

Abstract

Assistance robot

An assistance robot (1) provided with: a base (10), a moving member (30, 40, 60) configured to move at least up and down with respect to the base (10); a holding member (50) configured to hold a portion of a body of a care receiver (M), the holding member (50) being provided on the moving member (30, 40, 60); and a control section (80) configured to control the moving of the moving member (30, 40, 60) so as to perform standing assistance of the care receiver held by the holding member (50) from a sitting posture to a standing posture and sitting assistance of the care receiver held by the holding member (50) from a standing posture to a sitting posture. The holding member (50) is provided on the moving member (30, 40, 60) so as to be freely inclinable between a lower usage position and an upper retract position.

(Fig.2B)