n turns. Incidentally, in the second half of the pretightening procedure, the predetermined bolt revolution number may be based, for example, on half turn to increase the checking frequency and obtain a more accurate result. When no abnormality occurs in the pretightening routine, the tightening torque reaches the pretightening torque (10 kgf·cm), and the pretightening of step 3 for the diagonal bolts is completed.

The tightening device 1 is removed from the diagonal bolts and then set on the reverse diagonal bolts. Depression of the start key (step 8) starts pretightening of the reverse diagonal bolts (step 9). In step 9 which is the same as step 3, a predetermined bolt revolution number and predetermined torque for the reverse diagonal bolts are set (step 10). According to the pretightening routine, the tightening torque is checked as to whether it is in the range of predetermined torque (step 11). If the result is acceptable, an inquiry is made as to whether the tightening torque has reached the pretightening torque (10 kgf·cm) (step 12). When the pretightening torque is not reached, the next predetermined bolt revolution

number and predetermined torque for the reverse diagonal bolts are set (step 13), followed by pretightening routine of step 11. When no abnormality occurs in the pretightening routine, the tightening torque reaches
5 the pretightening torque (10 kgf·cm), and the pretightening of step 9 for the reverse diagonal bolts is completed. As to the predetermined torque values in steps 10 and 13, the first diagonal bolts differ from the reverse diagonal bolts in torque curve, so that
10 torques are predetermined based on the actual result of tightening operation for the reverse diagonal bolts.

When the reverse diagonal bolts are completely pretightened, the device 1 is removed from these bolts and fitted to the first diagonal bolts. Depression of
15 the start key (step 14) is followed by the main tightening of the diagonal bolts in accordance with the main tightening routine to be described below (step 15). The diagonal bolts are tightened in step 15 with main tightening torque (30 kgf·cm). The device 1 is
20 then removed from the first diagonal bolts and set on the reverse diagonal bolts. Depression of the start key (step 16) is followed by the main tightening of the reverse diagonal bolts according to the main tightening routine, and the reverse diagonal bolts are tightened
25 with the main tightening torque (30 kgf·cm), whereby a

sequence of tightening operations is completed for the four bolts (step 17). Step 2 follows again to repeat the foregoing steps when another set of four bolts are to be tightened up.

5 In the foregoing process, the bolt is rotated at a high speed for pretightening and at a low speed for main tightening. In the pretightening operation, the first half of the operation may be effected at a high speed, and the second half thereof at a low speed.

10 Next, the pretightening routine of the tightening method will be described with reference to FIG. 10.

 First, bolt (1) and bolt (2) are rotated at a high speed for the start of tightening, and flags for torque (1) and torque (2) are reset (step 21). The flags for
15 torque (1) and torque (2) are set when the torque of bolt (1) and bolt (2) becomes not smaller than a value corresponding to a predetermined revolution number. Next, an inquiry is made as to whether the flag for torque (1) is set (step 22). If the answer is
20 affirmative, the flag for torque (2) is checked as to whether it is set (step 23).

 If the flag for the torque (2) is on, this indicates that the absolute level of tightening torque of bolts (1) and (2) is within a predetermined range,
25 followed by checking of relative level. More

specifically, revolution number (1) of bolt (1) is compared with revolution number (2) of bolt (2) (step 24). If the number (1) is greater, the number (2) is subtracted from the number (1) to calculate the
5 difference ΔP in bolt revolution number (step 25). If the number (1) is not greater than the number (2), the number (1) is subtracted from the number (2) to determine the difference ΔP in bolt revolution number (step 26). An inquiry is then made as to whether the
10 bolt revolution number difference ΔP is within a predetermined range (step 27). When the answer is affirmative, the bolts are judged to be properly tightened, whereupon the sequence comes to an end (step 42). When the answer to the inquiry of step 27 is
15 negative, bolts are judges to be unequivalently tightened, and an unequivalent tightening error is indicated (step 43), followed by a change-over to a manual mode routine (step 45).

If the flag for torque (1) is not found to be on
20 in step 22, revolution number (1) is read, and an inquiry is made as to whether the number is at least the predetermined revolution number lower limit (step 35). When the answer to the inquiry of step 35 is affirmative, an inquiry is further made as to whether
25 revolution number (1) is up to the predetermined

revolution number upper limit (step 36). If the answer to the inquiry of step 36 is affirmative, torque (1) of bolt (1) is read (step 37) and checked as to whether torque (1) is not lower than the predetermined torque (step 38). When torque (1) is not lower than the predetermined torque, this is interpreted as indicating that bolt (1) is normally tightened, tightening of bolt (1) is discontinued (step 39), the flag for torque (1) is set (step 40), and the sequence proceeds to step 23 wherein flag (2) is checked as to whether it is set. If torque (1) is found to be lower than the predetermined torque in step 38, an inquiry is made in step 23 as to whether the flag for torque (2) is set, with bolt (1) continuously tightened. If revolution number (1) is found to be lower than the predetermined lower limit in step 35, torque (1) is read, and an inquiry is made as to whether it is up to the predetermined torque (step 41). When the answer is affirmative, step 23 follows in which the flag for torque (2) is checked as to whether it is set, with bolt (1) continuously tightened. If the answer to the inquiry of step 41 is negative, this is interpreted as indicating that torque (1) has reached the predetermined torque before revolution number (1) reaches the predetermined lower limit, whereupon

abnormal torque is indicated (step 44), followed by a change-over to the manual mode routine (step 45).

In the case where the flag for torque (2) is not found to be on in step 23, revolution number (2) is
5 read, followed by the same procedure as steps 35 to 41 for bolt (1). More specifically, an inquiry is made as to whether revolution number (2) is at least the predetermined revolution number lower limit (step 28). When the number (2) is at least the predetermined
10 revolution number lower limit, an inquiry is further made as to whether revolution number (2) is up to the predetermined revolution number upper limit (step 29). If the answer to the inquiry of step 29 is affirmative, torque (2) of bolt (2) is read (step 30) and checked as
15 to whether torque (2) is not lower than the predetermined torque (step 31). When torque (2) is not lower than the predetermined torque, this is interpreted as indicating that bolt (2) is normally tightened, tightening of bolt (2) is discontinued (step
20 32), the flag for torque (2) is set (step 33), and the sequence returns to step 22 wherein the flag for torque (2) is checked as to whether it is set. If torque (2) is found to be lower than the predetermined torque in step 31, the sequence returns to step 22 in which the
25 flag for torque (1) is checked as to whether the flag

set, with bolt (1) continuously tightened. If revolution number (2) is found to be lower than the predetermined lower limit in step 28, torque (2) is read, and an inquiry is made as to whether it is up to the predetermined torque (step 34). When the answer is affirmative, step 22 follows again in which the flag for torque (1) is checked as to whether it is set. If the answer to the inquiry of step 34 is negative, this is interpreted as indicating that torque (2) has reached the predetermined torque before revolution number (2) reaches the predetermined lower limit, whereupon torque abnormality is indicated (step 44), followed by a change-over to the manual mode routine (step 45).

When torque (1) and torque (2) are not abnormal, the flags for torque (1) and torque (2) are both eventually set, followed by step 24 in which revolution number (1) is compared with revolution number (2) for the checking of relative level.

For example if torque (1) of bolt (1) reaches the predetermined torque first in the pretightening routine described, tightening of bolt (1) is discontinued, and bolt (2) only is tightened. Accordingly, bolt (1) is unlikely to be overtightened. Upon revolution number (2) of bolt (2) exceeding the predetermined upper limit

before torque (2) reaches the predetermined torque, the bolts are judged to be unequivally tightened.

Further if torque (2) reaches the predetermined torque before revolution number (2) of bolt (2) reaches the
5 predetermined upper limit, the bolts are judged to be unequivally tightened in step 27 in the case where revolution number (2) of bolt (2) is excessively greater than that of bolt (1). Further even with torques (1), (2) of bolts (1), (2) reaching the
10 predetermined torque, an abnormality is recognized in step 34 or 41 if revolution number (1) or (2) is below the predetermined lower limit in this case. This eliminates the likelihood of the operator forgetting to insert the gasket to be installed in the sealed
15 portion. Thus, the bolt is judged to be properly tightened only when the predetermined torque is reached, with the revolution number within the predetermined limits. When the bolts are thus found properly tightened, the sequence proceeds to the
20 subsequent step.

Next, the main tightening routine of the present tightening method will be described with reference to FIG. 11.

First, bolt (1) and bolt (2) are rotated at a low
25 speed for the start of tightening, and flags for torque

(1) and torque (2) are reset (step 51). The flags for torque (1) and torque (2) are set when the torque of bolt (1) and bolt (2) increases least to the predetermined final tightening torque value. The flag
5 for torque (1) is subsequently checked as to whether it is set (step 52). If the flag is found on in step 52, the flag for torque (2) is checked as to whether it is on (step 53). If it is found to be on in step 53, the bolts are judged to be tightened properly to terminate
10 the routine (step 54).

In the case where the flag for torque (1) is not found to be on in step 52, torque (1) of bolt (1) is read (step 59), and an inquiry is made as to whether the torque is at least the final tightening torque
15 value (step 60). If the answer to the inquiry of step 60 is affirmative, main tightening of bolt (1) is judged to be effected normally, tightening of bolt (1) is discontinued (step 61), the flag for torque (1) is set (step 62), and step 53 follows to check whether the
20 flag for torque (2) is set. If the torque (1) is smaller than the final tightening torque in step 60, bolt (1) is continuously tightened, followed by step 53 to check whether the flag for torque (2) is set. If the flag is not found to be on in step 53, torque (2) of
25 bolt (2) is read (step 55), and an inquiry is made as

to whether the torque is at least the final tightening torque value (step 56). If the answer to the inquiry of step 56 is affirmative, main tightening of bolt (2) is judged to be effected normally, tightening of bolt
5 (2) is discontinued (step 57), the flag for torque (2) is set (step 58), and the sequence returns to step 52 to check whether the flag for torque (1) is on. If the torque (2) is smaller than the final tightening value in step 56, step 52 follows again to check whether the
10 flag for torque (1) is set, with bolt (2) continuously tightened. In this way, the flags for torques (1), (2) are eventually set, and the sequence proceeds to step 54 to terminate the routine.

The pretightening routine increases the torque of
15 the bolt to the predetermined torque, with the number of revolutions thereof within the predetermined range, so that it is unnecessary to check in the main tightening routine whether the revolution number is within the predetermined range. This serves to
20 simplify the program by a corresponding amount. The final revolution number may be checked as to whether it is within a predetermined range, or the main tightening routine may of course be performed in exactly the same manner as the pretightening routine.

25 The four bolts can be tightened up equivalently

with proper torque by the above mode of tightening method in the same manner as in the bolt revolution number control mode using the device 1 for tightening two bolts at the same time.

- 5 According to the tightening method as practiced in the bolt tightening torque control mode unlike the bolt revolution number control mode, the bolt is checked in the initial stage of tightening and subsequently several times as to whether it is tightened properly.
- 10 The torque control mode therefore has the advantage that abnormalities in tightening are detectable early to preclude the deformation of the bolts and the member to be fastened.

- Although the tightening method as practiced in
- 15 either of the two modes comprises a pretightening routine and main tightening routine separate therefrom, the entire tightening operation may be carried out in the same manner as the pretightening routine shown in FIG. 6 or 10 without resorting to the main tightening
- 20 routine. The flow chart of FIG. 6 or 10 is concerned with a case where two bolts are tightened up, whereas the flow chart can be readily expanded for tightening up three or four bolts. Three or four bolts can be tightened up at the same time according to the expanded
- 25 flow chart. Although the device 1 described is adapted

to tighten up two bolts 44 at the same time, a multishaft tightening device is readily available for tightening up three or four bolts at the same time by using three or four sets of rotary shafts 6, wrench portions 8 and motors 3. Three or four bolts can be tightened up simultaneously by using the multishaft device. For example, four bolts can be tightened at the same time by using a four-shaft tightening device and using a method of tightening the four bolts while checking these bolts for absolute level and relative level. With this method of tightening up threaded members, it is also possible to tighten up the members at a time until the eventual tightening torque is reached with the pretightening procedure omitted, hence a simplified tightening procedure. On the other hand, the tightening device 1 described in detail and adapted to simultaneously tighten up two bolts has the advantage of being simpler in construction and in control program than is the case with the method of tightening four threaded members.



What is claimed is:

1. A tightening device for tightening up a plurality of threaded members at the same time, the tightening device comprising a plurality of rotary
5 shafts each provided at a forward end thereof with a wrench portion fittable to the threaded member, drive means for individually driving the rotary shafts, and control means for detecting the amount of tightening of each threaded member and the tightening torque thereof
10 and controlling the drive means based on the values detected, the control means comprising drive stop means for discontinuing the drive upon the amount of tightening of each threaded member reaching a specified value based on the time when the tightening torque
15 reaches a predetermined value, and judging means for judging each threaded member to be properly tightened in the case where the tightening torque of the threaded member is within a predetermined range, with the difference in tightening torque between the threaded
20 members within a predetermined range, when the drive is discontinued.

2. A tightening device as defined in claim 1 wherein the specified value for the amount of tightening is smaller than a proper value for the final
25 amount of tightening, and the control means further



comprises main tightening means for finally tightening up each threaded member to the proper value when the threaded member is judged to be properly tightened.

3. A tightening device for tightening up a
5 plurality of threaded members at the same time, the tightening device comprising a plurality of rotary shafts each provided at a forward end thereof with a wrench portion fittable to the threaded member, drive means for individually driving the rotary shafts, and
10 control means for detecting the amount of tightening of each threaded member and the tightening torque thereof and controlling the drive means based on the values detected, the control means comprising drive stop means for discontinuing the drive upon the tightening torque
15 of each threaded member reaching a predetermined value with the tightening amount within a specified range, and judging means for judging each threaded member to be properly tightened in the case where the difference in tightening torque between the threaded members is
20 within a predetermined range when the drive is discontinued.

4. A tightening device as defined in claim 3 wherein the predetermined value for the tightening torque is smaller than a proper value for final
25 tightening torque, and the control means further



comprises main tightening means for tightening up each threaded member until the proper final torque value is reached when the threaded member is judged to be properly tightened.

5 5. A tightening device as defined in claim 3 wherein the control means further comprises excessive torque abnormality indicating means for discontinuing tightening and indicating abnormal tightening upon the tightening torque of one of the threaded members
10 exceeding the predetermined value before the amount of tightening of the threaded member reaches a specified lower limit.

 6. A tightening device as defined in claim 5 wherein the control means further comprises deficient
15 torque abnormality indicating means for discontinuing tightening and indicating abnormal tightening when the tightening torque of one of the threaded members is below the predetermined value even if the amount of tightening of the threaded member reaches a specified
20 upper limit.

 7. A tightening device as defined in any one of claims 1 to 6 which is characterized in that the drive means comprises motors for driving the respective rotary shafts, each of the motors having a spur gear
25 attached to a forward end of a drive shaft thereof, and



each of the rotary shafts having a pinion attached to a base end thereof and meshing with the spur gear.

8. A tightening device as defined in claim 7 which is characterized in that the spur gear is attached to the forward end of the motor drive shaft by a joint, with play provided between the joint and the motor drive shaft for permitting the spur gear to rotate slightly about an axis of the motor shaft relative to the shaft.

9. A tightening device as defined in any one of claims 1 to 6 which is characterized in that the wrench portion is connected to the rotary shaft movably axially thereof.

10. A tightening device as defined in claim 9 which is characterized in that a coiled compression spring is provided for biasing the wrench portion so as to move the wrench portion forward relative to the rotary shaft.