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## ADAPTIVE CORING FOR VIDEO PEAKING

### Technical Field

- 5 The present invention relates to video signal processing and in particular to a means of enhancing the sharpness of a video images.

### Background of the Invention

- 10 Video peaking techniques have been used to enhance the sharpness of video images. Conventional video peaking techniques typically involve enhancing the "edges" or transition regions within an image by filtering a luminance signal with a high-pass or band-pass filter, scaling the filtered signal with a gain factor, then adding the scaled signal with the original luminance signal to generate an output signal having sharper edges.
- 15 Prior art inventions also tend to involve the use of peaking techniques in combination with noise coring techniques which is the process by which a range of signal levels are suppressed (ie. are not peaked) so as to avoid amplifying the visible noise in the signal.
- 20 For instance, prior art document US6,377,313 discloses an edge enhancement circuit that comprises a high pass filter for filtering an input signal, a noise coring circuit to remove the filtered signal below a defined magnitude, and, a circuit in parallel to the coring circuit to derive a variable peaking strength.
- 25 However, prior art solutions are problematic in that, whilst they enhance the edge components of a video signal, they also tend to amplify noise components of the signal which occupy the same frequency range. This results in visible distortion in the displayed video image. Moreover, the noise characteristics of a video signal may vary throughout the signal, and prior art peaking techniques are not sensitive to these fluctuations meaning
- 30 that optimal peaking and noise coring is difficult to achieve.

Another problem inherent in prior art inventions is that they are unable to scale the filtered signal such that weak edges are enhanced without over-enhancing strong edges.

It is also noted that video transmission signals interleavc luminance and chrominance components of a video signal as a "composite signal". Prior art techniques employ notch  
5 filters to decode the chrominance components from the luminance component of the composite signal. However, these filters tend to leave residual chroma in the luminance signals which is susceptible to peaking and appears as moving noise when peaked.

10 The present invention seeks to alleviate at least some of the problems discussed above.

## Summary of the Invention

In a first broad form, the present invention provides a processor for enhancing an input  
15 luminance signal including:

a means for calculating a chroma edge value associated with the input luminance signal;

a means for measuring a luminance gradient associated with the input luminance signal;

20                    a peaking filter for processing the input luminance signal;

a gain adjustment circuit having a gain function that is adjustable relative to the calculated chroma edge value, the gain adjustment circuit being operable to adjust the magnitude of the output of the peaking filter wherein:

25                   - in a first range of luminance gradients, the output is an attenuated version of the input;

- in a second range of luminance gradients the output is directly proportional to the input;

- in a third range of luminance gradients, the output is inversely proportional to the input;

30 wherein said enhanced luminance signal is the sum of the input and output of the peaking filter.

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Preferably, the input luminance signal represents an inter-pixel array for display. More preferably, the input luminance signal represents a two-dimensional pixel array.

5 Preferably, the chroma edge value includes the sum of chroma gradients of a first and a second chroma signal associated with the input luminance signal. More preferably, the means for calculating the chroma edge value includes an edge detector. Typically, the edge detector includes a pair of Sobel detectors, however, a person skilled in the art would appreciate that any other suitable choice of edge detector may be used. Advantageously,  
10 by detecting the chroma gradients in the first and second chroma signals associated with the input luminance signal, the presence of chroma residues in the luminance signal may be located and suppressed. More preferably the means for measuring the chroma gradients includes a pair of Sobel detectors. It would be understood by a person skilled in the art that in alternative embodiments of the present invention the chroma edge value may  
15 include the measurement of a single chroma gradient in a single chroma signal associated with the luminance signal.

Preferably, the luminance gradient corresponds to the difference between a maximum and a minimum pixel luminance within the inter-pixel array.

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Preferably, the luminance gradients within the first range are smaller than the luminance gradients within the second range, and, the luminance gradients within the second range are smaller than the luminance gradients within the third range. Advantageously, the order of the ranges enables peaking of small details in images without over-enhancing larger  
25 details.

Preferably, the gain function of the gain adjustment circuit may be further adjustable such that, in a fourth range of luminance gradients, the output of the peaked filter is amplified by a constant value. More preferably, the luminance gradients within the fourth range of  
30 luminance gradients are smaller than luminance gradients within the third range, and, are larger than the luminance gradients within the second range. Preferably, the constant value

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is 1.0, however, it would be appreciated by a person skilled in the art that any other constant value, or, substantially constant value may be suitable.

- Preferably, the present invention includes a means for measuring a noise value associated with the input luminance signal wherein, the gain function is adjustable relative to the calculated noise value. Also preferably, the means for measuring the noise value includes calculating the sum-of-absolute differences in luminance between adjacent pixels in the inter-pixel array. Also preferably, any absolute differences in luminance between adjacent pixels which are equal to, or greater than, a predetermined threshold value are excluded from the calculation of the noise value. Advantageously, measured values which are equal to, or greater than, the predetermined threshold value are considered to represent edge values and are excluded from the calculation of the sum-of-absolute differences so as not to provide an inaccurate measurement of the noise value.
- 15 Preferably, the present invention includes a means for measuring an average luminance of pixels within the inter-pixel array, wherein, the gain function of the gain adjustment circuit is adjustable relative to the measured average luminance. Also preferably, the gain function of the gain adjustment circuit is adjustable relative to the measured average luminance, whereby the first range of luminance gradients attenuated by the gain function increases relative to a decrease in the measured average luminance. Advantageously, the present invention adjusts the gain function of the gain adjustment circuit to increase the chance of coring relatively darker regions of the input luminance signal where noise is more readily visible. Conversely, for regions of the input luminance signal having relatively strong luminance, the gain function is adjusted whereby the region of the input
- 20
- 25 luminance signal is more likely to be peaked.

- Preferably, the peaking filter includes a horizontal peaking filter for filtering a horizontal component of the input luminance signal. Preferably, the peaking filter also includes a vertical peaking filter. The peaking filter may also include a two-dimensional peaking
- 30 filter.

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Preferably, the output of the gain adjustment circuit may be amplified by a user-defined gain value.

In a second broad form, the present invention provides a processor for enhancing an input  
5 luminance signal including:

a means for calculating a noise value associated with the input luminance signal;

a means for measuring a luminance gradient associated with the input luminance signal;

10 a peaking filter for processing the input luminance signal;

a gain adjustment circuit having a gain function that is adjustable relative to the calculated noise value, the gain adjustment circuit being operable to adjust the magnitude of the output of the peaking filter wherein:

- 15 - in a first range of luminance gradients, the output is an attenuated version of the input;
- in a second range of luminance gradients the output is directly proportional to the input;
- in a third range of luminance gradients, the output is inversely proportional to the input;

20 wherein said enhanced luminance signal is the sum of the input and output of the peaking filter.

In a third broad form, the present invention provides a method of enhancing an input luminance signal including the steps of:

- 25 (i) calculating a chroma edge value associated with the input luminance signal;
- (ii) measuring a luminance gradient associated with the input luminance signal;
- (iii) filtering the input luminance signal with a peaking filter;;

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(iv) adjusting a gain function of a gain adjustment circuit relative to the calculated chroma edge value, the gain adjustment circuit being operable to adjust the magnitude of the output of the peaking filter wherein:

- 5           - in a first range of luminance gradients, the output is an attenuated version of the input;
- in a second range of luminance gradients the output is directly proportional to the input;
- in a third range of luminance gradients, the output is inversely proportional to the input;

10       wherein said enhanced luminance signal is the sum of the input and output of the peaking filter.

In a fourth broad form, the present invention provides a method of enhancing an input luminance signal including the steps of:

- 15           (i) calculating a noise value associated with the input luminance signal;
- (ii) measuring a luminance gradient associated with the input luminance signal;
- (iii) filtering the input luminance signal with a peaking filter;
- (iv) adjusting a gain function of a gain adjustment circuit relative to the
- 20       calculated noise value, the gain adjustment circuit being operable to adjust the magnitude of the output of the peaking filter wherein:
- in a first range of luminance gradients, the output is an attenuated version of the input;
- in a second range of luminance gradients the output is directly
- 25       proportional to the input;
- in a third range of luminance gradients, the output is inversely proportional to the input;

wherein said enhanced luminance signal is the sum of the input and output of the peaking filter.

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### **Brief description of the drawings**

The present invention will become more fully understood from the following detailed description of a preferred but non-limiting embodiment thereof, described in connection  
5 with the accompanying drawings, wherein:

- Figure 1 shows a block diagram of one aspect of a first embodiment of the present invention.
- 10 • Figures 2A and 2B show a first embodiment of a horizontal and a vertical pixel window respectively used to calculate luminance gradients associated with a current pixel of interest.
- Figures 3A and 3B show the horizontal and vertical masks of Sobel edge detectors  
15 used as chroma edge detectors in the first embodiment of the present invention.
- Figure 4 shows a block diagram of a second aspect of the first embodiment of the present invention.
- 20 • Figures 5A to 5C illustrates the relationship between the gain of the gain adjustment circuits and the luminance gradients associated with the pixel of current interest in the first embodiment of the present invention.
- Figure 6 shows a curve depicting the relationship between the dynamic off-set value  
25 and the average luminance value as used in the first embodiment of the present invention.
- Figure 7 shows a first embodiment of the pixel windows used to calculate the noise value of a current pixel of interest in the first embodiment of the present invention.

- Figures 8A and 8B shows the first and second component curves used to generate the luminance gradient vs gain curve of the gain adjustment circuits in the first embodiment of the present invention.

## 5 Description of the Preferred Embodiment

Throughout the specification, the term "peaking" refers to an image enhancement technique whereby "edges" or transition areas within an image are sharpened by selectively emphasising frequency components of a signal which represents the image. The term  
 10 "peaking filter" refers to a filter which may emphasise selected frequency bands of a signal relative to other frequency bands within the signal. The term "coring" refers to the suppression of peaking effects across specific frequency components of a signal and is typically employed to minimise the enhancement of noise components within the input luminance signal.

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Figure 1 illustrates a first embodiment of the present invention for processing an input luminance signal (401) such as is produced by a composite signal decoder, an MPEG decoder, or the like. In the present embodiment, the input luminance signal (401) represents a stream of pixel luminance values corresponding to pixels which comprise a  
 20 two-dimensional image for display. The pixel luminance values are obtained by sampling the input luminance signal using techniques known to persons skilled in the art. The pixel luminance values are stored in a memory array to allow for digital processing of the input luminance signal on a pixel-by-pixel basis. For the purposes of simplicity, the following description describes the processing of a current pixel of interest, and, it would be  
 25 understood by a person skilled in the art that the present embodiment of the invention processes each successive pixel in a similar manner.

In the present embodiment, a horizontal peaking filter (402) and a vertical peaking filter (403) are arranged in parallel as shown in Fig. 1. The horizontal peaking filter (402) has a  
 30 gain and phase response which enables the extraction of a frequency band within the input luminance signal (401) in which edge transitions in a horizontal direction of the image are

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typically present. The horizontal filter (402) may be a band-pass filter with a minimum of 7 taps, or, a high-pass filter with a minimum of 5 taps.

Similarly, the vertical peaking filter (403) extracts a frequency band within the input  
5 luminance signal (401) in which edge transitions in a vertical direction of the image are typically present. The vertical peaking filter (403) in this embodiment includes a minimum of 3 taps.

In alternative embodiments of the present invention it would be appreciated by a person  
10 skilled in the art that a two-dimensional peaking filter may be used in place of separate horizontal and vertical peaking filters.

A horizontal range detector (404) and a vertical range detector (405) are arranged in parallel with the horizontal and vertical peaking filters (402,403) as shown in Fig. 1. The  
15 horizontal and vertical range detectors (404,405) process the same input luminance signal (401) as is fed into the horizontal and vertical peaking filters (402,403). The horizontal range detector (404) outputs a luminance gradient value for the current pixel of interest by examining the luminance characteristics of the pixel relative to its neighbouring pixels. In the present embodiment, this is achieved by examining each pixel within a 5 x 3 pixel  
20 window such as is depicted in Fig. 2A. The current pixel of interest is depicted by a shaded box in Fig. 2A and the unshaded boxes represent neighbouring pixels in the 5 x 3 pixel window centred around the current pixel of interest.

The horizontal range detector (404) measures the range (i.e. the difference between the  
25 maximum and minimum pixel luminance values) in each of the horizontal lines (A), (B) and (C) of the 5 x 3 pixel window. The output of the range detector is the luminance gradient of the current pixel of interest which is calculated as the average range across lines (A), (B) and (C) of the pixel window. This process is repeated for each pixel value represented by the input luminance signal in a horizontal direction of the pixel window. In  
30 the present embodiment, a smoothing filter is used to provide a luminance gradient for

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each pixel, although other filters suitable for this purpose may be known to a person skilled in the art.

The vertical range detector (404) operates upon the input luminance signal in a similar  
5 manner to the horizontal range detector (405) except that it determines the luminance  
gradient of each pixel in a vertical direction by reference to a 3 x 3 pixel window rather  
than a 5 x 3 pixel window as shown in Fig. 2B. It is noted that a 3 x 3 pixel window is  
applied when measuring the luminance gradient of the current pixel of interest in the  
vertical direction to provide greater ease of implementation of the present embodiment. For  
10 instance, if a 3 x 5 pixel window were scanned in the vertical direction, this would entail  
additional memory resources in order to store two additional lines of raster scanning  
information.

It would be understood by a person skilled in the art that in alternative embodiments of the  
15 present invention, the luminance gradient may be calculated using other suitable  
techniques including the use of a derivative filter.

A first range adjustment circuit (406) receives the output of the horizontal range detector  
(404), and, a second range adjustment circuit (407) receives the output of the vertical range  
20 detector (405).

The magnitude of the gain by which the first and second range adjustment circuits  
(406,407) will amplify the pixel luminance value of the current pixel of interest will  
depend upon the luminance gradient associated with the current pixel of interest.

25

In the present embodiment, the relationship between the luminance gradient of a pixel and  
the gain with which the gain adjustment circuits (406,407) amplify the pixel luminance is  
depicted in Figs. 5A to 5C wherein the gain is plotted along the y-axis, and, luminance  
gradient values are plotted along the x-axis.

30

In the present embodiment of the invention, the luminance-gradient vs gain curve includes up to four distinct gain regions. As shown in Fig. 5A, pixels having luminance gradients falling within a first coring range (800) of luminance gradients are attenuated by the gain adjustment circuits. Thus, as the first coring range (800) of luminance gradients is increased, the likelihood that the current pixel of interest will be cored increases.

10 Pixels having luminance gradients falling within a second range of luminance gradients (810) are scaled proportionally along a positive linear slope. Pixels having luminance gradients falling within a third range of luminance gradients (820) are amplified by a constant gain of 1.0. The third range (820) is intended to allow peaking of components of the input luminance signal representing small edges. Pixels having luminance gradients falling within a fourth range (830) of luminance gradients are amplified proportionally along an exponentially decreasing slope. The fourth range (830) is intended to rapidly decrease the gain provided to components of the input luminance signal representing relatively large edges.

Each of the curves depicted in Figs. 5A to 5C may be generated by simply over-laying a first component curve and a second component curve as shown in Figs. 8A and 8B respectively. It would be evident to a person skilled in the art that as the first component curve in Fig. 8A is positively shifted along the x-axis relative to the second component curve, the first range of luminance gradients increases. In the present embodiment, the first coring ranges of the gain adjustment circuits are dynamically adjusted relative to at least one of the following inputs associated with the current pixel of interest:

- 25 (i) a noise value associated with the current pixel of interest which in the present embodiment is the sum-of-absolute difference associated with the current pixel of interest within a pixel window;
- (ii) a chroma edge value associated with the current pixel of interest;
- (iii) a dynamic off-set value associated with the current pixel of interest.

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In the present embodiment, the noise value associated with the current pixel of interest is calculated as the sum of the sum-of-absolute differences (SAD) of horizontally-adjacent pixels within a 5 x 3 pixel window centred around the current pixel of interest, and, the SAD of vertically-adjacent pixels within a 3 x 3 pixel window centred around the current  
5 pixel of interest.

An SAD calculator (411) firstly computes the SAD of inter-pixel luminance values in a horizontal direction for a 5 x 3 pixel window centred around the current pixel of interest. Figure 7 shows a pixel window used in the present embodiment for the purposes of  
10 measuring the SAD in the horizontal direction within the pixel window. The horizontal SAD is derived by summing up absolute differences between horizontally-adjacent pixels as indicated by the bi-directional arrows in Fig. 7. However, where an absolute difference in pixel luminance values between any two horizontally-adjacent pixels in the pixel window is greater than a predetermined threshold value (discussed below), the measured  
15 absolute difference between the adjacent pixels in question is excluded from the horizontal SAD value. Such differences that are greater than the predetermined threshold are considered to indicate the presence of an edge, and if included in the horizontal SAD value, this would over-state the magnitude of the noise value.

20 Similarly, an SAD value is calculated for the current pixel of interest in a vertical direction within a 3 x 3 pixel window centred around the current pixel of interest. The vertical SAD is derived by summing the absolute differences between vertically-adjacent pixels as indicated by bi-directional arrows in Fig. 7 and excludes values which fall below the predetermined threshold.

25

The noise value associated with the current pixel of interest is ascertained by adding the horizontal SAD value with the vertical SAD value. The SAD calculator (411) used in the present embodiment may be implemented by way of an application specific integrated circuit using techniques which are commonly known to persons skilled in the art and  
30 commercially available.

In the present embodiment, the predetermined threshold value is pre-programmed into the SAD calculator (411). A threshold value of 16 is found to be suitable for a broad range of pictures with noise. Higher threshold values tend to give rise to the inclusion of small edges in the noise value total while lower threshold values tend to reduce the effectiveness of the SAD calculator (411) to localised noise.

Chrominance signal residues may also contribute noise to the luminance signal as a result of the imperfect separation of the luminance signal from the chrominance signals Cr and Cb (413,414) when a composite signal (i.e. combined input luminance and associated chrominance signals Cr and Cb) is decoded by a notch-filter. The present embodiment includes a chroma edge detector (412) which is used to compute a chroma edge value from chrominance gradients of chrominance signals Cr (413) and Cb (414) associated with the input luminance signal (401). The gain adjustment circuits (406,407) are dynamically adjusted relative to the calculated chroma edge value.

The chroma edge detector (412) is switched on whenever it detects that the notch filter in the composite signal decoder is in use. In the present embodiment, the chroma edge detector (412) is implemented using a pair of Sobel edge detectors as depicted in Figs. 3A and 3B which are overlayed as a pair of vertical and horizontal 3 x 3 pixel masks respectively centred around the current pixel of interest. It would be readily evident to a person skilled in the art that other suitable means of detecting chroma gradients may be used in alternative embodiments.

The horizontal chroma gradient value is computed in accordance with the following steps:

- (i) overlap the horizontal 3 x 3 Sobel mask over the current pixel of interest;
- (ii) multiply the mask values by their corresponding pixel luminance values;
- (iii) sum each multiple in the 3 x 3 window and take the absolute value;

Similarly, the vertical chroma gradient value may be computed in accordance with the following steps:

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- (i) overlap the vertical 3 x 3 Sobel mask over the current pixel of interest;
- (ii) multiply the mask values by their corresponding pixel luminance values;
- (iii) sum each multiple in the 3 x 3 window and take the absolute value;

5 The overall chroma edge value is equal to the sum of the absolute gradients computed by the masks in the vertical and horizontal directions. The input chroma sampling format is set at a ratio of 4:2:2 for optimal use of the Sobel edge detectors. However, it would be understood by a person skilled in the art that other suitable edge detector circuits may be used for different chroma sampling formats.

10

As shown in Fig. 1, the present embodiment also includes a dynamic off-set circuit (410) arranged in parallel with the peaking filters (402,403) and the range detectors (404,405) which is switched on in the presence of localised noise around the current pixel of interest. A control signal may be used to activate the dynamic off-set circuit (410) when noise is  
15 detected around the current pixel of interest. The dynamic off-set circuit (410) receives and processes the input luminance signal (401), and outputs a dynamic off-set value which contributes toward the dynamic adjustment of the gain adjustment circuits (406,407).

The luminance gradient vs gain curves of the gain adjustment circuits (406,407) are  
20 adjusted relative to the dynamic offset value of the current pixel of interest whereby darker regions of an image relative to other regions with similar SAD characteristics, will be more likely to be cored.

In order to determine the dynamic off-set value, an average luminance value is first  
25 measured in respect to the current pixel of interest. This is performed by measuring the average luminance of pixel luminance values within a 3 x 3 pixel window centred around the current pixel of interest. The measured average luminance value (in 8-bit gray-scale) is mapped on to the curve shown in Fig. 6 which depicts the relationship between the average luminance and the dynamic off-set value. In the present embodiment, the dynamic off-set  
30 range is limited to a peak value of 16 whilst points L1 and L2 along the x-axis are set at 16 and 80 (in 8-bit gray-scale) respectively. It is evident from Fig. 6 that the maximum

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dynamic off-set value of 16 is output from the dynamic off-set circuit when the average luminance value is 16 or below.

5 The noise value, the chroma edge value and the dynamic off-set value are weighted by a first, a second, and a third weighting circuit (721,722,723) respectively before being summed to provide a combined gain adjustment value. The luminance gradient vs gain curves of the gain adjustment circuits (406,407) are adjusted relative to the gain adjustment value. Specifically, in the present embodiment, the first component curve is shifted relative to the second component curve.

10

The individual effects of each of the noise value, the chroma edge value, and the dynamic off-set value upon the first coring ranges of the gain adjustment circuits (406,407) should first be observed, and then weightings should be applied if necessary using the first, the second, and/or the third weighting circuits (721,722,723) respectively.

15

Referring now to Fig 4., if noise is detected with respect to the current pixel of interest, the SAD calculator (411) is switched on via multiplexer (711). The first weighting circuit (721) receives the noise value from the SAD calculator (411), multiplies the noise value by a weighting gain  $G_0$ , adds a value  $C_0$  to the noise value, and outputs a weighted noise value.

20

The weighting gain  $G_0$  and off-set  $C_0$  are manually set such that relatively small edges are not cored by the gain functions of the gain adjustment circuits (406,407), whilst flat regions with local noise are cored. The weighting gain  $G_0$  and the off-set  $C_0$  are manually adjusted in accordance with the following steps:

25

- (i) set the weighting gains  $G_1$  and  $G_2$  to zero for the second and third weighting circuits respectively. In this way, the effects of the noise value upon the gain function of the gain adjustment circuits can be observed in isolation from the effects of the dynamic off-set circuit and the chroma edge detector circuit;

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- (ii) select a sample input image containing relatively small levels of noise;
- (iii) set weighting gain  $G_0$  to 1, and,  $C_0$  to zero;
- (iv) perform relatively strong peaking;
- (v) view subjectively the output and carefully observe if noise regions are cored  
5 and small edges are not cored;
- (vi) decrease the value of weighting gain  $G_0$  if regions other than the noise  
regions are cored or increase  $G_0$  if noise regions are not sufficiently cored;
- (vii) decrease  $C_0$  if small edges are cored;
- (viii) repeat steps (iv) to (vii) until it is visually observable that only noise regions  
10 are cored and peaking on small edges are recovered.

The dynamic off-set value is weighted by a weighting gain  $G_1$  to produce a weighted  
dynamic off-set value. The weighting gain  $G_1$  of the second weighting circuit is pre-set in  
the presence of a properly weighted noise value and/or weighted chroma edge value in  
15 accordance with the following steps:

- (i) select an input image with low noise and significant dark areas;
- (ii) set  $G_1$  to 1;
- (iii) perform relatively strong peaking;
- (iv) observe the output on a cathode ray tube display and carefully observe if the  
20 noise regions in the dark areas are visible;
- (v) increase  $G_1$  if dark noise regions are peaked, or, decrease  $G_1$  if the other  
areas of detail are cored;
- (vi) repeat steps (iii) to (v) until dark noise regions are cored with affecting  
25 peaking performance of other regions.

The third weighting circuit (723) processes the chroma edge value and outputs a weighted  
chroma edge value. The weighting gain  $G_2$  of the weighting circuit (723) is adjusted in  
accordance with the following steps:

- (i) isolate the first and second weighting circuits from the adders (71) and  
30 (714) respectively so that the effect of the chroma edge value upon the gain

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function of the gain adjustment circuits can be observed in isolation. This may be achieved by setting  $G_1$ ,  $C_0$  and  $G_2$  to zero;

- (ii) capture a typical noise-free colour-bar test pattern sequence from the output of the composite signal decoder using the notch filter. Chroma residues are readily observable along edges between the colours;
- (iii) set weighting gain  $G_2$  to 1;
- (iv) perform relatively strong peaking;
- (v) observe whether the chroma residues are not amplified especially when the sequence is played;
- (vi) increase the magnitude of weighting  $G_2$  if chroma residues are not cored, or, decrease  $G_2$  if chroma residues are cored;
- (vii) repeat steps (iv) to (vi) until a value of  $G_2$  is determined wherein the chroma residues are observably cored, and below which, chroma residues are amplified.

15

The weighted outputs of the first, second, and third weighting circuits (721,722,723) are accumulated via adders (712), (714), and (717) and output a coring value. The present embodiment further includes a means for comparing the magnitude of the dynamically-generated coring level with the magnitude of a user-defined coring value wherein the greater of the two coring levels selectively output. The user-defined coring value is generated by a picture-noise-estimator circuit wherein the user-defined coring value is adjusted relative to an estimated picture-noise-value measured for each picture that is displayed. It would be understood that picture-noise-estimator circuits are commonly known by persons skilled in the art. The higher of the two coring values is subsequently processed by a low pass filter (702) such that discontinuities are alleviated between the peaking and the coring of successively processed pixels. The coring value is processed by a saturation circuit (703) which clips the coring value to within a pre-defined range. In the present embodiment, the coring range is clipped to a range of 0-64 in the gain adjustment circuits (406,407).

30

The coring value is received by the gain adjustment circuits (406,407) which adjust the first coring ranges in proportion to the received coring value. The gain adjustment circuits amplify the pixel luminance of the current pixel of interest in accordance with the dynamically-adjusted luminance gradient vs gain curve values. It would be understood by  
5 a person skilled in the art that calculations involved in adjusting the first coring range of the gain adjustment circuits could be performed using well known operations upon the curve data stored in random-access-memory.

The output of the gain adjustment circuits (406,407) are multiplied by a horizontal and a  
10 vertical user-defined gain value respectively before the peaked vertical and horizontal filtered components of the input luminance signal (401) are summed to produce an output signal (408).

Those skilled in the art will appreciate that the invention described herein is susceptible to  
15 variations and modifications other than those specifically described without departing from the scope of the invention. All such variations and modification which become apparent to persons skilled in the art, should be considered to fall within the spirit and scope of the invention as broadly hereinbefore described. It is to be understood that the invention includes all such variations and modifications. The invention also includes all of the steps  
20 and features, referred or indicated in the specification, individually or collectively, and any and all combinations of any two or more of said steps or features.

**THE CLAIMS DEFINING THE INVENTION ARE AS FOLLOWS:**

1. A processor for enhancing an input luminance signal including:
  - a means for calculating a chroma edge value associated with the input
  - 5 luminance signal;
  - a means for measuring a luminance gradient associated with the input
  - luminance signal;
  - a peaking filter for processing the input luminance signal;
  - a gain adjustment circuit having a gain function that is adjustable relative to
  - 10 the calculated chroma edge value, the gain adjustment circuit being operable to
  - adjust the magnitude of the output of the peaking filter wherein:
    - in a first range of luminance gradients, the output is an attenuated
    - version of the input;
    - in a second range of luminance gradients the output is directly
    - 15 proportional to the input;
    - in a third range of luminance gradients, the output is inversely
    - proportional to the input;
  - wherein said enhanced luminance signal is the sum of the input and output of the
  - peaking filter.
  - 20
2. A processor as claimed in claim 1 wherein the input luminance signal represents an
- inter-pixel array for display.
3. A processor as claimed in any one of claims 1 or 2 wherein the means for
- 25 calculating the chroma edge value includes calculating the sum of chroma gradients of a
- first and a second chroma signal associated with the input luminance signal.
4. A processor as claimed in any one of the preceding claims wherein the means for
- calculating the chroma edge value includes an edge detector.
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5. A processor as claimed in claim 4 wherein the edge detector includes a pair of Sobel detectors.

6. A processor as claimed in any one of claims 2 to 5 wherein the luminance gradient  
5 corresponds to the difference between a maximum and a minimum pixel luminance within the inter-pixel array.

7. A processor as claimed in any one of claims 1 to 6 wherein the luminance gradients  
within the first range are smaller than the luminance gradients within the second range,  
10 and, the luminance gradients within the second range are smaller than the luminance gradients within the third range.

8. A processor as claimed in any one of claims 1 to 7 wherein the gain function of the  
gain adjustment circuit is further adjustable such that, in a fourth range of luminance  
15 gradients, the output of the peaked filter is amplified by a constant value.

9. A processor as claimed in claim 8 wherein the luminance gradients within the  
fourth range of the luminance gradients are smaller than the luminance gradients within the  
third range, and, are larger than the luminance gradients within the second range.

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10. A processor as claimed in any one of claims 8 or 9 wherein the constant value is  
1.0.

11. A processor as claimed in any one of the preceding claims including a means for  
25 measuring a noise value associated with the input luminance signal wherein, the gain function of the gain adjustment circuit is adjustable relative to the calculated noise value.

12. A processor as claimed in claim 11 wherein the means for measuring the noise  
value includes calculating the sum-of-absolute differences in luminance between adjacent  
30 pixels in the inter-pixel array.

13. A processor as claimed in claim 12 wherein absolute differences in luminance between adjacent pixels which are greater than, or equal to, a predetermined threshold value are not included in the calculation of the noise value.
- 5 14. A processor as claimed in any one of claims 2 to 13 including a means for measuring an average luminance of pixels within the inter-pixel array, wherein, the gain function of the gain adjustment circuit is adjustable relative to the measured average luminance.
- 10 15. A processor as claimed in claim 14 wherein the gain function of the gain adjustment circuit is adjustable relative to the measured average luminance, whereby the first range of luminance gradients attenuated by the gain function increases relative to a decrease in the measured average luminance.
- 15 16. A processor as claimed in any one of the preceding claims wherein the peaking filter includes a horizontal peaking filter for filtering a horizontal component of the input luminance signal.
17. A processor as claimed in any one of the preceding claims wherein the peaking  
20 filter includes a vertical peaking filter for filtering a vertical component of the input luminance signal.
18. A processor as claimed in any one of the preceding claims wherein the peaking  
25 filter includes a two-dimensional peaking filter a horizontal and a vertical component of the input luminance signal.
19. A processor as claimed in any one of the preceding claims wherein the output of the gain adjustment circuit may be amplified by a user-defined gain value.
- 30 20. A processor for enhancing an input luminance signal including:

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a means for calculating a noise value associated with the input luminance signal;

a means for measuring a luminance gradient associated with the input luminance signal;

5 a peaking filter for processing the input luminance signal;

a gain adjustment circuit having a gain function that is adjustable relative to the calculated noise value, the gain adjustment circuit being operable to adjust the magnitude of the output of the peaking filter wherein:

- 10 - in a first range of luminance gradients, the output is an attenuated version of the input;
- in a second range of luminance gradients the output is directly proportional to the input;
- in a third range of luminance gradients, the output is inversely proportional to the input;

15 wherein said enhanced luminance signal is the sum of the input and output of the peaking filter.

21. A processor as claimed in claim 1 wherein the input luminance signal represents an inter-pixel array for display.

20

22. A processor as claimed in claim 21 wherein the means for calculating the noise value includes measuring a sum-of-absolute differences in luminances between pixels in the inter-pixel array.

25 23. A processor as claimed in any one of claims 21 or 22 wherein absolute differences in luminance between pixels which are equal to, or greater than, a predetermined threshold are excluded from the calculation of the noise value.

24. A processor as claimed in any one of claims 20 to 23 including a means for  
30 measuring a chroma edge value associated with the input luminance signal, wherein, the

gain function of the gain adjustment circuit is adjustable relative to the calculated chroma edge value.

25. A processor as claimed in claim 24 wherein the means for calculating the chroma  
5 edge value includes measuring the sum of gradients of a first and a second chroma signal associated with the input luminance signal.

26. A processor as claimed in any one of claims 20 to 25 wherein the means for calculating the chroma edge value includes an edge detector.

10

27. A processor as claimed in claim 26 wherein the edge detector includes a pair of Sobel detectors.

28. A processor as claimed in any one of claims 21 to 27 wherein the luminance  
15 gradient corresponds to the difference between a maximum and a minimum pixel luminance within the inter-pixel array.

29. A processor as claimed in any one of claims 20 to 28 wherein the luminance  
gradients within the first range are smaller than the luminance gradients within the second  
20 range, and, the luminance gradients within the second range are smaller than the luminance gradients within the third range.

30. A processor as claimed in any one of claims 20 to 29 wherein the gain function of the gain adjustment circuit is further adjustable such that, in a fourth range of luminance  
25 gradients, the output of the peaked filter is amplified by a constant amplitude.

31. A processor as claimed in claim 30 wherein the constant value is 1.0.

32. A processor as claimed in any one of claims 21 to 31 including a means for  
30 measuring an average luminance of pixels within the inter-pixel array, wherein, the gain

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function of the gain adjustment circuit is adjustable relative to the measured average luminance.

33. A processor as claimed in claim 32 wherein, the first range of luminance gradients  
5 attenuated by the gain function increases relative to a decrease in the measured average luminance.

34. A processor as claimed in any one of claims 20 to 33 wherein the peaking filter  
10 includes a horizontal peaking filter for filtering a horizontal component of the input luminance signal.

35. A processor as claimed in any one of claims 20 to 34 wherein the peaking filter  
includes a vertical peaking filter for filtering a vertical component of the input luminance  
15 signal.

36. A processor as claimed in any one of claims 20 to 35 wherein the peaking filter  
includes a two-dimensional peaking filter for filtering a horizontal and a vertical  
component of the input luminance signal.

20 37. A processor as claimed in claims 20 to 26 wherein the output of the gain adjustment circuit may be amplified by a user-defined gain value.

38. A method of enhancing an input luminance signal including the steps of:

25 (i) calculating a chroma edge value associated with the input luminance signal;

(ii) measuring a luminance gradient associated with the input luminance signal;

(iii) filtering the input luminance signal with a peaking filter;;

30 (iv) adjusting a gain function of a gain adjustment circuit relative to the calculated chroma edge value, the gain adjustment circuit being operable to adjust the magnitude of the output of the peaking filter wherein:

- 25 -

- in a first range of luminance gradients, the output is an attenuated version of the input;
- in a second range of luminance gradients the output is directly proportional to the input;
- 5       - in a third range of luminance gradients, the output is inversely proportional to the input;

wherein said enhanced luminance signal is the sum of the input and output of the peaking filter.

10   39.    A method as claimed in claim 38 wherein the input luminance signal represents an inter-pixel array for display.

40.    A method as claimed in any one of claims 38 or 39 wherein the step of calculating the chroma edge value includes calculating the sum of chroma gradients of a first and a  
15   second chroma signal associated with the input luminance signal.

41.    A method as claimed in any one of claims 38 to 40 wherein the step of calculating the chroma edge value includes using an edge detector.

20   42.    A method as claimed in claim 41 wherein the edge detector includes a pair of Sobel detectors.

43.    A method as claimed in any one of claims 39 to 42 wherein the luminance gradient corresponds to the difference between a maximum and a minimum pixel luminance within  
25   the inter-pixel array.

44.    A method as claimed in any one of claims 38 to 43 wherein the luminance gradients within the first range are smaller than the luminance gradients within the second range, and, the luminance gradients within the second range are smaller than the luminance  
30   gradients within the third range.

45. A method as claimed in any one of claims 38 to 44 wherein the gain adjustment circuit is further adjustable such that, in a fourth range of luminance gradients, the output of the peaked filter is amplified by a constant value.

5 46. A method as claimed in claim 45 wherein luminance gradients within the fourth range of luminance gradients are smaller than luminance gradients within the third range, and, are larger than the luminance gradients within the second range.

47. A method as claimed in any one of claims 45 or 46 wherein the constant value is  
10 1.0.

48. A method as claimed in any one of claims 38 to 47 including the step of measuring a noise value associated with the input luminance signal wherein, the gain function is adjustable relative to the calculated noise value.

15

49. A method as claimed in claim 48 wherein the step of measuring the noise value includes calculating the sum-of-absolute differences in luminance between adjacent pixels in the inter-pixel array.

20 50. A method as claimed in claim 49 wherein absolute differences in luminance between adjacent pixels which are equal to, or greater than, a predetermined threshold value are excluded from the calculation of the noise value.

51. A method as claimed in any one of claims 39 to 50 including the step of measuring  
25 an average luminance of pixels within the inter-pixel array, wherein, the gain function of the gain adjustment circuit is adjustable relative to the measured average luminance.

52. A method as claimed in claim 51 wherein the gain function of the gain adjustment circuit is adjustable relative to the measured average luminance, whereby the first range of  
30 luminance gradients attenuated by the gain function increases relative to a decrease in the measured average luminance.

53. A method as claimed in any one of claims 38 to 52 wherein the peaking filter includes a horizontal peaking filter for filtering a horizontal component of the input luminance signal.

5 54. A method as claimed in any one of claims 38 to 53 wherein the peaking filter includes a vertical peaking filter for filtering a vertical component of the input luminance signal.

55. A method as claimed in any one of the claims 38 to 54 wherein the peaking filter  
10 includes a two-dimensional peaking filter for filtering a horizontal and a vertical component of the input luminance signal.

56. A method as claimed in any one of claims 38 to 55 wherein the output of the gain adjustment circuit may be amplified by a user-defined gain value.

15

57. A method of enhancing an input luminance signal including the steps of:

- (iii) calculating a noise value associated with the input luminance signal;
- (iv) measuring a luminance gradient associated with the input luminance signal;
- 20 (iii) filtering the input luminance signal with a peaking filter;
- (iv) adjusting a gain function of a gain adjustment circuit relative to the calculated noise value, the gain adjustment circuit being operable to adjust the magnitude of the output of the peaking filter wherein:
  - in a first range of luminance gradients, the output is an attenuated  
25 version of the input;
  - in a second range of luminance gradients the output is directly proportional to the input;
  - in a third range of luminance gradients, the output is inversely proportional to the input;
- 30 wherein said enhanced luminance signal is the sum of the input and output of the peaking filter.

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58. A method as claimed in claim 57 wherein the input luminance signal represents an inter-pixel array for display.

59. A method as claimed in claim 58 wherein the step of calculating the noise value  
5 includes measuring a sum-of-absolute differences in luminances between pixels in the inter-pixel array.

60. A method as claimed in any one of claims 58 or 59 wherein absolute differences in luminance between pixels which fall below a predetermined threshold are excluded from  
10 the calculation of the noise value.

61. A method as claimed in any one of claims 57 to 60 including the step of calculating a chroma edge value associated with the input luminance signal, wherein, the gain function of the gain adjustment circuit is adjustable relative to the calculated chroma edge value.  
15

62. A method as claimed in claim 61 wherein the step of calculating the chroma edge value includes calculating the sum of gradients of a first and a second chroma signal associated with the input luminance signal.

20 63. A method as claimed in any one of claims 57 to 62 wherein the step of calculating the chroma edge value includes using an edge detector.

64. A method as claimed in claim 63 wherein the edge detector includes a pair of Sobel detectors.  
25

65. A method as claimed in any one of claims 57 to 64 wherein the luminance gradient corresponds to the difference between a maximum and a minimum pixel luminance within the inter-pixel array.

30 66. A method as claimed in any one of claims 57 to 65 wherein the luminance gradients within the first range are smaller than the luminance gradients within the second

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range, and, the luminance gradients within the second range are smaller than the luminance gradients within the third range.

67. A method as claimed in any one of claims 57 to 66 wherein the gain function of the gain adjustment circuit is further adjustable such that, in a fourth range of luminance gradients, the output of the peaked filter is amplified by a constant amplitude.

68. A method as claimed in claim 67 wherein the constant value is 1.0.

69. A method as claimed in any one of claims 58 to 68 including the step of measuring an average luminance of pixels within the inter-pixel array, wherein, the gain function of the gain adjustment circuit is adjustable relative to the measured average luminance.

70. A method as claimed in claim 69 wherein, the first range of luminance gradients attenuated by the gain function increases relative to a decrease in the measured average luminance.

71. A method as claimed in any one of claims 57 to 70 wherein the peaking filter includes a horizontal peaking filter for filtering a horizontal component of the input luminance signal.

72. A method as claimed in any one of claims 57 to 71 wherein the peaking filter includes a vertical peaking filter for filtering a vertical component of the input luminance signal.

73. A processor as claimed in any one of claims 57 to 72 wherein the peaking filter includes a two-dimensional peaking filter for filtering a vertical and a horizontal component of the input luminance signal.

74. A method as claimed in any one of claims 57 to 73 wherein the output of the gain adjustment circuit may be amplified by a user-defined gain value.