

POSITIONING METHOD

ABSTRACT

A positioning method includes detecting coordinates (X_{11}, Y_{11}) of a rotation center on a surface of a holding table with a first image capturing unit and stores the detected coordinates as a new first reference position, detecting coordinates (X_{21}, Y_{21}) of a rotation center on another surface of the holding table with a second image capturing unit and stores the detected coordinates as a new second reference position, calculating a first deviation between a previous rotation center on the surface of the holding table and the coordinates (X_{11}, Y_{11}) , calculating a second deviation between a previous rotation center on the other surface of the holding table and the coordinates (X_{21}, Y_{21}) , correcting a coordinate system of images captured by the first image capturing unit to eliminate the first deviation, and correcting a coordinate system of images captured by the second image capturing unit to eliminate the second deviation.

[FIG. 1]