

ABSTRACT

Disclosed are a logistics system and a control device therefor, the system comprising: a map management unit for setting at least one region within an operation boundary as a region of interest on the basis of map information corresponding to a preset operation boundary; and a monitoring unit for determining whether a logistics robot has entered the set region of interest, and instructing that the logistics robot adjusts the adjacent recognition range thereof on the basis of the determination result of whether entering has occurred.

Fig. 3