

ABSTRACT

REINFORCING BAR BINDING ROBOT AND CONTROL METHOD THEREOF

5 A reinforcing bar binding robot according to the present disclosure includes: a
reinforcing bar binding unit configured to bind an intersecting section of at least two reinforcing
bars among a plurality of reinforcing bars; a traveling unit configured to travel on the plurality
of reinforcing bars; a first sensor and a second sensor configured to detect at least one
reinforcing bar among the plurality of reinforcing bars and arranged away from each other along
10 a first direction; and a control device configured to set a target point on the at least one
reinforcing bar and control traveling of the traveling unit based on the target point.