

Abstract

Example embodiments relate to surgical devices, systems, and methods. The system includes a surgical arm, rotary driving assembly, and telescopic driving assembly. The surgical arm includes a plurality of segments and joints. The rotary driving assembly may be securable to a portion of a proximal end of the surgical arm. The rotary driving assembly may be configurable to rotate the surgical arm. The telescopic driving assembly may be securable to a portion of the proximal end of the surgical arm. The telescopic driving assembly may be configurable to provide a linear displacement of the surgical arm.