

Abstract

An unmanned aircraft 1 according to an embodiment of the present invention provides an unmanned aircraft that properly makes a forced landing in case of an abnormality. The unmanned aircraft 1 is configured as a multicopter that flies with lift and thrust generated by rotation of six rotors 13. The unmanned aircraft 1 identifies a forced landing site in a case of having detected an abnormality during flight and controls motors 12 configured to drive the respective rotors 13, to make a landing at the identified forced landing site. The unmanned aircraft 1 is consequently enabled to make an autonomous forced landing at a specific site in case of an abnormality.

FIG. 1