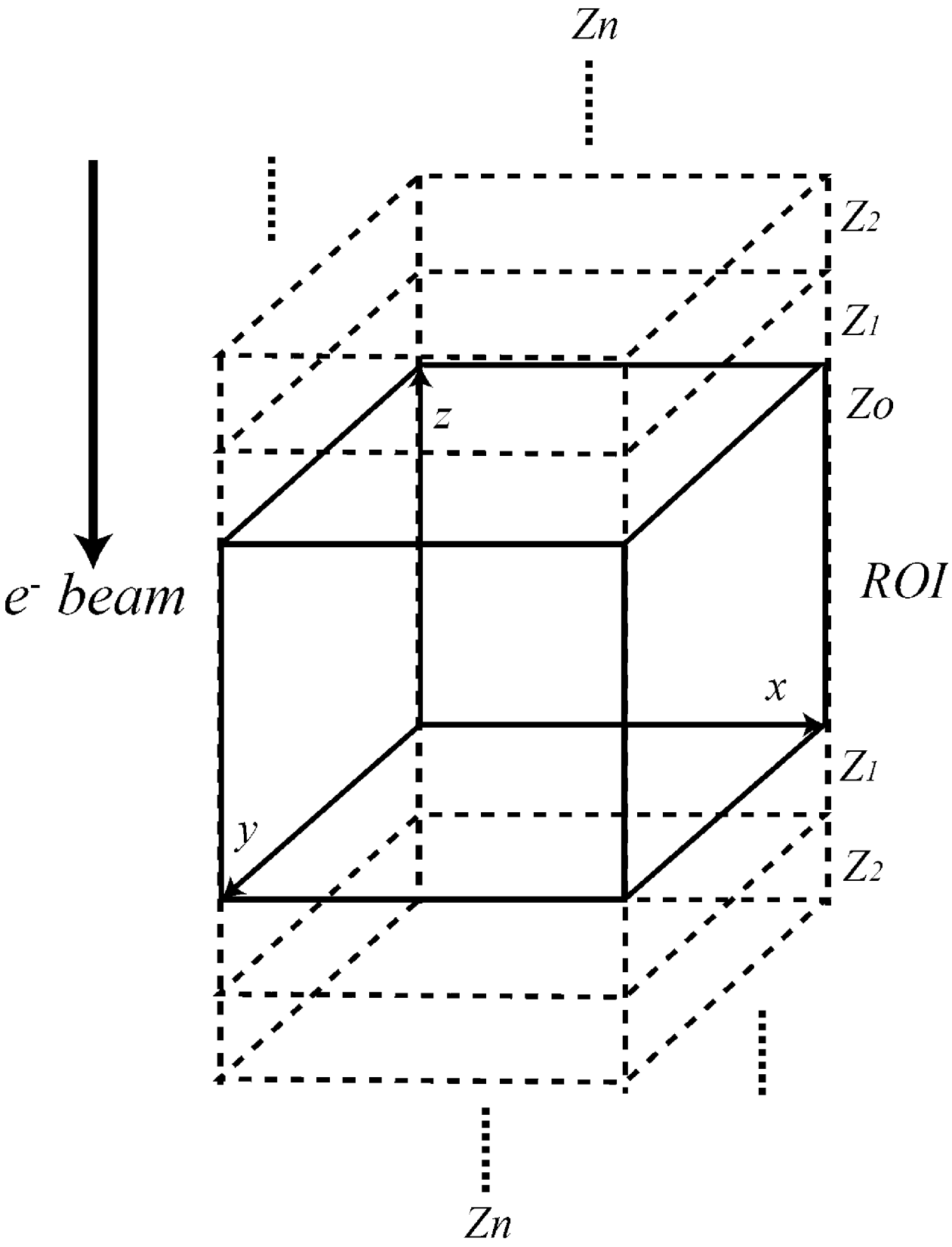
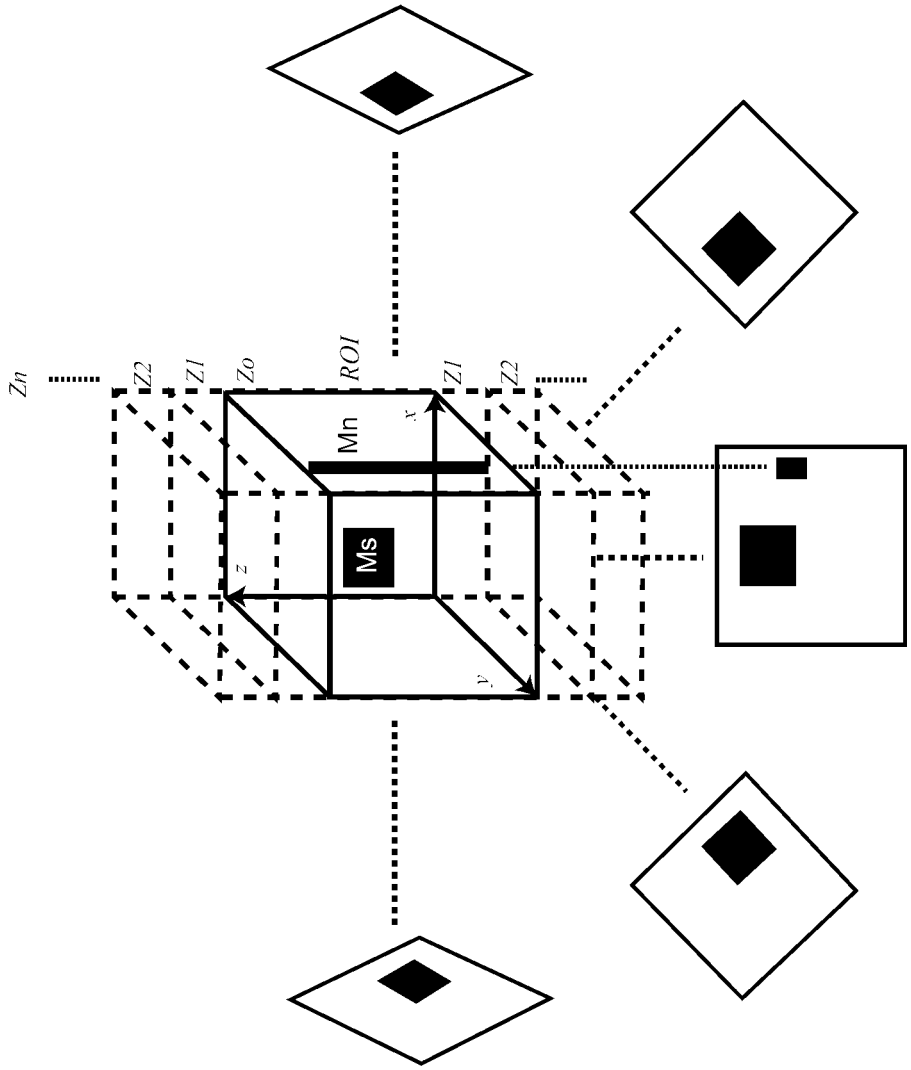
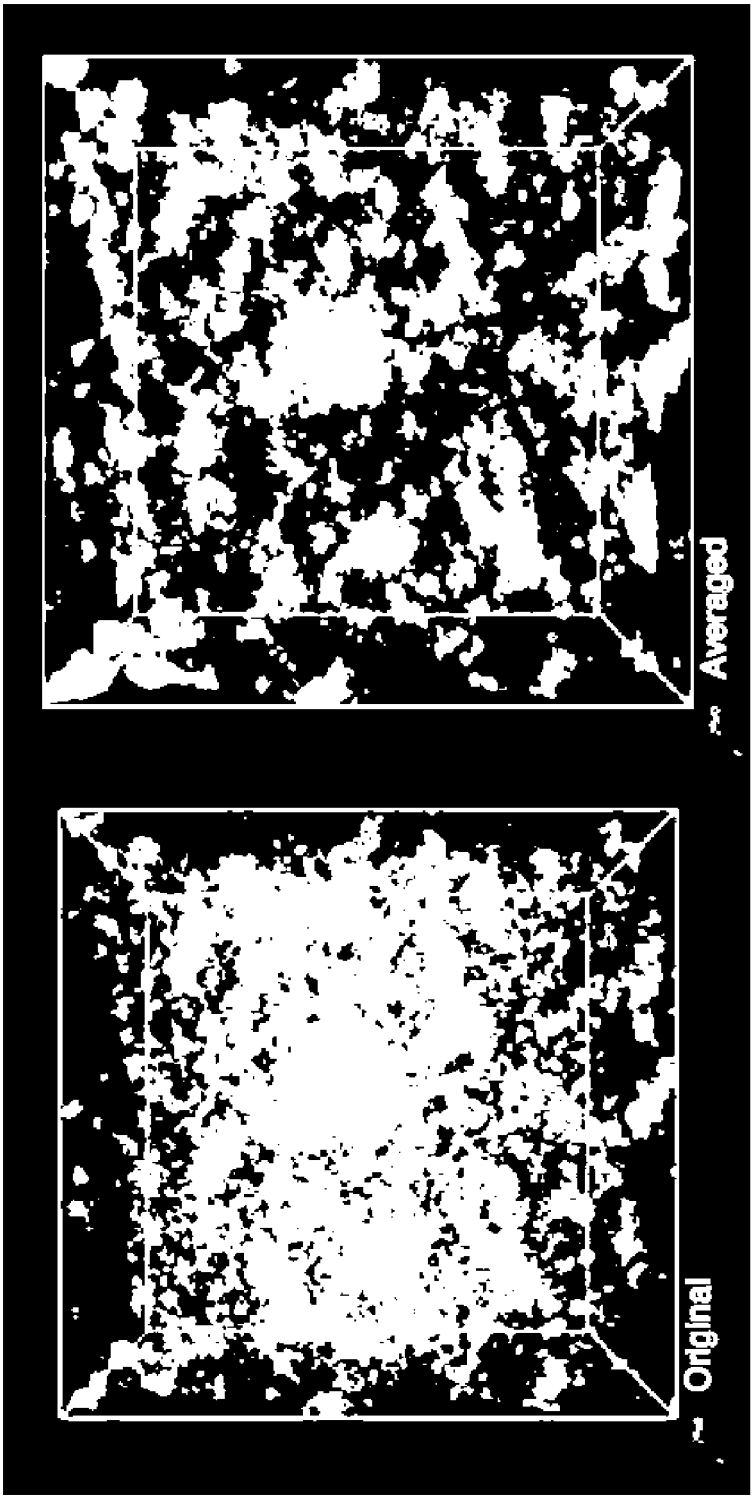
[Fig. 1]



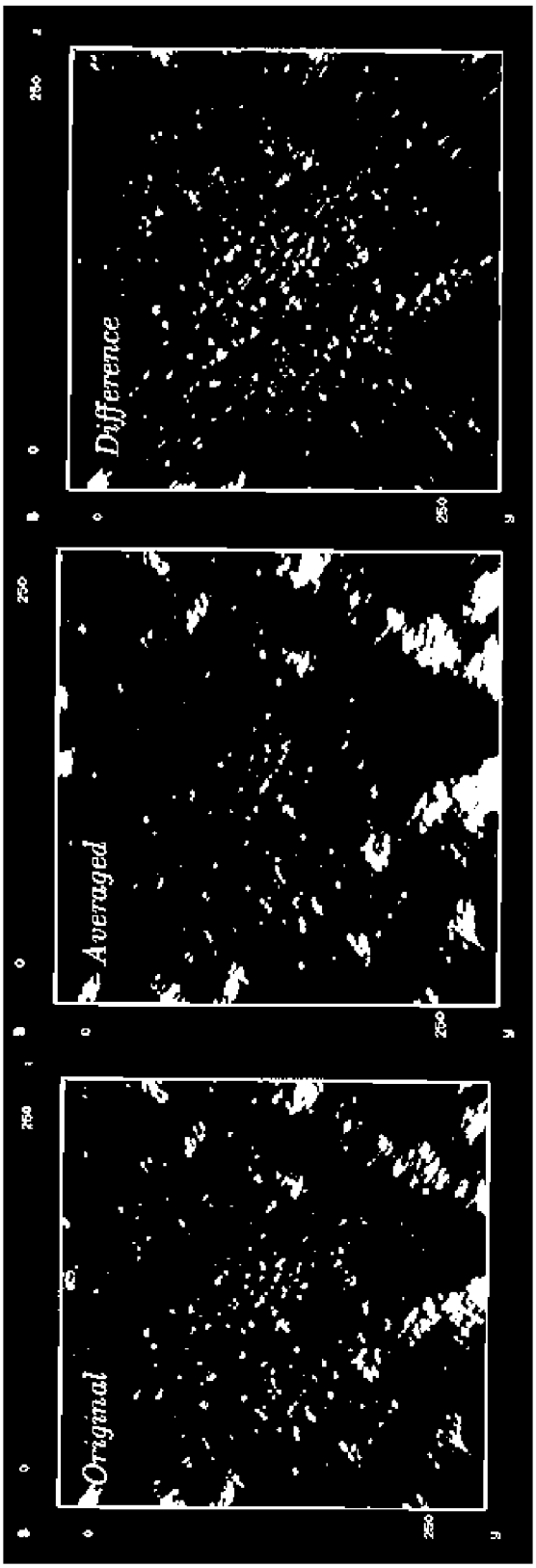
[Fig. 2]



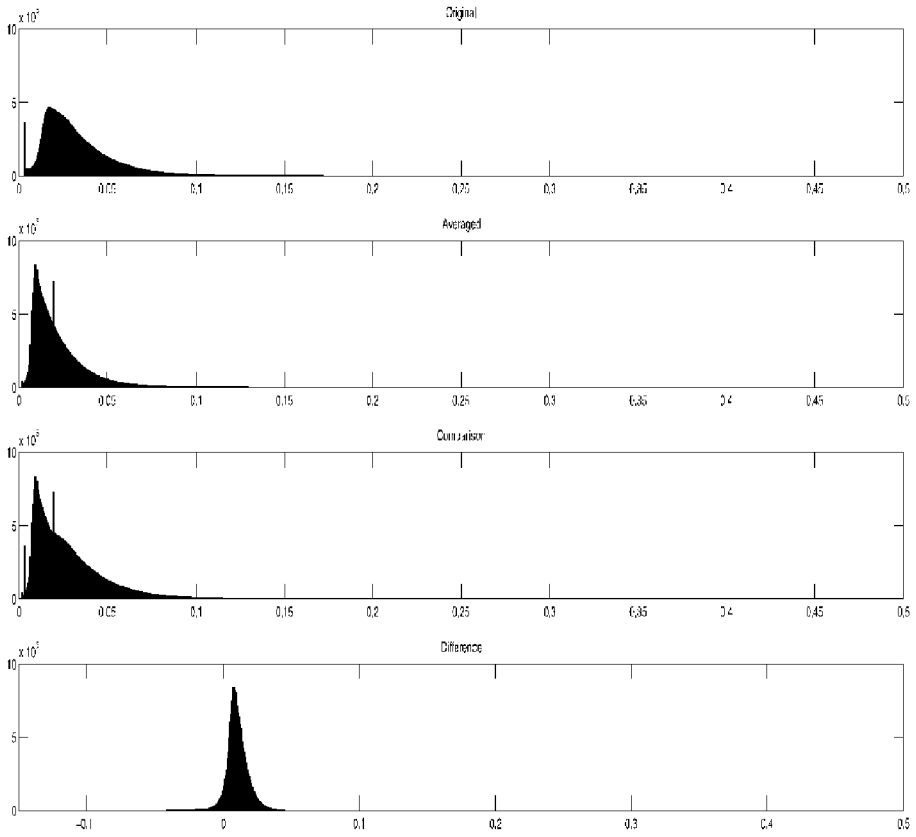
[Fig. 3]



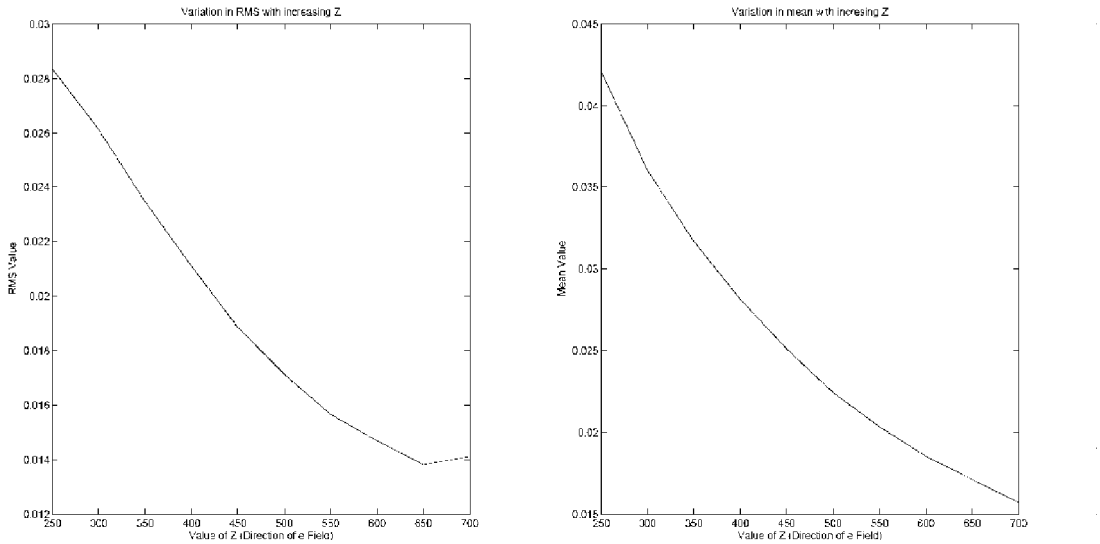
[Fig. 4]



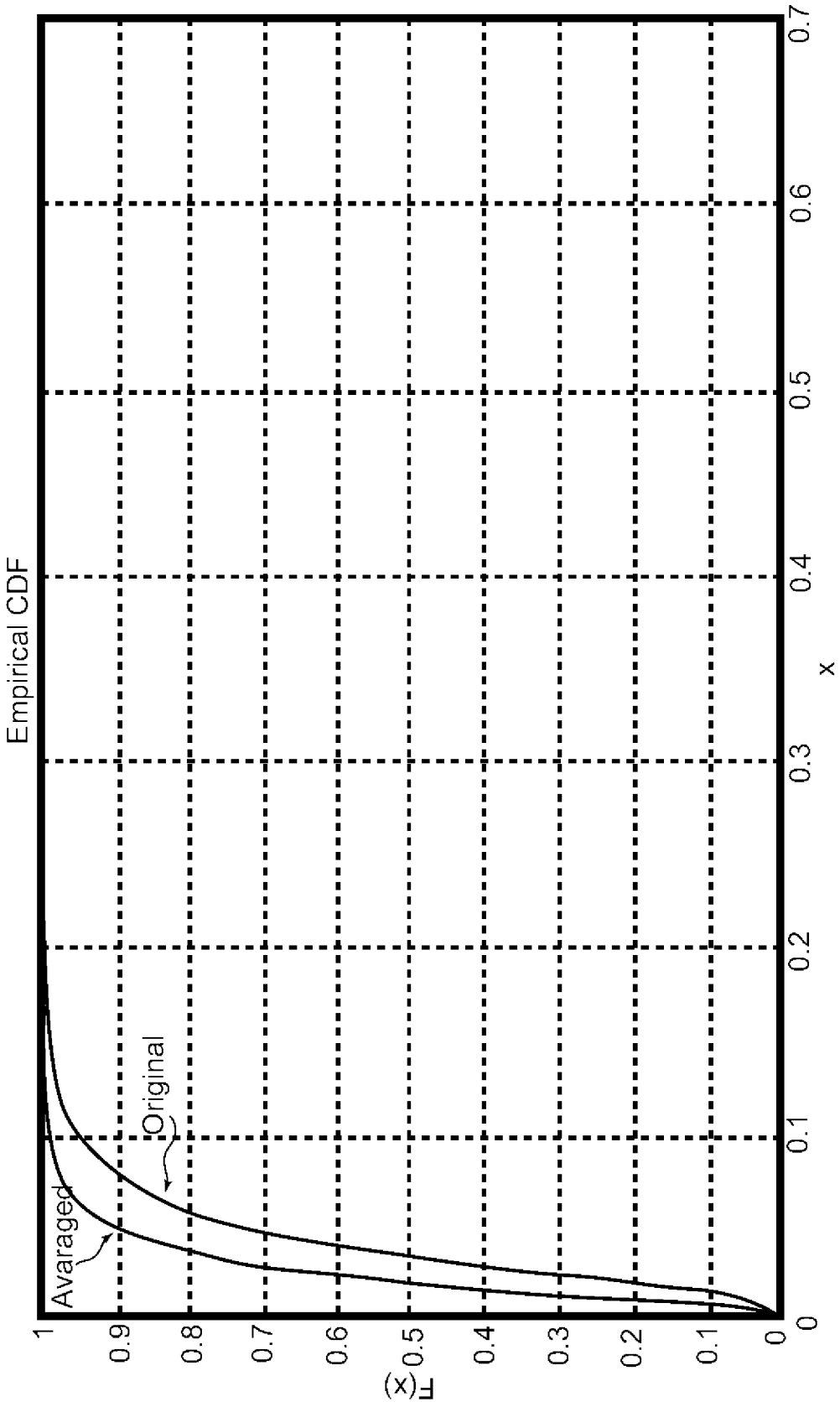
[Fig. 5]


Original
Averaged
Comparison
Difference

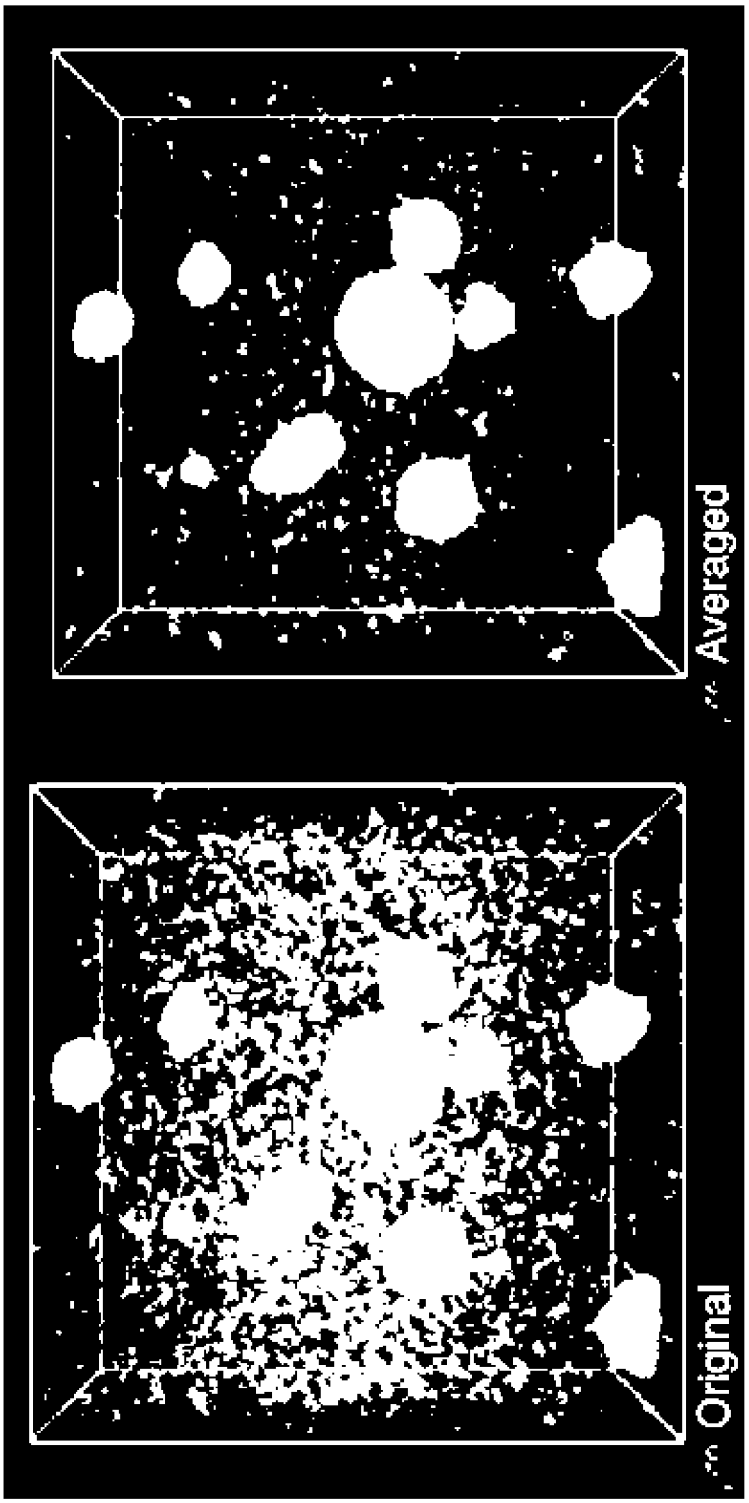
[Fig. 6]


Variation in RMS with Increasing Z
RMS Value
Value of Z (Direction of e Field)
Variation in mean with Increasing Z
Mean Value
Value of Z (Direction of e Field)

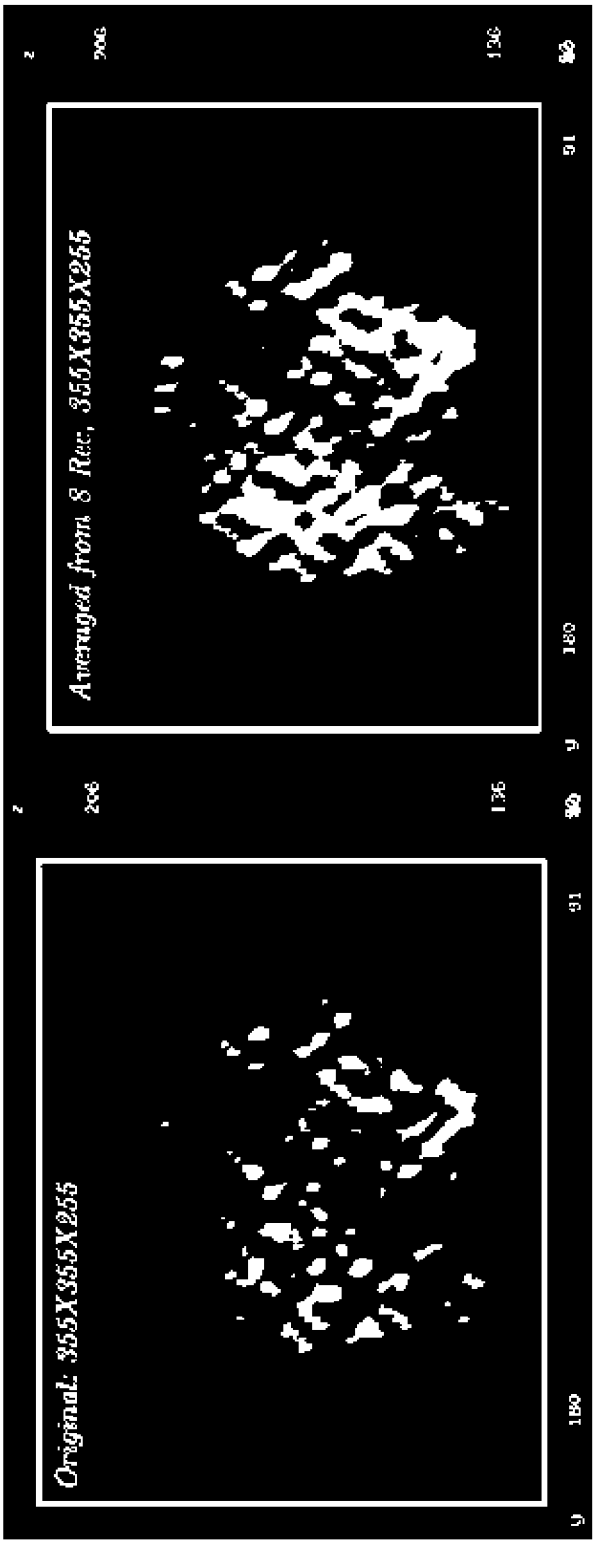
[Fig. 7]


Empirical CDF
F(x)
x
Original
Avaraged
0
0.1
0.2
0.3
0.4
0.5
0.6
0.7
0.8
0.9
1

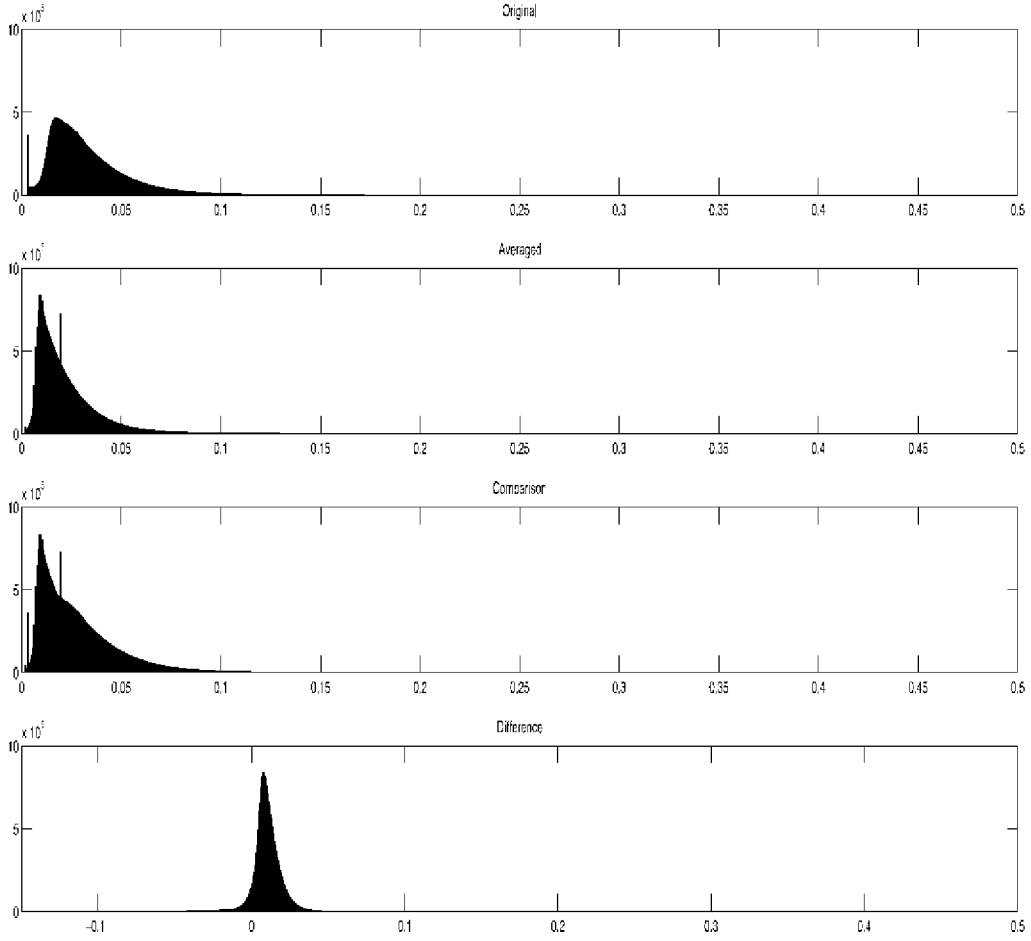
[Fig. 8]



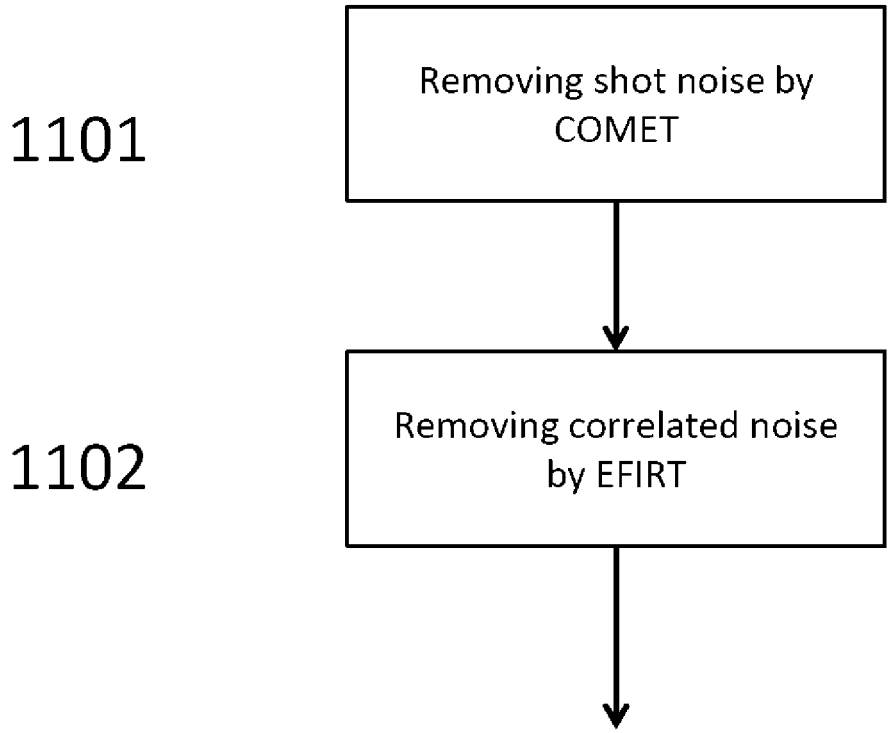
[Fig. 9]


Original: 355X355X255
Averaged from 8 Rec, 355X355X255
z
208
136
y
180
91
0

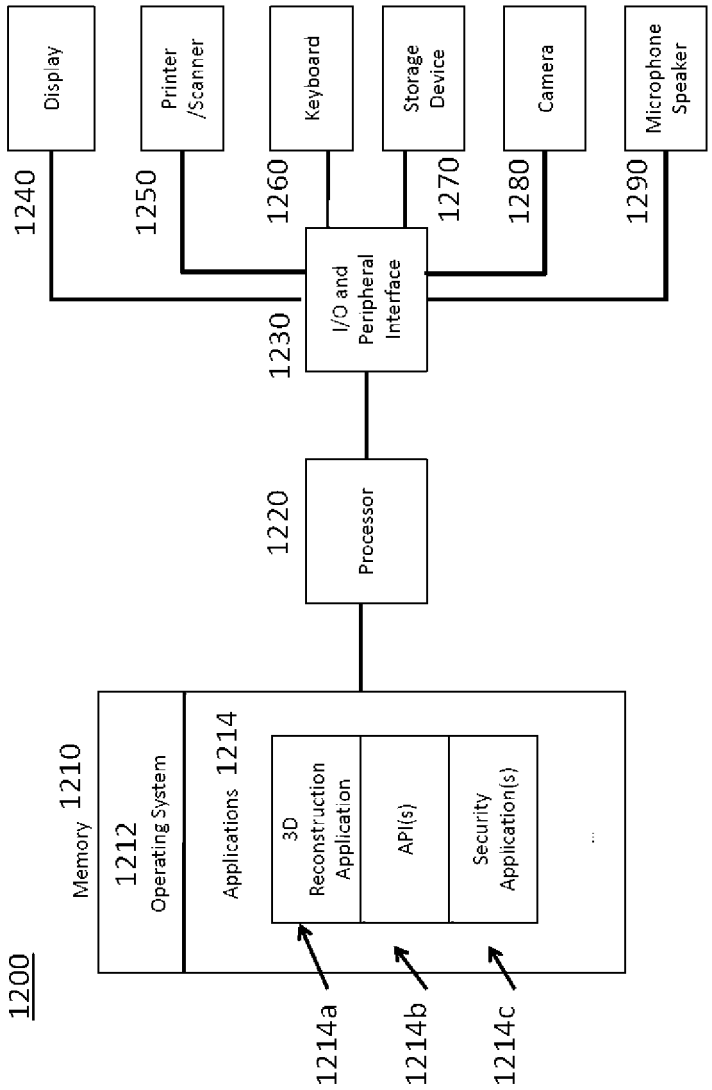
[Fig. 10]



[Fig. 11]


1101
Removing shot noise by COMET
1102
Removing correlated noise by EFIRT

[Fig. 12]


Display
Printer /Scanner
Keyboard
Storage Device
Camera
Microphone Speaker
1240
1250
1260
1270
1280
1290
I/O and Peripheral Interface
1230
Processor
1220
Memory 1210
1212 Operating System
Applications 1214
3D Reconstruction Application
API(s)
Security Application(s)
...
1200
1214a
1214b
1214c