ABSTRACT

ROLLING ROBOT COMPRISING AN ARM

The invention relates to a rolling robot (1000) comprising movement means (1010, 1020) that allow it to move parallel to a first movement plane (P1) or alternatively parallel to a second movement plane (P2), and also a body (1030), the volume of which is confined between the two movement planes (P1, P2), characterized in that it also comprises an arm (1040) that is mounted on the body and assumes either a stowed configuration (R) in which it is confined between the two movement planes, or a first deployed configuration (D1) in which it projects through the first movement plane (P1), or a second deployed configuration (D2) in which it projects through the second movement plane (P2).

FIG 1