

ABSTRACT

**METHOD FOR PRODUCING AN AUTONOMOUS NAVIGATION MAP FOR A
VEHICLE**

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The method of preparing a navigation autonomy map for a vehicle covering a zone including path segments, comprises the following steps: identifying (1) the path segments for which the map needs to be prepared; for each
10 path segment, calculating (3) a primary autonomy index in accordance with at least two distinct functions; and calculating (4) for each path segment a final autonomy index by taking a weighted average of the primary autonomy indices.

15 An autonomy map, an application of the autonomy map, and a vehicle using such an autonomy map.

(Fig. 1)