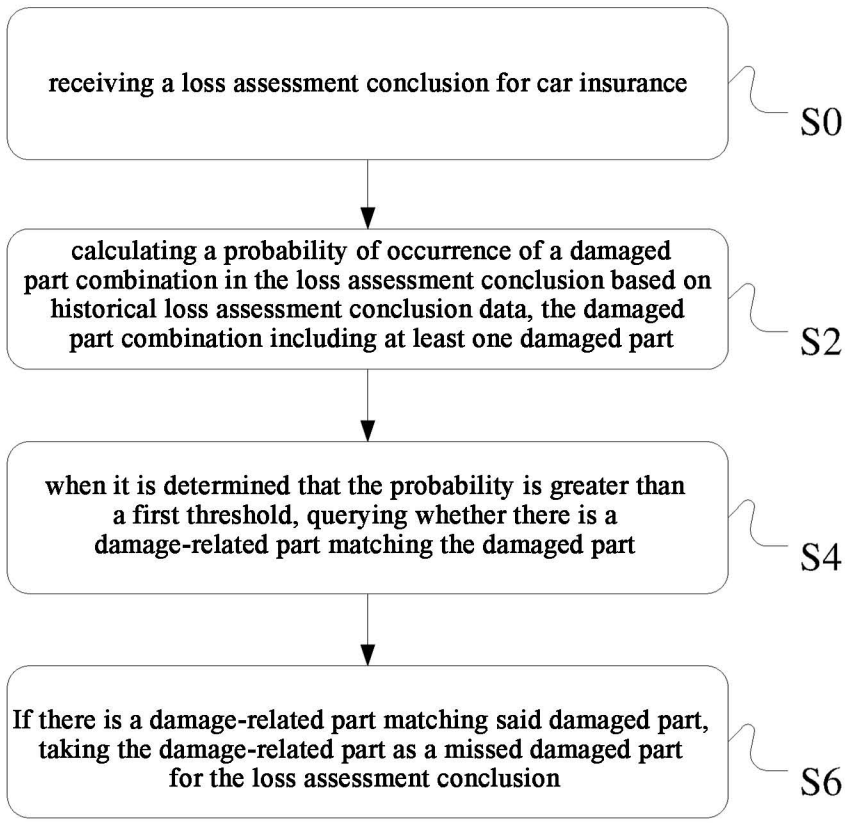

receiving a loss assessment conclusion for car insurance
S0
calculating a probability of occurrence of a damaged part combination in the loss assessment conclusion based on historical loss assessment conclusion data, the damaged part combination including at least one damaged part
S2
when it is determined that the probability is greater than a first threshold, querying whether there is a damage-related part matching the damaged part
S4
If there is a damage-related part matching said damaged part, taking the damage-related part as a missed damaged part for the loss assessment conclusion
S6

Fig. 1

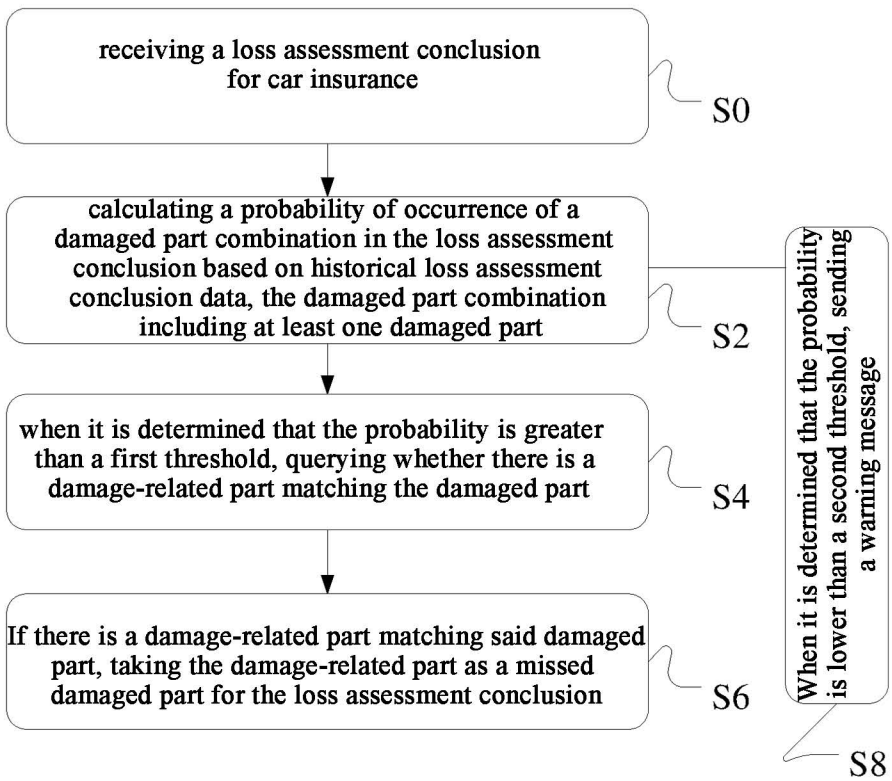

receiving a loss assessment conclusion for car insurance
S0
calculating a probability of occurrence of a damaged part combination in the loss assessment conclusion based on historical loss assessment conclusion data, the damaged part combination including at least one damaged part
S2
when it is determined that the probability is greater than a first threshold, querying whether there is a damage-related part matching the damaged part
S4
If there is a damage-related part matching said damaged part, taking the damage-related part as a missed damaged part for the loss assessment conclusion
S6
When it is determined that the probability is lower than a second threshold, sending a warning message
S8

Fig. 2

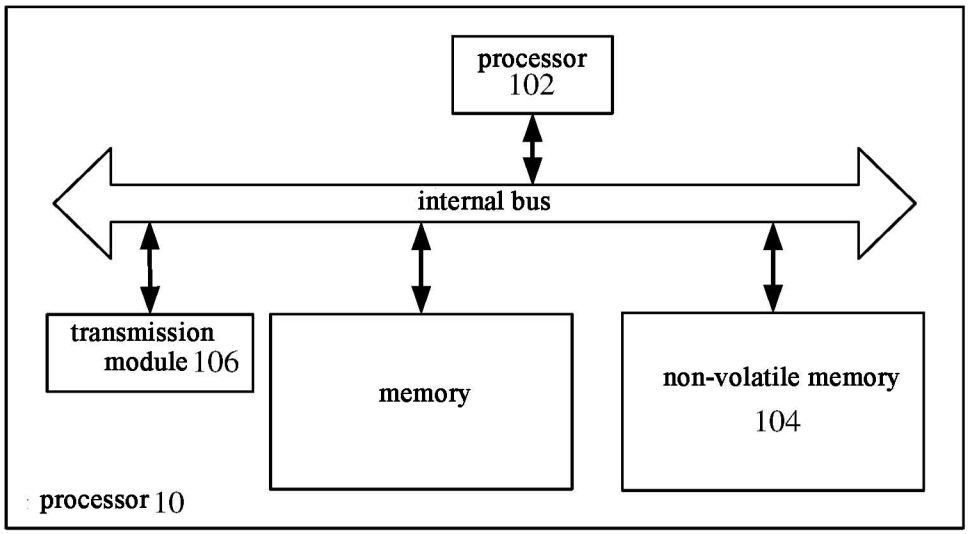

processor
102
internal bus
transmission
module 106
memory
non-volatile memory
104
processor 10

Fig. 3

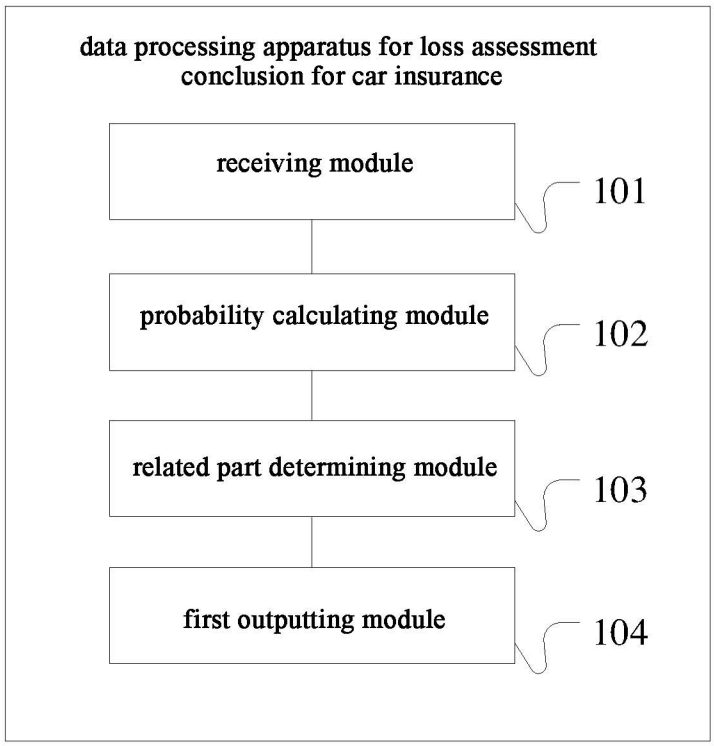

data processing apparatus for loss assessment
conclusion for car insurance
receiving module
101
probability calculating module
102
related part determining module
103
first outputting module
104

Fig. 4

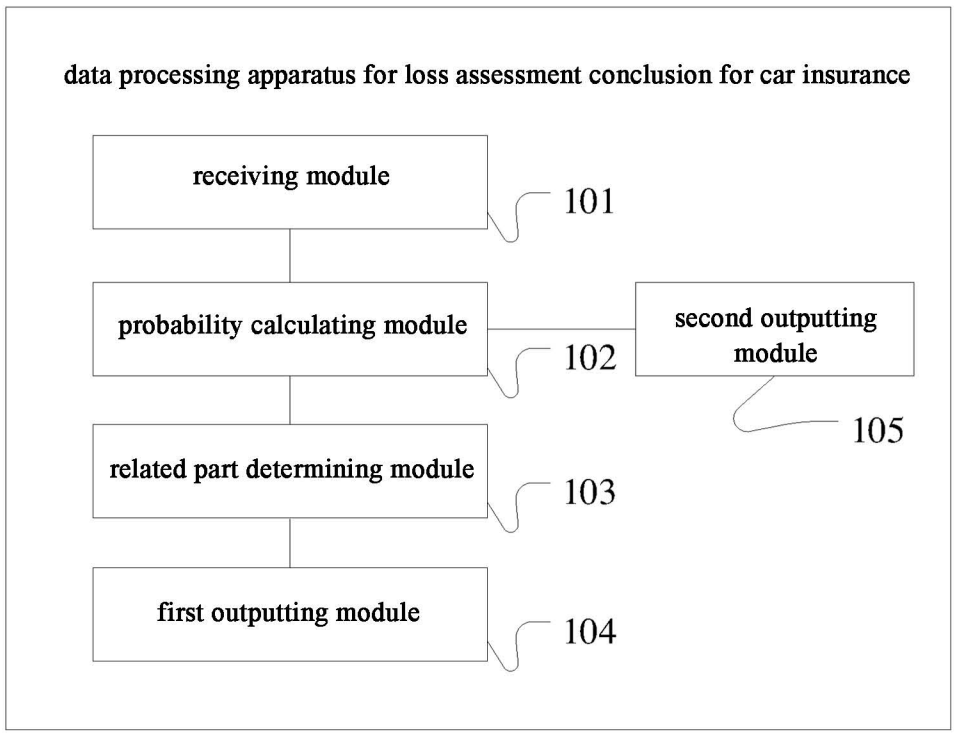

data processing apparatus for loss assessment conclusion for car insurance
receiving module
101
probability calculating module
102
second outputting module
105
related part determining module
103
first outputting module
104

Fig. 5

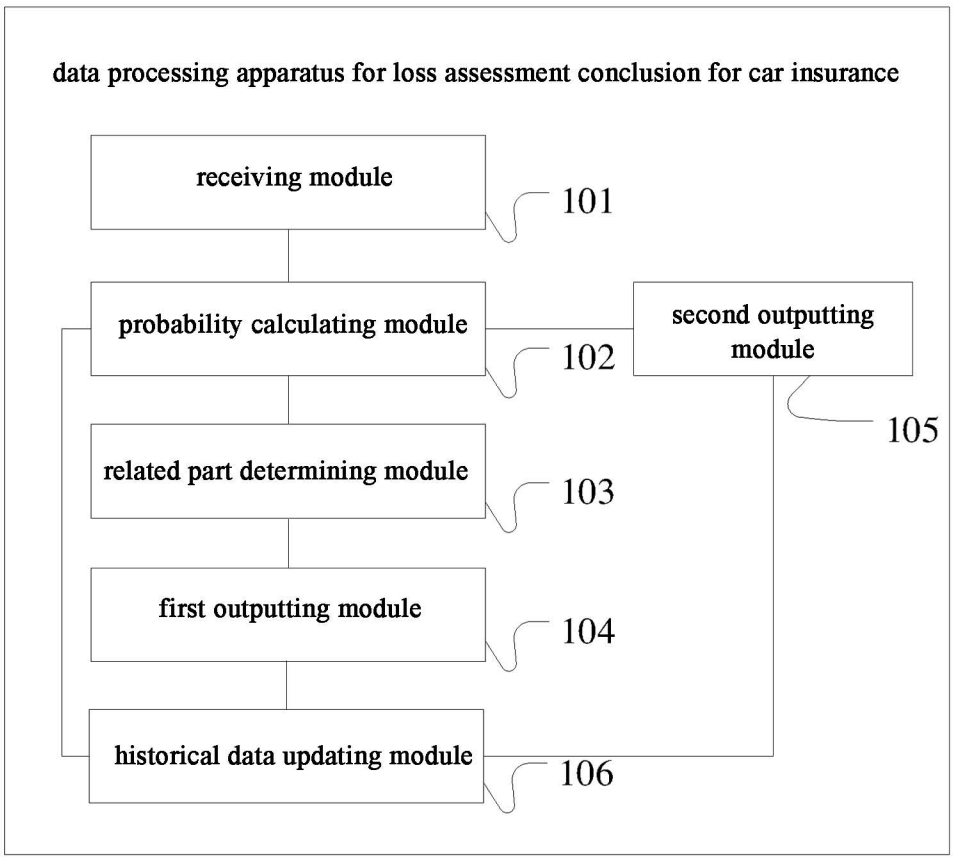

data processing apparatus for loss assessment conclusion for car insurance
receiving module
101
probability calculating module
102
second outputting module
105
related part determining module
103
first outputting module
104
historical data updating module
106

Fig. 6

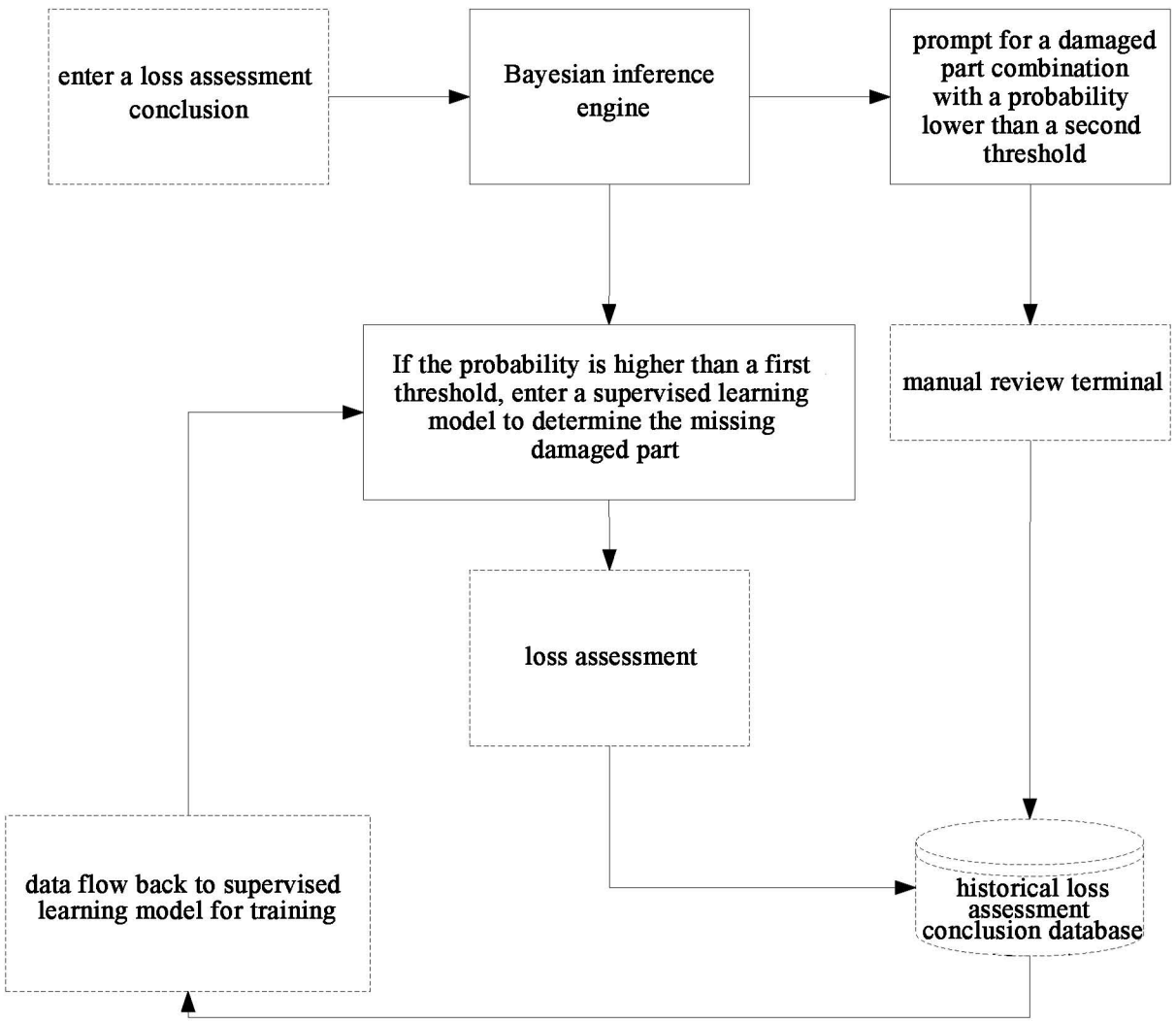

enter a loss assessment conclusion
Bayesian inference engine
prompt for a damaged part combination with a probability lower than a second threshold
If the probability is higher than a first threshold, enter a supervised learning model to determine the missing damaged part
manual review terminal
loss assessment
data flow back to supervised learning model for training
historical loss assessment conclusion database

Fig. 7