

ABSTRACT

Introduced is a method and a system for controlling a logistics robot, comprising the steps of: setting one or more path pairs connecting at least one origin and destination;
5 determining at least one candidate path pair related to a mission of a logistics robot among the set one or more path pairs on the basis of information related to the production of goods; and performing transportation control of the
10 logistics robot on the basis of the at least one determined candidate path pair.

Fig. 10