

Figure 1

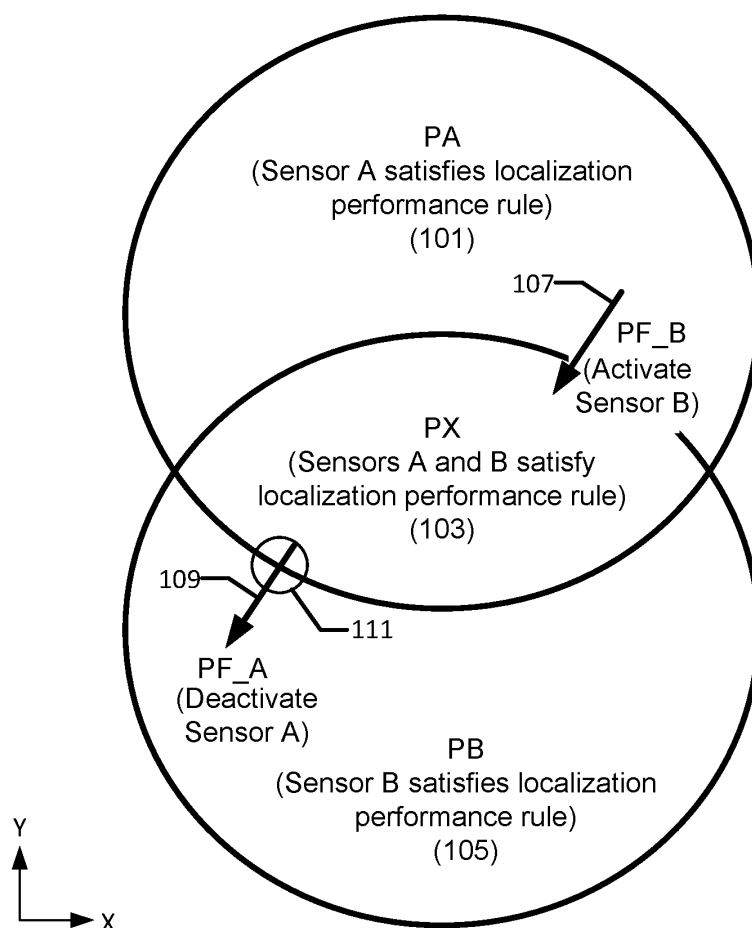


Figure 2

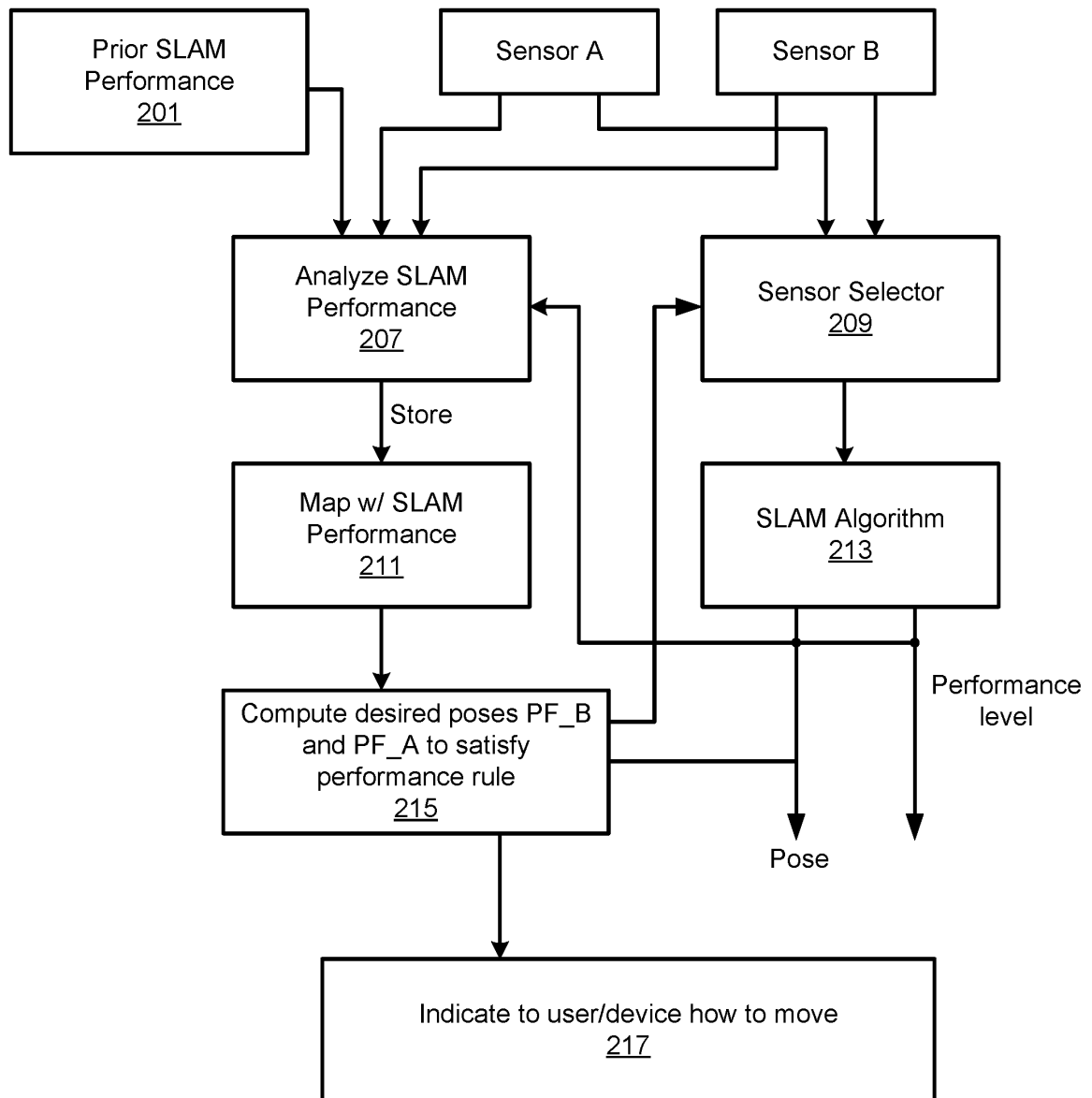


Figure 3

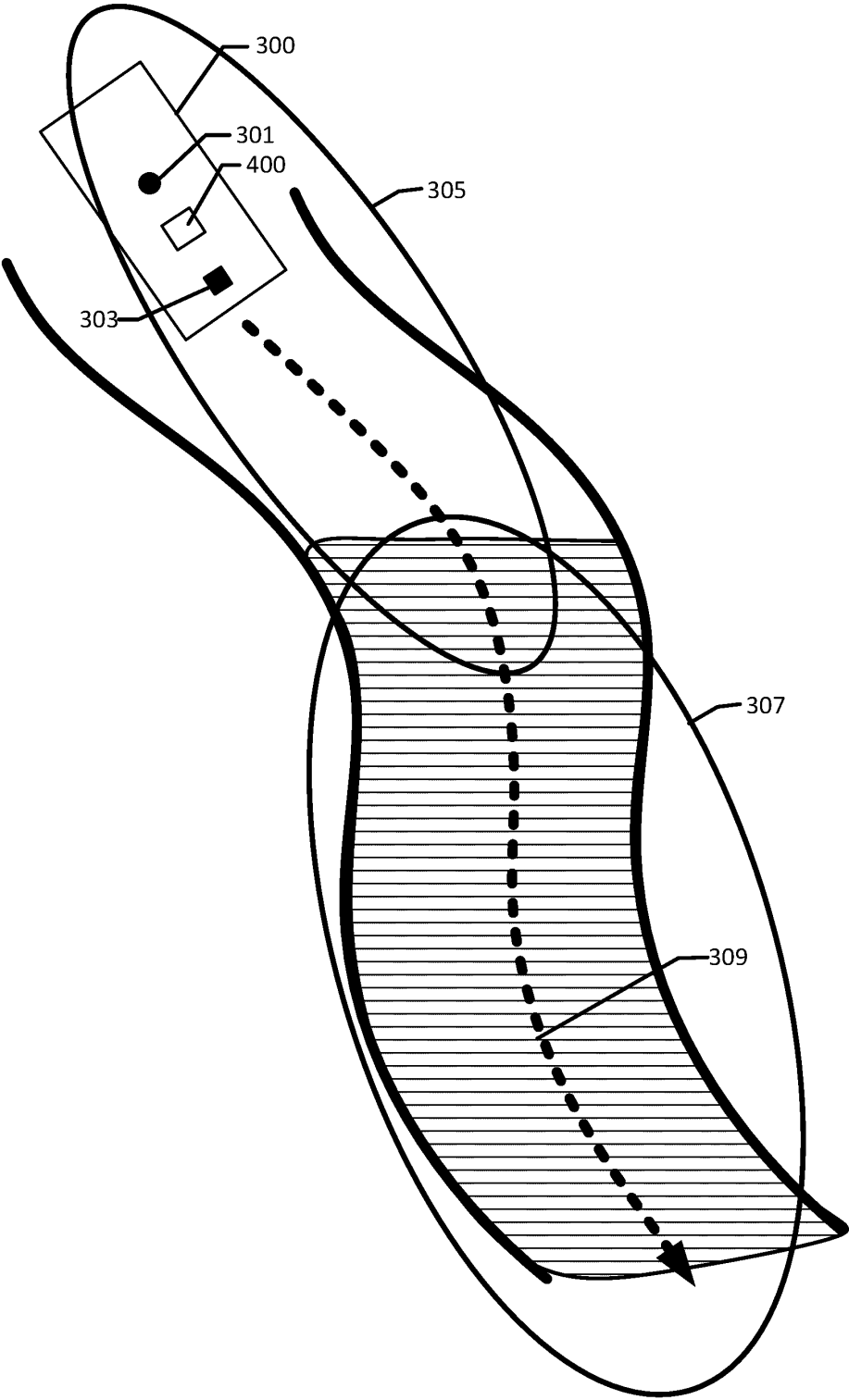


Figure 4

System 450

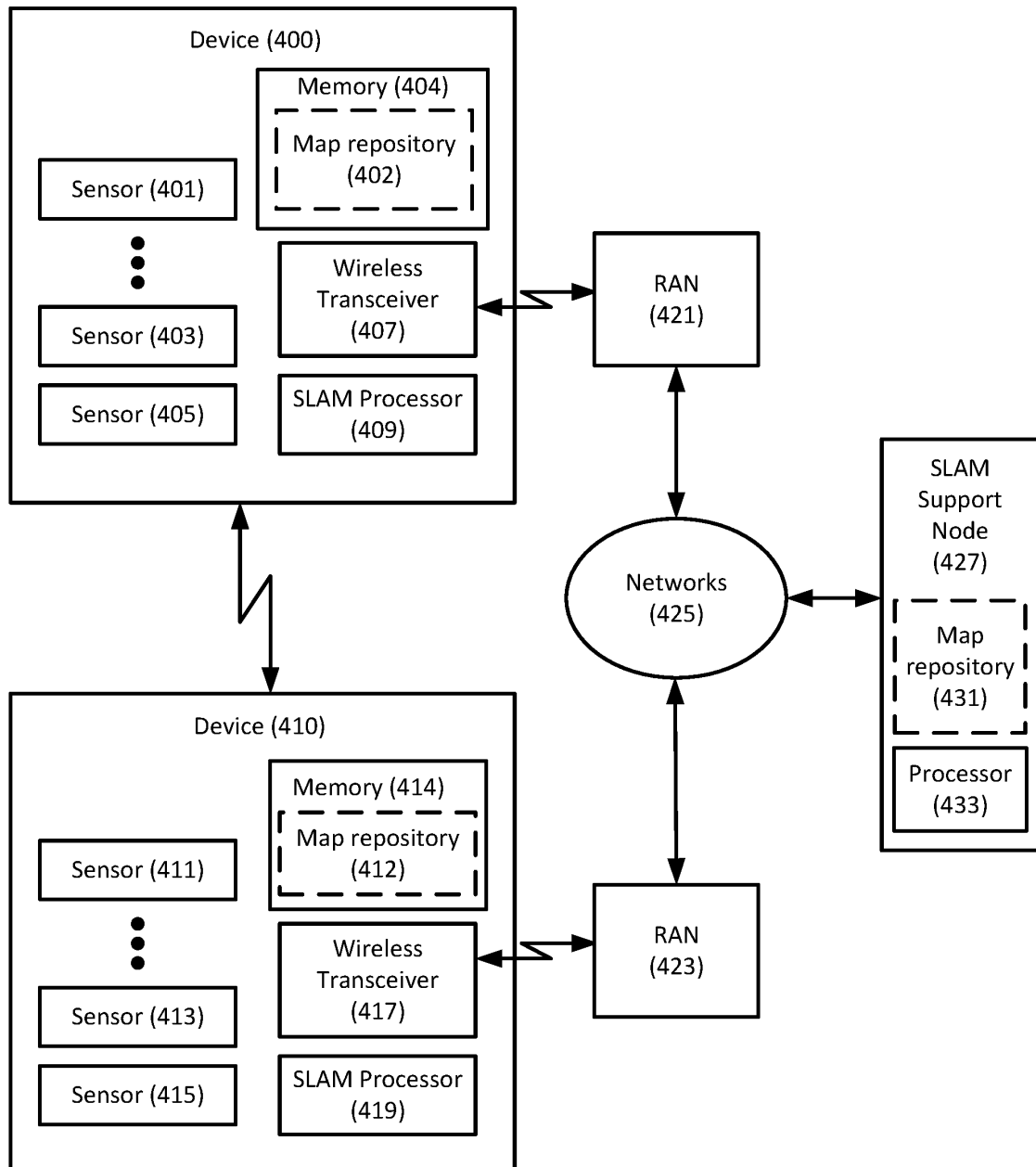


Figure 5

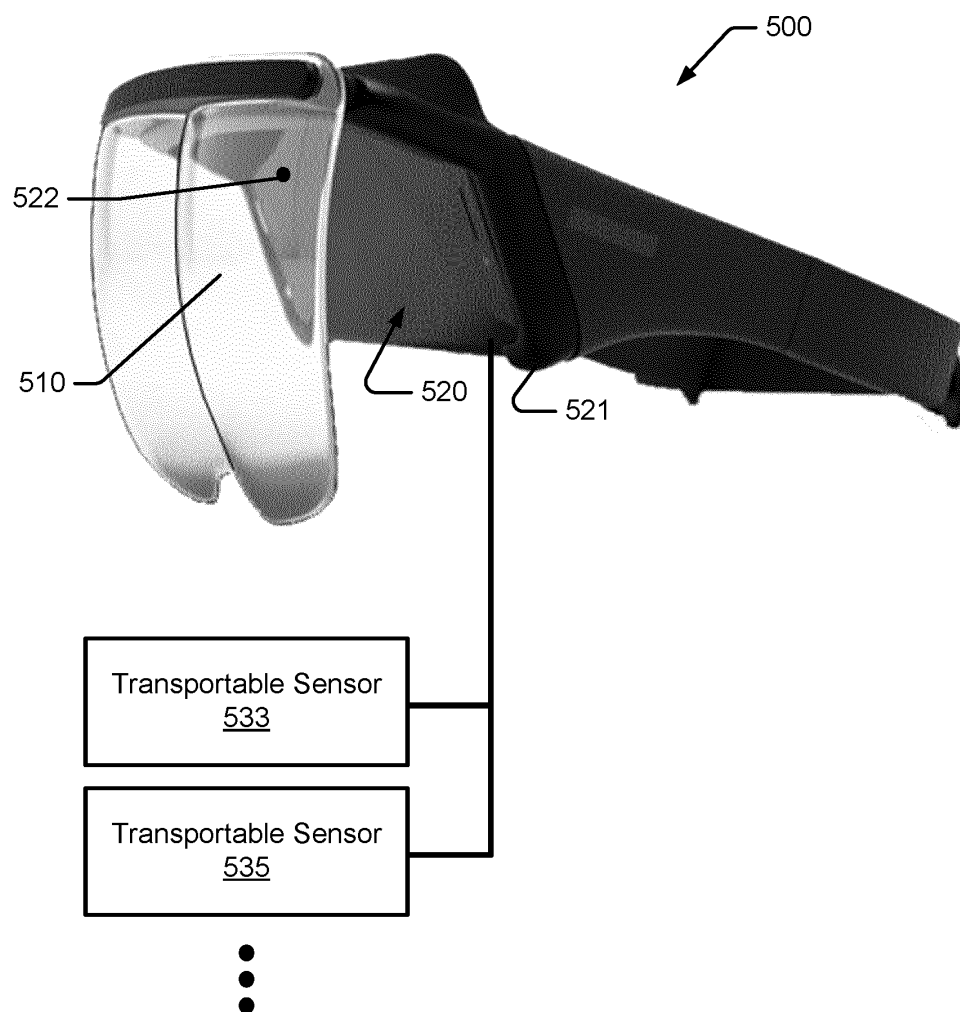


Figure 6

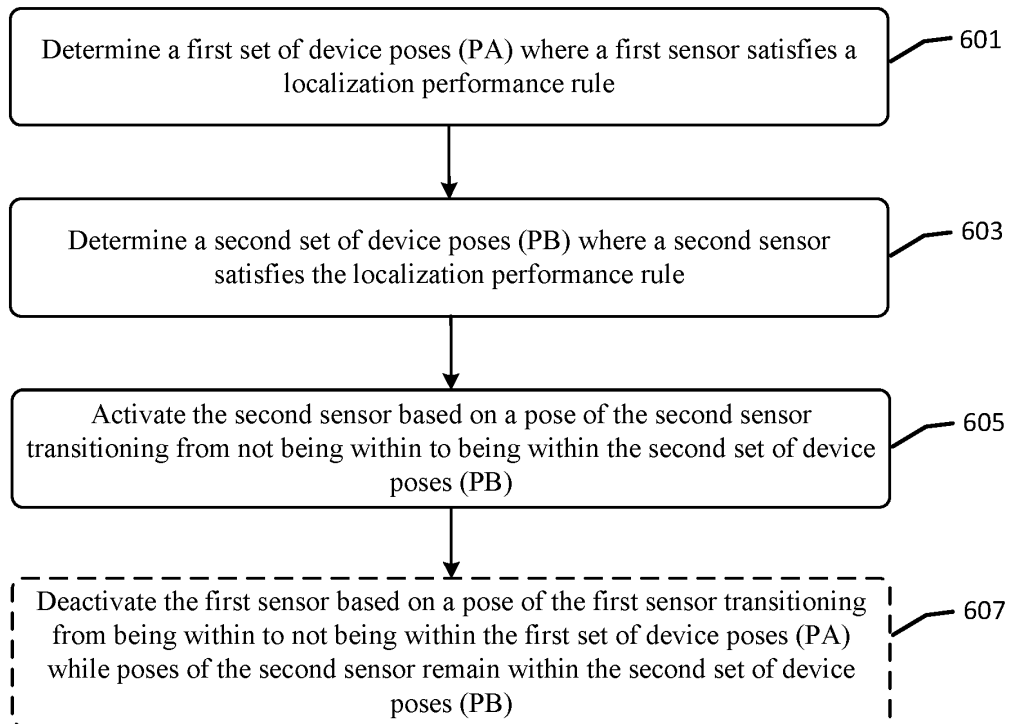


Figure 7

Direct movement of the device to transition a pose of the second sensor from not being within to being within the second set of device poses (PB)

701

Figure 8

Search among the second set of device poses (PB) to identify a subset of at least one device pose for the second sensor where localization performance of the second sensor satisfies the localization performance rule

801

Figure 9

Determine localization of the first sensor relative to a map defined by a data structure identifying previously sensed features of a localized environment

901

Determine a localization performance score for the first sensor with the device at one or more poses based on whether the first sensor senses the previously sensed features identified by the data structure

903

Determine whether the localization performance score for the first sensor with the device at the one or more poses satisfies the localization performance rule

905

Figure 10

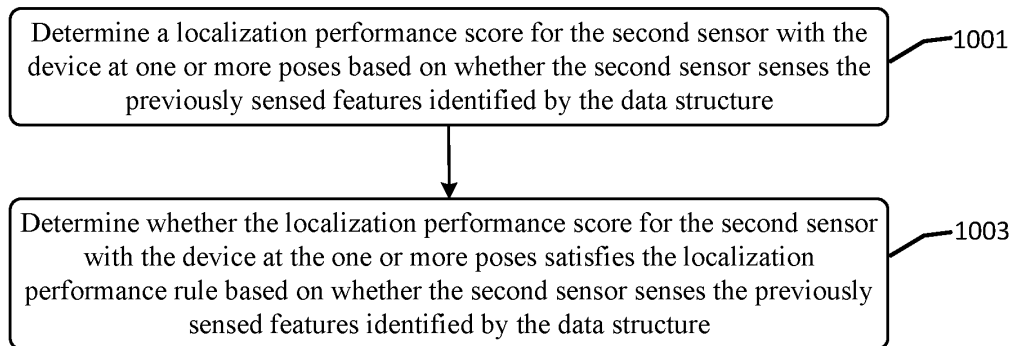


Figure 11

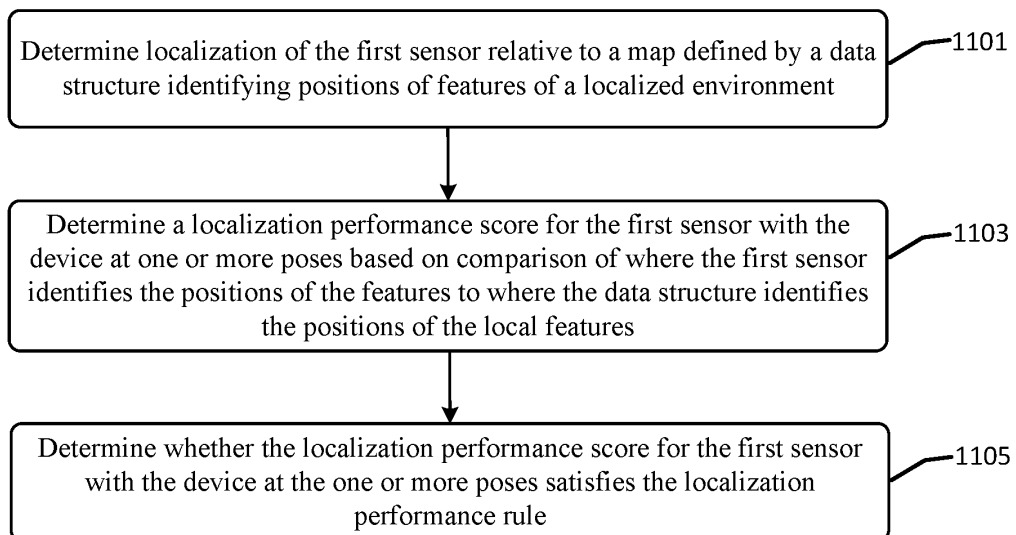


Figure 12

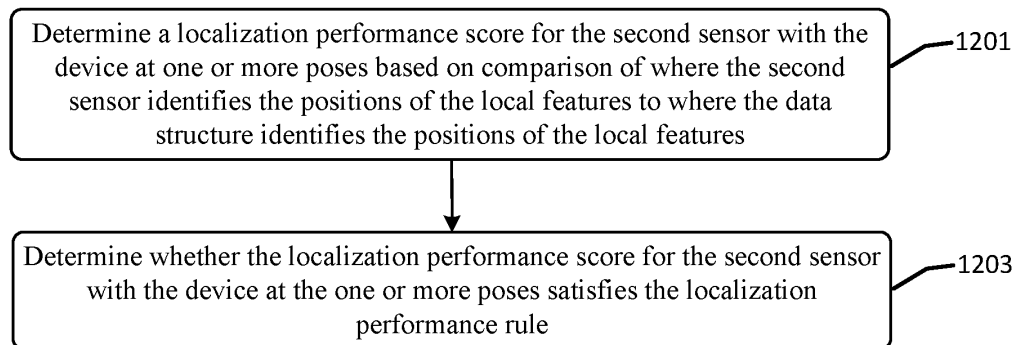


Figure 13

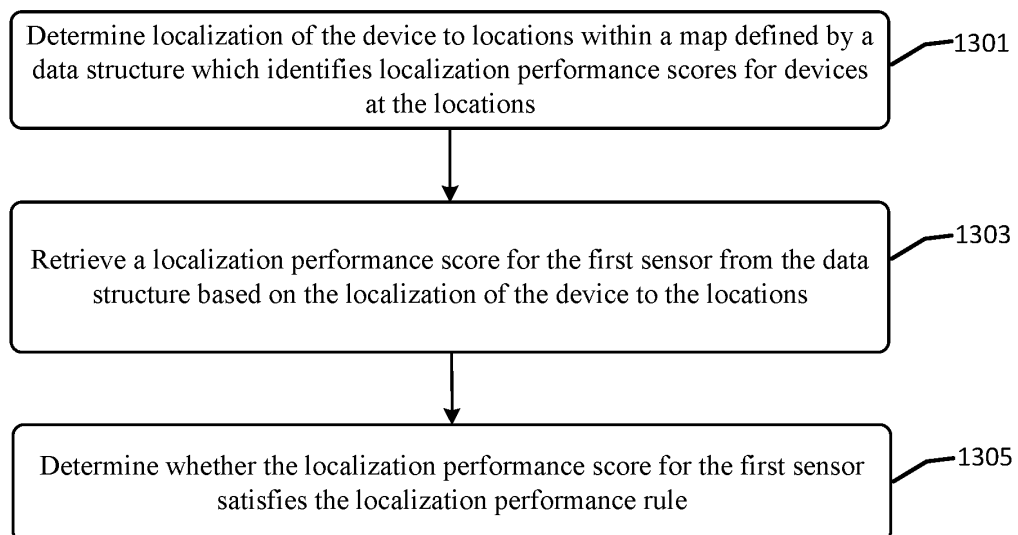


Figure 14

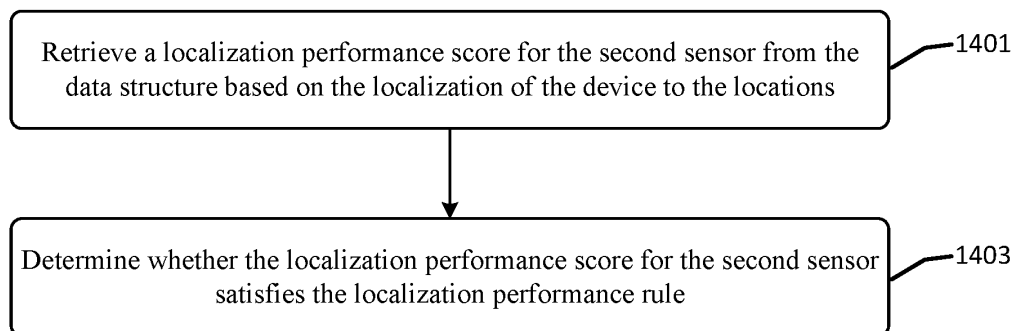


Figure 15

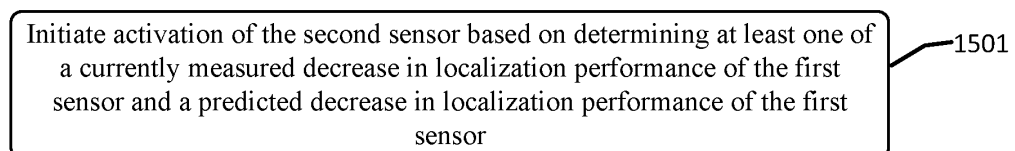


Figure 16

