

Description

Title of Invention: POWER CONVERSION DEVICE

Technical Field

[0001] The present invention relates to a power converter including a power buffer
5 circuit.

Background Art

[0002] A full-wave rectifying circuit is typically used to obtain a DC voltage from a single-phase AC voltage input from a single-phase AC power supply. An output from the full-wave rectifying circuit, however, has power pulsations having a frequency twice
10 the frequency of the single-phase AC voltage. To reduce the power pulsations, a power buffer circuit for buffering a power is thus required between an output of the full-wave rectifying circuit and a load. A capacitive element, for example, referred to as a smoothing capacitor is required for buffering a power.

[0003] Non-patent Document 1 discloses a technique for connecting a buffer capacitor to
15 a smoothing capacitor via a current-reversible chopper to absorb a pulsating power. This technique reduces the electrostatic capacitance of the smoothing capacitor and further allows voltage ripples at the buffer side to greatly reduce the total electrostatic capacitance required for smoothing.

[0004] Non-patent Document 2 and Patent Document 1 disclose a technique for
20 connecting a buffer capacitor to a DC link via a switching element while removing the smoothing capacitor of Non-patent Document 1. A direct conversion circuit is described that generates a voltage source by this technique and generates a high-frequency link along with a power supply voltage.

[0005] Non-patent Document 3 further discloses a technique for converting an input
25 waveform into a sinusoidal waveform and increasing efficiency.

[0006] The techniques described in Non-patent Documents 2 and 3 improve a voltage utilization ratio (a ratio of a voltage across a DC link to a crest value of a power supply voltage) from 0.5 to $1/\sqrt{2} = 0.71$, compared with the conventionally proposed technique involving the use of an active snubber (for example, see Non-patent Document 4).

5 However, the voltage across the DC link is low compared with a typical single-phase rectifier. This may increase the current capacity of a power device of an inverter.

[0007] To solve the problem above, Patent Document 2 proposes a technique for controlling the voltage across a DC link to have a waveform obtained by full-wave rectification of a two-phase AC and setting an average voltage utilization ratio to 0.9 at
10 maximum.

[0008] As described above, the techniques proposed in Non-patent Documents 2 and 3 and Patent Documents 1 and 2, which are based on the concept of a power flow, buffer the power pulsations by a power buffer circuit to supply a steady power to an inverter.

Prior Art Documents

15 Patent Documents

[0009] Patent Document 1: Japanese Patent Application Laid-Open No. 2011-193678

Patent Document 2: Japanese Patent No. 5454732

Patent Document 3: Japanese Patent Application Laid-Open No. 2014-082926

Patent Document 4: Japanese Patent Application Laid-Open No. 2015-084637

20 Non-patent Documents

[0008] Non-patent Document 1: Irie, Yamashita, and Takemoto, "Ripple Compensation for a Single-Phase Rectifier by 2-Quadrant Chopper and Auxiliary Capacitor", the Institute of Electrical Engineers of Japan (IEEJ) Transactions D, Vol. 112, No. 7, pp. 623-629 (1992).

25 Non-patent Document 2: Ohnuma, Itoh, "Circuit Configuration and Control

Strategy of single-to-three Phase Power Converter with Active Buffer and Charge Circuit", the 2010 Annual Meeting of IEEJ, 4-057 (2010).

Non-patent Document 3: Ohnuma, Itoh, "Comparison between a Boost Chopper and an Active Buffer as a Single to Three Phase Converter", 2011 Annual Meeting of IEEJ, 4-042 (2011).

Non-patent Document 4: Ohnuma, Itoh, "Control Strategy of Single Phase to Three Phase Power Converter Using an Active Snubber", 2008 IEEJ Industry Applications Society Conference, 1-20 (2008).

10 Summary of Invention

Problem to be Solved by Invention

[0011] Patent Document 3 proposes a technique for generating a voltage across a DC link using the voltage at the power supply and the voltage at the power buffer circuit. This can increase the voltage across the DC link. In view of the breakdown voltage of a capacitor used in the power buffer circuit, however, the voltage of the power buffer circuit is desirably adjusted to be not greater than 1.2 times the crest value of the power supply voltage. When the voltage of the power buffer circuit is set to such a value, the power buffer circuit mainly covers the power. In this case, the power supplied from the full-wave rectifying circuit to the inverter is an auxiliary power, and there is a trade-off between boosting the voltage across the DC link and obtaining high efficiency characteristics that are a feature of the direct power converter.

[0012] The present application therefore has an object to provide a technique for increasing the voltage across a DC link without increasing the power covered by a power buffer circuit.

25 Means for Solving the Problem

[0013] A power converter according to the present invention includes an h including a first power supply line (LH) and a second power supply line (LL), a converter (3) that receives a single-phase AC voltage (V_{in}) and outputs a pulsating power (P_{in}) to the DC link, an inverter (5) that receives a power from the DC link and outputs an AC current (I_u , I_v , I_w), and a power buffer circuit (4) that receives a charge power (P_l) from the DC link and outputs a discharge power (P_c) to the DC link.

[0014] In a first aspect, an input power (P_{dc}) input to the inverter (5) takes a value ($P_{in} + P_c - P_l$) obtained, from the DC link (7), by subtracting the charge power from a sum of the pulsating power and the discharge power. The charge power (P_l) takes a value ($P_{in}/2$) that is a half of the pulsating power (P_{in}). The discharge power (P_c) takes a value ($P_{in}^2 + P_l$) obtained by adding the charge power to an AC component (P_{in}^2) of the pulsating power. The converter (3) applies a rectified voltage (V_{rec}) obtained by full-wave rectifying the single-phase AC voltage (V_{in}) to the DC link (7) while setting the first power supply line (LH) to have a higher potential than the second power supply line (LL). The power buffer circuit (4) includes a discharge circuit (4a) and a charge circuit (4b). The discharge circuit (4a) includes a capacitor (C_4) and a switch (S_c , D_{42}) connected in series to the capacitor adjacent to the first power supply line between the first power supply line and the second power supply line. The charge circuit (4b) charges the capacitor. A discharge duty (d_c) that is a duty at which the switch is conductive takes a value ($(V_m/V_c)\cos^2(\omega t)$) obtained by dividing a product of a crest value (V_m) of the single-phase AC voltage and a square ($\cos^2(\omega t)$) of a cosine value of a phase of the single-phase AC voltage by a both-end voltage (V_c) across the capacitor. The converter is conductive at a rectifying duty (d_{rec}). A DC voltage (V_{dc}) that is a sum of a product ($d_{rec} \cdot V_{rec}$) of the rectified voltage and the rectifying duty and a product ($d_c \cdot V_c$) of the both-end voltage and the discharge duty varies in a period that is a

half of a period of the single-phase AC voltage.

[0015] In a second aspect of the power converter according to the present invention, in the first aspect, the rectifying duty takes any one smaller value of an absolute value ($|\sin(\omega t)|$) of a sine value of the phase and a value $(1 - dc)$ obtained by subtracting the discharge duty (dc) from 1.

[0016] In a third aspect of the power converter according to the present invention, in the first aspect, the rectifying duty takes a value $(1 - dc)$ obtained by subtracting the discharge duty (dc) from 1.

[0017] In a fourth aspect of the power converter according to the present invention, in any one of the first to third aspects, a ratio (V_c/V_m) of the both-end voltage (V_c) to the crest value (V_m) is 1 or more and 1.2 or less.

[0018] In a fifth aspect of the power converter according to the present invention, in any one of the first to fourth aspects, the inverter (5) performs DC-AC conversion with a minimum value of the DC voltage (V_{dc}) as an upper limit.

[0019] In a sixth aspect of the power converter according to the present invention, in any one of the first to fourth aspects, the DC voltage varies with a quarter of the period of the single-phase AC as a fundamental period.

[0020] In a seventh aspect of the power converter according to the present invention, in any one of the first to fourth aspects, the DC voltage varies in a pair of sections that are not adjacent to each other among sections equally dividing the period of the single-phase AC into four and is constant in the other pair of sections.

Effects of the Invention

[0021] The DC voltage (V_{dc}) varies in a period in which the discharge duty (dc) varies. This increases a crest value/both-end voltage (V_m/V_c) that affects the discharge duty (dc) (i.e., reduces the both-end voltage (V_c)) to increase the DC voltage (V_{dc}). In other

words, the both-end voltage (V_c) that is required for obtaining a desired DC voltage (V_{dc}) is reduced, thus reducing a breakdown voltage required for the capacitor (C4).

[0022] The objects, features, aspects, and advantages of the present invention will become more apparent from the following detailed description and the accompanying
5 drawings.

Brief Description of Drawings

[0023] [FIG. 1] A block diagram showing a configuration of a direct power converter according to an embodiment.

10 [FIG. 2] A block diagram showing a power balance in the direct power converter according to the embodiment.

[FIG. 3] A circuit diagram showing an equivalent circuit of a circuit shown in FIG. 1.

[FIG. 4] A graph showing an operation of the direct power converter when a basic
15 setting of duty is adopted.

[FIG. 5] A graph showing a voltage utilization ratio to a voltage ratio when the basic setting of duty is adopted.

[FIG. 6] A graph showing an operation of the direct power converter when the technique described in Patent Document 3 is used.

20 [FIG. 7] A graph showing an operation of the direct power converter when a first modification of duty is adopted.

[FIG. 8] A graph showing a rectifying duty, a discharge duty, and a zero duty when the first modification of duty is adopted and when a second modification of duty is adopted.

25 [FIG. 9] A graph showing the validity of an approximation.

[FIG. 10] A graph showing the validity of an approximation.

[FIG. 11] A graph showing the dependence of voltage utilization ratio on phase when the second modification of duty is adopted.

[FIG. 12] A graph showing the dependence of voltage utilization ratio on phase
5 when the first modification of duty is adopted.

[FIG. 13] A graph showing the dependence of voltage utilization ratio on phase when the basic setting of duty is adopted.

[FIG. 14] A graph showing the dependence of a voltage utilization ratio R on a voltage ratio α .

10 [FIG. 15] A graph showing the dependence of duties on phase when the basic setting of duty is used.

[FIG. 16] A graph showing the dependence of duties on phase when the first modification of duty is used and when the second modification is used.

[FIG. 17] A graph showing an operation of the direct power converter when the
15 first modification of duty is adopted.

[FIG. 18] A graph showing an operation of the direct power converter when the basic setting of duty is adopted.

[FIG. 19] A graph showing a ratio between two types of powers.

[FIG. 20] A graph showing an operation of a switch of an equivalent circuit and an
20 operation of a switching element of an inverter.

[FIG. 21] A circuit diagram showing a first modification.

[FIG. 22] A graph showing an operation of the direct power converter according to a second modification.

[FIG. 23] A graph showing an operation of the direct power converter according
25 to a third modification.

Description of Embodiments

[0024] A. Configuration of Direct Power Converter

FIG. 1 is a block diagram showing a configuration of a direct power converter to which a control method described in this embodiment is applied. The direct power converter includes a converter 3, a power buffer circuit 4, an inverter 5, and a DC link 7.

[0025] The converter 3 is connected with a single-phase AC power supply 1 via, for example, a filter 2. The filter 2 includes a reactor L2 and a capacitor C2. The reactor L2 is provided between the converter 3 and one of two output terminals of the single-phase AC power supply 1. The capacitor C2 is provided between the two output terminals of the single-phase AC power supply 1. The filter 2 removes the high frequency components of a current. The filter 2 may be omitted. For the sake of brevity, the following description will be made ignoring the function of the filter 2.

[0026] The DC link 7 includes DC power supply lines LH and LL.

[0027] The converter 3 uses a diode bridge, for example, and includes diodes D31 to D34.

The diodes D31 to D34, which constitute a bridge circuit, convert a single-phase AC voltage V_{in} , which is an input voltage input from the single-phase AC power supply 1, by single-phase full-wave rectification into a rectified voltage V_{rec} and output it across the power supply lines LH and LL. A higher potential is applied to the DC power supply line LH than to the DC power supply line LL. An input current I_{in} flows into the converter 3 from the single-phase AC power supply 1.

[0028] The power buffer circuit 4 includes a discharge circuit 4a and a charge circuit 4b and provides and receives powers to and from the DC link 7. The discharge circuit 4a includes a capacitor C4, and the charge circuit 4b boosts the rectified voltage V_{rec} and charges the capacitor C4.

[0029] The discharge circuit 4a further includes a transistor (herein an insulated gate

bipolar transistor: hereinafter abbreviated as an "IGBT") Sc connected in antiparallel to a diode D42. The transistor Sc is connected in series to the capacitor C4 adjacent to the DC power supply line LH between the DC power supply lines LH and LL. Herein, being connected in antiparallel refers to being connected in parallel with forward

5 directions being opposite to each other. Specifically, the forward direction of the transistor Sc is a direction from the DC power supply line LL toward the DC power supply line LH, and the forward direction of the diode D42 is a direction from the DC power supply line LH toward the DC power supply line LL. The transistor Sc and the diode D42 can be collectively understood as a switch element (switch Sc). When the

10 switch Sc is conductive, the capacitor C4 discharges to provide a power to the DC link 7.

[0030] The charge circuit 4b includes, for example, a diode D40, a reactor L4, and a transistor (herein an IGBT) Sl. The diode D40 has a cathode and an anode, and the cathode is connected between the switch Sc and the capacitor C4. This configuration is known as a so-called boost chopper.

15 [0031] The reactor L4 is connected between the DC power supply line LH and the anode of the diode D40. The transistor Sl is connected between the DC power supply line LL and the anode of the diode D40. The transistor Sl is connected in antiparallel with a diode D41, and they can be collectively understood as a switch element (switch S1). Specifically, the forward direction of the transistor Sl is a direction from the DC power

20 supply line LH toward the DC power supply line LL, and the forward direction of the diode D41 is a direction from the DC power supply line LL toward the DC power supply line LH.

[0032] The capacitor C4 is charged by the charge circuit 4b, and a both-end voltage Vc higher than the rectified voltage Vrec is generated in the capacitor C4. Specifically, a

25 current is caused to flow from the DC power supply line LH to the DC power supply line

LL via the switch S1 to store energy in the reactor L4, and then the switch S1 is turned off to store the energy in the capacitor C4 via the diode D40.

[0033] Since the both-end voltage V_c is higher than the rectified voltage V_{rec} , no current basically flows through the diode D42. Conduction/non-conduction of the switch Sc thus solely depends on that of the transistor Sc. Herein, the diode D42 acts to achieve a reverse breakdown voltage at which the both-end voltage V_c is lower than the rectified voltage V_{rec} and to allow a reverse conduction of a current that is refluxed from an inductive load 6 to the DC link 7 when the inverter 5 stops due to abnormality.

[0034] Since the DC power supply line LH is higher than the DC power supply line LL in potential, no current basically flows through the diode D41. Conduction/non-conduction of the switch S1 thus solely depends on that of the transistor S1. Although herein the diode D41 is a diode for reverse breakdown voltage and reverse conduction and is illustrated as an internal diode of the transistor S1 configured by an IGBT, the diode D41 itself is not involved in a circuit operation.

[0035] The inverter 5 converts a DC voltage across the DC power supply lines LH and LL into an AC voltage and outputs it to output terminals Pu, Pv, and Pw. The inverter 5 includes six switching elements Sup, Svp, Swp, Sun, Svn, and Swn. The switching elements Sup, Svp, and Swp are respectively connected between the DC power supply line LH and the output terminals Pu, Pv, and Pw, and the switching elements Sun, Svn, and Swn are respectively connected between the DC power supply line LL and the output terminals Pu, Pv, and Pw. The inverter 5 comprises a so-called voltage source inverter, and includes six diodes Dup, Dvp, Dwp, Dun, Dvn, and Dwn.

[0036] The diodes Dup, Dvp, Dwp, Dun, Dvn, and Dwn are arranged with their cathodes directed toward the DC power supply line LH and their anodes directed toward the DC power supply line LL. The diode Dup is connected in parallel to the switching element

Sup between the output terminal Pu and the DC power supply line LH. Similarly, the diodes Dvp, Dwp, Dun, Dvn, and Dwn are respectively connected in parallel to the switching elements Svp, Swp, Sun, Svn, and Swn. AC currents Iu, Iv, and Iw are respectively output from the output terminals Pu, Pv, and Pw and constitute a three-phase AC current. For example, IGBTs are used as the switching elements Sup, Svp, Swp, Sun, Svn, and Swn.

[0037] The inductive load 6 is a rotary machine, for example, and is shown by an equivalent circuit representing an inductive load. Specifically, a reactor Lu and a resistor Ru are connected in series to each other, and one end of the series body is connected to the output terminal Pu. The same applies to a reactor Lv and a resistor Rv and to a reactor Lw and a resistor Rw. Respective opposite ends of these series bodies are connected to one another.

[0038] When a control system is illustrated with the inductive load 6 being a synchronous machine, a velocity detector 9 detects the AC currents Iu, Iv, and Iw flowing through the inductive load 6 and, based on these currents, provides a controller 10 with a rotation angular velocity ω_m , and a q-axis current Iq and a d-axis current Id.

[0039] The controller 10 receives the rotation angular velocity ω_m , and the q-axis current Iq and the d-axis current Id, as well as crest values Vm and Im, a power supply angular velocity ω , and a command value ω_m^* of the rotation angular velocity, which will be described below, and based on voltage command values Vu*, Vv*, and Vw* (which will be described below with reference to FIG. 20), obtains signals SSup, SSvp, SSwp, SSun, SSvn, and SSwn for respectively controlling the operations of the switching elements Sup, Svp, Swp, Sun, Svn, and Swn of the inverter 5 through arithmetic processing (not shown: for example, see Patent Document 1).

[0040] The controller 10 also generates signals SSc and SSi for respectively controlling

the operations of the switches Sc and Sl, which are generated based on duties drec, dc, dz, and dl (for example, see Patent Document 1).

[0041] B. Control Method

(b-1) Basic Concept of Power Reduction

5 An instantaneous input power P_{in} input to the converter 3 is expressed by Formula (1) below with an input power factor being 1. Note that a crest value V_m and a power supply angular velocity ω of the single-phase AC voltage V_{in} , a crest value I_m of the AC input current I_{in} , and a time t are introduced. A product ωt of the power supply angular velocity ω and the time t represents a phase of the single-phase AC voltage V_{in} . An AC
10 waveform is understood as the product of a sine value of the phase ωt of the AC waveform and a crest value.

[0042] [Math 1]

$$\begin{aligned} P_{in} &= V_m \cdot I_m \cdot \sin^2(\omega t) \\ &= \frac{1}{2} V_m \cdot I_m - \frac{1}{2} V_m \cdot I_m \cdot \cos(2\omega t) \quad \dots(1) \end{aligned}$$

[0043] The instantaneous input power P_{in} has an AC component $(-1/2) \cdot V_m \cdot I_m \cdot \cos(2\omega t)$
15 (hereinafter, also referred to as an "AC component $P_{in}^{\wedge}$ ") shown by the second term of the right-hand side of Formula (1). The instantaneous input power P_{in} is thus hereinafter also referred to as a pulsating power P_{in} .

[0044] The power converter shown in FIG. 1 can be understood as follows:

[0045] The DC link 7 includes the DC power supply lines LH and LL;

20 The converter 3 receives the single-phase AC voltage V_{in} and outputs the pulsating power P_{in} ;

The power buffer circuit 4 receives a charge power P_l from the DC link 7 and outputs a discharge power P_c to the DC link 7; and

The inverter 5 receives, from the DC link 7, an input power P_{dc} ($= P_{in} + P_c - P_l$)

obtained by subtracting the charge power P_l from the sum of the pulsating power P_{in} and the discharge power P_c and outputs the AC currents I_u , I_v , and I_w .

[0046] FIG. 2 is a block diagram schematically showing a power balance in the direct power converter shown in FIG. 1. A power subjected to buffering (hereinafter, referred to as a "buffering power P_{buf} ") by the power buffer circuit 4 is equal to a power difference ($P_c - P_l$) obtained by subtracting the charge power P_l from the discharge power P_c . A power P_{rec} directed from the converter 3 toward the inverter 5 is equal to $P_{in} - P_l$. Thus, $P_{dc} = P_{rec} + P_c$ holds.

[0047] In the techniques shown in Non-patent Document 2 and Patent Document 1, to counteract the above-mentioned AC component $\hat{P}_{in}$, different types of control are performed alternately for each quarter period ($(1/4)$ period) of the single-phase AC voltage V_{in} (such control is also referred to as "quarter-period control" for the sake of convenience). Specifically, control to set $P_l = \hat{P}_{in}$ and $P_c = 0$ and control to set $P_l = 0$ and $P_c = -\hat{P}_{in}$ are performed alternately for each quarter period of the single-phase AC voltage V_{in} . As a result, $P_{dc} = P_{in} + P_c - P_l = P_{in} - \hat{P}_{in} = (1/2) \cdot V_m \cdot I_m$ holds over a whole period, thus avoiding power pulsations. In these techniques, however, a maximum value of the voltage utilization ratio remains at $1/\sqrt{2}$.

[0048] In the technique described in Patent Document 2, even if a voltage utilization ratio can be increased, the voltage across the DC link and the current flowing through the DC link are more likely to be distorted in a quarter period of the single-phase AC voltage V_{in} .

[0049] Thus, considered below is the control without the premise that $P_l = 0$ and $P_c = 0$ are set alternately for each quarter period of the single-phase AC voltage V_{in} .

[0050] (b-2) Specific Examples of Charge Power P_l and Discharge Power P_c

In and after this section, the above-mentioned charge power P_l and discharge power P_c are respectively determined by Formulas (2) and (3) as examples.

[0051] [Math 2]

$$P_l = \frac{1}{2} \cdot V_m \cdot I_m \cdot \sin^2(\omega t) \quad \dots(2)$$

[0052] [Math 3]

$$\begin{aligned} P_c &= \frac{1}{2} \cdot V_m \cdot I_m \cdot \cos^2(\omega t) \\ &= \frac{1}{2} \cdot V_m \cdot I_m \cdot \cos(2\omega t) + P_l \quad \dots(3) \end{aligned}$$

- 5 [0053] This means that the charge power P_l is a half power of the pulsating power P_{in} , and the discharge power P_c is a power obtained by subtracting the AC component $P_{in}^{\wedge}$ from the charge power P_l .

[0054] The charge power P_l can be understood as a power $(1/2) \cdot P_{in}$ distributed from the pulsating power P_{in} to the power buffer circuit 4 via the DC link 7 at a distribution ratio
10 of 1/2.

[0055] From Formulas (2) and (3) and $P_{buf} = P_c - P_l$, the buffering power P_{buf} is also expressed by Formula (4).

[0056] [Math 4]

$$P_{buf} = \frac{1}{2} \cdot V_m \cdot I_m \cdot \cos(2\omega t) \quad \dots(4)$$

- 15 [0057] It is obvious that the charge power P_l and the discharge power P_c are different from those in the quarter-period control described above.

[0058] Discharge is dominant over charge in a period (hereinafter, also referred to as a "discharge dominant period") in which $P_c > P_l$ (i.e., $P_{buf} > 0$), and charge is dominant over discharge in a period (hereinafter, also referred to as a "charge dominant period") in
20 which $P_c < P_l$ (i.e., $P_{buf} < 0$). As can be understood from Formulas (2) and (3), a period in which $(n+1/4)\pi \leq \omega t \leq (n+3/4)\pi$ is the charge dominant period, and a period in which

$(n+3/4)\pi \leq \omega t \leq (n+5/4)\pi$ is the discharge dominant period (n is an integer: the same applies to the description below).

[0059] The voltage utilization ratio can be set up to 1 by determining the charge power P_l and the discharge power P_c as described above, which will be described below.

5 [0060] (b-3) Distribution of Current

This section will describe a technique for setting a current i_{rec1} flowing from the converter 3 to the inverter 5 out of a current i_{rec} output from the converter 3 to a half of the current i_{rec} .

[0061] The rectified voltage V_{rec} expressed by Formula (5) is applied to the output side
10 of the converter 3.

[0062] [Math 5]

$$V_{rec} = |V_{in}| = V_m \cdot |\sin(\omega t)| \quad \dots(5)$$

[0063] Formula (6) below holds as $P_{rec} = P_{in} - P_l$.

[0064] [Math 6]

$$15 \quad P_{rec} = \frac{1}{2} \cdot V_m \cdot I_m \cdot \sin^2(\omega t) = |V_{in}| \cdot i_{rec1} \quad \dots(6)$$

[0065] The current i_{rec1} is thus expressed by Formula (7) below.

[0066] [Math 7]

$$i_{rec1} = \frac{1}{2} \cdot I_m \cdot |\sin(\omega t)| \quad \dots(7)$$

[0067] Formula (1) is based on the premise that the input current I_{in} is expressed by
20 $I_m \cdot \sin(\omega t)$, that is, has a sinusoidal waveform, and thus, the current i_l satisfies Formula (8) below. As can be seen from FIG. 2, this is because the current i_{rec} output from the converter 3 is equal to the sum of the current i_{rec1} and the current i_l .

[0068] [Math 8]

$$i_l = \frac{1}{2} \cdot I_m \cdot |\sin(\omega t)| \quad \dots(8)$$

[0069] When a discharge current i_c flowing from the capacitor C4 to the inverter 5 is introduced, the discharge power P_c output from the power buffer circuit 4 is expressed by a product $V_c \cdot i_c$. In order for the discharge power P_c to satisfy Formula (3), thus, it suffices that the discharge current i_c satisfies Formula (9) below.

[0070] [Math 9]

$$i_c = \frac{P_c}{V_c} = \frac{V_m \cdot I_m}{2V_c} \cdot \cos^2(\omega t) \quad \dots(9)$$

[0071] FIG. 3 shows an equivalent circuit of the circuit shown in FIG. 1. The equivalent circuit is introduced in Patent Document 1, for example. In the equivalent circuit, the current i_{rec1} is equivalently expressed as a current i_{rec1} passing through a switch S_{rec} when this switch is conductive. Similarly, the discharge current i_c is equivalently expressed as a current i_c passing through the switch S_c when this switch is conductive.

[0072] A current flowing through the inverter 5 to the inductive load 6 when the output terminals Pu, Pv, and Pw are connected in common to any one of the DC power supply lines LH and LL in the inverter 5 is also equivalently expressed as a zero-phase current i_z flowing through a switch S_z when this switch is conductive.

[0073] FIG. 3 also shows the reactor L4, the diode D40, and the switch S1 constituting the charge circuit 4b, and additionally shows the current i_l flowing through the reactor L4.

[0074] In the thus obtained equivalent circuit, Formula (10) below holds by introducing the duties d_{rec} , d_c , and d_z at which the switches S_{rec} , S_c , and S_z are respectively conductive and a DC current I_{dc} input into the inverter 5.

[0075] [Math 10]

$$\begin{bmatrix} i_{rec} \\ i_c \\ i_z \end{bmatrix} = \begin{bmatrix} d_{rec} & 1 \\ d_c & 0 \\ d_z & 0 \end{bmatrix} \cdot \begin{bmatrix} I_{dc} \\ i_l \end{bmatrix} \quad \dots(10)$$

[0076] The currents i_{rec1} , i_c , and i_z are respectively obtained by multiplying the DC current I_{dc} by the duties d_{rec} , d_c , and d_z , and are accordingly average values in switching cycles of the respective switches S_{rec} , S_c , and S_z .

- 5 [0077] The DC current I_{dc} is the sum of the currents i_{rec1} , i_c , and i_z conducted by the respective switches S_{rec} , S_c , and S_z , and thus, the following formula holds. Note that $0 \leq d_{rec} \leq 1$, $0 \leq d_c \leq 1$, and $0 \leq d_z \leq 1$.

[0078] [Math 11]

$$d_{rec} + d_c + d_z = 1 \quad \dots(11)$$

- 10 [0079] The duties d_{rec} , d_c , and d_z can thus be considered as current distribution ratios of the DC current I_{dc} to the respective currents i_{rec1} , i_c , and i_z . The duty d_{rec} may hereinafter also be referred to as a rectifying duty d_{rec} because it is a duty at which a period in which the converter 3 is connected to the DC link 7 and allows a current to flow through the inverter 5 is set. The duty d_c may hereinafter also be referred to as a discharge duty d_c because it is a duty at which the capacitor C4 discharges. The duty d_z may hereinafter also be referred to as a zero duty d_z because the duty d_z is a duty at which the zero-phase current i_z always flows through the inverter 5 regardless of a voltage output from the inverter 5.
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[0080] The rectifying duty d_{rec} and the discharge duty d_c are respectively set by

- 20 Formulas (12) and (13) below from Formulas (7), (9), and (10).

[0081] [Math 12]

$$d_{rec} = \frac{1}{2} \cdot \frac{I_m}{I_{dc}} \cdot |\sin(\omega t)| \quad \dots(12)$$

[0082] [Math 13]

$$d_c = \frac{V_m}{2V_c} \cdot \frac{I_m}{I_{dc}} \cdot \cos^2(\omega t) \quad \dots(13)$$

[0083] That is to say, Formulas (7), (9), (12), and (13) are used to meet the demand for power balance, and Formula (8) is used to further meet the demand for making the input
5 current I_{in} be a sinusoidal waveform and satisfaction of Formula (1) on which the above-mentioned formulas are based.

[0084] When the converter 3 uses a diode bridge, the converter 3 cannot be actively switched at the rectifying duty d_{rec} expressed by Formula (12). By switching the inverter 5 and the switch S_c respectively in accordance with the zero duty d_z and the
10 discharge duty d_c determined by Formulas (11), (12), and (13), the current i_{rec1} expressed by Formula (7) can be obtained.

[0085] The inverter 5 cannot use the DC voltage at the DC link 7 in a period in which the zero-phase current i_z flows. The DC voltage used in power supply to the inverter 5 in the DC link 7 is thus important in power conversion. In other words, the instantaneous
15 DC voltage that is not used by the inverter 5 in power conversion is not important also in the consideration of a voltage utilization ratio. The DC voltage V_{dc} that is important in power conversion can thus be expressed as follows:

[0086] [Math 14]

$$V_{dc} = V_{rec} \cdot d_{rec} + V_c \cdot d_c + 0 \cdot d_z \quad \dots(14)$$

20 [0087] On the other hand, the DC voltage V_{dc} can be understood as a voltage applied to the DC link 7 as an average of the maximum value of a voltage that the inverter 5 can output, in a period in which switching of the switches S_c and S_l and the inverter 5 is controlled. This is because though the inverter 5 can contribute to the voltage across the DC link 7 at a ratio, zero duty d_z , the inverter 5 is insulated from any one of the DC

power supply lines LL and LH of the DC link 7 in the period corresponding to the zero duty dz.

[0088] The DC voltage Vdc is additionally shown in FIG. 3 as a voltage generated across a current source Idc (which flows the DC current Idc) representing the inverter 5 and a load thereof.

[0089] The input power Pdc input from the DC link 7 to the inverter 5 is the product of the DC voltage Vdc and the DC current Idc. Since the inverter 5 obtains, from the DC link 7, the input power Pdc (= Pin + Pc - Pl) obtained by subtracting the charge power Pl from the sum of the pulsating power Pin and the discharge power Pc, Formula (15) below holds.

[0090] [Math 15]

$$\begin{aligned} I_{dc} &= \frac{P_{in} + P_c - P_l}{V_{dc}} \\ &= \frac{V_m \cdot I_m}{2V_{dc}} \quad \dots(15) \end{aligned}$$

[0091] Formulas (12) and (13) can be expressed as Formulas (16) and (17).

[0092] [Math 16]

$$\begin{aligned} d_{rec} &= \frac{V_{dc}}{V_m} |\sin(\omega t)| \\ &= \frac{V_{dc}}{V_{rec}} \cdot \sin^2(\omega t) \quad \dots(16) \end{aligned}$$

[0093] [Math 17]

$$\begin{aligned} d_c &= \frac{V_{dc}}{V_c} \cdot \cos^2(\omega t) \\ &= \frac{V_{dc}}{2V_c} (1 + \cos(2\omega t)) \quad \dots(17) \end{aligned}$$

[0094] When the right-hand side of Formula (14) is calculated using Formulas (16) and (17), Formula (18) below is obtained, which matches the left-hand side of Formula (14).

[0095] [Math 18]

$$\begin{aligned} d_{rec} \cdot V_{rec} + d_c \cdot V_c &= V_{dc} |\sin(\omega t)| \cdot |\sin(\omega t)| + V_{dc} \cdot \cos^2(\omega t) \\ &= V_{dc} \quad \dots(18) \end{aligned}$$

[0096] In other words, it can be said that the rectifying duty d_{rec} and the discharge duty d_c are respectively determined by Formulas (16) and (17) as a result of the determination
5 of one DC voltage V_{dc} .

[0097] It is found from the forms of the functions of Formulas (16) and (17) or from the maximum values of the rectifying duty d_{rec} and the discharge duty d_c being 1 that the DC voltage V_{dc} can be controlled at a constant value if $V_{dc} \leq V_m$ and $V_{dc} \leq V_c$. On this occasion, the rectifying duty d_{rec} can be determined by measuring a crest value V_m and
10 designating one command value of the DC voltage V_{dc} .

[0098] The voltage utilization ratio can be expressed as a ratio $R (= V_{dc}/V_m)$ of a DC voltage V_{dc} to a crest value V_m . Formulas (10), (11), and (14) reveal that the period in which the inverter 5 flows a zero-phase current is made shorter as the zero duty d_z is made smaller, resulting in a longer period in which the voltage applied to the DC link
15 voltage is used. This increases the voltage utilization ratio R .

[0099] Based on the premise that the input current I_{in} is expressed by $I_m \cdot \sin(\omega t)$, that is, has a sinusoidal waveform, the current i_l depends on the DC current I_{dc} and satisfies Formula (19) below. Herein, Formulas (7) and (15) are taken into account.

[0100] [Math 19]

$$\begin{aligned} i_l &= I_m |\sin(\omega t)| - d_{rec} \cdot I_{dc} \\ &= (I_m - \frac{V_{dc}}{V_m} \cdot I_{dc}) \cdot |\sin(\omega t)| \\ &= \frac{I_m}{2} \cdot |\sin(\omega t)| = i_{rec1} \quad \dots(19) \end{aligned}$$

[0101] That is to say, as in Formula (8), a half of the absolute value of the input current

I_{in} flows as a current i_l . It is therefore understood that the rectifying duty d_{rec} and the discharge duty d_c are determined such that the input current I_{in} has a sinusoidal waveform.

[0102] FIG. 4 is a graph showing the operation of the direct power converter at $V_c = 1.5$
 5 V_m when the rectifying duty d_{rec} and the discharge duty d_c are respectively set by Formulas (16) and (17) as described above while maintaining $d_z \geq 0$ in a whole section of the phase ωt (this corresponds to a "basic setting of duty", which will be described below: for example, see Patent Document 4).

[0103] In FIG. 4, the first tier shows the duties d_{rec} , d_c , and d_z , the second tier shows the
 10 DC voltage V_{dc} , a first component $d_{rec} \cdot V_{rec}$ and a second component $d_c \cdot V_c$ thereof, and the DC current I_{dc} , the third tier shows the current i_{rec} (equal to the absolute value of the input current I_{in}) output from the converter 3 and the currents i_{rec1} , i_l , and i_c , and the fourth tier shows the powers P_{in} , P_c , P_{buf} , and P_{rec} . In each of the graphs, the horizontal axis represents the phase ωt with "degree" as the unit.

15 [0104] The first component $d_{rec} \cdot V_{rec}$ of the DC voltage V_{dc} is a voltage appearing in the first term of Formula (14) and indicates the contribution of the converter 3 to the DC voltage V_{dc} . The second component $d_c \cdot V_c$ of the DC voltage V_{dc} is a voltage appearing in the second term of Formula (14) and indicates the contribution of the capacitor C4 to the DC voltage V_{dc} .

20 [0105] Herein, voltage is normalized by the crest value V_m , and the DC current I_{dc} is converted with the crest value I_m of the input current I_{in} being $\sqrt{2}$.

[0106] Since the lower limit of the zero duty d_z is zero, the duties d_{rec} and d_c at which the DC voltage V_{dc} is maximized are obtained when the zero duty d_z is zero.

[0107] If the zero duty d_z is zero, Formula (20) is obtained from Formulas (11), (16), and
 25 (17). Herein $x = |\sin(\omega t)|$ is introduced.

[0108] [Math 20]

$$d_{rec} + d_c = \frac{V_{dc}}{V_m} \cdot x + \frac{V_{dc}}{V_c} \cdot (1 - x^2) = 1 \quad \dots(20)$$

[0109] Formula (21) is obtained by transforming Formula (20).

[0110] [Math 21]

$$5 \quad V_{dc} = \frac{1}{\frac{x}{V_m} + \frac{1-x^2}{V_c}} = \frac{V_m}{x + \frac{V_m}{V_c}(1-x^2)} \quad \dots(21)$$

[0111] The phase ωt providing a maximum value of the DC voltage V_{dc} provides a minimum value of a denominator of the right-hand side of Formula (21). Therefore, such a phase ωt is obtained as the phase ωt in which a value of Formula (22) indicating a derivative of the denominator is zero.

10 [0112] [Math 22]

$$\begin{aligned} \frac{d}{d(\omega t)} \left[\left| \sin(\omega t) \right| + \frac{V_m}{V_c} (1 - \sin^2(\omega t)) \right] \\ = \cos(\omega t) \cdot \left[1 - \frac{2V_m}{V_c} \sin(\omega t) \right] \quad \dots(22) \end{aligned}$$

[0113] In this case, $x = V_c/(2 \cdot V_m)$. For example, in the above-mentioned example, it is understood that the maximum value of the DC voltage V_{dc} that is constant is approximately 0.96 V_m because $V_c = 1.5 V_m$. Formula (15) reveals that the DC current I_{dc} is 0.96/ $\sqrt{2}$ times the crest value I_m .

[0114] The adoption of a distribution ratio 1/2 as described above can fix the respective duties in accordance with Formulas (11), (12), and (13) and set the DC voltage V_{dc} constant. Moreover, it is revealed that by reducing the zero duty d_z , the voltage utilization ratio R is $\alpha/(1+\alpha \cdot \alpha/4)$ ($\alpha = V_c/V_m$: hereinafter referred to as a "voltage ratio α ") in Formula (21) by setting $x = V_c/(2 \cdot V_m)$.

[0115] The voltage utilization ratio $R = \alpha/(1+\alpha \cdot \alpha/4)$ is greater than the voltage utilization

ratio ($1/\sqrt{2}$) introduced in Non-patent Document 2 and Patent Document 1, and thus, the condition that the voltage ratio α should satisfy is $2\sqrt{2}-2 < \alpha < 2\sqrt{2} + 2$. The both-end voltage V_c is charged to be higher than the crest value V_m , and the voltage ratio α is greater than 1. To set the DC voltage V_{dc} constant, $V_c/V_m \leq 2$ from $x = |\sin(\omega t)| = \alpha/2$.

5 The condition is thus satisfied, yielding a voltage utilization ratio R greater than the voltage utilization ratio ($1/\sqrt{2}$) introduced in Non-patent Document 2 and Patent Document 1.

[0116] It is understood that the voltage utilization ratio R takes a maximum value, 1, when a value obtained by differentiating the voltage utilization ratio R with respect to the ratio α is zero, that is, $\alpha = 2$. That is to say, the maximum value, 1, can be obtained as
10 the voltage utilization ratio R by setting the both-end voltage V_c to be twice the crest value V_m .

[0117] However, increasing the both-end voltage V_c requires increasing the breakdown voltage of the capacitor C_4 . For example, in the use of an electrolytic capacitor having a
15 breakdown voltage of 400 V, which is used in a 200 V system, if a derating is set to 0.9 and an effective value of the power supply voltage is 230 V, $\alpha = 400/(230 \times \sqrt{2}) \times 0.9 = 1.11$. If derating is set to 0.95, $\alpha = 1.17$. Further, when the fact that the power supply voltage increases by 10% is taken into account, the electrolytic capacitor having a breakdown voltage of 450 V is used, and α is 1.13 to 1.19 (a derating is 0.9 to 0.95).

20 [0118] FIG. 5 is a graph showing a voltage utilization ratio R to a voltage ratio α . It is indicated that the both-end voltage V_c needs to be increased to increase the voltage utilization ratio R as described above. For example, R remains at approximately 0.87 if $\alpha = 1.17$.

[0119] FIG. 6 is a graph showing the operation of the direct power converter when the
25 technique described in Patent Document 3 is used, and the quantities are shown as in FIG.

4. Herein, $\alpha = 1.17$. In the technique described in Patent Document 3, the voltage utilization ratio R is set to 1 (i.e., $V_{dc} = V_m$) even when α is approximately 1.17, and the DC current I_{dc} increases up to $1/\sqrt{2}$ of the crest value I_m of the input current I_{in} .

[0120] In the technique described in Patent Document 3, though the DC voltage V_{dc} increases up to the crest value V_m , the current i_l is large and the current i_{rec1} is small compared with the graph of FIG. 4. It is therefore revealed that the charge power P_l is large (power $(-P_1)$ is shown in the graph) and the power P_{rec} is small. This is disadvantageous from the viewpoint of increasing efficiency, as described above.

[0121] (b-4) Correction of Duties

Then, the rectifying duty d_{rec} and the discharge duty d_c are corrected to increase the voltage utilization ratio R at a low voltage ratio α without increasing the charge power P_l . Unlike in the previous section, this correction does not make the current i_{rec1} be a half of the current i_{rec} .

[0122] First, values obtained using the crest value V_m as the DC voltage V_{dc} respectively in Formulas (16) and (17) are adopted as the rectifying duty d_{rec} and the discharge duty d_c . This corresponds to the use of the crest value V_m as the command value V_{dc}^* .

[0123] The rectifying duty d_{rec} is passively determined in accordance with the zero duty d_z and the discharge duty d_c . The sum of the rectifying duty d_{rec} and the discharge duty d_c exceeding 1 is contrary to Formula (11) (because $d_z \geq 0$).

[0124] If the sum of the rectifying duty d_{rec} and the discharge duty d_c exceeds 1, the rectifying duty d_{rec} is determined by setting the zero duty d_z to 0.

[0125] That is to say, the rectifying duty d_{rec} is set to any smaller one of a value obtained by setting $V_{dc} = V_m$ in Formula (16) (hereinafter referred to as a "first correction value") and a value obtained by subtracting the discharge duty d_c (this is a value obtained by setting $V_{dc} = V_m$ in Formula (17)) from 1 (hereinafter referred to as a "second correction

value"). Such a setting will be referred to as a "first modification of duty" below. In the first modification of duty, the zero duty d_z is 0 when the rectifying duty d_{rec} is set to the second correction value.

[0126] Setting the rectifying duty d_{rec} and the discharge duty d_c from Formulas (16) and
 5 (17) while keeping a minimum value of the zero duty d_z to zero or more will be referred to as a "basic setting of duty".

[0127] Adoption of the first modification of rectifying duty decreases the first component $d_{rec} \cdot V_{rec}$ more than in the adoption of the basic setting of duty. Formula (18) thus does not hold. The resultant DC voltage V_{dc} is equal to or smaller than the command value
 10 $V_{dc}^* = V_m$.

[0128] Specifically, the DC voltage V_{dc} pulsates at the command value $V_{dc}^* = V_m$ or less. The DC current I_{dc} is inversely proportional to the DC voltage V_{dc} (see Formula (15)) and accordingly pulsates in opposite phase to the pulsations of the DC voltage V_{dc} .

[0129] However, at the same voltage ratio α , a minimum value of the DC voltage V_{dc}
 15 obtained through pulsations is higher than the DC voltage V_{dc} obtained with reference to Non-patent Document 2 or Patent Document 1, thus increasing the voltage utilization ratio R .

[0130] FIG. 7 is a graph showing the operation of the direct power converter when the first modification of duty is adopted, and the quantities are shown as in FIG. 4. Herein,
 20 $\alpha = 1.17$.

[0131] It is revealed that the adoption of the first modification of rectifying duty as described above yields $V_{dc} = 0.95 V_m$ on average, and the voltage utilization ratio $R = 0.95$ even if $\alpha = 1.17$. This means that improvements were obtained greatly in view of the fact that only $R = 0.87$ was obtained at $\alpha = 1.17$ when the basic setting of duty was
 25 used.

[0132] Formulas (16) and (17) reveal that as the rectifying duty d_{rec} and the discharge duty d_c (even when $V_{dc} = V_m$ is set), a value folded back symmetrically about a phase of 45 degrees is adopted in phases of 0 to 90 degrees, a value folded back symmetrically about a phase of 135 degrees is adopted in phases of 90 to 180 degrees, a value folded back symmetrically about a phase of 225 degrees is adopted in phases of 180 to 270 degrees, and a value folded back symmetrically about a phase of 315 degrees is adopted in phases of 270 to 360 degrees.

[0133] The reason why the voltage utilization ratio R is improved as described above will be described below step by step.

[0134] For the sake of brevity, the case in which the rectifying duty d_{rec} is always set to the second correction value will be described first. Such a setting will be referred to as a "second modification of duty" below. Description will be given of the fact that especially at a small voltage ratio $\alpha (\geq 1)$, the result obtained in the second modification of duty is almost the same as the result obtained in the first modification of duty.

[0135] The zero duty d_z in FIG. 7 is positive only in the neighborhood of the phases of 0, 180, and 360 degrees and is zero at the other degrees. The first correction value is small during the period in which the zero duty d_z is positive and differs little from that in the case in which the second correction value is adopted.

[0136] FIG. 8 is a graph showing the rectifying duty d_{rec} , the discharge duty d_c , and the zero duty d_z when the first modification of duty is adopted and when the second modification of duty is adopted. As in FIG. 7, $\alpha = 1.17$. The rectifying duty d_{rec} set in the first modification of duty is indicated by a waveform d_{rec1} , and the rectifying duty d_{rec} set in the second modification of duty is indicated by a waveform d_{rec2} .

[0137] Herein, the zero duty d_z is a value calculated by Formula (11) when the first correction value is always set to the rectifying duty d_{rec} .

[0138] During the period in which the zero duty d_z is positive, for the first component $d_{rec} \cdot V_{rec}$, a difference between the first component $d_{rec} \cdot V_{rec}$ obtained in the first modification of rectifying duty and the first component $d_{rec} \cdot V_{rec}$ obtained in the second modification of rectifying duty is small because the rectified voltage V_{rec} is also small.

5 A difference in the DC voltage V_{dc} determined by Formula (14) is also small.

[0139] Even when the rectifying duty d_{rec} is set in the second modification of rectifying duty using the quantities used to obtain FIG. 7, a difference in waveform that is shown in the middle tier of FIG. 7 is not visually confirmed.

[0140] The DC voltage V_{dc} obtained by Formula (14) will now be described. Focusing
10 on the second correction value of the rectifying duty d_{rec} being $(1 - d_c)$, from Formula (14), the DC voltage V_{dc} is calculated by Formula (23) below.

[0141] [Math 23]

$$\begin{aligned}
 V_{dc} &= (1 - d_c) \cdot V_{rec} + d_c \cdot V_c \\
 &= V_m \cdot |\sin(\omega t)| + \frac{V_m}{V_c} \cos^2(\omega t) \cdot (V_c - V_m \cdot |\sin(\omega t)|) \\
 &= V_m \cdot |\sin(\omega t)| + V_m \cdot \cos^2(\omega t) - \frac{V_m^2}{V_c} \cos^2(\omega t) \cdot |\sin(\omega t)| \\
 &= V_m + V_m \cdot |\sin(\omega t)| \cdot (1 - |\sin(\omega t)|) - \frac{1}{\alpha} \cos^2(\omega t) \quad \dots (23)
 \end{aligned}$$

[0142] From the function form of Formula (23), an average value of the DC voltage V_{dc}
15 is obtained by substituting a value $\pi/4$ into the phase ωt in Formula (23). For example, if 1.17 is adopted as the voltage ratio α , $V_{dc} \approx 0.952 V_m$. An average voltage utilization ratio R is thus 0.952, revealing that it is higher than $R = 0.87$ shown in FIG. 5.

[0143] The conceivable reason why the voltage utilization ratio R can be increased as described above is that the pulsations of the DC voltage V_{dc} are allowed. Then, the
20 behavior of the pulsations will be considered. A pulsating component ΔV of the DC voltage V_{dc} is expressed by Formula (24) below.

[0144] [Math 24]

$$\begin{aligned}\Delta V &= V_{dc} - V_m \\ &= V_m \cdot |\sin(\omega t)| \cdot \left(1 - |\sin(\omega t)| - \frac{1}{\alpha} \cos^2(\omega t)\right) \quad \dots(24)\end{aligned}$$

[0145] As described above, the voltage ratio α is desirably smaller in view of the breakdown voltage of the capacitor C4, and thus, the voltage ratio α is approximated to 1.

5 Formula (24) is approximated by Formula (25) below.

[0146] [Math 25]

$$\begin{aligned}\Delta V &\approx V_m \cdot |\sin(\omega t)| \cdot (-|\sin(\omega t)| + \sin^2(\omega t)) \\ &= V_m \cdot \frac{1 - \cos(2\omega t)}{2} (|\sin(\omega t)| - 1) \quad \dots(25)\end{aligned}$$

[0147] Further, the approximate expression of Formula (26) is introduced.

[0148] [Math 26]

10 $|\sin(\omega t)| \approx \sin^2(\omega t) \quad \dots(26)$

[0149] The pulsating component ΔV is thus approximated by Formula (27) from Formulas (25) and (26).

[0150] [Math 27]

$$\begin{aligned}\Delta V &\approx V_m \cdot \frac{1 - \cos(2\omega t)}{2} \cdot (-1) \cdot \frac{1 + \cos(2\omega t)}{2} \\ &= -\frac{V_m}{4} \cdot (1 - \cos^2(\omega t)) = \frac{V_m}{4} \cdot (\cos(4\omega t) - 1) \quad \dots(27)\end{aligned}$$

15 [0151] It is revealed that the DC voltage V_{dc} pulsates at a frequency four times the frequency (hereinafter referred to as a "power supply frequency") of the single-phase AC voltage V_{in} in this manner.

[0152] FIGs. 9 and 10 are graphs showing the validity of the approximation from Formula (25) to Formula (27). In FIGs. 9 and 10, a waveform G1 indicates a function

20 $(1/2)(1 - \cos(2\omega t))$. In FIG. 9, a waveform G2 indicates a function $(|\sin(\omega t)| - 1)$, and a waveform G3 indicates a function $(1/2)(1 - \cos(2\omega t)) \cdot (|\sin(\omega t)| - 1)$. In FIG. 10, a

waveform G4 indicates a function $(-1) \cdot (1 + \cos(2\omega t))/2$, and a waveform G5 indicates a function $(1/2)(1 - \cos(2\omega t)) \cdot (-1) \cdot (1 + \cos(2\omega t))/2$.

[0153] It is revealed that the waveform G3 corresponding to Formula (25) closely resembles the waveform G5 corresponding to Formula (27) and that the introduction of
5 the approximation of Formula (26) is valid.

[0154] Formula (27) reveals that the pulsating component ΔV pulsates in a quarter period of the single-phase AC voltage V_{in} . The pulsating component ΔV has a maximum value, 0, and takes values equal to or smaller than 0. In other words, it can be said that the voltage utilization ratio R is improved by the DC voltage V_{dc} pulsating in the quarter
10 period and having a crest value V_m as its maximum value.

[0155] The approximation of Formula (25) cannot be said to be valid if the voltage ratio α is high. The influence of the voltage ratio α on the DC voltage V_{dc} including the influences of the first and second modifications of duty will be described below.

[0156] FIGs. 11 and 12 are graphs showing the dependence of the voltage utilization ratio
15 R on phase, showing a plurality of waveforms with different voltage ratios α . FIG. 11 shows the case in which the second modification of duty is adopted, and FIG. 12 shows the case in which the first modification of duty is adopted.

[0157] The ratio of the DC voltage V_{dc} to the crest value V_m is the voltage utilization ratio R as described above, and thus, the pulsations of the voltage utilization ratio R are
20 directly proportional to those of the DC voltage V_{dc} .

[0158] The waveforms of FIG. 12 are waveforms obtained by clamping the waveforms of FIG. 11 at $R \geq 1$ to $R = 1$. This is because the phase domain in which $R \geq 1$ with the waveforms of FIG. 11 corresponds to the case in which the rectifying duty d_{rec} takes the first correction value, that is, the case in which $dz \geq 0$.

25 [0159] The comparison between FIGs. 11 and 12 reveals that there is no significant

difference between the adoptions of the first and second modifications of duty at a voltage ratio α of 1 to 1.2 and that the waveforms are sinusoidal waveforms that pulsate in the quarter period.

[0160] Conversely, if the voltage ratio α is approximately 1.5, the waveform of the DC voltage V_{dc} is distorted greatly from the sinusoidal waveform.

[0161] For reference, FIG. 13 shows a graph showing the dependence of the voltage utilization ratio R on phase when the basic setting of duty is adopted. In such a case, the DC voltage V_{dc} is constant. The case in which $\alpha = 1.5$ in FIG. 13 corresponds to the graph of the quantities in FIG. 4. The DC voltage V_{dc} takes a constant value in FIG. 4, which also appears in FIG. 13.

[0162] The dependence of the voltage utilization ratio R on the voltage ratio α , appearing in FIG. 13, has been shown in FIG. 5.

[0163] (b-5) Comparison between Results

FIG. 14 is a graph showing the dependence of the voltage utilization ratio R on the voltage ratio α . A waveform G7 indicates the same details as those of the graph shown in FIG. 5.

[0164] A waveform G6 indicates an average value of the voltage utilization ratio R when the first modification of duty is adopted. An average value, 0.952 V_m , of the DC voltage V_{dc} obtained from Formula (23) by adopting 1.17 as the voltage ratio α reveals that an average value of the voltage utilization ratio R takes a value 0.952. This means that the waveform G6 nearly matches the voltage utilization ratio R indicated at $\alpha = 1.17$. It is revealed that if the voltage ratio α is around 1, as described above, there is no significant difference between the adoptions of the first and second modifications of duty.

Since the waveform G6 indicates a greater voltage utilization ratio R than the waveform G7 (at the same voltage ratio α), it is revealed that the voltage utilization ratio R is made

higher when the first modification of duty is adopted than when the basic setting of duty is adopted. At a voltage ratio α of approximately 1 to 1.2 that is desirable from the viewpoint of the breakdown voltage of the capacitor C4, the voltage utilization ratio R is improved by approximately 0.03 to 0.04.

5 [0165] This is because when the first or second modification of duty is adopted, due to the fact that the second correction value is determined, $V_{dc} = V_m$ is set in Formula (17) as the discharge duty d_c ; when the basic setting of duty is adopted, the discharge duty d_c is directly proportional to the DC voltage V_{dc} as in Formula (17), and is accordingly directly proportional to the voltage ratio ($1/\alpha$).

10 [0166] When the basic setting of duty is adopted as described above, the discharge duty d_c becomes greater as the voltage ratio α is smaller, and the voltage utilization ratio R decreases remarkably. In contrast, when the first modification of duty is adopted (and when the second modification of duty is adopted in the domain with a small voltage ratio α), the DC voltage V_{dc} takes the crest value V_m almost for each phase $\pi/2$, resulting in a
15 greater average value of the DC voltage V_{dc} . A difference between the waveforms G6 and G7 is more remarkable as the voltage ratio α is smaller.

[0167] FIGs. 15 and 16 are graphs showing the dependence of duties on phase, where voltage ratio α is set to 1. FIG. 15 shows the case in which basic setting of duty is used, and FIG. 16 shows the case in which first modification of duty is used and the case in
20 which the second modification of duty is used.

[0168] The same quantities as those in FIG. 16 have already been shown in FIG. 8. FIG. 8 shows the case of the voltage ratio $\alpha = 1.17$, where there is a difference between the waveforms d_{rec1} and d_{rec2} . FIG. 16, however, shows the case of the voltage ratio $\alpha = 1$, and no difference is visually confirmed between these waveforms. Thus, when the zero
25 duty d_z is shown in accordance with Formula (11) in FIG. 16, its value is equal to or

smaller than zero in almost all the phases.

[0169] As is obvious from the comparison between FIGs. 15 and 16, when the basic setting of duty is adopted, the discharge duty d_c is greater at a smaller voltage ratio α . This incurs a decrease in voltage utilization ratio R as described above.

5 [0170] Referring back to FIG. 14, a waveform G8 shows the dependence of the voltage utilization ratio R obtained using the minimum value of the DC voltage V_{dc} on the voltage ratio α in the first modification of duty. That is to say, it is revealed that not with an average value but even with a minimum value of the DC voltage V_{dc} that pulsates, the voltage utilization ratio R is made higher when the first modification of duty
10 is adopted than when the basic setting of duty is adopted.

[0171] Obtaining the voltage utilization ratio R using the minimum value of the DC voltage V_{dc} has the following meaning. That is to say, a modulation factor of the inverter 5 is set to V^*/V_{dc} by introducing the command value V^* of an amplitude of a voltage output from the inverter 5. This enables control of a modulation factor in which
15 the pulsations of the DC voltage V_{dc} have been compensated.

[0172] When the command value V^* reaches a minimum value of the DC voltage V_{dc} , the modulation factor is subjected to amplitude modification. Thus, the voltage utilization ratio R using the minimum value of the DC voltage V_{dc} applies to the voltage utilization ratio R of the DC voltage V_{dc} used by the inverter 5. In other words, the
20 inverter 5 can perform DC/AC conversion with the minimum value of the DC voltage V_{dc} as its upper limit.

[0173] FIGs. 17 and 18 are graphs showing an operation of the direct power converter as in FIG. 6 and show the quantities as in FIG. 4. A common value, 1.17, is adopted as the voltage ratio α in FIGs. 6, 17, and 18. FIG. 6 shows the case in which the technique
25 described in Patent Document 3 is adopted, while FIG. 17 shows the case in which the

first modification of duty is adopted. Although the DC voltage V_{dc} becomes smaller when the first modification of duty is adopted by an amount of the pulsations of the DC voltage V_{dc} than when the technique described in Patent Document 3 is adopted, it can be seen that the current i_l is small and efficiency is high.

5 [0174] FIG. 18 shows the case in which the DC voltage V_{dc} is made constant using the basic setting of duty, and R remains at approximately 0.87 if $\alpha = 1.17$ as described with reference to FIG. 5 (as also indicated by the waveform G7 of FIG. 14).

[0175] FIG. 19 is a graph showing the ratio between the power P_{rec} (from the converter 3 toward the inverter 5) and the charge power P_i (input to the power buffer circuit 4). An
10 input power $P_{dc} (= (1/2) \cdot V_m \cdot I_m)$ expressed by the first term of the left-hand side of Formula (1) is $\sqrt{2}/2 (\approx 0.7)$ using $V_m = 1$ and $I_m = \sqrt{2}$, according to FIG. 4.

[0176] When the basic setting of duty is adopted, since $i_{rec1} = i_l$ as expressed by Formula (19), P_{rec} matches P_i nearly at 0.35. This value does not depend on the voltage ratio α . The powers P_{rec} and P_i are indicated by a waveform G10.

15 [0177] As is obvious from the comparison between FIGs. 18 and 17, at the same voltage ratio α , the current i_{rec1} is larger and the current i_l is smaller when the first modification of duty is adopted than when the basic setting of duty is adopted. However, when the first modification of duty is adopted, discrepancies of the power P_{rec} (indicated by a waveform G11) or the charge power P_i (indicated by a waveform G12) from a value 0.35
20 become more conspicuous at a smaller voltage ratio α but remain at approximately 10% or less.

[0178] Contrastingly, in the technique described in Patent Document 3, the current i_l increases and the current i_{rec1} decreases as described with reference to FIG. 6, and such a tendency becomes remarkable especially in the domain with a small voltage ratio α . As
25 described above, the voltage ratio α is desirably kept at 1.2 or less in consideration of the

derating of the capacitor C4, and in such a domain, the power P_{rec1} (indicated by a waveform G13) is much smaller than the charge power P_l (indicated by a waveform G14). In the technique described in Patent Document 3, accordingly, efficiency becomes lower than in the case in which the basic setting of duty is adopted. In contrast, the comparison between the waveforms G10 and G11 and the comparison between the waveforms G10 and G12 also show that the efficiency does not decrease but, on the contrary, is improved slightly by the adoption of the first modification of duty.

[0179] As described above, adopting the first modification of duty can increase the voltage utilization ratio R without decreasing the efficiency. This means that, in other words, the DC voltage V_{dc} can be increased without increasing the power covered by the power buffer circuit 4.

[0180] One reason why this advantage is achieved is that the discharge duty d_c is obtained at $V_{dc} = V_m$ in Formula (17). That is to say, one reason why the above advantage is achieved is that the discharge duty d_c is set to a value $(V_m/V_c)\cos^2(\omega t)$ obtained by dividing the product of the crest value V_m and a square $\cos^2(\omega t)$ of a cosine value $\cos(\omega t)$ of the phase ωt by the both-end voltage V_c across the capacitor C4.

[0181] Another reason is that the DC voltage V_{dc} pulsates in the quarter period, that is, with a quarter of the period of the single-phase AC voltage V_{in} as its fundamental period. The DC voltage V_{dc} varies with a half of the period in which the discharge duty d_c varies as its fundamental period. Consequently, the DC voltage V_{dc} can be increased by increasing the ratio (the inverse of the voltage ratio α) of the crest value V_m to the both-end voltage V_c (i.e., by reducing the both-end voltage V_c), which affects the discharge duty d_c . This decreases the both-end voltage V_c required for obtaining a desired DC voltage V_{dc} , so that the breakdown voltage required for the capacitor C4 is reduced.

[0182] Such pulsations of the DC voltage V_{dc} can be achieved by setting the rectifying duty d_{rec} in a first setting of duty or a second setting of duty. The first correction value of the rectifying duty d_{rec} is an absolute value $|\sin(\omega t)|$ of the sine value $\sin(\omega t)$ of the phase ωt , and the second correction value is a value $(1 - d_c)$ obtained by subtracting the discharge duty d_c from 1.

[0183] In the basic setting of duty, the zero duty d_z is difficult to be reduced because a minimum value of the zero duty d_z needs to be kept at zero or more. Thus, the use of the first setting of duty or the second setting of duty can easily reduce the zero duty d_z while keeping a minimum value of the zero duty d_z at zero or more.

[0184] If the voltage ratio α is 1 or more and 1.2 or less as described above, there is no significant difference between the result obtained when the first setting of duty is used and the result obtained when the second setting of duty is used, and the pulsations of the DC voltage V_{dc} have almost a sinusoidal waveform. The use of the second setting of duty is advantageous in that the need for comparing the first correction value with the second correction value in magnitude is eliminated, simplifying control.

[0185] As described in a second modification and a third modification, which will be described below, the above-mentioned advantage can be achieved even when the DC voltage V_{dc} pulsates with a half of the period of the single-phase AC voltage V_{in} as a period. In other words, the DC voltage V_{dc} may vary in the period in which the discharge duty d_c varies.

[0186] (b-6) Correction of Command Value Associated with Correction of Duty

The correction of the discharge duty d_c and the rectifying duty d_{rec} as described above results in the correction of the operation of the inverter 5 as well. Typically, the technique using a carrier for inverter and a command value to the carrier in, for example,

Non-patent Documents 2 and 4 and Patent Document 1 is publicly known as the

technique for controlling the inverter 5 on the basis of the rectifying duty d_{rec} , the discharge duty d_c , and the zero duty.

[0187] How the command value is corrected in association with the correction of duty will be merely described below, and a detailed description on the control of the inverter 5 will be omitted.

[0188] FIG. 20 is a graph showing the operations of switches S_{rec} , S_c , and S_z of the equivalent circuit shown in FIG. 3 and the operations of the switching elements S_{up} , S_{vp} , and S_{wp} of the inverter 5. The switching elements S_{un} , S_{vn} , and S_{wn} of the inverter 5 are basically complementary to the operations of the switching elements S_{up} , S_{vp} , and S_{wp} , description of which will be omitted here.

[0189] For the sake of brevity, description will be given of the case in which a carrier C serves as a carrier for controlling the power buffer circuit 4 and a carrier for controlling the inverter 5. Such a technique is used also in Non-patent Document 2 and Patent Document 1.

[0190] A duration t_s of a period of the carrier C is introduced, and the first correction value d_{rec1} and the second correction value d_{rec2} of the rectifying duty d_{rec} are introduced.

[0191] FIG. 20 shows the case in which the rectifying duty d_{rec} takes the second correction value d_{rec2} when the first modification of rectifying duty is adopted. In other words, this is the case in which $d_{rec1} + d_c = |\sin(\omega t)| + (1/\alpha)\cos^2(\omega t) > 1$.

[0192] A duration t_c is a duration in which the carrier C is equal to or greater than a value $(1 - d_c)$, which is a duration in which the switch S_c is conductive (indicated by "on" in the figure: the same applies to the other portion). The duration t_c is equal to a product $d_c \cdot t_s$ of the discharge duty d_c and the duration t_s .

[0193] The duration t_{rec} is a duration in which the carrier C is equal to or smaller than the

first correction value d_{rec1} , which is equal to a product $d_{rec1} \cdot t_s$ of the first correction value d_{rec1} and the duration t_s . However, the case of $d_{rec1} + d_c > 1$ is shown, and the duration t_{rec} is not a duration in which the switch S_{rec} is conductive. The reason for the above is as follows: since the voltage ratio α is equal to or greater than 1, when the switch S_c is conductive and the both-end voltage V_c across the capacitor C_4 is applied to the DC link 7, no current flows from the converter 3 to the DC link 7, and the switch S_{rec} is accordingly not conductive. This corresponds to the virtual zero duty $d_{z1}=1-d_{rec1}-d_c$ being negative.

[0194] For reference, FIG. 20 shows, by an extended dashed line, a duration in which the switch S_{rec} is conductive assuming that the switch S_{rec} is conductive during the duration t_{rec} . The switch S_{rec} , however, is complementarily conductive with the switch S_c , and the switch S_z is always non-conductive during the duration t_s (indicated by "off" in the figure: the same applies to the other portion).

[0195] When the first setting of duty is used, the period in which the switch S_{rec} is conductive is a duration in which the carrier C is equal to or smaller than the second correction value d_{rec2} . The second correction value d_{rec2} is equal to the value $(1 - d_c)$. This is also equal to a sum $(d_{rec1} + d_{z1})$ of the first correction value d_{rec1} and the virtual zero duty d_{z1} .

[0196] As described above, a signal SS_c for controlling the operation of the switch S_c is achieved through the comparison between the carrier C and the value $(1 - d_c)$.

[0197] The signal SS_l is obtained by a publicly known technique (for example, Patent Document 1) once the current i_l is determined, description of which will be omitted here. The current i_l is obtained by a calculation $(I_m \cdot |\sin(\omega t)| - d_{rec} \cdot V_{dc})$ of the right-hand side of the first equal sign of Formula (19). In this calculation, $d_{rec} = 1 - d_c$ and $I_{dc} =$

$P_{dc}/V_{dc} = V_m \cdot I_m / (2 \cdot V_{dc})$ may be used. In such a calculation, the approximate

expression of Formula (27) is useful from the viewpoint of easily obtaining the DC voltage V_{dc} .

[0198] The second correction value $drec2$ of the rectifying duty $drec$ is used as the rectifying duty $drec$ as described above, and accordingly, the command values to the carrier C for obtaining the voltage command values V_u^* , V_v^* , and V_w^* of the three-phase voltage to be output from the inverter 5 are $drec2+dc \cdot V_w^*$, $drec2+dc \cdot V_v^*$, $drec2+dc \cdot V_u^*$, $drec2 \cdot (1-V_u^*)$, $drec2 \cdot (1-V_v^*)$, and $drec2 \cdot (1-V_w^*)$.

[0199] The switching element Sup is conductive when the carrier C is equal to or greater than the command value $drec2+dc \cdot V_u^*$ or is equal to or smaller than the command value $drec2 \cdot (1-V_u^*)$. The switching element Svp is conductive when the carrier C is equal to or greater than the command value $drec2+dc \cdot V_v^*$ or is equal to or smaller than the command value $drec2 \cdot (1-V_v^*)$. The switching element Swp is always non-conductive during the duration t_s .

[0200] FIG. 20 additionally shows voltage vectors V_0 , V_4 , and V_6 . The voltage vector V_0 shows the state in which all the switching elements Sup , Svp , and Swp are non-conductive (all the switching elements S_{un} , S_{vn} , and S_{wn} are accordingly conductive), the voltage vector V_4 shows the state in which the switching element Sup is conductive and the switching elements Svp and Swp are non-conductive (accordingly, the switching element S_{un} is non-conductive and the switching elements S_{vn} and S_{wn} are conductive), and the voltage vector V_6 shows the state in which the switching elements Sup and Svp are conductive and the switching element Swp is non-conductive (accordingly, the switching elements S_{un} and S_{vn} are non-conductive and the switching element S_{wn} is conductive).

[0201] The correction of the command values when $dz1 < 0$ as described above is introduced in, for example, Patent Document 2 in view of $drec2 = drec1 + dz1$, detailed

description of which will be omitted. The generation of the signals SSup, SSvp, SSwp, SSun, SSvn, and SSwn associated with the correction is introduced in, for example, Patent Document 2, detailed description of which will be omitted.

[0202] C. Modifications

5 (c-1) First Modification

The filter 2 can also be provided between the converter 3 and the power buffer circuit 4 even when any of the techniques described above is used.

[0203] FIG. 21 is a circuit diagram showing, as the modification, only the vicinity of the converter 3, the power buffer circuit 4, and the filter 2 that is provided therebetween.

10 [0204] When such a configuration is used, a diode D0 is desirably provided between the filter 2 and the discharge circuit 4a in the DC power supply line LH. The anode of the diode D0 is located adjacent to the filter 2, and the cathode of the diode D0 is located remote from the discharge circuit 4a.

[0205] The diode D0 prevents the both-end voltage across the capacitor C2 from being
15 affected by the both-end voltage Vc across the capacitor C4 by switching of the switch Sc.

[0206] (c-2) Second and Third Modifications

The basic setting of duty and the first modification of duty may be used together. Specifically, the basic setting of duty and the first modification of duty can be used
20 alternately for each quarter of the period of the single-phase AC voltage Vin. Consequently, the DC voltage Vdc varies in a pair of sections that are not adjacent to each other among the sections equally dividing the period into four and is constant in the other pair of the sections.

[0207] FIG. 22 is a graph showing the operation of the direct power converter when the
25 basic setting of duty in a quarter period centered around an integral multiple of 180

degrees of the phase ωt and adopts the first modification of duty in the other quarter periods (hereinafter referred to as a "second modification"). FIG. 23 is a graph showing an operation of the direct power converter when the first modification of duty in a quarter period around an integral multiple of 180 degrees of the phase ωt and adopts the basic setting of duty in the other quarter periods (hereinafter referred to as a "third modification"). Since a value 1.17 is used as the voltage ratio α in both the cases, FIG. 22 shows the waveforms in which the graph shown in FIG. 17 and the graph shown in FIG. 18 are used alternately per quarter period. The voltage utilization ratio R is 0.913 in any of the cases, which is a value between a value 0.95 of the voltage utilization ratio R when the first modification of duty is used and a value 0.87 of the voltage utilization ratio R when the basic setting of duty is used.

[0208] It can be regarded in both of the second modification and the third modification that the DC voltage V_{dc} varies with a half of the period of the single-phase AC voltage V_{in} as its fundamental period or the DC current I_{dc} varies with a half of the above-mentioned period as its fundamental period. Since the DC voltage V_{dc} when the first modification of duty is used varies with a quarter of the above-mentioned period as its fundamental period, it can be regarded that the voltage V_{dc} varies in a half period that its twice the fundamental period.

[0209] A case in which the input power P_{dc} takes a constant value is assumed as expressed by Expression (15) and also as indicated by a waveform in both of FIGs. 22 and 23. In such a case, when the DC voltage V_{dc} is varied with $1/N$ of the above-mentioned period as its fundamental period, the controller 10 is required to have a current control band that is N or more times the power supply frequency. Compared with the case in which the first setting of duty is used, the second modification and the third modification are advantageous in that a current control band required for the

controller 10 is mitigated.

[0210] As described in Patent Document 4, control for making a buffering power P_{buf} smaller than an AC component $P_{in}^{\wedge}$ is desired to reduce the power capacity of the power buffer circuit 4. In other words, control is desirably performed to make an AC component $P_{in}^{\wedge}$ greater than the buffering power P_{buf} . In this case, the DC current I_{dc} is desirably large during a duration in which the rectified voltage V_{rec} is large and small during a duration in which the rectified voltage V_{rec} is small. Thus, it is desirable that the basic setting of duty in a quarter period centered around an integral multiple of 180 degrees of the phase ωt and adopt the first modification of duty in the other quarter periods as in the second modification.

[0211] Such a behavior of the DC current I_{dc} is preferable when the inductive load 6 having a relatively small torque load is used, such as a motor (e.g., magnet-embedded motor) that drives a compressor of an air conditioner. This is because in the domain that requires torque current to increase an rpm, the advancement of a current phase required in a so-called flux-weakening domain is regulated by increasing a voltage that can be output from the inverter 5. This is desirable in view of increasing an upper limit of the rpm compared with the case in which the basic setting of duty is used or compared with the third modification.

[0212] While the present invention has been described in detail, the foregoing description is in all aspects illustrative and not restrictive. It is therefore understood that numerous modifications that have not been described can be devised without departing from the scope of the present invention.

CLAIMS

1. A power converter comprising:

a DC link (7) including a first power supply line (LH) and a second power supply line (LL);

5 a converter (3) that receives a single-phase AC voltage (V_{in}) and outputs a pulsating power (P_{in}) to said DC link;

an inverter (5) that receives a power from said DC link and outputs an AC current (I_u, I_v, I_w); and

a power buffer circuit (4) that receives a charge power (P_l) from said DC link and
10 outputs a discharge power (P_c) to said DC link,

wherein

an input power (P_{dc}) input to said inverter (5) takes a value ($P_{in} + P_c - P_l$) obtained, from said DC link (7), by subtracting said charge power from a sum of said pulsating power and said discharge power,

15 said charge power (P_l) takes a value ($P_{in}/2$) that is a half of said pulsating power (P_{in}),

said discharge power (P_c) takes a value ($P_{in}^{\wedge} + P_l$) obtained by adding said charge power to an AC component ($P_{in}^{\wedge}$) of said pulsating power,

said converter (3) applies a rectified voltage (V_{rec}) obtained by full-wave
20 rectifying said single-phase AC voltage (V_{in}) to said DC link (7) while setting said first power supply line (LH) to have a higher potential than said second power supply line (LL),

said power buffer circuit (4) includes

a discharge circuit (4a) including a capacitor (C_4) and a switch (Sc, D_{42})
25 connected in series to said capacitor (C_4) adjacent to said first power supply line between

said first power supply line and said second power supply line, and

a charge circuit (4b) that charges said capacitor,

a discharge duty (dc) that is a duty at which said switch is conductive takes a value $((V_m/V_c)\cos^2(\omega t))$ obtained by dividing a product of a crest value (V_m) of said

5 single-phase AC voltage and a square ($\cos^2(\omega t)$) of a cosine value of a phase of said single-phase AC voltage by a both-end voltage (V_c) across said capacitor,

said converter is conductive at a rectifying duty (drec), and

a DC voltage (V_{dc}) that is a sum of a product ($d_{rec} \cdot V_{rec}$) of said rectified voltage and said rectifying duty and a product ($dc \cdot V_c$) of said both-end voltage and said
10 discharge duty varies in a period that is a half of a period of said single-phase AC voltage.

2. The power converter according to claim 1, wherein said rectifying duty takes any one smaller value of an absolute value ($|\sin(\omega t)|$) of a sine value of said phase and a value ($1 - dc$) obtained by subtracting said discharge duty (dc) from 1.

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3. The power converter according to claim 1, wherein said rectifying duty takes a value ($1 - dc$) obtained by subtracting said discharge duty (dc) from 1.

4. The power converter according to any one of claims 1 to 3, wherein a ratio
20 (V_c/V_m) of said both-end voltage (V_c) to said crest value (V_m) is 1 or more and 1.2 or less.

5. The power converter according to any one of claims 1 to 3, wherein said inverter (5) performs DC-AC conversion with a minimum value of said DC voltage (V_{dc})
25 as an upper limit.

6. The power converter according to claim 4, wherein said inverter (5) performs DC-AC conversion with a minimum value of said DC voltage (V_{dc}) as an upper limit.

5 7. The power converter according to any one of claims 1 to 3, wherein said DC voltage varies with a quarter of said period of said single-phase AC as a fundamental period.

8. The power converter according to claim 4, wherein said DC voltage varies with
10 a quarter of said period of said single-phase AC as a fundamental period.

9. The power converter according to any one of claims 1 to 3, wherein said DC voltage varies in a pair of sections that are not adjacent to each other among sections equally dividing said period of said single-phase AC into four and is constant in the other
15 pair of sections.

10. The power converter according to claim 4, wherein said DC voltage varies in a pair of sections that are not adjacent to each other among sections equally dividing said period of said single-phase AC into four and is constant in the other pair of sections.