

SMIF CONTAINER LATCH MECHANISM

CLAIM OF PRIORITY

This application claims priority to Provisional patent application Serial No. 60/217,204, filed July 10, 2000, entitled SMIF Container With Latch Lock Mechanism.

BACKGROUND OF THE INVENTIONField of the Invention

The present invention relates to the transfer of workpieces such as semiconductor wafers within a storage and transport pod, and in particular to a latch locking mechanism preventing unwanted opening of the pod.

Description of Related Art

A SMIF system proposed by the Hewlett-Packard Company is disclosed in U.S. Patent Nos. 4,532,970 and 4,534,389. The purpose of a SMIF system is to reduce particle fluxes onto semiconductor wafers during storage and transport of the wafers through the semiconductor fabrication process. This purpose is accomplished, in part, by mechanically ensuring that during storage and transport, the gaseous media (such as air or nitrogen) surrounding the wafers is essentially stationary relative to the wafers, and by ensuring that particles from the ambient environment do not enter the immediate wafer environment.

A SMIF system has three main components: (1) minimum volume, sealed pods used for storing and transporting wafers and/or wafer cassettes; (2) an input/output (I/O) minienvironment located on a semiconductor processing tool to provide a miniature clean space (upon being filled with clean air) in which exposed wafers and/or wafer cassettes may be transferred to and from the interior of the processing tool; and (3) an interface for transferring the wafers and/or wafer cassettes between the SMIF pods and the SMIF minienvironment without exposure of the wafers or cassettes to particulates. Further details of one proposed SMIF system are described in the paper entitled "SMIF: A TECHNOLOGY FOR WAFER CASSETTE TRANSFER IN VLSI

MANUFACTURING," by Mihir Parikh and Ulrich Kaempf, Solid State Technology, July 1984, pp. 111-115.

5 Systems of the above type are concerned with particle sizes which range from below 0.02 microns (μm) to above 200 μm . Particles with these sizes can be very damaging in semiconductor processing because of the small geometries employed in fabricating semiconductor devices. Typical advanced semiconductor processes today employ geometries which are one-half μm and under. Unwanted contamination particles which have geometries measuring greater than 0.1 μm substantially interfere with 1 μm geometry semiconductor devices. The trend, of course, is to have smaller and smaller semiconductor processing geometries which today in research and development labs approach 0.1 μm and below. In the future, geometries will become smaller and smaller and hence smaller and smaller contamination particles and molecular contaminants become of interest.

15 SMIF pods are in general comprised of a pod door which mates with a pod shell to provide a sealed environment in which wafers may be stored and transferred. So called "bottom opening" pods are known, where the pod door is horizontally provided at the bottom of the pod, and the wafers are supported in a cassette which is in turn supported on the pod door. It is also known to provide "front opening" pods, in which the pod door is located in a vertical plane, and the wafers are supported either in a cassette mounted within the pod shell, or to shelves mounted directly in the pod shell itself.

20 In order to transfer wafers between a SMIF pod and a process tool in a bottom opening system, a pod is typically loaded either manually or automatedly onto a load port on a front of the tool so that the pod door lies adjacent the port door of the process tool. Thereafter, mechanisms within the load port decouple the pod door from the pod shell and lower the pod door and port door together into the minienvironment, with a wafer carrying cassette remaining seated on the pod door. The pod shell remains in position against the interface port to maintain a seal at the port and to define a sealed, clean environment including the interior of the process tool and pod shell. A wafer handling robot within the process tool may thereafter access particular wafers supported in the pod shell for transfer between the pod and the process tool.

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During wafer storage and transport, the pod door is typically held affixed to the pod shell by one of two different latch assemblies. In a first system, referred to herein as a perimeter latch assembly, four independently operated latches are mounted to a bottom perimeter of the pod shell, with an engagement portion of each latch extending inward
5 under the pod door to maintain the pod door in a sealed position in the pod. When it is desired to separate the pod door from the pod shell, each of the four latches is actuated outwardly, to withdraw each engagement portion from under the pod door, at which time the pod door may be separated. Each of the latches needs to be actuated outward to disengage the pod door from the pod shell. In conventional perimeter latch systems, the
10 latches may be disengaged manually, or the pod may be seated on a load port or other support surface including four actuation pins. The pins fit into slots formed on each of the latches, and, after the pod is properly positioned on the support surface, the actuation pins move the each of the latches outward to withdraw the engagement portion of each latch from under the pod door. Thereafter, the pod door may be separated from the pod
15 shell.

A single latch of a perimeter latch lock assembly is shown in prior art Fig. 1. As explained above, a latch 20 is mounted on the lower perimeter of pod shell 22, and includes an engagement portion 24 extending under the pod door 26. The latch 20 may be actuated either manually or by means of a pin (not shown) on a support surface
20 engaged within slot 28 so as to move to the left from the perspective of Fig. 1. Once the latch 20 is moved sufficiently so that engagement portion 24 is clear of the pod door (and the other latches are similarly actuated, the pod door may be separated from the pod shell. The latch may be biased into sealing position shown in Fig. 1 by a spring or other biasing scheme, such as leaf spring 30 shown in Fig. 1.

25 A second type of latch assembly (not shown) is disclosed in United States Patent No. 4,995,430, entitled "Sealable Transportable Container Having Improved Latch Mechanism", to Bonora et al., which patent is owned by the assignee of the present application. The mechanism disclosed therein includes a latch hub centrally mounted within the pod door, which latch hub engages with first and second translating latch
30 plates. The latch plates include ends which extend beyond the footprint of the pod door

and into slots in the pod shell. When the latch plates are in an extended position, the ends fit into the slots in the pod shell to seal the pod. When the latch plates are in a retracted position, the ends of the latch plates withdraw into the footprint of the pod door to allow separation of the pod door from the pod shell. When a pod including this type of latch assembly is mounted on a load port or other such support surface, mechanisms within the support surface rotate the hub to move the latch plates between their extended and retracted positions.

In the perimeter latch assembly, it can happen that an operator manually disengages each of the latches to open the pod when in fact the pod should not be opened. Such unwanted pod openings can lead to contamination of the workpieces within the pod and/or an improper exchange of one workpiece lot for another within the pod.

BRIEF SUMMARY OF THE INVENTION

The present invention includes a latch mechanism for latching a first member to a second member, such as a pod door to a pod shell in a semiconductor environment. The latch mechanism includes a latch lock mounted to the first member, comprising a finger portion and an angled portion. A latch is mounted to the first member, adapted to move between a latched position and an unlatched position. The latch has an engagement portion that contacts a portion of the second member when the latch is in the latched position, so as to maintain contact between the first and second members. The latch also has a slot for receiving the finger of the latch lock. An actuation pin is positioned in the slot of the latch. The actuation pin is adapted move laterally between a first position and a second position. The actuation pin slidably contacts the angled portion, such that when the actuation pin moves between the first position and the second position the angled portion moves in a direction orthogonal to the lateral movement. This allows the finger portion to move into and out of the slot. The latch may then be moved between the latched and unlatched positions when the finger portion is not positioned in the slot.

BRIEF DESCRIPTION OF THE DRAWINGS

FIGURE 1 is a prior art perspective view of a single latch of a perimeter latch

assembly;

FIGURE 2 is a partial bottom perspective view of a pod shell including a latch lock in accordance with one embodiment of the present invention;

FIGURE 3 is a partial bottom perspective view of a pod including a perimeter latch and a latch lock in accordance with one embodiment of the present invention;

FIGURE 4 is a perspective view of a pod including a perimeter latch in accordance with one embodiment of the present invention;

FIGURES 5A and 5B are bottom views of a pod including a perimeter latch and a latch lock in accordance with one embodiment of the present invention;

FIGURES 6A through 6D are bottom views of a pod seated on a support surface including an actuation pin for moving a latch lock out of locking position while opening the perimeter latch, in accordance with one embodiment of the present invention.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

The present invention will now be described as referenced to **Figs. 2-6D** which in preferred embodiments relate to a latch lock for locking a perimeter latch in position to prevent unwanted opening of the pod. It is understood the type of pod is not critical to the present invention, and the pod may house various work pieces such as semiconductor wafers, reticles or flat panel displays. Moreover, while a preferred embodiment of the pod according to the present invention operates according to SMIF technology, it is understood that the present invention may be used with containers operating according to technologies other than SMIF technology in alternative embodiments of the present invention.

Referring now to **Fig. 2**, there is shown a bottom perspective view of a pod shell **100** including a latch lock **102** according to the present invention. Latch lock **102** may be formed between an inner wall **100a** and an outer wall **100b** on the pod shell **100**, and may be injection molded as part of the pod shell. The latch lock **102** may be formed of various polymers including polycarbonate and acrylonitrile-butadiene-styrene (ABS). Although one such latch lock **102** is shown in **Fig. 2**, it is understood that there is preferably one latch lock for each perimeter latch on the pod. Thus, there are preferably 4 latch locks.

The following description applies to each of the latch locks. It is understood that there may be less latch locks than perimeter latches in alternative embodiments.

Latch lock **102** includes a first portion **104** having a finger **106** which represents the lowest point on the latch lock when held in its normal position facing downward.

5 Latch lock **102** further includes a second, angled portion **108** which angled with respect to first portion **104** for purposes as will be explained hereinafter. The latch lock **102** may be approximately three-quarters of an inch in length and may be flexible so as to deflect as explained hereinafter. It is understood that the latch lock **102** may be longer or shorter than three-quarters of an inch in alternative embodiments.

10 Referring to **Fig. 3**, there is shown a bottom view of a pod including a pod shell **100** and a pod door **110** which together define a sealed environment (not shown) for a work piece within a container. **Fig. 3** further shows a perimeter latch **112** mounted to pod shell **100** via a leaf spring **114**. Perimeter latch **112** is preferably of conventional design. As shown in **Fig. 4**, leaf springs **114** attach to the pod shell and flex to allow perimeter

15 latch **112** to move between an unbiased position shown in **Fig. 3** and a flexed position shown for example in **Fig. 6D** in which the latch **112** allows the pod door **110** to be removed (While **Fig. 4** shows a reticle pod, as explained above, the container including a latch lock according to the present invention may house various workpieces).

Latch **112** further includes an engaging portion **116** which extends under a portion

20 of the pod door **110** so as to maintain the pod door **110** sealed within the pod. Latch **112** additionally includes a slot **118** for receiving an actuation pin **120** (explained hereinafter with respect to **Figs. 6A-6D**) and for receiving the finger **106** of latch lock **102**.

Referring now to **Figs. 5A** and **5B**, finger **106** extends into slot **118** so that, if an attempt is made to manually move latch **112** to a position free of the pod door, finger **106**

25 abuts against a portion of the wall defining slot **118** as shown in **Fig. 5B** to prevent the engagement portion **116** from moving clear of the pod door **110**. Thus, the latch lock **102** according to the present invention prevents unwanted separation of the pod door from the pod shell.

On the other hand, referring to the bottom view of **Figs. 6A** through **6D**, when the

30 pod is located on a support surface (not shown), an actuation pin **120** seats in slot **118**.

Once the pod is properly positioned on a support surface, a motor beneath the support surface actuates the pins laterally outward (to the right from the perspective of **Figs. 6A-6D**). Upon moving laterally, in addition to moving the latch **112**, actuation pin **120** bears against the angled portion **108** (**Figs. 2 and 6A-6D**) so as to deflect latch lock **102** and finger **106** downward from the view shown in **Figs. 6A-6D** (*i.e.*, substantially perpendicular to the movement of the actuation pin **120**). In moving downward, the finger **106** moves out of slot **118** and no longer prevents the latch **112** from moving laterally so that the engagement portion **116** may move clear of the pod door as shown in **Fig. 6D**.

As is further shown in **Fig. 6D**, once the latch **112** is moved laterally to free the pod door from the pod, the actuation pin **120** also moves clear of the latch lock **102**. At this point, the latch lock moves back to its unflexed position. Thus, while the pod door is clear of the pod during processing of the workpiece(s), the latch lock is unflexed so as to minimize fatigue on the latch lock. When in the position shown in **Fig. 6D**, the finger **106** resides in a detent formed on the top side of the perimeter latch (shown in phantom in the bottom views of **Figs. 6A through 6D**). The finger **106** abuts against the wall of the slot **118** and is prevented from entering this detent unless the finger is first deflected downward by the actuation pin **120** at the same time the perimeter latch **112** moves laterally.

After processing of the work pieces within the pod is completed, and the pod door is returned to its mated position with the pod shell, the actuation pins **120** may move the latch **112** back to its coupling position (*i.e.* the engagement pin **120** moves to the left with respect to the views shown in **Figs. 6A-6D**). When the actuation pin **120** begins its lateral movement to the left from the perspective of **Figs. 6A through 6D**, the finger **106** is again deflected downward by the pin **120** as the perimeter latch is moved to the left so that the finger can once again seat within the slot **118** (**Fig. 6A**). Once returned to this home position, the actuation pins **120** no longer contact the angled portion **108** of the latch locks **102** so that the latch locks **102** return to their undeflected position.

Although the invention has been described in detail herein, it should be understood that the invention is not limited to the embodiments herein disclosed. Various

changes, substitutions and modifications may be made thereto by those skilled in the art without departing from the spirit or scope of the invention.

CLAIMS

What is claimed is:

1. A latch mechanism for latching a first member to a second member, said latch mechanism comprising:
 - 5 (a) a latch lock mounted to said first member, said latch lock comprising:
 - (i) a finger portion; and
 - (ii) an angled portion angled with respect to said finger portion;
 - (b) a latch mounted to said first member, said latch adapted to move between a latched position and an unlatched position, said latch comprising:
 - 10 (i) an engagement portion adapted to contact a portion of said second member when said latch is in said latched position so as to maintain contact between said first member and said second member; and
 - (ii) a slot for receiving said finger of said latch lock; and
 - 15 (c) an actuation pin positioned in said slot of said latch and adapted move laterally between a first position and a second position, said actuation pin adapted to slidably contact said angled portion such that when said actuation pin moves between said first position and said second position said angled portion moves in a direction orthogonal to the lateral
 - 20 movement such that said finger portion is moved into and out of said slot, said latch adapted to move between said latched and unlatched positions when said finger portion is not positioned in said slot.
2. A latch mechanism according to claim 1, further comprising a spring adapted to
25 mount said latch to said first member.
3. A latch mechanism according to claim 2, wherein said spring is a leaf spring.
4. A latch mechanism according to claim 2, wherein said spring is adapted to allow
30 said latch to move between said latched and unlatched positions, said spring being flexed

when said latch is in said unlatched position.

5. A latch mechanism according to claim 1, wherein said slot has a wall portion, and said finger portion is adapted to contact said wall portion to prevent said engagement portion from losing contact with said second member when said finger portion is in said slot.

6. A latch mechanism according to claim 1, further comprising a support surface for supporting said first and second members.

7. A latch mechanism according to claim 6, wherein said actuation pin is mounted to said support surface.

8. A latch mechanism according to claim 6, further comprising a motor adapted to drive the lateral movement of said actuation pin.

9. A latch mechanism according to claim 1, wherein said actuation pin is further adapted to move clear of said latch when said finger portion is out of said slot.

10. A latch mechanism according to claim 9, wherein said latch lock is adapted to move back to said latched position when said first and second members are not in contact.

11. A latch mechanism for latching a door to a container, said latch mechanism comprising:

- (a) a latch lock mounted to said container, said latch lock comprising:
- (i) a finger portion; and
 - (ii) an angled portion angled with respect to said finger portion;
- (b) a latch mounted to said container, said latch adapted to move between a latched position and an unlatched position, said latch comprising:
- (i) an engagement portion adapted to contact a portion of said door when

said latch is in said latched position so as to maintain contact between said door and said container and

(ii) a slot for receiving said finger of said latch lock; and

5 (c) an actuation pin positioned in said slot of said latch and adapted move laterally between a first position and a second position, said actuation pin adapted to slidably contact said angled portion such that when said actuation pin moves between said first position and said second position said angled portion moves in a direction orthogonal to the lateral movement such that said finger portion is moved into and out of said slot,
10 said latch adapted to move between said latched and unlatched positions when said finger portion is not positioned in said slot.

12. A latch mechanism according to claim 11, further comprising a spring adapted to mount said latch to said container and allow said latch to move between said latched and
15 unlatched positions, said spring being flexed when said latch is in said unlatched position.

13. A latch mechanism according to claim 11, wherein said slot has a wall portion, and said finger portion is adapted to contact said wall portion to prevent said engagement portion from losing contact with said door when said finger portion is in said slot.
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14. A latch mechanism according to claim 11, further comprising a support surface for supporting said container.

15. A latch mechanism according to claim 14, wherein said actuation pin is mounted to said support surface.
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16. A latch mechanism according to claim 11, further comprising a motor adapted to drive the lateral movement of said actuation pin.

30 17. A latch mechanism according to claim 11, wherein said container has an inner

wall and an outer wall, and said latch lock is formed between said inner wall and said outer wall of said container.

18. A latch mechanism according to claim 11, wherein said latch lock is molded as
5 part of the container.

19. A latch mechanism according to claim 11, wherein said latch lock is comprised of a polymer.

10 20. A latch mechanism according to claim 19, wherein said polymer is selected from the group consisting of polycarbonate and acrylonitrile-butadiene-styrene (ABS).

21. A latch mechanism according to claim 11, wherein said latch lock is approximately three-quarters of an inch in length.

15 22. A latch mechanism according to claim 11, wherein said door and said container define a sealed environment.

23. A latch mechanism for latching a pod door to a shell of a pod adapted to contain
20 a workpiece, said latch mechanism comprising:

(a) a latch lock mounted to said shell, said latch lock comprising:

(i) a finger portion; and

(ii) an angled portion angled with respect to said finger portion;

(b) a perimeter latch mounted to said shell, said perimeter latch adapted to move
25 between a latched position and an unlatched position, said perimeter latch comprising:

(i) an engagement portion adapted to contact a portion of said pod door when said perimeter latch is in said latched position so as to maintain contact between said pod door and said shell; and

30 (ii) a slot for receiving said finger of said latch lock; and

5 (c) an actuation pin positioned in said slot of said perimeter latch and adapted to move laterally between a first position and a second position, said actuation pin adapted to slidably contact said angled portion such that when said actuation pin moves between said first position and said second position said angled portion moves in a direction orthogonal to the lateral movement such that said finger portion is moved into and out of said slot, said latch adapted to move between said latched and unlatched positions when said finger portion is not positioned in said slot.

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24. A latch mechanism according to claim 23, further comprising a spring adapted to mount said perimeter latch to said shell and allow said perimeter latch to move between said latched and unlatched positions, said spring being flexed when said perimeter latch is in said unlatched position.

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25. A latch mechanism according to claim 23, further comprising a support surface for supporting said pod.

20 26. A latch mechanism according to claim 23, wherein said actuation pin is mounted to said support surface.

27. A latch mechanism according to claim 23, further comprising a motor adapted to drive the lateral movement of said actuation pin.

25 28. A latch mechanism according to claim 23, wherein said pod defines a sealed environment.

29. A latch mechanism according to claim 23, wherein said workpiece is selected from the group consisting of semiconductor wafers, reticles, and flat panel displays.

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30. A latch mechanism according to claim 23, wherein said pod operates according to SMIF technology.

31. A latch mechanism according to claim 23, wherein said pod comprises multiple
5 said latch mechanisms.