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MOVING PICTURES ENCODING WITH CONSTANT OVERALL BIT-RATE

Field of the invention

The present invention relates to a method and apparatus for encoding moving pictures. In particular, the present invention relates to a method and apparatus for performing variable bit rate control in a digital video encoder while maintaining a particular overall bit-rate.

Background of the Invention

One of the main obstacles faced by industry dealing with digital video processing, storage and transmission is the large amount of data needed to represent analog video in the digital domain. Accordingly, digital compression is often applied to moving pictures to achieve a reduction in required transmission bandwidth or storage size. One variety of such compression techniques can be derived from the ISO/IEC MPEG Standards, the ISO/IEC 11172-3 (MPEG-1), the ISO/IEC 13818-2 (MPEG-2) and the MPEG-2 TM5 (test model 5), developed by the Moving Picture Experts Group of the International Organisation for Standardization. The disclosures of those standards documents are hereby expressly incorporated into this specification by reference. MPEG-1 is the compression standard used in VideoCD while MPEG-2 is the video compression standard used in DVD and many digital broadcasting systems.

The MPEG standards specify only the syntax of the compressed bitstreams and method of decoding. The method of implementation in the encoder is left to the developer, and any form of encoder may be employed as long as the resulting bitstream conforms with the specified syntax.

In certain applications such as video storage device (recorder), it is possible to use variable bit rate (VBR) encoding. A VBR encoder is able to vary its output bit-rate over a larger range than a CBR encoder, and this would generate an output which has a more constant

visual quality. An example of a VBR encoder is described in United States patent number 5,650,860, entitled "Adaptive Quantization". In order to maintain a maximum bit rate allowed by the target storage device as well as an overall bit-rate which enables input picture sequence to be stored into a defined storage space, such VBR encoders utilise multiple encoding passes.

In the first encoding pass, the bit utilisation information is determined for each scene or each picture in the input sequence. This may be done by fixing the reference quantisation step size and disabling the VBV control. The determined bit utilisation information is then used to generate a bit budget for each scene or picture such that an overall target number of bits to code the sequence is fixed, and that the maximum bit rate is not violated. In cases that bit utilisation information obtained is not close to that required for generating the bit budget, steps from the first coding pass must be repeated with an adjusted reference quantisation step-size. The input sequence is coded in a final pass using the generated bit budget information to achieve the target bits or overall bit rate.

Multiple-pass VBR encoders requires large storage memory for intermediate bit utilisation information, and large computation needs for the additional passes and bit budget generation. Furthermore, such a VBR encoder cannot process input sequences in real-time as required by certain applications.

Summary of the Invention

It is an object of the present invention to provide a single-pass real-time variable bit rate encoder for moving pictures. It is also an object of the present invention to provide variable bit rate encoding of moving pictures such that the change in encoded picture quality from one scene to another is minimised. A further object is to provide a real-time variable bit rate encoding algorithm which produces a constant overall bit rate.

In particular, the present invention encodes an input moving pictures sequence one

segment at a time according to a target encoding quality which is determined by a target segment bit rate. The target segment bit rate of a current segment is preferably derived from the differences between the target segment bit rates and the actual coding bit rates of previous or previous few encoded segments.

To maintain consistent encoding quality for all pictures within a segment, the actual target bit rate for encoding the pictures is made variable according to their scene complexities as well as the target encoding quality of the segment.

As the target encoding quality of each segment is modified based on the differences between the target and the actual bit rates of previous or previous few encoded segments, the change of target encoding quality from segment to segment is made relatively smooth compared to that of a Constant Bit-Rate Encoder, and furthermore, the overall bit rate of encoding is maintained constant.

In accordance with the present invention, there is provided a method for use in a moving pictures encoder for encoding a sequence of segments each having at least one image, comprising the steps of:

a) determining an overall target bit rate for encoding the sequence of images;

b) determining a bit allocation and target quantisation step size for encoding a first segment on the basis of a segment target bit rate calculated using said overall target bit rate;

c) encoding said first segment using a variable bit rate encoding method according to the target quantisation step size;

d) determining a difference between the number of bits used to encode said first segment and said first segment bit allocation;

e) distributing said difference for use in encoding at least one subsequent segment to determine a subsequent segment bit allocation;

f) determining a new target quantisation step size for encoding a said subsequent segment on the basis of a new target segment bit rate calculated using

said segment target bit rate and the distributed difference; and

g) encoding said subsequent segment using a variable bit rate encoding method according to the new target quantisation step size;

wherein variable bit rate encoding is employed for encoding pictures within a segment whilst maintaining a substantially constant bit rate over said sequence.

The present invention also provides a method for encoding moving pictures in a moving pictures encoder wherein a sequence of images are provided as input, the sequence of images comprising a plurality of segments each having a plurality of images, the method including:

a) determining an overall target bit rate for encoding the sequence of images;

b) maintaining a distribution record of bits from at least one previously encoded segment allocated for use in encoding at least one segment to be encoded;

c) determining a target segment bit rate for a segment of the sequence of images on the basis of the overall target bit rate and a bit rate change calculated from the corresponding allocated bits from the distribution record;

d) determining a target segment encoding quality from the target segment bit rate, a preceding target segment bit rate and a preceding target segment encoding quality,; and

e) encoding the images of the segment according to the target segment encoding quality using a variable bit rate encoding technique taking into account scene complexities of the images in the segment;

wherein maintaining said distribution record includes determining a difference between the number of bits used to encode a particular segment and the number of bits allocated for encoding the particular segment on the basis of the target segment encoding quality.

According to the current invention, a moving pictures sequence is divided into segments. The size of each segment may be suitably determined. Each segment is encoded with a target encoding quality derived from its target segment bit rate. A variable bit rate (VBR)

encoder is utilised to encode the segment according to its target encoding quality.

The target segment bit rate of an initial segment is obtained from a user defined target overall bit rate. After encoding the segment, the difference between the actual bit rate used and the target segment bit rate is obtained. This difference is propagated to the next or next few segments to be coded. This process is repeated for each segment; therefore, for each subsequent segment, a new target segment bit rate is determined from the user defined target overall bit rate and the differences between the target segment bit rates and actual bit rates of previous or previous few segments.

The present invention further provides a method for controlling bit allocation in a moving pictures encoder for encoding a sequence of images comprising a plurality of segments each having a plurality of images, the method including, for each segment:

determining a difference between a number of bits used for encoding a previous segment and a number of bits allocated for encoding the previous segment;

calculating a bits distribution from the determined bits difference and a predetermined distribution function;

calculating a bit rate change from the bits distribution and a predetermined number of images in the segment;

calculating a target segment bit rate from the bit rate change and a predetermined target overall bit rate for the sequence of images: and

determining a target segment encoding quality from the target segment bit rate.

The present invention further provides an encoding quality adjustment processor for generating a target segment encoding quality value in a moving pictures encoder for encoding a series of segments each having at least one image using a variable bit rate encoding scheme whilst maintaining a substantially constant overall bit rate, comprising:

a bits difference computation means coupled to receive a segment encoding bit utilisation value and a target segment bit rate and generate therefrom a bits difference value representing a difference in bits allocated and bits used for encoding a segment;

a bits distribution means coupled to the bits difference computation means for computing at least one bits distribution value from the bits difference value and a predetermined distribution function;

a bit rate difference computation means coupled to the bits distribution means for computing a segment bit rate difference from the at least one bits distribution value and a predetermined number of images in a segment;

a target segment bit rate adjustment means coupled to the bit rate difference computation means and the bits difference computation means for computing said target segment bit rate from the segment bit rate difference and a predetermined target overall bit rate for the sequence of segments; and

an encoding quality computation means coupled to the target segment bit rate adjustment means for computing a target segment encoding quality value from said target segment bit rate.

The present invention further provides a moving pictures encoder comprising:

a coding processor for encoding picture data based on macroblocks according to a quantisation step size;

a virtual buffer processor coupled to the coding processor for tracking a number of bits used for encoding successive macroblocks in a picture and a number of bits used for encoding successive pictures in a group of pictures;

a quantisation step size processor coupled to the coding processor for determining said quantisation step size from a target number bits allocated for a picture and the number of bits already used for encoding macroblocks in that picture;

a picture bit allocation processor coupled to the quantisation step size processor for determining said target number of bits allocated for a picture from a target bit rate and the number of bits already used for encoding pictures in a current group of pictures;

a bit rate adjustment processor coupled to the picture bit allocation processor, the virtual buffer processor and the quantisation step size processor for determining said target bit rate from the number of bits already used for encoding successive pictures in the current group of pictures, a target encoding quantisation step size and an average

quantisation step size for pictures in the current group of pictures; and

a target encoding quantisation step size processor coupled to the bit rate adjustment processor and the virtual buffer processor for determining said target encoding quantisation step size from a predetermined target overall bit rate and the number of bits used for encoding a preceding group of pictures.

Brief Description of the Drawings

The invention is described in greater detail hereinafter, by way of example only, with reference to the accompanying drawings, wherein:

Figure 1 is a block diagram of the constant bit-rate controller based on TM5;

Figure 2 illustrates the difference between a target bit allocation and an actual bits consumption at macroblock level for one frame (a P-picture is chosen for this case), where d_j is the virtual buffer fullness at a particular instance;

Figure 3 is a block diagram of the variable bit-rate encoder with constant overall bit-rate control;

Figure 4 is a block diagram of the constant overall bit-rate controller;

Figure 5 illustrates how the difference in bit count for the last segment is redistributed over the next four segments (e.g. f(m)=1/4); and

Figure 6 is a flow chart of a VBR algorithm with constant overall bit-rate control.

Detailed Description of the Preferred Embodiments

In a standard MPEG compliant video encoder, a sequence of moving pictures (e.g. video) is input to the encoder where it is compressed with a user defined target bitrate. The target bitrate is set according to the communication channel bandwidth in which the compressed video is to be transmitted, or the storage media capacity in which the compressed video sequence is to be stored. A typical MPEG encoder involves motion estimation/prediction, Inter/Intra classification, discrete cosine transform (DCT) computation, quantisation, zig-zag scanning, variable length coding and rate-control.

Several different forms of coding can be employed depending upon the character of the input pictures, referred to as I-pictures, P-pictures, or B-pictures. The I-pictures are intra-coded pictures used mainly for random access or scene update. The P-pictures use forward motion predictive coding with reference to previously coded I- or P- pictures (anchor pictures), and the B-pictures use both forward and backward motion predictive/interpolative coding with reference to previously coded I-or P-pictures. Furthermore, a group of pictures (GOP) is formed in encoded order starting with an I-picture and ending with the picture before the next I-picture in the sequence.

The pictures are partitioned into smaller and non-overlapping blocks of pixel data called macroblocks (MBs) before encoding. Each MB from a P- or B-picture is subjected to a motion estimation process in which forward motion vectors, and backward motion vectors in the case of a B-picture MB, are determined using reference pictures from a frame buffer. The target macroblock in the current picture is matched with a set of displaced macroblocks in the reference picture, the macroblock that best matches the target macroblock is used as the predicted macroblock. The position of this predicted macroblock is specified by a set of vectors known as motion vectors, which describe the vertical and horizontal displacement between the target and predicted macroblock. For a B-picture, the process is similar except there are two reference pictures: anchor pictures immediately preceding and following the B-picture.

With the determined motion vectors, motion compensation is performed where the intra-or inter-picture prediction mode of the MB is first determined according to the accuracy of the motion vectors found, followed by generating the necessary predicted MB. I-pictures are always intra coded while for P and B-pictures, a decision on whether intra or inter coding will be used (at macroblock level) is made depending on which method will give rise to a more efficient coding.

Transformation of the macroblock using a DCT is then carried out on the 8x8 pixel blocks within the macroblock. For intra coding, the actual picture data is coded, while for inter

coding the prediction error is coded. This is followed by a quantisation process of the DCT coefficients which involves a quantisation matrix and a quantisation step size. The quantized coefficients are then run-length encoded with variable length codes.

The resultant bit usage and statistical data are passed onto a rate control module, which is used for allocating a target number of bits used to encode each picture and each macroblock within the picture. This is an important module in the encoder as it plays a major role in maintaining the quality of the encoded picture.

The rate control in MPEG-2 Test Model 5 (TM5) comprises the steps of allocating the target amount of bits for coding each picture, deriving the reference quantisation parameter (Q_j) to be used on each macroblock in a picture, and modulating the Q_j based on the activity masking level of the surrounding blocks of the corresponding macroblock to obtain the modulated quantisation step size (*Mquant*) used to quantise the macroblock.

An objective of this rate controller is to ensure all pictures maintain a similar level of quality. It assumes that the subjective quality of a single coded picture can be qualified with a single number V, described by factor K/Q where K is a constant particular to a picture type and Q is the quantisation step size for the picture being coded. That is, the rate controller will try to preserve the following equation:

$$V = \frac{K_i}{Q_i} = \frac{K_p}{Q_p} = \frac{K_b}{Q_b}$$

The subscripts i, p, b refers to I, P, and B-picture types. The parameters K_i, K_p, and K_b are experimentally determined constants for all I, P, and B pictures respectively, and K_i usually is normalised to the value of 1.

Figure 1 illustrates a block diagram of a known embodiment of the TM5 rate controller. A group-of-pictures (GOP) is a collection of one I picture, some P pictures and B pictures, and serves as a basic access unit with the I picture as the entry point to facilitate random

access. The controller comprises three levels of processing: a GOP level 111, a picture level 110, and a macroblock (MB) level 109. At the start of every new GOP at the GOP level 111, a GOP bit allocation process 100 computes the total number of bits (R_{gop}) allocated for the GOP. The value of R_{gop} is given by:

$$R_{gop} = \frac{bit_rate \times N}{picture_rate} \qquad (1)$$

where *bit_rate* is the target bit rate for encoding the picture sequence,
picture_rate is the number of pictures coded per second, and
N is the total number of pictures coded in the GOP.

The remaining bits (R) for the GOP is determined at the picture level 110 by a remaining bits determination process 106. The value of R is updated as:

$R = R - S$ where S is the number of bits used by previously coded pictures in the GOP, and

$R = R + R_{gop}$ for a new GOP.

With the computed value of R, a picture bit allocation process 101 at the picture level 110 then computes a target bit value (T) allocated to the current picture according to the equations below for corresponding I, P or B picture type:

$$T_i = \max\left\{\frac{R}{1+\frac{N_p X_p}{X_i K_p}+\frac{N_b X_b}{X_i K_b}}, \frac{bit_rate}{K \times picture_rate}\right\} \qquad (2)$$

$$T_p = \max\left\{\frac{R}{N_p+\frac{N_b K_p X_b}{X_p K_b}}, \frac{bit_rate}{K \times picture_rate}\right\} \qquad (3)$$

$$T_b = \max\left[\frac{R}{N_b + \frac{N_p K_b X_p}{X_b K_p}}, \frac{bit_rate}{K \times picture_rate}\right] \quad (4)$$

where

T_i, T_p, T_b Represents target bits for the next picture (I,P,B)

N_b, N_p Represents the remaining number of pictures (P,B) in the GOP

X_i, X_p, X_b Represents global complexity measures and gives a measure of the actual number of bits required to represent the picture (without compression), and

$X_i = Q_i \times S_i$

$X_p = Q_p \times S_p$

$X_b = Q_b \times S_b$

S_i, S_p, S_b are the actual number of bits used to code the previous I/P/B frame.

K is a constant (e.g. 8)

After computing the target bits for the picture, a reference quantisation step-size (Q_j) computation 102 is carried out at the MB level 109 for each macroblock within the picture. The value of Q_j is computed based on the determined target bit allocation (T_i, T_p, or T_b) and a buffer fullness value (d_j). Each of the three picture types has a virtual buffer associated with it and these buffers are updated after coding each macro block of the picture type according to the following equations:

$$d_j^i = d_0^i + B_{j-1} - \frac{T_i \times (j-1)}{MB_Cnt} \quad (5)$$

$$d_j^p = d_0^p + B_{j-1} - \frac{T_p \times (j-1)}{MB_Cnt} \quad (6)$$

$$d_j^b = d_0^b + B_{j-1} - \frac{T_b \times (j-1)}{MB_Cnt} \quad (7)$$

where d_0 is the initial virtual buffer fullness,

d_j is the virtual buffer fullness when coding the j^{th} MB,

B_{j-1} is the actual bits consumed up to and including $(j-1)^{th}$ MB as provided by a virtual buffer update process 105, and

MB_Cnt is the number of MBs in the picture.

Equations (5) to (7) effectively track the differences between the actual number of bits used and the target bits allocated, and these differences are then added to the respective virtual buffers which are used to compute Q_j. This allows the rate controller to control the bits allocation based on the consumption pattern of the picture. Q_j is computed from the buffer fullness via the equation:

$$Q_j = (d_j \times 31) / r = d_j \times \text{constant} \quad (8)$$

where r is a reaction parameter = 2 x *bit_rate / picture_rate*

The reaction parameter, as the name implies, is a factor that can control the sensitivity of the algorithm from a change in d_j. Large r will cause the reaction to be slower, which may cause the target bits and actual bits to differ significantly, but it brings about a more gradual rate of change in bit consumption which is favourable for scene changes. On the other hand, a small r causes the controller to be more reactive to changes, giving rise to a closer target and actual bits value, but a faster response also means a less gradual change

during scene change which is not desirable. A graph illustrating the difference between the target bit allocation and the actual bits allocated within a frame is shown in Figure 2.

The value of Q_j is further modified by an activity masking process 103 to give the modulated quantisation step size, *Mquant*. Basically, the spatial masking ability of the macroblock is used to place a correction factor onto the computed Q_j value. Spatial masking ability is the ability to contain noise masked from human visual systems. Typically, an area with complex texture will have a larger correction factor than an area with simple texture, hence,

$$Mquant = N_act_j \times Q_j \qquad (9)$$

where N_act_j is the normalised value of macroblock activity level and may have a value of between 0.5 and 2

With the computed *Mquant*, the macroblock coding process 104 is performed where the macro block is compressed according to the MPEG standards.

At the end of coding a picture, the bit count S used for coding the picture is used to perform a VBV check 107 and to compute the remaining bits R for the current GOP at the remaining bits determination process 106. The VBV (video buffer verifier) is a virtual buffer emulating the status of the decoding buffer. The VBV check (107) is performed to detect any overflow or underflow of the decoding buffer with reference to the target bit rate.

When coding a picture sequence with varying scene complexity, a constant bit rate (CBR) encoder is unable to vary the bit-rate according to the scene complexity. This results in scenarios whereby simple scenes are allocated more bits than required while complex scenes are allocated insufficient bits, and therefore results in a variation of output visual

quality between scenes of different complexities.

An embodiment of a moving pictures encoding apparatus according to the present invention is illustrated in block diagram form in Figure 3. The encoding apparatus as illustrated is arranged in four levels corresponding to processing stages in the bit rate control process, namely a segment level 313, a GOP level 312, a picture level 311 and a macroblock (MB) level 310. An input moving pictures sequence is encoded in such a way that on the average, or at the end of encoding, the output bit rate is close to a user definable target overall bit rate (*overall_BR*) 320. The input sequence is divided into segments and groups of pictures (GOP). The purpose of a segment is for monitoring of output bit rate with reference to the *overall_BR*, and the purpose of the GOP is primarily to facilitate random access. A segment may be defined to include a number of GOP(*s*) depending on the need in terms of frequency of monitoring output bit rate. Each GOP comprises at least an I-picture and optionally one or more P-pictures and/or B-pictures. Each picture is divided into macroblocks of pixels for encoding. Hence, a method of rate control according to the current invention may contain processes at the segment level 313, GOP level 312, picture level 311, and finally macroblock level 310.

With a new group of pictures, a GOP bit allocation processor 300 computes the number of bits allocated to the current GOP (R'_{gop}) as follows:

$$R'_{gop} = BR \times \frac{N_{gop}}{picture_rate} \qquad (10)$$

where:

N_{gop} is the number of pictures in the GOP,

picture_rate is the number of pictures coded per second, and

BR is a target bit rate.

The target bit rate *BR* is determined for each picture or plurality of pictures by a bit rate

adjustment processor 306 which is described hereinbelow. A remaining number of bits (R') for the GOP is determined at the picture level 311 by a remaining bits determination processor 308, which carries out the steps of:

(a) before encoding the first picture in a GOP, adjusting R' with a new R'_{gop}:

$R' \mathrel{+}= R'_{gop}$, and then set $BR_{old} = BR$

(b) otherwise if the picture to be coded is not the first picture of a GOP, and a new target bit rate BR is determined, then adjusting R' with the new BR according to:

$$R' \mathrel{+}= \frac{N}{picture_rate} \times (BR - BR_{old}), \text{ and then set } BR_{old} = BR$$

where N is remaining number of pictures in the current GOP

(c) and removing number of bits used by the last coded picture S from the remaining bits value R', hence:

$$R' = R' - S$$

The computed R' is then passed to a picture bit allocation processor 301 to compute the target bit (T) allocated to a current picture to be coded. For example, equations (2), (3) and (4) described hereinabove may be used for that purpose, with the parameters K_p, K_b, N_p, N_b and *pict_type* being supplied. Note that the lower limit of *bit_rate*/(8**picture_rate*) is only optional and may be adjusted if necessary.

At the macroblock (MB) level 310, a reference quantisation step-size computation processor 302 computes a reference quantisation step-size Q_j for each MB using the computed target bit allocation T and a bit utilisation parameter B determined by a virtual buffer update processor 305. An example of a method for computing Q_j for the j^{th} MB of

the current picture is represented by:

$$Q_j = \frac{K_1 \times D_j \times picture_rate}{K_2 \times BR} \qquad (11)$$

where K_1 and K_2 are constants (eg. 31 and 2 respectively),

BR is the determined target bit rate,

picture_rate is the number of coded pictures per second, and

D_j is a virtual buffer fullness

The virtual buffer fullness of the j^{th} MB is determined by:

$$D_j = D_0 + B - \frac{T \times (j-K_3)}{MB_Cnt} \qquad (12)$$

where D_0 is an initial buffer fullness before coding the current picture, ie. D_j at end of the previous picture,

B is the bit utilisation information supplied by the virtual buffer update processor 305, ie. bits used to code the 1^{st} MB to $(j-k_3)^{th}$ MB,

MB_Cnt is the total number of MB in the current picture, and

K_3 is a constant (eg. 1).

Three independent current and initial virtual buffers fullness values (D_j^I, D_j^P, D_j^b, D_0^I, D_0^P, D_0^b) may be maintained for the three picture types (I-pictures, P-pictures, and B-pictures). The computed Q_j may also be further scaled by an activity masking processor 303 according to a masking factor determined by the surrounding activity levels of the MB to form the final quantisation step-size, *Mquant*, for coding the current MB. A method of masking factor determination can be found in the aforementioned MPEG-2 TM5.

Macroblock coding (304) is then performed to encode the current MB. A macroblock coding processor 304 may employ, for example, methods according to the MPEG-1 or MPEG-2 video encoding standards. Such encoding methods include necessary motion

compensation, discrete cosine transform, quantisation with the determined quantisation step-size, and run-length encoding with variable length codes. The methods also include necessary decoding processes such that motion compensation can be performed. The number of bits utilised by the macroblock coding processor 304 to code each MB is passed to the virtual buffer update processor 305.

In applications where a maximum and/or minimum bit rate must be maintained for encoding, a VBV checking processor 307 is utilised. User definable maximum and/or minimum bit rates (*max/min BR*) are input at 321 to the VBV checker 307, a method of VBV checking according to the MPEG standards is used to examine bit utilisation information from the virtual buffer 305, and necessary corrections are made to ensure compliance and that the output bit rate is within the defined *max/min BR*.

At the end of coding a picture or a plurality of pictures, bit rate adjustment is applied by the bit rate adjustment processor 306 to provide any necessary correction to the current target bit rate *BR*. The correction is based on a target encoding quality provided by a target segment quality adjustment processor 309 and a resultant encoding quality of previously coded picture(s) such that the overall encoding qualities of pictures within a segment are relatively close to the target constant. The resultant encoding quality may be determined by the average value of the reference quantisation step size (ie. $average_Q_j$) of the previously coded picture(s). A method of target bit rate (*BR*) determination can be derived from a rate-quantisation model as given by:

$$BR = current_BR + \frac{K_1 \times (average_Q_j - target_Q_j)}{average_Q_j} \qquad (13)$$

where *current_BR* is a current estimated bit rate, or

$current_BR = S_i + N_p \times S_p + N_b \times S_b$,

S_i, S_p, S_b are bits used by previously coded I, P, and B-pictures respectively,

N_p, N_b are total number of P and B-pictures in the current GOP,

$average_Q_j$ is the average value of Q_j of previously coded picture(s)

target_Q$_j$ is the target encoding quality or target value of Q_j,
K_4 may be a constant, or a factor of previous *BR*, *max_BR*, or *current_BR*, and K_4 may also be separately determined for I, P, and B-picture types.

Maximum and/or minimum bit rates can be applied to the determined *BR* according to application requirements. The *max/min BR* input at 322 are used as given by:

if (*BR* > *max_BR*), then *BR* = *max_BR*
if (*BR* < *min_BR*), then *BR* = *min_BR*.

It is also possible to make use of the *target_Q*$_j$ at the macro-block level to increase efficiency of encoding. Basically, the *target_Q*$_j$ is used by the reference quantisation step-size computation processor 302 as a lower limit of the output reference quantisation step-size Q_j such that when this target (quality) is reached at the MB level, bits are saved for future encoding immediately. In this case, the output reference quantisation step size may be set according to:

if (Q_j < *target_Q*$_j$), then Q_j = *target_Q*$_j$.

The target bit rate *BR* is adjusted continuously with reference to a fixed target encoding quality within each segment. In turn at the beginning of each segment, the target encoding quality is adjusted so that a target overall bit rate is achieved. A segment may contain a few groups of pictures depending on the need in terms of frequency of monitoring output bit rate. A new segment may also be defined by a scene change detectable by any conventional scene change detector with a given range of time.

At the onset of a new segment, the target segment quality adjustment processor 309 executes a check on the overall bit-rate based on bits usage and makes any necessary adjustments to the target encoding quality for the bit rate adjustment processor 306 so that the overall bit-rate converges to a user definable target overall bit-rate 320 (*overall_BR*).

An example embodiment of a constant overall bit rate controller implementing the target segment quality adjustment process according to the present invention is illustrated in block diagram form in Figure 4. The bit count difference between the actual and target bit counts (*bits_diff*) for coding of a previous segment is calculated by a bits difference computation processor 401, utilising the steps of:

a) obtaining the actual bits (*bits_segment*) used for coding the previous segment according to the input bit utilisation of pictures (*S*) 400 in the previous segment, and

b) computing the value of *bits_diff* based on a corresponding target segment bit rate 406 (*segment_BR*) for the previous segment, according to:

$$bits_diff = \frac{segment_BR \times N_{segment}}{picture_rate} - bits_segment \qquad (14)$$

where $N_{segment}$ is the number of coded pictures in the previous segment.

The bit count difference (*bits_diff*) is then redistributed by a bit difference distribution processor 402 over the next k number of segments using a bit distribution function, $f(m)$, expressed as:

$$delta_bits_m = f(m) \times bits_diff \qquad (15)$$

where $m = 1,\ldots,k$.

$\Sigma^k f(m) = 1$,

$delta_bits_m$ is the bits difference distributed to next m^{th} segment.

For an example case of $k=4$ and $f(m)=1/k$, Figure 5 illustrates how the bit count difference (*bits_diff*) of an encoded segment is distributed over the next 4 segments. The period of k segments used for bits compensation is referred to as an adjustment interval.

A delta bit-rate computation processor 403 (Figure 4) accumulates all bit differences (*delta_bits*) distributed from previously encoded segments to the current segment to be coded, and computes a delta segment bit-rate ($\Delta segment_BR$) based on the accumulated *delta_bits* and the number of pictures in the current segment to be coded. The delta segment bit-rate and a user definable target overall bit-rate (*overall_BR*) input at 408 are used by the target segment BR adjustment processor 405 to derive the target segment bit rate (*segment_BR*) 406 for the current segment. The value of *segment_BR* can be expressed as:

$$segment_BR = overall_BR + \Delta segment_BR \tag{16}$$

A new target encoding quality ($target_Q_j$) 407 for encoding of the current segment is then determined from the target segment bit rate using a BR-Q_j modelling processor 404. The BR-Q_j modelling processor may operate, for example, according to:

$$\Delta Q_j = target_Q'_j \times \frac{(segment_BR - segment_BR')}{K_s \times segment_BR'} \tag{17}$$

$$target_Q_j = target_Q'_j + \Delta Q_j \tag{18}$$

where $target_Q'_j$ is the target Q_j of the previous segment,
$segment_BR'$ is the target segment bit rate of the previous segment, and
K_s is a constant which can be experimentally determined.

A maximum limit may be placed on the determined ΔQ_j so that there is no drastic change in output quality from one segment to another.

A flow chart for a process of variable bit rate (VBR) encoding with constant overall bit-

rate control according to an embodiment of the invention is illustrated in Figure 6. Initialisation of predetermined parameters is first carried out at step 600. Then, at step 601 the process determines whether processing is at the start of a new group-of-pictures (GOP) or not. Where a new GOP is determined, step 602 is carried out by updating the bit allocation for the new GOP. This may involve, for example, computation of the GOP bit allocation R'_{gop} according to Equation (10) described hereinabove and accumulating to the remaining bit value R' to give the R' for the new GOP.

For each picture in the current GOP, a target bit allocation value T is determined at step 603, and this may be computed according to Equations (2), (3) and (4), for example. Then, for each macroblock in the picture, a reference quantisation step size Q is determined using the computed target bit allocation T, such as by the process represented by Equations (11) and (12). Activity masking may also be included in this step. The macroblock of the picture is then encoded at step 605 using the computed quantisation step size, and steps 604 and 605 are repeated for all of the macroblocks in the picture until the end of the picture is determined at step 606.

When the end of the sequence of moving pictures which is being encoded is reached, this is determined at step 607, which terminates the process at step 611 upon that occurrence. Otherwise, the process continues to step 608 where it is determined whether the end of the current segment of pictures has been reached.

When the end of a segment of pictures is reached and processing of a new segment about to begin, the target encoding quality is adjusted at step 609. This is performed by firstly computing the difference between the number of bits allocated for coding the previous segment and the actual number of bits used in coding that segment, such as by the process represented by Equation (14). This quantity, *bits_diff*, represents extra bits which are left over from the previous segment of pictures, and may be distributed for use in encoding the ensuing picture segments. The left over bits *bits_diff* are distributed for use over one or more segments according to a bit distribution function, an example of which is described

in connection with Equation (15). In essence, the left over bits from the previous segment are divided into a plurality of k, preferably equal, amounts and allocated to the following k segments for encoding with. The dividends allocated from all of the k previously processed segments are accumulated and used to determine a change in segment bit rate, $\Delta segment_BR$, according to the accumulated bits difference and the number of pictures in the segment to be coded. This can then be used to compute an allocated bit rate for the segment to be coded according to Equation (16). Finally, a target encoding quality, $target_Q_j$, can be computed according to Equations (17) and (18), for example.

If the end of a segment has not been reached at step 608, or after the target quality adjustment of step 609, the target quality and the actual quality of encoded pictures is compared, and a new bit rate for encoding the next picture is computed based on the difference. This step can be carried out as described in relation to Equation (13), for example. The procedure then returns to step 601, described above.

In summary, embodiments of the present invention provide methods and apparatus for encoding moving pictures with a variable bit rate whilst maintaining a consistent output encoding quality according to a determined target quality. The target quality is adjusted at the beginning of every moving pictures segment according to a bit distribution function to ensure an overall bit rate that meets a defined target. Furthermore, the segment based bit distribution function provides smooth and flexible modulation of the encoding quality. The method can be implemented at low cost and with the ability to encode an input moving pictures sequence in one-pass at real-time.

It will be readily apparent to those of ordinary skill in the art that the foregoing detailed description of the present invention has been presented by way of example only, and is not intended to be considered limiting to the invention as defined in the claims appended hereto. In particular, it is envisaged that numerous variations to the embodiments as described can be made without departing from the spirit and scope of the invention.

Throughout this specification and the claims which follow, unless the context requires otherwise, the word "comprise", and variations such as "comprises" and "comprising", will be understood to imply the inclusion of a stated integer or step or group of integers or steps but not the exclusion of any other integer or step or group of integers or steps.

Glossary:

VBV	video buffer verifier
VBR	variable bit rate
CBR	constant bit rate
MPEG	Moving Picture Experts Group
DCT	discrete cosine transform
GOP	group of pictures
MB	macroblock
Q	quantisation parameter (picture quality)
Q_j	quantisation parameter for macroblock j
Q_i, Q_b, Q_p	quantisation parameters for I, B and P type pictures
R_{gop}	number of bits allocated for encoding a group of pictures
bit_rate	target bit rate for a picture sequence
picture_rate	number of pictures coded per second
N	total number of pictures in the group of pictures
N_b, N_p	remaining number of P,B pictures in the group of pictures
R, R'	remaining number of bits for encoding a group of pictures
S	number of bits already used in coding a group of pictures
T_i, T_p, T_b	target number of bits for coding next I, P, B type picture
X_i, X_p, X_b	global complexity measures for I, P, B type picture
d_j, D_j	virtual buffer fullness when coding the j^{th} macroblock
d_0, D_0	initial virtual buffer fullness
B_{j-1}	actual bits used up to and including $(j-1)^{th}$ macroblock
MB_Cnt	number of macroblocks in the picture
r	reaction parameter (= 2 x *bit_rate* / *picture_rate*)
N_act_j	normalised macroblock activity level
Mquant	modulated quantisation step size (= N_act_j x Q_j)
overall_BR	definable target overall bit rate
BR	target bit rate

B	bit utilisation information (eg. bits used to code previous MBs in picture)
$current_BR$	current estimated bit rate
$average_Q_j$	average value of quantisation parameter for previously coded pictures
$target_Q_j$	quantisation parameter value for target encoding quality
max_BR	maximum permitted bit rate
min_BR	minimum permitted bit rate
$bits_diff$	difference between actual and target bits used in coding previous segment
$segment_BR$	target segment bit rate
$bits_segment$	actual number of bits used in coding previous segment
$N_{segment}$	number of coded pictures in previous segment
$delta_bits_m$	number of difference bits available to next m^{th} segment
$f(m)$	bits distribution function
$\Delta segment_BR$	available difference in segment bit rate

Claims:

1. A method for use in a moving pictures encoder for encoding a sequence of segments each having at least one image, comprising the steps of:

a) determining an overall target bit rate for encoding the sequence of images;

b) determining a bit allocation and target quantisation step size for encoding a first segment on the basis of a segment target bit rate calculated using said overall target bit rate;

c) encoding said first segment using a variable bit rate encoding method according to the target quantisation step size;

d) determining a difference between the number of bits used to encode said first segment and said first segment bit allocation;

e) distributing said difference for use in encoding at least one subsequent segment to determine a subsequent segment bit allocation;

f) determining a new target quantisation step size for encoding a said subsequent segment on the basis of a new target segment bit rate calculated using said segment target bit rate and the distributed difference; and

g) encoding said subsequent segment using a variable bit rate encoding method according to the new target quantisation step size;

wherein variable bit rate encoding is employed for encoding pictures within a segment whilst maintaining a substantially constant bit rate over said sequence.

2. A method as claimed in claim 1, wherein the steps d) to g) are carried out iteratively using the number of bits used to encode the subsequent segment and the subsequent segment bit allocation for determining said difference.

3. A method as claimed in claim 1 or 2, wherein each segment comprises at least one group of pictures having an I-picture and optionally at least one P and/or B-picture.

4. A method as claimed in claim 2 or 3, wherein the difference between the number

of bits used to encode the first segment and said first segment bit allocation is determined according to:

$$bits_diff = \frac{overall_BR \times N_{segment}}{picture_rate} - bits_segment$$

where:

bits_diff is said difference,

overall_BR is the overall target bit rate,

$N_{segment}$ is the number of coded images in the first segment, and

bits_segment is the actual number of bits used to encode the first segment.

5. A method as claimed in claim 4, wherein said difference is distributed according to:

$$delta_bits_m = f(m) \times bits_diff$$

where $delta_bits_m$ is the bits difference distributed to next m^{th} segment in the sequence,

$m = 1,\ldots,k$,

k is a positive integer, and

$f(m)$ is a bit distribution function, where $\Sigma^k f(m) = 1$.

6. A method as claimed in claim 5, where $f(m) = 1/k$.

7. A method as claimed in claim 5 or 6, wherein the steps d) to g) are carried out iteratively using the number of bits used to encode the subsequent segment and the subsequent segment bit allocation for determining said difference.

8. A method as claimed in claim 7, wherein the new target quantisation step size is calculated according to:

$$\Delta Q = target_Q' \times \frac{(segment_BR - segment_BR')}{K \times segment_BR'}$$

$$target_Q = target_Q' + \Delta Q$$

where *target_Q* is the new target quantisation step size,

segment_BR is the new target bit rate,

target_Q' is the target quantisation step size of the preceding segment,

segment_BR' is the target segment bit rate of the preceding segment, and

K is a constant.

9. A method as claimed in claim 7 or 8, wherein for each subsequent segment the difference between the number of bits used to encode the segment and the segment bit allocation is determined according to:

$$bits_diff = \frac{segment_BR \times N_{segment}}{picture_rate} - bits_segment$$

where:

bits_diff is said difference,

segment_BR is the segment target bit rate,

$N_{segment}$ is the number of coded images in the segment, and

bits_segment is the actual number of bits used to encode the segment.

10. A method as claimed in claim 9, wherein said difference is distributed according to:

$$delta_bits_m = f(m) \times bits_diff$$

where $delta_bits_m$ is the bits difference distributed to next m^{th} segment in the sequence.

$m = 1,\ldots,k$,

k is a positive integer, and

$f(m)$ is a bit distribution function, where $\Sigma^k f(m) = 1$.

11. A method as claimed in claim 10, where $f(m) = 1/k$.

12. A method for encoding moving pictures in a moving pictures encoder wherein a sequence of images are provided as input, the sequence of images comprising a plurality of segments each having a plurality of images, the method including:

a) determining an overall target bit rate for encoding the sequence of images;

b) maintaining a distribution record of bits from at least one previously encoded segment allocated for use in encoding at least one segment to be encoded;

c) determining a target segment bit rate for a segment of the sequence of images on the basis of the overall target bit rate and a bit rate change calculated from the corresponding allocated bits from the distribution record;

d) determining a target segment encoding quality from the target segment bit rate, a preceding target segment bit rate and a preceding target segment encoding quality,; and

e) encoding the images of the segment according to the target segment encoding quality using a variable bit rate encoding technique taking into account scene complexities of the images in the segment;

wherein maintaining said distribution record includes determining a difference between the number of bits used to encode a particular segment and the number of bits allocated for encoding the particular segment on the basis of the target segment encoding quality.

13. A method as claimed in claim 12, wherein steps b) to e) are carried out iteratively for said sequence of segments.

14. A method as claimed in claim 13, wherein each segment comprises at least one group of pictures having an I-picture and optionally at least one P and/or B-picture.

15. A method as claimed in claim 12, 13 or 14, wherein the target segment encoding quality is calculated according to:

$$\Delta Q = target_Q' \times \frac{(segment_BR - segment_BR')}{K \times segment_BR'}$$

$$target_Q = target_Q' + \Delta Q$$

where *target_Q* is the target segment encoding quality,

segment_BR is the target segment bit rate,

target_Q' is the preceding target segment encoding quality,

segment_BR' is the preceding target segment bit rate, and

K is a constant.

16. A method as claimed in claim 15, wherein the difference between the number of bits used to encode a particular segment and the number of bits allocated for encoding the particular segment is determined according to:

$$bits_diff = \frac{segment_BR \times N_{segment}}{picture_rate} - bits_segment$$

where:

bits_diff is said difference,

segment_BR is the segment target bit rate,

$N_{segment}$ is the number of coded images in the segment, and

bits_segment is the actual number of bits used to encode the segment.

17. A method as claimed in claim 16, wherein the allocation of bits in the distribution record is calculated according to:

$$delta_bits_m = f(m) \times bits_diff$$

where $delta_bits_m$ is the bits difference allocated to next m^{th} segment in the sequence,

$m = 1....,k$,

k is a positive integer, and

$f(m)$ is a bit distribution function, where $\Sigma^k f(m) = 1$.

18. A method as claimed in claim 17, where $f(m) = 1/k$.

19. A method for controlling bit allocation in a moving pictures encoder for encoding a sequence of images comprising a plurality of segments each having a plurality of images, the method including, for each segment:

determining a difference between a number of bits used for encoding a previous segment and a number of bits allocated for encoding the previous segment;

calculating a bits distribution from the determined bits difference and a predetermined distribution function;

calculating a bit rate change from the bits distribution and a predetermined number of images in the segment;

calculating a target segment bit rate from the bit rate change and a predetermined target overall bit rate for the sequence of images; and

determining a target segment encoding quality from the target segment bit rate.

20. A method as claimed in claim 19, wherein the difference between the number of bits used for encoding the previous segment and the number of bits allocated for encoding the previous segment is determined according to:

$$bits_diff = \frac{segment_BR \times N_{segment}}{picture_rate} - bits_segment$$

where:

$bits_diff$	is said difference,
$segment_BR$	is the previous segment target bit rate,
$N_{segment}$	is the number of coded images in the previous segment, and
$bits_segment$	is the actual number of bits used to encode the previous segment.

21. A method as claimed in claim 20, wherein the bits distribution is calculated according to:

$$delta_bits_m = f(m) \times bits_diff$$

where $delta_bits_m$ is the number of bits difference allocated to next m^{th} segment in the sequence.

$m = 1,\ldots,k$,

k is a positive integer, and

$f(m)$ is a bit distribution function, where $\Sigma^{k} f(m) = 1$.

22. A method as claimed in claim 21, where $f(m) = 1/k$.

23. A method as claimed in any one of claims 19 to 22, wherein the target segment encoding quality is calculated according to:

$$\Delta Q = target_Q' \times \frac{(segment_BR - segment_BR')}{K \times segment_BR'}$$

$$target_Q = target_Q' + \Delta Q$$

where $target_Q$ is the target segment encoding quality,

$segment_BR$ is the target segment bit rate,

$target_Q'$ is the previous segment target segment encoding quality,

$segment_BR'$ is the previous segment target segment bit rate, and

K is a constant.

24. An encoding quality adjustment processor for generating a target segment encoding quality value in a moving pictures encoder for encoding a series of segments each having at least one image using a variable bit rate encoding scheme whilst maintaining a substantially constant overall bit rate, comprising:

a bits difference computation means coupled to receive a segment encoding bit utilisation value and a target segment bit rate and generate therefrom a bits difference value representing a difference in bits allocated and bits used for encoding a segment;

a bits distribution means coupled to the bits difference computation means for computing at least one bits distribution value from the bits difference value and a predetermined distribution function;

a bit rate difference computation means coupled to the bits distribution means for computing a segment bit rate difference from the at least one bits distribution value and a predetermined number of images in a segment;

a target segment bit rate adjustment means coupled to the bit rate difference computation means and the bits difference computation means for computing said target segment bit rate from the segment bit rate difference and a predetermined target overall bit rate for the sequence of segments; and

an encoding quality computation means coupled to the target segment bit rate adjustment means for computing a target segment encoding quality value from said target segment bit rate.

25. A moving pictures encoder comprising:

a coding processor for encoding picture data based on macroblocks according to a quantisation step size;

a virtual buffer processor coupled to the coding processor for tracking a number of bits used for encoding successive macroblocks in a picture and a number of bits used for encoding successive pictures in a group of pictures;

a quantisation step size processor coupled to the coding processor for determining said quantisation step size from a target number bits allocated for a picture and the number of bits already used for encoding macroblocks in that picture;

a picture bit allocation processor coupled to the quantisation step size processor for determining said target number of bits allocated for a picture from a target bit rate and the number of bits already used for encoding pictures in a current group of pictures;

a bit rate adjustment processor coupled to the picture bit allocation processor, the virtual buffer processor and the quantisation step size processor for determining said target bit rate from the number of bits already used for encoding successive pictures in the current group of pictures, a target encoding quantisation step size and an average quantisation step size for pictures in the current group of pictures; and

a target encoding quantisation step size processor coupled to the bit rate adjustment processor and the virtual buffer processor for determining said target encoding

quantisation step size from a predetermined target overall bit rate and the number of bits used for encoding a preceding group of pictures.