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(54) Title: METHOD AND CONTROL DEVICE FOR CONTROLLING DRIVING OPERATION OF AN ARTICULATED TRACKED VEHICLE

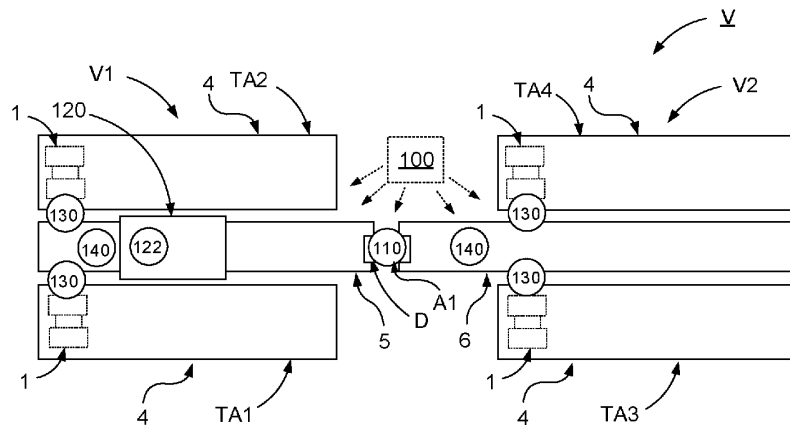


Fig. 4b

(57) Abstract: The present invention relates to a method (M1) performed by a control device (100) for controlling driving operation of an articulated tracked vehicle (V). Said articulated tracked vehicle (V) comprises a drive arrangement (120) for operating the vehicle. The articulated tracked vehicle (V) comprises a first vehicle unit (V1) and a second vehicle unit (V2) steerably connected to the first vehicle unit (V1) by means of a steering device (D) for mutually pivoting said vehicle units (V1, V2). The mutual pivoting comprises steering movement about a steering axis (Y). The steering device (D) comprises a steering arrangement (A1) for said steering movement. The method comprises the step of controlling (S1) the steering arrangement (A1) of the steering device (D) so as to control mutual steering movement of said vehicle units (V1, V2) for dynamic stability control. The present invention also relates to a control device for controlling driving operation of an articulated tracked vehicle. The present invention also relates to a computer program and a computer readable medium.

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