11. The system of claim 1, wherein said remotely operated attachment device comprises a propulsion system, said propulsion system capable of maneuvering said remotely operated attachment device within the body of water.

12. The system of claim 1, wherein said remotely operated attachment device comprises a weight detection device, said weight detection device capable of detecting said at least one weight on the floor of the body of water.

13. The system of claim 1, wherein said remotely operated attachment device locates said at least one weight using a wireless positioning system.

14. The system of claim ~~10~~13, wherein said wireless positioning system comprises a transmitter associated with said remotely operated attachment device communicating with a receiver associated with said at least one weight.

15. The system of claim ~~11~~13, wherein said wireless positioning system further comprises positioning beacons on the floor of the body of water.

16. The system of claim 1, wherein said at least one weight is shaped to contain and control an air ballast so as to be substantially buoyant.

17. The system of claim 1, wherein said at least one weight is shaped to minimize drag forces during movement between the first and second elevation positions.

18. The system of claim 1, wherein said platform comprises an up-weight management system, said up-weight management system configured to store and prepare a plurality of weights of said at least one weight.

19. The system of claim 18, wherein said up-weight management system is configured to attach and detach said plurality of weights to and from said hoist system.

20. The system of claim 18, wherein said system is configured to sequentially lower each of said plurality of weights from said platform to the floor of the body of water.

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