

3. The method according to any one of claims 1 to 2,
wherein the second-partition element indexing scheme is specified per transmission point cell.
4. The method according to any one of according to claims 1 to 2,
wherein at least one of the second-partition element index and information regarding first partition elements is unique per user equipment.
5. The method according to any one of claims 1 to 4,
wherein each second-partition element index is mapped to one or more third-partition element indexes.
6. The method according to any one of claims 1 to 5, wherein
determining the number of second-partition elements comprises deriving the number from a subframe type.
7. The method according to any one of claims 1 to 6, wherein
the second-partition element indices are determined so as to form a continuous set of indices.
8. The method according to any one of claims 1 to 7, wherein
the second-partition element indices are determined starting from the second-partition element on the first partition element with the lowest index.
9. The method according to any one of claims 1 to 7, wherein
the second-partition element indices are determined starting from the second-partition element on the first partition element with the highest index.
10. The method according to any one of claims 1 to 9, wherein
determining at least one third-partition element index comprises one-to-one mapping between the second-partition element index and the third-partition element index starting from the lowest second-partition element index.
11. The method according to any one of claims 1 to 9, wherein