WHAT IS CLAIMED IS:

1. A system for enabling autonomous navigation of a mobile platform, the system comprising:

a memory having computer readable instructions stored thereon; and

at least one processor configured to execute the computer readable instructions to:

receive a first set of coordinates corresponding to a first location of a user from an electronic device communicatively coupled to the at least one processor;

determine a different second location for the mobile platform, wherein the mobile platform is a wheelchair and wherein the second location is the actual location of the wheelchair;

navigate the mobile platform from the second location to the first location;

receive a different second set of coordinates from the user; and

maneuver the mobile platform with the user therein to the second set of coordinates received from the user.

2. The system of Claim 1, wherein the receipt of the different second set of coordinates is before or after the navigation of the mobile platform from the second location to the first location.

3. The system of Claim 1, wherein the at least one processor is further configured to execute the computer readable instructions to:

transmit one or more commands to one or more actuators on the mobile platform, the one or more commands configured to enable the navigation of the mobile platform.

4. The system of Claim 3, wherein the at least one processor is further configured to execute the computer readable instructions to:

receive a mode selection command, the mode selection command configured to enable at least one of a first mode and a different second mode for the mobile platform, the first mode corresponding to a powered-manual mode, and the second mode corresponding to an autonomous mode; or

receive data from one or more sensors, the data corresponds to time of arrival of the mobile platform at the first set of coordinates; or

display a plurality of locations on a display device, the plurality of locations comprises the second set of coordinates for the user.

5. The system of Claim 4, wherein the data is based on visual identification of at least one marker by the one or more sensors, the marker is external to the mobile platform and within an environment of the mobile platform; or wherein the data is based on radio identification of a marker within an environment of the mobile platform.

6. A non-transitory computer readable medium having computer readable instructions stored thereon, that when executed by at least one processor, configure the at least one processor to:

receive coordinates for a first set of coordinates corresponding to a first location for a user from an electronic device communicatively coupled to the at least one processor;

determine a different second location for a mobile platform, wherein the mobile platform is a wheelchair and wherein the second location is the actual location of the wheelchair;

navigate the mobile platform between the second location and the first location;

receive destination coordinates for the user; and

maneuver the first mobile platform with the user therein to the destination coordinates received from the user.

7. The non-transitory computer readable medium of Claim 6, wherein the at least one processor is further configured to execute the computer readable instructions to:

transmit information corresponding to coordinates of the mobile platform to at least one processor coupled to a second mobile platform, wherein the second mobile platform is a different wheelchair.

8. The non-transitory computer readable medium of Claim 6, wherein the at least one processor is coupled to the mobile platform and is further configured to execute the computer readable instructions to:

receive information from one or more sensors, the received information configured to navigate the first mobile platform along a first path.

9. The non-transitory computer readable medium of Claim 8, wherein the at least one processor coupled to the mobile platform is further configured to execute the computer readable instructions to:

alter the first path of navigation for the mobile platform in response to the received information from the one or more sensors.

10. The non-transitory computer readable medium of Claim 9, wherein:

the received information from the one or more sensors is in relation to the user of the mobile platform; and

the at least one processor coupled to the mobile platform is further configured to execute the computer readable instructions to output a command based on the alteration of the first path, the command corresponds to a halt movement of the mobile platform.

11. The non-transitory computer readable medium of Claim 10, wherein:

the received information from the one or more sensors is based on one or more objects in an environment of the mobile platform, and

the at least one processor coupled to the mobile platform is further configured to execute the computer readable instructions to output a command based on the alteration of the first path, the path corresponds to avoiding a collision with the one or more objects.

12. A method for enabling autonomous navigation of a mobile platform, the method comprising:

receiving a first set of coordinates corresponding to a first location of a user from an electronic device communicatively coupled to at least one processor;

determining a different second location for the mobile platform, wherein the mobile platform is a wheelchair, and wherein the second location is the actual location of the wheelchair;

navigating the mobile platform between the second location and the first location;

receiving a different second set of coordinates from the user; and

maneuvering the mobile platform with the user therein to the second set of coordinates received from the user.

13. The method of Claim 12, wherein the receiving of the second set of coordinates from the user is prior to arriving of the mobile platform at the first location.

14. The method of Claim 12 further comprising:

providing one or more commands to one or more actuators on the mobile platform, the one or more commands configured to enable the navigating of the mobile platform; or

receiving data from one or more sensors, the data configured to enable determination of arrival time at the first location for the user; or

issuing the second set of coordinates to the user; and

the receiving of the second set of coordinates for the user comprises scanning the issued second set of coordinates.

15. The method of Claim 14, wherein the receiving of the data comprises identifying at least one marker within an environment of the mobile platform, the marker is external to the mobile platform.