

Intra-Frame Prediction Method and Apparatus, and Computer-Readable Storage Medium

Technical Field

Embodiments of the present application relate to video coding and decoding technology,
5 relate but are not limited to a method and an apparatus for intra prediction, and a computer readable storage medium.

Background

In versatile video coding and decoding, when intra prediction is performed on a current
10 processing block, an optimal prediction mode (i.e., a prediction mode signalled in a bitstream) of a corresponding or spatial neighboring prediction block (also called a previous reconstructed block) for which intra prediction has been completed, a derivative mode of an optimal direction of the previous reconstructed block, and a combination of some preset intra prediction modes, are usually used as a candidate prediction mode set of the current processing block, and intra
15 prediction is performed on the current processing block based on multiple candidate prediction modes in the set. Traditional intra prediction modes include DC mode, PLANAR and an angle prediction mode, and the DC mode is further discussed here.

At present, a process of intra prediction of the current processing block by using the DC mode is that: pixel units of a neighboring previous row and a neighboring left column of the
20 current processing block are used as reference pixel units, and a DC coefficient is obtained through averaging the reference pixel values of the reference pixel units, the DC coefficient is used as a prediction value of the current processing block to construct the prediction value of the current processing block.

However, since the above DC coefficient is obtained by averaging neighboring reference
25 pixel units, and the larger the processing block size, the more the number of reference pixel units which are needed to construct the DC coefficient, and the higher the complexity of averaging. Therefore, the computational complexity will increase with the increase of processing block size.

Summary

Embodiments of the present application provide a method and an apparatus for intra prediction, and a computer readable storage medium, which can reduce calculation amount and complexity of intra prediction, thereby improving coding and decoding efficiency.

In a first aspect, an embodiment of the present application provides a method for intra prediction, including: acquiring a first reference pixel set corresponding to a current processing block, wherein the first reference pixel set includes at least one of a reference row or a reference column adjacent to the current processing block; selecting a second reference pixel set from the first reference pixel set based on a preset selection mode, wherein the second reference pixel set includes at least one reference pixel unit in the reference row or the reference column adjacent to the current processing block; obtaining a prediction value of the current processing block based on the second reference pixel set; and performing intra prediction on the current processing block based on the prediction value.

In the above solution, the preset selection mode includes at least one of a preset position, a preset sampling rate or a preset statistical characteristics.

In the above solution, when the preset selection mode is the preset position, selecting the second reference pixel set from the first reference pixel set based on the preset selection mode includes: determining a sub-reference pixel unit at the preset position of each reference row or each reference column respectively from the first reference pixel set; and determining the sub-reference pixel unit as the second reference pixel set.

In the above solution, when the preset selection mode is the preset sampling rate, selecting the second reference pixel set from the first reference pixel set based on the preset selection mode includes: downsampling the reference row or the reference column in the first reference pixel set according to the preset sampling rate to obtain a down-sampled reference pixel unit; and determining the down-sampled reference pixel unit as the second reference pixel set.

In the above solution, when the preset selection mode is the preset statistical characteristics, selecting the second reference pixel set from the first reference pixel set based

on the preset selection mode includes: selecting the second reference pixel set from the reference row or the reference column in the first reference pixel set according to the preset statistical characteristics.

5 In the above solution, when the second reference pixel set includes at least two reference pixel units, obtaining the prediction value of the current processing block based on the second reference pixel set includes: averaging pixel values of the at least two reference pixel units to obtain an average value; and setting the prediction value of the current processing block equal to the average value.

10 In the above solution, when the second reference pixel set includes one reference pixel unit, obtaining the prediction value of the current processing block based on the second reference pixel set includes: determining a pixel value of the reference pixel unit as the prediction value of the current processing block.

In the above solution, the preset position is a middle position of the reference row or the reference column.

15 In the above solution, the preset sampling rate is one half.

In a second aspect, an apparatus for intra prediction is characterized by including: an acquiring unit, configured to acquire a first reference pixel set corresponding to a current processing block, wherein the first reference pixel set includes at least one of a reference row or a reference column adjacent to the current processing block; a determining unit, configured to
20 select a second reference pixel set from the first reference pixel set based on a preset selection mode, wherein the second reference pixel set includes at least one reference pixel unit in the reference row or the reference column adjacent to the current processing block; and obtain a prediction value of the current processing block based on the second reference pixel set; and a predicting unit, configured to perform intra prediction on the current processing block based on
25 the prediction value.

In the above solution, the preset selection mode includes at least one of a preset position, a preset sampling rate or a preset statistical characteristics.

In the above solution, when the preset selection mode is the preset position, the

determining unit is specifically configured to respectively determine a sub-reference pixel unit at the preset position of each reference row or each reference column respectively from the first reference pixel set; and determine the sub-reference pixel unit as the second reference pixel set.

5 In the above solution, when the preset selection mode is the preset sampling rate, the determining unit is specifically configured to downsample the reference row or the reference column in the first reference pixel set according to the preset sampling rate to obtain a down-sampled reference pixel unit; and determine the down-sampled reference pixel unit as the second reference pixel set.

10 In the above solution, when the preset selection mode is the preset statistical characteristics, the determining unit is specifically configured to select the second reference pixel set from the reference row or the reference column in the first reference pixel set according to the preset statistical characteristics.

15 In the above solution, when the second reference pixel set includes at least two reference pixel units, the determining unit is specifically configured to average pixel values of the at least two reference pixel units to obtain an average value; and set the prediction value of the current processing block equal to the average value.

In the above solution, when the second reference pixel set includes one reference pixel unit, the determining unit is specifically configured to determine a pixel value of the reference pixel unit as the prediction value of the current processing block.

20 In the above solution, the preset position is a middle position of the reference row or the reference column.

In the above solution, the preset sampling rate is one half.

25 In a third aspect, an embodiment of the present application provides an apparatus for intra prediction, including: a memory and a processor, wherein the memory stores a computer program which is runnable on the processor, and the processor implements the above method for intra prediction when executing the program.

In a fourth aspect, an embodiment of the present application provides a computer-readable storage medium, on which a computer program is stored, wherein the computer program, when

executed by a processor, implements the above method for intra prediction.

Embodiments of the present application provide a method for intra prediction and an apparatus, and a computer readable storage medium. The apparatus for intra prediction obtains a first reference pixel set corresponding to a current processing block, wherein, the first
5 reference pixel set includes at least one of a reference row or a reference column adjacent to the current processing block; selects a second reference pixel set from the first reference pixel set based on a preset selection mode, wherein, the second reference pixel set includes at least one reference pixel unit in the reference row or the reference column adjacent to the current processing block; obtains a prediction value of the current processing block based on the second
10 reference pixel set; and performs intra prediction on the current processing block based on the prediction value. According to the above technical implementation solution, since when the apparatus for intra prediction performs intra prediction on the current processing block, part of reference pixel units are selected from the reference row or the reference column adjacent to the current processing block, and the prediction value of the current processing block is obtained
15 based on the part of reference pixel units, the number of reference pixel units is relatively small, which reduces calculation amount and complexity of intra prediction, thereby improving coding and decoding efficiency.

Brief Description of Drawings

20 FIG. 1 is a first schematic diagram of a relationship between a current processing block and a reference pixel set in the prior art.

FIG. 2A is a second schematic diagram of a relationship between a current processing block and a reference pixel set in the prior art.

25 FIG. 2B is a third schematic diagram of a relationship between a current processing block and a reference pixel set in the prior art.

FIG. 3 is a schematic block diagram of composition of a video decoding system according to an embodiment of the present application.

FIG. 4A is a schematic structure diagram of composition of a video encoder according to

an embodiment of the present application.

FIG. 4B is a schematic structure diagram of composition of a video decoder according to an embodiment of the present application.

FIG. 5 is a first flow chart of a method for intra prediction according to an embodiment of
5 the present application.

FIG. 6 is a second flow chart of a method for intra prediction according to an embodiment of the present application.

FIG. 7 is a first schematic diagram of an exemplary relationship between a current processing block and a reference pixel set according to an embodiment of the present
10 application.

FIG. 8 is a second schematic diagram of an exemplary relationship between a current processing block and a reference pixel set according to an embodiment of the present application.

FIG. 9 is a third schematic diagram of an exemplary relationship between a current processing block and a reference pixel set according to an embodiment of the present
15 application.

FIG. 10 is a fourth schematic diagram of an exemplary relationship between a current processing block and a reference pixel set according to an embodiment of the present application.

FIG. 11 is a third flow chart of a method for intra prediction according to an embodiment of the present application.
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FIG. 12 is a fifth schematic diagram of an exemplary relationship between a current processing block and a reference pixel set according to an embodiment of the present application.

FIG. 13 is a sixth schematic diagram of an exemplary relationship between a current processing block and a reference pixel set according to an embodiment of the present
25 application.

FIG. 14 is a fourth flow chart of a method for intra prediction according to an embodiment

of the present application.

FIG. 15 is a first schematic structure diagram of an apparatus for intra prediction according to an embodiment of the present application.

FIG. 16 is a second schematic structure diagram of an apparatus for intra prediction
5 according to an embodiment of the present application.

Detailed Description

In order to understand features and technical contents of embodiments of the present invention in more detail, implementation modes of the embodiments of the present invention
10 will be described in detail below in conjunction with the accompanying drawings, which are for reference only and are not intended to limit the embodiments of the present invention.

Firstly, concepts of intra prediction, video coding and decoding, and the like are introduced below.

A main function of prediction of coding and decoding is to construct a prediction value of
15 a current processing block by using an existing reconstructed picture in space or time in video coding and decoding, and only transmit a difference between an original value and the prediction value, so as to reduce the amount of transmitted data.

A main function of intra prediction is to construct a prediction value of a current processing block by using the current processing block and pixel units in a previous row and
20 pixel units in a left column adjacent to the current processing block. As shown in FIG. 1, each pixel unit of a current processing block 101 is predicted by using restored neighboring pixels around the current processing block 101 (i.e., pixel units in a previous row 102 and pixel units in a left column 103 adjacent to the current processing block).

In an embodiment of the present application, the intra prediction is performed for the
25 processing block in a relatively planar region, and DC mode (a square block DC mode as shown in FIG. 2A and a rectangular block DC mode as shown in FIG. 2B) and PLANAR mode may be adopted. Herein, in the DC mode, a whole current processing block is filled with an average value of pixel values (e.g., chrominance values or luminance values) corresponding to

pixel units in the previous row or the left column, and in the PLANAR mode, the current processing block is filled in a gradual way.

Herein, a region 1 shown in FIG. 2A is a neighboring reconstruction reference pixel unit.

It should be noted that Versatile Video Coding (VVC) and previous video coding technologies support various coding unit divisions such as quadtree, binary tree and trigeminal tree, etc., and a processing block generated by such division is a rectangular block. Therefore, when prediction in the DC mode is performed, if divided into square blocks, a prediction process for the square block is the same as that shown in FIG. 2A, and a reference pixel set of the left column (a reference column) and the previous row (a reference row) of the current processing block is used for prediction. The DC mode of rectangular block is as shown in FIG. 2B. For a rectangular block, a DC coefficient is obtained by using a reference pixel unit of the long side (i.e. region 2) or a reference pixel unit of a short side. An advantage of using only the reference pixel unit of the long side is that a division operation when averaging pixel values may be avoided, and coding and decoding quality is almost unchanged. For example, assuming that a size of the current processing block is 8x4, considering that the number of reference pixel units of the long side is 8, which is the power of 2, averaging may be performed directly by a displacement operation, thus reducing computational complexity.

On the basis of the above concepts, an embodiment of the present application provides a network architecture of a video coding and decoding system including a method for intra prediction. FIG. 3 is a schematic structure diagram of composition of a network architecture for video coding and decoding according to an embodiment of the present application. As shown in FIG. 3, the network architecture includes one or more electronic devices 11 to 1N and a communication network 01, wherein the electronic devices 11 to 1N may perform video interaction through the communication network 01. The electronic devices may be various types of devices with video coding and decoding functions in implementation processes. For example, the electronic devices may include mobile phones, tablet computers, personal computers, personal digital assistants, navigators, digital phones, video phones, televisions, sensing devices, servers, etc., which is not limited in the embodiments of the present application. Herein, an apparatus for intra prediction in an embodiment of the present application may be

the above electronic device.

Herein, the electronic device in an embodiment of the present application has video coding and decoding functions, and generally includes a video encoder and a video decoder.

For example, as shown in FIG. 4A, a structure of composition of a video encoder 21 includes: a transforming and quantizing unit 211, an intra estimating unit 212, an intra predicting unit 213, a motion compensating unit 214, a motion estimating unit 215, an inverse transforming and inverse quantizing unit 216, a filter controlling and analyzing unit 217, a filtering unit 218, an entropy coding unit 219, a decoded-picture buffering unit 210, etc.. Herein, the filtering unit 218 may perform deblocking filtering and Sample Adaptive Offset (SAO) filtering, and the entropy coding unit 219 may perform header information coding and Context-based Adaptive Binary Arithmetic Coding (CABAC). For an input source video data, one block to be coded of a current video frame may be obtained by dividing a Coding Tree Unit (CTU), and then obtained residual information is transformed by the transforming and quantizing unit 211 after intra prediction or inter prediction is performed on the block to be coded, including transforming the residual information from a pixel domain to a transform domain, and quantizing an obtained transform coefficient to further reduce a bit rate. The intra estimating unit 212 and the intra predicting unit 213 are used for performing intra prediction on the block to be encoded, for example, determining an intra prediction mode for encoding the block to be encoded. The motion compensating unit 214 and the motion estimating unit 215 are used for performing inter prediction encoding of the block to be encoded relative to one or more blocks in one or more reference frames to provide time prediction information. Herein, the motion estimating unit 215 is used for estimating a motion vector, the motion vector may be used for estimating the motion of the block to be encoded, and then the motion compensating unit 214 performs motion compensation based on the motion vector. After determining the intra prediction mode, the intra predicting unit 213 is also used for providing selected intra prediction data to the entropy coding unit 219, and the motion estimating unit 215 also sends the calculated and determined motion vector data to the entropy coding unit 219. In addition, the inverse transforming and inverse quantizing unit 216 is used for reconstructing the block to be encoded, reconstructing a residual block in the pixel domain, removing blocking artifacts for

the reconstructed residual block through the filter controlling and analyzing unit 217 and the filtering unit 218, and then adding the reconstructed residual block to one predictive block in a frame of the decoded-picture buffering unit 210 to generate a reconstructed video encoding block. The entropy coding unit 219 is used for coding various coding parameters and quantized transform coefficients, and in a coding algorithm based on CABAC, a context content may be based on neighboring coding blocks, and may be used for coding information indicating the determined intra prediction mode, and outputting a bitstream of the video data. And the decoded-picture buffering unit 210 is used for storing the reconstructed video coding block for reference in prediction. With the progress of video coding, new reconstructed video coding blocks will be generated continuously, and these reconstructed video coding blocks will be stored in the decoded-picture buffering unit 210.

A video decoder 22 corresponding to the video encoder 21, a structure of composition of which is as shown in FIG. 4B, includes: an entropy decoding unit 221, an inverse transforming and inverse quantizing unit 222, an intra predicting unit 223, a motion compensating unit 224, a filtering unit 225, a decoded-picture buffering unit 226, etc.. Herein the entropy decoding unit 221 may realize header information decoding and CABAC decoding, and the filtering unit 225 may realize deblocking filtering and SAO filtering. After an input video signal is encoded in FIG. 4A, a bitstream of the video signal is output. The bitstream is input into the video decoder 22, and first passes through the entropy decoding unit 221 to obtain a decoded transform coefficient. The transform coefficient is processed by the inverse transforming and inverse quantizing unit 222 to generate a residual block in the pixel domain. The intra predicting unit 223 may be used for generating prediction data of a current decoded block based on a determined intra prediction mode and data from a current frame or a picture which passes through via a decoded block previously. The motion compensating unit 224 determines prediction information of the current decoding block by parsing a motion vector and other associated syntax element, and uses the prediction information to generate a predictive block of the current decoding block which is being decoded. A decoded video block is formed by summing the residual block from the inverse transforming and inverse quantizing unit 222 with the corresponding predictive block generated by the intra predicting unit 223 or the motion compensating unit 224. The decoded video block passes through the filtering unit 225 so as to

remove the blocking artifacts, thereby improving a video quality. Then, the decoded video block is stored in the decoded-picture buffering unit 226, the decoded-picture buffering unit 226 stores a reference picture which is used for subsequent intra prediction or motion compensation, and is also used for output display of a video signal.

5 Based on this, the technical solution of the present application will be further elaborated with reference to the drawings and embodiments. The method for intra prediction according to an embodiment of the present application may be applied to both the video encoder 21 and the video decoder 22, which is not specifically limited in an embodiment of the present application.

10 An embodiment of the present application provides a method for intra prediction, wherein the method is applied to an apparatus for intra prediction, and a function realized by the method may be realized by a processor in the apparatus for intra prediction calling program codes. Of course, the program code may be stored in a computer storage medium. It may be seen that the apparatus for intra prediction at least includes a processor and a storage medium.

15 FIG. 5 is a schematic flowchart of an implementation of a method for intra prediction according to an embodiment of the present application. As shown in FIG. 5, the method includes acts S101 to S104.

In S101, a first reference pixel set corresponding to a current processing block is acquired, the first reference pixel set includes at least one of a reference row or a reference column adjacent to the current processing block.

20 In S102, a second reference pixel set is selected from the first reference pixel set based on a preset selection mode, the second reference pixel set includes at least one reference pixel unit in the reference row or the reference column adjacent to the current processing block.

In S103, a prediction value of the current processing block is obtained based on the second reference pixel set.

25 In S104, intra prediction is performed on the current processing block based on the prediction value.

In S101, the current processing block in an embodiment of the present application is a block to be coded or a block to be decoded, wherein the block to be coded is a picture region,

on which prediction encoding needs to be performed currently, in a video frame. The block to be decoded is a picture region, on which decoding needs to be performed at present, in a video frame. The reason why reconstructed pixels outside the current processing block are called reference pixels or reference pixel units is that when predicting the current processing block, it is necessary to refer to attribute information of these reconstructed pixels (such as luminance component, chrominance component, etc.) to predict pixels to be predicted in the current processing block. Therefore, the reconstructed pixel is a pixel point for which prediction has been completed.

In an embodiment of the present application, when encoding and decoding the current processing block, the apparatus for intra prediction needs to obtain a first reference pixel set corresponding to the current processing block, and then perform intra prediction based on the first reference pixel set.

For example, for the DC mode, the first reference pixel set here includes at least one of a reference row or a reference column adjacent to the current processing block. That is to say, in an embodiment of the present application, the first reference pixel set represents three types of reference pixel, i.e., reference row pixels, reference column pixels, or reference row and reference column pixels.

It should be noted that the reference row pixels and the reference column pixels contain multiple pixel units. Selection of the first reference pixel set in an embodiment of the present application may be acquired according to the actual regulation and requirement, which is not limited in an embodiment of the present application.

For example, the first reference pixel set in FIG. 1 may include all reconstructed pixels (reference row pixels) in the previous row region 102 of the current processing block 101; or, the first reference pixel set includes all reconstructed pixels (reference row pixels) in the left column region 103 of the current processing block 101; or, the first reference pixel set includes all reconstructed pixels in the previous row region 102 of the current processing block 101 and all reconstructed pixels in the left column region 103 (i.e., reference row and reference column pixels).

In S102, when performing intra prediction, the apparatus for intra prediction sets a preset

selection mode in advance, and the apparatus for intra prediction may select a reference pixel unit from the first reference pixel set by using the preset selection mode, that is, select part of reference pixel units from the first reference pixel set, and realize intra prediction of the current processing block based on the part of the reference pixel units.

- 5 Specifically, the apparatus for intra prediction uses a preset selection mode to select a second reference pixel set from the first reference pixel set. The second reference pixel set includes at least one reference pixel unit in the reference row or the reference column adjacent to the current processing block.

- 10 It should be noted that the first reference pixel set is at least one of the reference row or the reference column adjacent to the current processing block. Then, the reference pixel unit selected from the first reference pixel set includes at least one reference pixel unit in the reference row or the reference column adjacent to the current processing block. That is, the second reference pixel set may be at least one reference pixel unit in reference row pixels, at least one reference pixel unit in reference column pixels, or may be obtained through a
15 combination of at least one reference pixel unit in reference row pixels and at least one reference pixel unit in reference column pixels. A specific combination mode of the second reference pixel set may be designed according to an actual situation, which is not limited in an embodiment of the present application.

- 20 In S103 and S104, after obtaining the second reference pixel set, the apparatus for intra prediction may obtain the prediction value of the current processing block based on the second reference pixel set, and perform intra prediction on the current processing block based on the prediction value.

 Herein, the second reference pixel set includes a pixel identification of a reconstructed pixel, such as a pixel number.

- 25 In an embodiment of the present application, because the quantity of reference pixel units in the second reference pixel set is indefinite, and may be one or more (that is, at least two) with respect to the quantity of reference pixel units, modes of obtaining the prediction value of the current processing block by the apparatus for intra prediction are different, which is as follows.

 Mode 1: when the second reference pixel set includes at least two reference pixel units,

the apparatus for intra prediction averages pixel values of the at least two reference pixel units to obtain an average value; and the prediction value of the current processing block is set to be equal to the average value.

Mode 2: when the second reference pixel set includes one reference pixel unit, the
5 apparatus for intra prediction determines a pixel value of the reference pixel unit as the prediction value of the current processing block.

For example, for the DC mode, in an embodiment of the present application, the apparatus for intra prediction needs to determine the reference pixel unit of the current processing block first, that is, the second reference pixel set, then deduce a DC coefficient of the current
10 processing block based on the reference pixel unit in the second reference pixel set, and obtain the prediction value of the current processing block based on the DC coefficient.

In an embodiment of the present application, when the second reference pixel set includes at least two reference pixel units, the apparatus for intra prediction averages the pixel values of the at least two reference pixel units to obtain an average value; and the DC coefficient of the
15 current processing block is set to be equal to the average value, that is, the prediction value of the current processing block. When the second reference pixel set includes one reference pixel unit, the apparatus for intra prediction determines the pixel value of the reference pixel unit as the DC coefficient of the current processing block, that is, the prediction value of the current processing block.

20 It may be understood that for a large-area planar processing block, the prediction value of the current processing block is constructed by using part of existing reference pixel sets, which reduces algorithm complexity and computation amount, thus improving coding and decoding efficiency.

In some embodiments of the present application, the preset selection mode includes at
25 least one of a preset position, a preset sampling rate or a preset statistical characteristics, which is not limited in an embodiment of the present application.

Based on different preset selection modes, the second reference pixel sets on which the method for intra prediction is based are different.

In some embodiments of the present application, as shown in FIG. 6, when the preset selection mode is the preset position, a process of an intra prediction mode according to an embodiment of the present application includes acts S201 to S205.

5 In S201, a first reference pixel set corresponding to a current processing block is acquired; wherein the first reference pixel set includes at least one of a reference row or a reference column adjacent to the current processing block.

An implementation of S201 in an embodiment of the present application is consistent with the description of the implementation process of S101, and will not be repeated here.

10 In S202, a sub-reference pixel unit at a preset position of each reference row or each reference column is/are determined respectively from the first reference pixel set.

In S203, the sub-reference pixel unit is/are determined as the second reference pixel set.

15 In S202 and S203, based on the description of the implementation of S102, the apparatus for intra prediction may select a sub-reference pixel unit at a preset position as the second reference pixel set with respect to a reference row or a reference column in the first reference pixel set, that is, determine a sub-reference pixel unit at a preset position of each reference row or each reference column respectively from the first reference pixel set, and determine the sub-reference pixel unit as the second reference pixel set.

20 In an embodiment of the present application, when the first reference pixel set includes reference row pixels, the apparatus for intra prediction acquires a reference pixel unit at a preset position in the reference row pixels as a sub-reference pixel unit, and determines the sub-reference pixel unit as a second reference pixel set. When the first reference pixel set includes reference column pixels, the apparatus for intra prediction acquires a reference pixel unit at a preset position in the reference column pixels as a sub-reference pixel unit, and determines the sub-reference pixel unit as a second reference pixel set. When the first reference pixel set includes reference row and reference column pixels, the apparatus for intra prediction acquires a first reference pixel unit at a preset position in reference column pixels and a second reference pixel unit at a preset position in reference row pixels, combines the first reference pixel unit and the second reference pixel unit as sub-reference pixel units, and determines the sub-reference pixel units as a second reference pixel set.

In an embodiment of the present application, the preset position is a middle position of a reference row or a reference column, or the preset positions may also be multiple positions on both sides of the reference row or the reference column, etc., which is not limited in an embodiment of the present application.

5 For example, the DC mode is taken as an example for explanation. The apparatus for intra prediction selects two sub-reference pixel units from an existing first reference pixel set based on the preset position, and an average value of the two sub-reference pixel units is used as a DC coefficient. Assuming that the preset position is the middle position of the reference row or the reference column, when the current processing block is a square, part of pixel units in a left
10 column pixel set and a previous row pixel set of a center position of the current processing block are selected as part of reference pixel units. Assuming that a size of the current processing block is $N \times N$, the pixel units at the $N/2$ position (a position index starts from 0) in the pixel set in the left column and at the $N/2$ position (a position index starts from 0) in the pixel set in the previous row are respectively selected as sub-reference pixel units. For example,
15 in FIG. 7, the size of the current block is 8×8 , and pixels represented by lines are an existing reference pixel set, that is, the first reference pixel set. At this time, a pixel unit at a position with an index number 4 in the pixel set in the left column and the previous row is selected as the sub-reference pixel unit, that is, the second reference pixel set, for constructing the DC coefficient. When the current processing block is a rectangle, a reference pixel unit at a position
20 of $1/2$ of a long side in the rectangle is selected as the sub-reference pixel unit. Assuming that the size of the current block is $N \times M$ ($N > M$), a pixel unit at a position of $N/2$ of a side with a length N is selected as the sub-reference pixel unit. For example, in FIG. 8, the size of the current processing block is 8×4 , and pixels represented by lines are an existing reference pixel set, that is, the first reference pixel set. At this time, a pixel unit at a position with an index
25 number 4 in the pixel set in the previous row is selected as the sub-reference pixel unit, that is, the second reference pixel set, for constructing the DC coefficient.

It may be understood that computational complexity of DC coefficient derivation may be greatly reduced by using the intra predicting mode in the present application, and computation amount for square blocks is reduced by $1/2$, and computation amount for rectangular blocks is

reduced by 3/4. With VTM4.0 as a benchmark, coding time and decoding time can be reduced with the coding rate unchanged under a premise of a same recovered video quality.

It should be noted that, for a video picture, a video frame may be divided into squares or rectangles, etc. At this time, for a situation that there are both reference row pixels and a reference column pixels in the first reference pixel set, the preset position may be different positions or the same position for the reference row pixels and the reference column pixels, which is not limited in an embodiment of the present application.

In an embodiment of the present application, for the current processing block, no matter it is a square block or a rectangular block, a combination of sub-reference pixel units at preset positions in the pixel sets of the left column and the previous row is uniformly selected as a second reference pixel set for constructing the DC coefficient. Or, for the current processing block, no matter it is a square block or a rectangular block, only a first sub-reference pixel unit at the preset position in the pixel set of the left column or a second sub-reference pixel unit at the preset position in the pixel set of the previous row is uniformly used, and the first sub-reference pixel unit or the second sub-reference pixel unit is used as the second reference pixel set for constructing the DC coefficient.

For example, as shown in FIGs. 9 and 10, a combination of sub-reference pixel units at preset positions in the pixel sets of the left column and the previous row is uniformly selected as the second reference pixel set. For a square block (FIG. 9) and a rectangular block (FIG. 10), reference pixel units A and B of the left column and the previous column of a center position are uniformly selected as the second reference pixel set for constructing the DC coefficient.

For example, only a first sub-reference pixel unit at the preset position in the pixel set of the left column or a second sub-reference pixel unit at the preset position in the pixel set of the previous row is uniformly used, and the first sub-reference pixel unit or the second sub-reference pixel unit is used as the second reference pixel set for constructing the DC coefficient, as described below, (1) for a rectangular block, a sub-reference pixel unit at a position of 1/2 of a long side is selected as the second reference pixel set; and for a square block, a combination of a sub-reference pixel unit at a position of 1/2 in a previous row or a left column is selected as the second reference pixel set. (2) For a rectangular block, a sub-reference

pixel unit at a position of 1/2 of a short side is selected as the second reference pixel set, and for a square block, a combination of a sub-reference pixel unit at a position of 1/2 of a previous row or a left column is selected as the second reference pixel set. That is to say, for a rectangular block, a sub-reference pixel unit at a preset position on one side may be selected as
5 the second reference pixel set, which is not limited in an embodiment of the present application.

In S204, based on the second reference pixel set, a prediction value of a current processing block is obtained.

An implementation of S204 in an embodiment of the present application is consistent with the description of the implementation process of S103, and will not be repeated here.

10 In S205, based on the prediction value, intra prediction is performed on the current processing block.

An implementation of S205 in an embodiment of the present application is consistent with the description of the implementation process of S104, and will not be repeated here.

It may be understood that for a large-area planar processing block, the prediction value of
15 the current processing block is constructed by using part of existing reference pixel sets, which reduces algorithm complexity and computation amount, thus improving coding and decoding efficiency.

In some embodiments of the present application, as shown in FIG. 11, when the preset selection mode is the preset sampling rate, a process of an intra prediction mode according to an
20 embodiment of the present application includes acts S301 to S305.

In S301, a first reference pixel set corresponding to a current processing block is acquired; wherein the first reference pixel set includes at least one of a reference row or a reference column adjacent to the current processing block.

An implementation of S301 in an embodiment of the present application is consistent with
25 the description of the implementation process of S101, and will not be repeated here.

In S302, the reference row or the reference column in the first reference pixel set is downsampled according to the preset sampling rate to obtain a down-sampled reference pixel unit.

In S303, the down-sampled reference pixel unit is/are determined as the second reference pixel set.

5 In S302 and S303, based on the description of the implementation of S102, the apparatus for intra prediction may downsample the reference row or the reference column in the first reference pixel set according to the preset sampling rate to obtain the down-sampled reference pixel unit, wherein the down-sampled reference pixel unit is/are used as the second reference pixel set.

10 In an embodiment of the present application, the preset sampling rate may be one-half or other sampling values, such as three-quarters, two-fifths, which is not limited in an embodiment of the present application.

For example, a current first reference pixel set is down-sampled by $1/2$, and a DC coefficient is constructed by using the down-sampled reference pixel unit. For a square block, as shown in FIG. 12, lines represent a down-sampled reference pixel unit C. As shown in FIG. 13, lines represent a down-sampled reference pixel unit D.

15 It should be noted that the preset sampling rate may be understood as a mode of selecting the preset position, so the principle of acquiring the second reference pixel set by the apparatus for intra prediction according to the preset sampling rate is the same as the principle of acquiring the second reference pixel set according to the preset position, which is not limited in an embodiment of the present application.

20 In S304, based on the second reference pixel set, a prediction value of a current processing block is obtained.

An implementation of S304 in an embodiment of the present application is consistent with the description of the implementation process of S103, and will not be repeated here.

25 In S305, based on the prediction value, intra prediction is performed on the current processing block.

An implementation of S305 in an embodiment of the present application is consistent with the description of the implementation process of S104, and will not be repeated here.

It may be understood that for a large-area planar processing block, the prediction value of

the current processing block is constructed by using part of existing reference pixel sets, which reduces algorithm complexity and computation amount, thus improving coding and decoding efficiency.

5 In some embodiments of the present application, as shown in FIG. 14, when the preset selection mode is the preset statistical characteristics, a process of an intra prediction mode according to an embodiment of the present application includes acts S401 to S404.

In S401, a first reference pixel set corresponding to a current processing block is acquired; wherein the first reference pixel set includes at least one of a reference row or a reference column adjacent to the current processing block.

10 An implementation of S401 in an embodiment of the present application is consistent with the description of the implementation process of S101, and will not be repeated here.

In S402, a second reference pixel set is selected from the reference row or the reference column in the first reference pixel set according to the preset statistical characteristics.

15 In an embodiment of the present application, the apparatus for intra prediction may select, according to the preset statistical characteristics, the second reference pixel set that meets the statistical characteristics from the reference row or the reference column in the first reference pixel set.

20 In an embodiment of the present application, the preset statistical characteristics represents a pixel point, which best represents the neighboring reference pixel unit, in the reference row or the reference column.

25 It should be noted that the preset statistical characteristics may be understood as a mode of selecting the preset position, so the principle of acquiring the second reference pixel set by the apparatus for intra prediction according to the preset statistical characteristics is the same as the principle of acquiring the second reference pixel set according to the preset position, which is not limited in an embodiment of the present application.

In S403, based on the second reference pixel set, a prediction value of the current processing block is obtained.

An implementation of S403 in an embodiment of the present application is consistent with

the description of the implementation process of S103, and will not be repeated here.

In S404, based on the prediction value, intra prediction is performed on the current processing block.

5 An implementation of S404 in an embodiment of the present application is consistent with the description of the implementation process of S104, and will not be repeated here.

It may be understood that for a large-area planar processing block, the prediction value of the current processing block is constructed by using part of existing reference pixel sets, which reduces algorithm complexity and computation amount, thus improving coding and decoding efficiency.

10 Based on the foregoing embodiment, an embodiment of the present application provides an apparatus for intra prediction, various units included in the apparatus and various modules included in the various units may be realized by a processor in the apparatus for intra prediction. Of course, it may also be realized by a specific logic circuit. In an implementation process, the processor may be a Central Processing Unit (CPU), a microprocessor (MPU), a Digital Signal
15 Processor (DSP) or a Field Programmable Gate Array (FPGA), etc.

As shown in FIG. 15, an embodiment of the present application provides an apparatus for intra prediction 3, which includes: an acquiring unit 30, configured to acquire a first reference pixel set corresponding to a current processing block, wherein the first reference pixel set includes at least one of a reference row or a reference column adjacent to the current processing
20 block; a determining unit 31, configured to select a second reference pixel set from the first reference pixel set based on a preset selection mode, wherein the second reference pixel set includes at least one reference pixel unit in the reference row or the reference column adjacent to the current processing block; and obtain a prediction value of the current processing block based on the second reference pixel set; and a predicting unit 32, configured to perform intra
25 prediction on the current processing block based on the prediction value.

In some embodiments of the present application, the preset selection mode includes at least one of a preset position, a preset sampling rate or a preset statistical characteristics.

In some embodiments of the present application, when the preset selection mode is the

preset position, the determining unit 31 is specifically configured to determine a sub-reference pixel unit at the preset position of each reference row or each reference column respectively from the first reference pixel set; and determine the sub-reference pixel unit as the second reference pixel set.

5 In some embodiments of the present application, when the preset selection mode is the preset sampling rate, the determining unit 31 is specifically configured to downsample the reference row or the reference column in the first reference pixel set according to the preset sampling rate to obtain a down-sampled reference pixel unit; and determine the down-sampled reference pixel unit as the second reference pixel set.

10 In some embodiments of the present application, when the preset selection mode is the preset statistical characteristics, the determining unit 31 is specifically configured to select the second reference pixel set from the reference row or the reference column in the first reference pixel set according to the preset statistical characteristics.

15 In some embodiments of the present application, when the second reference pixel set includes at least two reference pixel units, the determining unit 31 is specifically configured to average pixel values of the at least two reference pixel units to obtain an average value; and set the prediction value of the current processing block equal to the average value.

20 In some embodiments of the present application, when the second reference pixel set includes one reference pixel unit, the determining unit 31 is specifically configured to determine a pixel value of the reference pixel unit as the prediction value of the current processing block.

 In some embodiments of the present application, the preset position is a middle position of the reference row or the reference column.

 In some embodiments of the present application, the preset sampling rate is one half.

25 The description of the above apparatus embodiment is similar to the description of the above method embodiment, and has similar beneficial effects as the method embodiment. For technical details not disclosed in the apparatus embodiment of the present application, please refer to the description of the method embodiment of the present application to understand.

It should be noted that in the embodiments of the present application, if the above method for intra prediction is implemented in the form of a software function module and when sold or used as an independent product, it may also be stored in a computer readable storage medium. Based on this understanding, the technical solutions of the embodiments of the present application, in essence, or the part contributing to the related art, may be embodied in the form of a software product, the computer software product is stored in one storage medium and includes several instructions to make an electronic device (which may be a mobile phone, a tablet, a personal computer, a personal digital assistant, a navigator, a digital telephone, a video telephone, a television, a sensing device, a server, etc.) perform all or part of the method described in various embodiments of the present application. And the aforementioned storage medium includes various media which may store program codes, such as a U disk, a mobile hard disk, a Read Only Memory (ROM), a magnetic disk or an optical disk. Thus, the embodiments of the present application are not limited to any specific combination of hardware and software.

In practical application, as shown in FIG. 16, an embodiment of the present application provides an apparatus for intra prediction, which includes: a memory 33 and a processor 34, wherein the memory 33 stores a computer program that is runnable on the processor 34, and when the processor 34 executes the program, the acts in the method for intra prediction provided in the above embodiment are realized.

Accordingly, an embodiment of the present application provides a computer readable storage medium on which a computer program is stored, wherein when the computer program is executed by a processor, the acts in the method for intra prediction provided in the above embodiment are realized.

It should be pointed out here that the descriptions of the above storage medium and the apparatus embodiment are similar to the description of the above method embodiment, and they have similar beneficial effects as the method embodiment. For technical details not disclosed in the storage medium and the apparatus embodiment of the present application, please refer to the description of the method embodiment of the present application to understand.

What are described above are merely implementations of the present application, but the

protection scope of the present application is not limited thereto. Any variation or substitution that may easily occur to a person skilled in the art within the technical scope disclosed by the present application shall be included within the protection scope of the present application. Therefore, the protection scope of the present application shall be determined by the protection
5 scope of the claims.

Industrial Applicability

In embodiments of the present application, when an apparatus for intra prediction performs intra prediction on a current processing block, it selects part of reference pixel units
10 from a reference row or a reference column adjacent to the current processing block, and obtains a prediction value of the current processing block based on the part of reference pixel units, the number of reference pixel units is relatively small, which reduces calculation amount and complexity of intra prediction, thereby improving coding and decoding efficiency.

What is claimed is:

1. A method for intra prediction, comprising:

acquiring a first reference pixel set corresponding to a current processing block, wherein the first reference pixel set includes at least one of a reference row or a reference column
5 adjacent to the current processing block;

selecting a second reference pixel set from the first reference pixel set based on a preset selection mode, wherein the second reference pixel set includes at least one reference pixel unit in the reference row or the reference column adjacent to the current processing block;

acquiring a prediction value of the current processing block based on the second reference
10 pixel set; and

performing intra prediction on the current processing block based on the prediction value.

2. The method of claim 1, wherein, the preset selection mode comprises at least one of a preset position, a preset sampling rate or a preset statistical characteristics.

3. The method of claim 2, wherein when the preset selection mode is the preset position,
15 selecting the second reference pixel set from the first reference pixel set based on the preset selection mode comprises:

determining a sub-reference pixel unit at the preset position of each reference row or each reference column respectively from the first reference pixel set; and

determining the sub-reference pixel unit as the second reference pixel set.

20 4. The method of claim 2, wherein when the preset selection mode is the preset sampling rate, selecting the second reference pixel set from the first reference pixel set based on the preset selection mode comprises:

downsampling the reference row or the reference column in the first reference pixel set according to the preset sampling rate to acquire a down-sampled reference pixel unit; and

25 determining the down-sampled reference pixel unit as the second reference pixel set.

5. The method of claim 2, wherein when the preset selection mode is the preset statistical characteristics, selecting the second reference pixel set from the first reference pixel set based

on the preset selection mode comprises:

selecting the second reference pixel set from the reference row or the reference column in the first reference pixel set according to the preset statistical characteristics.

- 5 6. The method of any one of claims 1 to 5, wherein when the second reference pixel set comprises at least two reference pixel units, acquiring the prediction value of the current processing block based on the second reference pixel set comprises:

averaging pixel values of the at least two reference pixel units to acquire an average value; and

setting the prediction value of the current processing block equal to the average value.

- 10 7. The method of any one of claims 1 to 5, wherein when the second reference pixel set comprises one reference pixel unit, acquiring the prediction value of the current processing block based on the second reference pixel set comprises:

determining a pixel value of the reference pixel unit as the prediction value of the current processing block.

- 15 8. The method of claim 2, wherein, the preset position is a middle position of the reference row or the reference column.

9. The method of claim 2, wherein, the preset sampling rate is one half.

10. An apparatus for intra prediction, comprising:

- 20 an acquiring unit, configured to acquire a first reference pixel set corresponding to a current processing block, wherein the first reference pixel set includes at least one of a reference row or a reference column adjacent to the current processing block;

- 25 a determining unit, configured to select a second reference pixel set from the first reference pixel set based on a preset selection mode, wherein the second reference pixel set includes at least one reference pixel unit in the reference row or the reference column adjacent to the current processing block; and acquire a prediction value of the current processing block based on the second reference pixel set; and

a predicting unit, configured to perform intra prediction on the current processing block based on the prediction value.

11. The apparatus of claim 10, wherein the preset selection mode comprises at least one of a preset position, a preset sampling rate or a preset statistical characteristics.

12. The apparatus of claim 11, wherein when the preset selection mode is the preset position,

5 the determining unit is specifically configured to determine a sub-reference pixel unit at the preset position of each reference row or each reference column respectively from the first reference pixel set; and determine the sub-reference pixel unit as the second reference pixel set.

13. The apparatus of claim 11, wherein when the preset selection mode is the preset sampling rate,

10 the determining unit is specifically configured to downsample the reference row or the reference column in the first reference pixel set according to the preset sampling rate to acquire a down-sampled reference pixel unit; and determine the down-sampled reference pixel unit as the second reference pixel set.

14. The apparatus of claim 11, wherein when the preset selection mode is the preset
15 statistical characteristics,

the determining unit is specifically configured to select the second reference pixel set from the reference row or the reference column in the first reference pixel set according to the preset statistical characteristics.

15. The apparatus of any one of claims 10 to 14, wherein when the second reference pixel
20 set comprises at least two reference pixel units,

the determining unit is specifically configured to average pixel values of the at least two reference pixel units to acquire an average value; and set the prediction value of the current processing block equal to the average value.

16. The apparatus of any one of claims 10 to 14, wherein when the second reference pixel
25 set comprises one reference pixel unit,

the determining unit is specifically configured to determine a pixel value of the reference pixel unit as the prediction value of the current processing block.

17. The apparatus of claim 11, wherein the preset position is a middle position of the

reference row or the reference column.

18. The apparatus of claim 11, wherein the preset sampling rate is one half.

19. An apparatus for intra prediction, comprising:

5 a memory and a processor, wherein the memory stores a computer program which is
runnable on the processor, and the method for intra prediction of any one of claims 1 to 9 is
implemented when the processor executes the computer program.

20. A computer readable storage medium with a computer program stored thereon,
wherein when the computer program is executed by a processor, the method for intra prediction
of any one of claims 1 to 9 is implemented.

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