

Abstract

The invention relates to a method and to a device for producing a robot (R) with a robotic arm (2). Said method can be carried out using an assembly robot (M1;M2), wherein first housing segments (7) are arranged in an intended sequence for the robotic arm (2), drive units (9) are inserted into the first housing segments (7) and the respective complimentary second housing segments (12) are placed on the first housing segments (7) comprising the drive units (9).

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(Fig. 1a)