WE CLAIM:

1. A method implemented on a computing device having at least one processor, at least one computer-readable storage medium, and a communication platform connected to a network for displaying a driving path of a vehicle on a map, the method comprising:

obtaining a request for displaying a driving path of a vehicle from a terminal device;

obtaining location information of the vehicle;

obtaining scene related information associated with the driving path of the vehicle;

verifying the location information based on the scene related information; and

displaying the driving path of the vehicle based on the verified location information on a map implemented on the terminal device.

2. The method of claim 1, wherein the scene related information associated with the driving path of the vehicle includes at least one of

video information related to scenes along the driving path of the vehicle,

image information related to the scenes along the driving path of the vehicle, or

audio information related to the scenes along the driving path of the vehicle.

3. The method of claim 2, wherein obtaining the scene related information associated with the driving path of the vehicle includes:

communicating with an information acquisition device in the vehicle over the network; and

obtaining at least one of the video information, the image information, or the audio information recorded by the information acquisition device over the network.

4. The method of claim 2, wherein verifying the location information based on the scene related information includes:

identifying target objects on the driving path of the vehicle based on the video information, image information, or audio information;

determining whether the location information of the vehicle needs to be corrected based on the target objects on the driving path; and

in response to a determination that the location information of the vehicle associated with the driving path needs to be corrected, correcting the location information of the vehicle based on the target objects on the driving path of the vehicle.

5. The method of claim 4, further including:

displaying the driving path of the vehicle based on the corrected location information of the vehicle on the map implemented on the terminal device.

6. The method of claim 1, wherein displaying the driving path of the vehicle based on the verified location information on a map implemented on the terminal device includes:

obtaining an actual driving path generating speed of the vehicle; and

displaying dynamically the driving path of the vehicle on the map based on the actual driving path generating speed of the vehicle.

7. The method of claim 1, wherein displaying the driving path of the vehicle based on the verified location information on a map implemented on the terminal device includes:

dividing the driving path of the vehicle into a plurality of segments;

determining displaying properties for the plurality of segments; and

displaying the driving path of the vehicle on the map based on the displaying properties for the plurality of segments,

wherein at least two neighboring segments have different displaying properties.

8. The method of claim 7, wherein the displaying properties for the plurality of segments

are determined based on at least one of

traffic condition related to each of the plurality of segments,

time information related to each of the plurality of segments,

driver information related to each of the plurality of segments, or

driving data related to each of the plurality of segments.

9. The method of claim 7, wherein the displaying properties for the plurality of segments include at least one of brightness of the color, hue of the color, or thickness of the driving path.

10. The method of claim 7, further including:

obtaining abnormal events of the vehicle in a historical period;

determining whether an abnormal event occurred on the driving path of the vehicle; and

in response to a determination that an abnormal event occurred on the driving path of the vehicle, tagging a corresponding location to the abnormal event on the driving path of the vehicle.

11. A system for displaying a driving path of a vehicle on a map, comprising:

at least one storage medium storing a set of instructions;

at least one communication platform connected to a network; and

at least one processor configured to communicate with the at least one storage medium or the at least one communication platform, wherein when executing the set of instructions, the at least one processor is directed to cause the system to:

obtain a request for displaying a driving path of a vehicle from a terminal device;

obtain location information of the vehicle associated with the driving path via communicating with a service provider over a network;

obtain scene related information associated with the driving path of the vehicle;

verify the location information based on the scene related information; and

display the driving path of the vehicle based on the verified location information on a map implemented on the terminal device.

12. The system of claim 11, wherein the scene related information associated with the driving path of the vehicle includes at least one of

video information related to scenes along the driving path of the vehicle,

image information related to the scenes along the driving path of the vehicle, or

audio information related to the scenes along the driving path of the vehicle.

13. The system of claim 12, wherein to obtain the scene related information associated with the driving path of the vehicle, the at least one processor is further directed to cause the system to:

communicate with an information acquisition device in the vehicle over the network; and

obtain at least one of the video information, the image information, or the audio information recorded by the information acquisition device over the network.

14. The system of claim 12, wherein to verify the location information based on the scene related information, the at least one processor is further directed to cause the system to:

identify target objects on the driving path of the vehicle based on the video information, image information, or audio information;

determine whether the location information of the vehicle needs to be corrected based on the target objects on the driving path; and

in response to a determination that the location information of the vehicle associated with the driving path needs to be corrected, correct the location information of the vehicle

based on the target objects on the driving path of the vehicle.

15. The system of claim 14, wherein the at least one processor is further directed to cause the system to:

display the driving path of the vehicle based on the corrected location information of the vehicle on the map implemented on the terminal device.

16. The method of claim 11, wherein to display the driving path of the vehicle based on the verified location information on a map implemented on the terminal device, the at least one processor is further directed to cause the system to:

obtain an actual driving path generating speed of the vehicle; and

display dynamically the driving path of the vehicle on the map based on the actual driving path generating speed of the vehicle.

17. The system of claim 11, wherein to display the driving path of the vehicle based on the verified location information on a map implemented on the terminal device, the at least one processor is further directed to cause the system to:

divide the driving path of the vehicle into a plurality of segments;

determine displaying properties for the plurality of segments; and

display the driving path of the vehicle on the map based on the displaying properties for the plurality of segments,

wherein at least two neighboring segments have different displaying properties.

18. The system of claim 17, wherein the displaying properties for the plurality of segments are determined based on at least one of

traffic condition related to each of the plurality of segments,

time information related to each of the plurality of segments,

driver information related to each of the plurality of segments, or

driving data related to each of the plurality of segments.

19. The system of claim 17, wherein the displaying properties for the plurality of segments include at least one of brightness of the color, hue of the color, or thickness of the driving path.

20. The system of claim 17, wherein the at least one processor is further directed to cause the system to:

obtain abnormal events of the vehicle in a historical period;

determine whether an abnormal event occurred on the driving path of the vehicle; and

in response to a determination that an abnormal event occurred on the driving path of the vehicle, tag a corresponding location to the abnormal event on the driving path of the vehicle.

21. A non-transitory computer readable medium, comprising a set of instructions for displaying a driving path of a vehicle on a map, wherein when executed by at least one processor, the set of instructions directs the at least one processor to effectuate a method, the method comprising:

obtaining a request for displaying a driving path of a vehicle from a terminal device;

obtaining location information of the vehicle associated with the driving path via communicating with a service provider over a network;

obtaining scene related information associated with the driving path of the vehicle;

verifying the location information based on the scene related information; and

displaying the driving path of the vehicle based on the verified location information on a map implemented on the terminal device.