ABSTRACT

[Problem] Provided is a position estimation device that updates current position data while suppressing an influence of variation in GPS position data.

[Solution] A position estimation device according to the present disclosure is a position estimation device that updates and outputs current position data by using part of a plurality of pieces of GPS position data sequentially input from a GPS module, and includes a first data update unit that compares the current position data with GPS position data newly acquired, determines whether or not there is a change therebetween beyond a variation range of the GPS position data, and updates the current position data with that GPS position data when it is determined that there is a change beyond a fixed range predetermined as the variation range.

(FIG. 5)