

CONNECTION PATH SELECTION METHOD FOR
CROSS-CONNECT COMMUNICATIONS NETWORKS

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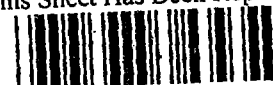
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TECHNICAL FIELD OF THE INVENTION

5 The present invention is concerned generally with
electronics and more specifically with communications
systems. Even more specifically, the invention is
concerned with a method and system that finds an optimal
path through a communications matrix using a set of
matrices or arrays that describe the status of the
communication matrix and include an input stage array, a
10 center stage array, and an output stage array, as well as
arrays representing idle links from the input stage
switches to the center stage switches and the idle links
from the center stage switches to the output stage
switches.

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☒ Claim(s) : paged ...⁶⁶... to paged ...⁷¹...
☒ Drawing(s) : paged ...¹... to paged ...²⁶...
☒ Abstract : paged ...⁷²... to paged ...

BACKGROUND OF THE INVENTION

Digital cross-connect communications network devices, such as the 1631 SX manufactured by Alcatel Network Systems, Inc., are designed to make connections between input gates on input switches and output gates on output switches. Known designs for such cross-connect devices make use of matrices to connect the input gates to the output gates. To limit the physical space and manufacturing costs of the matrices, designers seek to minimize the number of cross-connects in the matrix. This objective becomes more complicated as market demands for communications services increase. In particular, as network devices address larger markets, the devices must service more and more input and output signals. These factors exacerbate the space and cost limitation problems even more for communications matrix devices.

One matrix configuration that uses a minimal number of matrix cross-connects for a given number of input gates and output gates and that provides a potentially optimal solution is known as a "rearrangeable" matrix. For the rearrangeable matrix, the number of center stage switches must equal or exceed the number of input gates on each switch of the matrix. In a rearrangeable matrix, there exists a set of conditions such that, although the device does not use all input gates and all output gates, an attempt to use an idle input gate and an output gate is prohibited because existing connections block the signal flow through the matrix. This may happen, for example, if existing connections already occupy at least one link in every possible path between the input and output gates in question.

In a rearrangeable network, it is always possible to unblock a flow path from an idle input gate to an idle output gate by moving existing connections in the network. The term "rearrangeable," therefore, describes the property that for a given state of a network and any



given idle pair of input and output gates, the existing connections of the matrix may be reassigned to new paths, if necessary, to connect the idle pair.

Existing methods and systems for connecting inputs
5 to outputs in rearrangeable matrices generally use a standard rearrangement technique that determines which cross-connects of the matrix to rearrange to permit a signal to flow. N.C. Paull in "Reswitching of Connection Networks," The Bell System Technical Journal, May, 1962,
10 pp. 833-856, describes this known method for unblocking a rearrangeable matrix. This method (hereinafter referred to as Paull's Method) suffers from a major limitation. Paull's Method requires breaking some of the cross-connects and making some other of the cross-connects to
15 rearrange matrix. This procedure takes time and results in undesirable service delays or interruptions during matrix rearrangement.

It is an object of the present invention, therefore, to provide a method and system that selects an optimal
20 connection path for a rearrangeable communications matrix that permits immediate connection of idle input gates to idle output gates. The present invention achieves this object with a minimal amount of additional circuitry and avoids the service delays and interruptions of known
25 connection path selection methods and systems that cannot immediately select an optimal connection configuration.

It is also an object of the present invention to provide a method and system that finds an optimal connection path or configuration through a communications
30 matrix that uses a set of five matrices, the first of which represents the assignment of input gates of input switches to center stage switches using an input array of values that associate center stage switches to the input stage switches and input gates of the input switches, the
35 second of which represents center stage switch connections by a center stage array of values that



associate center stage switches with input stage switches and output stage switches, the third of which represents output stage connections by an output stage array having values that associate output stages switches with output gates and center stage switches the fourth of which represents the idle links from the input stage switches to the center stage switches by an idle input link array having values that indicate the idle status of the links, and the last of which represents the idle links from the center stage switches to the output stage switches by an idle output link array having values that indicate the idle status of the links, and then using these five arrays the method and system perform a process called "pumping" these arrays to determine an optimal center stage switch having an idle connection between a predetermined input gate and a predetermined output gate and then sets an associated input stage array value and output stage array value to indicate the optimal center stage switch for the connection configuration.

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BRIEF DESCRIPTION OF THE DRAWINGS

Other objects and advantages are apparent and best understood by reference to the following description of illustrative embodiments when read in conjunction with the accompanying drawings, wherein:

FIGURE 1, shows five-stage connecting network (TSSST) with embedded three-stage space matrix (SSS);

FIGURE 2 shows in more detail the three-stage connecting network that may be embedded logically in the five-stage TSSST network of FIGURE 1;

FIGURE 3 is a three-stage connecting network generalized to the $N(m,n,r)$ case;

FIGURE 4 introduces notation for understanding the preferred embodiment;

FIGURE 5 provides a flow chart of the method of the preferred embodiment;

FIGURES 6 through 14 illustrate an example of the sequence generating portion of the preferred embodiments; and

FIGURES 15 through 34 illustrate a simplified space-domain example of the preferred embodiment;

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DETAILED DESCRIPTION OF THE INVENTION

In FIGURE 1, a large matrix configuration is shown that provides for connection and test access for up to 1,024 DS3 ports (or equivalently, 32,678 DS1 ports) for the 1631 SX device. This is a five-stage, Time-Space-Space-Space-Time (TSSST)-division multiplexed connecting matrix network 50. Matrix configuration 50 includes time stage 52 that through connections 54 connects to three center space stage (SSS) designated generally by reference numeral 56. Three center space stage SSS 56 connects through output line 58 to output time stage 60. With this configuration, the network 50 includes a time-domain of time stages 52 and 60 and a space domain of three center space stage 56. FIGURE 1 illustrates logically the relationship between time stages 52 and 60 and the center space stages 56. Input time stage 52 uses 128 time slots per input 62. The time slots may be represented by the connections 64 between I/O shelf inputs 62 to each time slot 66 of matrix 56. Center space stage 56 includes 128 time slots 66, each of which time slot 66 includes a $N(17,16,16)$ matrix. The number 17 of time slot matrix 66 represents the number of center stage switches; the first number 16 represents the number of inputs to each input stage switch, and the second 16 the number of input stage switches. (By symmetry, there are 16 outputs from each output stage switch and 16 output stage switches.) Output time stage 60 uses 128 time slot connections such as connection 68 for each matrix output 70 to an I/O shelf.

In FIGURE 2, center space stage 56 is represented mathematically as a three-stage connecting network cube of matrices 72 for each of which the symbol $N(17,16,16)$ fully describes each of the matrices. Thus, for each $N(17,16,16)$ matrix 72 there are in the example of FIGURE 2, 16 input switches such as input switch 74, for which each receives 16 input gates such as input gate 76. The



total number of input gates 76 make up the I/O shelf-to-time slot connections 64 of FIGURE 1 for each time slot. From each input switch 74 go input switch-center switch connections 78 to the center switches such as center switch 80. In the preferred embodiment, each $N(17,16,16)$ matrix 72 includes 17 center stage switches 80. From each center stage switch 80 go 16 output switch connections 82 to output switches such as output switch 84. Each output switch 84 provides 16 output gates such as output gate 86 that connect to I/O shelves such as I/O shelf 70 of FIGURE 1. The total number of output gates 86 make up the time slot-to-I/O shelf connections 68 of FIGURE 1 for each time slot.

Connections are made between input gate 76 and output gate 86 immediately using the present connection technique. This technique sets up a connection by using a route through input switch 74, center switches 80 and output switches 84 that attempts to use the most used part of a matrix 72 first and the least used part of the matrix 72 last. By using the heavily-loaded part of the matrix where possible in making a given connection, when rearrangement of matrix 72 is necessary, the rearrangement process of the preferred embodiment encounters elements with the smallest number of pre-existing connections. This minimizes the volume of necessary computations for matrix rearrangement.

The preferred embodiment uses a dedicated time slot when rearrangement is necessary in the time domain. For example, referring to FIGURE 1, the 128th time slot may be dedicated as an extra time slot for use during matrix 50 rearrangement. Similarly, in the space domain, rearrangement uses a dedicated or extra center switch. For example, referring to FIGURE 2, center switch 17 may be the dedicated or extra center switch. The present connection technique automatically uses the dedicated or extra element (either the dedicated or extra time slot in



the time domain or the dedicated center stage switch in the space domain) when a rearrangeably blocked condition exists.

FIGURE 3 illustrates that $N(17,16,16)$ matrix 72 of
5 FIGURE 2 may be generalized to matrix 88 for which the expression $N(m,n,r)$ describes the configuration. Following the convention of the $N(17,16,16)$ matrix 16, the generalized notation $N(m,n,r)$ describes generalized matrix 88. In the $N(m,n,r)$ notation, m equals the number
10 of $r \times r$ center stage switches (as well as the number of outputs from each $n \times m$ input stage and the number of inputs to each $m \times n$ output stage switch); n equals the number of inputs to each $n \times m$ input stage switch (as well as the number of outputs from each $m \times n$ output stage
15 switch); and r equals the number of $n \times m$ input stage switches (as well as the number of $m \times n$ output stage switches). Note also that, in matrix 88, m at least equals $n+1$. This limitation on m for a given n assures that there exists at least one extra center stage switch.

20 Referring more particularly to FIGURE 3, generalized matrix 88 has n input gates 90 that connect to input switches, such as input switch 92, having m output connections 94. In generalized matrix 88, there may be,
25 for example, r input switches 92. The input switch-to-center switch connections 94 connect to the $r \times r$ center switches such as center switch 96 where each center switch 96 receives r center switch connections 94 and provides r output connections 98. In the example of
30 FIGURE 3, there are m center switches 96. Each center switch-to-output switch connection 98 from center switches 96 connects to an output switch 100. Each output switch 100 receives m center switch-to-output switch connections 98 and outputs to n output gates such
35 as output gate 102.



Both the $N(17,16,16)$ matrix 72 of FIGURE 2 and the $N(m,n,r)$ matrix 88 of FIGURE 3 are said to be rearrangeable matrices if, respectively, for a given state of the matrix and any given idle pair of input gates 76 or 90 and output gates 86 or 102, the existing connections within the matrices may be reassigned to new paths, if necessary, to allow connecting the respective idle pairs. The matrices are rearrangeable if and only if $m \geq n$. For convenience in notation, in a network described by the expression $N(m,n,r)$, the notation

$\Delta(m,n,r)$ denotes the number of connections that must be rearranged in order to connect an idle pair of input and output gates. Paull's Method derives from the property that $\Delta(n,n,n) \leq n-1$. In other words, for the $N(n,n,n)$ matrix, it is necessary to move at most $n-1$ connections to connect an idle input gate to an idle output gate. A particular application of this property means, for example, that for matrix 72 of FIGURE 2, rearrangement requires at most $n-1=17-1=16$ connection changes in order to connect an idle input gate to an idle output gate.

In the following discussion, FIGURE 4 introduces notation to assist in understanding the preferred embodiment. FIGURE 5 provides a flow chart to illustrate the basic concepts of the immediate connect method and system of the present invention. Thereafter, FIGURES 6 through 14 show an example of the operation of the method and system in the presence of a rearrangeably blocked condition of a matrix 72 of the three center stage space matrix 56. For the purpose of understanding the present invention in yet more detail, the operation of the method and system are described by way of FIGURES 15 through 34 that use a simplified $N(5,4,4)$ rearrangeable matrix having the ability to perform immediate connection in a rearrangeably blocked condition.

In FIGURE 4, notation beneficial for understanding the present invention uses square matrix 110 to represent



connections existing in a space domain matrix such as matrix 88 of FIGURE 3. Square matrix 110 has rows 112 designating input switches (such as input switch 92 of FIGURE 3) and columns 114 representing output switches (such as output switch 100 of FIGURE 3.) The simplified example of FIGURE 4 shows the number of rows 112 and columns 114 equals 8. Note that to correspond exactly to the $N(17,16,16)$ matrix of FIGURE 2, FIGURE 5 could show a matrix having 16 rows representing input switches 74 and 16 columns representing output switches such as output switch 84. Within each square matrix position such as matrix position 116, there are m possible symbols that may appear. These m symbols correspond to the center switches such as center stage switch 96 of FIGURE 3. For example, matrix position 116 may have m possible entries, one for each of the center stage switches 96 appearing in FIGURE 3.

In FIGURE 4, the ordered pair $(3,1)$ denotes matrix position 116, where 3 is the row designation, i.e., row 3 having reference numeral 118, and 1 is the column position, i.e., column 1 having the reference numeral 120. The entry B ($1 \leq B \leq m$) in matrix position $(3,1)$ corresponds to a connection from input switch 3 through intermediate switch B to output switch 1. No entry in a matrix position such as the empty matrix position $(3,2)$ that reference arrow 122 points to indicates the absence of any connection between input switch 3 and output switch 2.

Referring, for example, to FIGURE 3, since there may be only n input gates 90 to each input switch 92 and n output gates 102 from each output switch 100, only n symbols may appear in any row 112 or column 114. Since each input switch 92 has only one connection 94 to each center switch 96, no two symbols in any row 112 may be the same. Similarly, each output switch 100 has only one connection 98 from each center switch 96. No two symbols



in any column 114 may be the same. With the notation of FIGURE 4, a square matrix 110 satisfying these restrictions is said to be "legitimate" since it has only legitimate entries.

5 Note, that a trivial blocking case occurs if all of the input lines to an input switch such as input switch 1 designated by row 1 are already connected. This would correspond to having n symbols (e.g., 16 symbols in the case of FIGURE 2) in row 1. Similarly, if all the output
10 lines to output switch 3, for example, were already connected corresponding to n symbols in column 3 (e.g., 16 symbols for the example of FIGURE 2) the network matrix 72 of FIGURE 2 and 88 of FIGURE 3 is trivially blocked and square matrix 110 will represent this fact.

15 In FIGURE 5, flow chart 140 describes the steps and functions of the preferred embodiment of the present invention. Beginning at start step 142, the method is first to query, as query block 144 indicates, whether there is a pair of ports presented for connection. In
20 the example of FIGURE 3, the step is to query whether there is an idle input gate 90 to connect to an idle output gate 102. If there is such a pair, then flow goes to block 146 to begin time domain connections. If there is not a pair of ports presented for connection, then
25 flow goes to block 148 which is described below. At begin time domain step 146, flow goes to block 150 where the method selects the lowest numbered time slot available for connection. Then, at block 152 space domain operations begin for selecting the lowest numbered
30 center stage input switch available for connection at step 154. Having selected the lowest numbered center stage for connection, the connections are made at block 156 and square matrix 110 or a similar status table designating connections is updated at block 158.

35 At block 160, a query of whether space rearrangement is required takes place. If so, then flow goes to block



162 where the step is to select two center stage switches for rearrangement. Next, at block 164, the step is to find the connections to be rearranged and, from the connections, the query at block 166 is of which path
5 requires the least number of rearrangements. If the path X-A requires the least number of rearrangements, then program flow takes path 168. If X-B requires the least number of rearrangements, then program flow takes path 170. Regardless of which path program flow takes, at
10 step 172 connections are rearranged, one at a time, using a "hitless roll." The discussion below defines the term "hitless roll." And flow returns to step 174 to end space domain operations. Note that if no space rearrangement was necessary, then flow from query block
15 160 goes directly to end space domain step at block 174.

At query 176, the question is whether time rearrangement is required. If so, then flow goes to step 178 at which point the method is to select two time slots for rearrangement. Then, at block 180, the step is to
20 find connections to be arranged. At block 182, a query occurs of which path requires the least number of rearrangements. If the X-A path requires the least number of rearrangements, flow goes along path 184. On the other hand, if the X-B path requires the least number
25 of rearrangements, then flow follows path 186. The next step, regardless of whether program flow takes path 184 or 186, is to rearrange connections one-at-a-time, again using a hitless roll in the time domain at step 188. Program flow then goes to step 190 to end time-domain
30 operations. Note that if query block 176 determines that no time rearrangement was required, flow proceeds directly to end time domain block 190.

From end time domain block 190, flow goes to query 148 where the method determines whether a pair of ports
35 is presented for disconnect. If not, then flow returns to query block 144 to proceed as previously described.



If a pair of ports is presented for disconnect, at this point the method is to remove connections as requested per block 192 and then update data tables reflecting the connections for the matrix at step 194.

5 At query 196, the method determines whether a "pack connections after a disconnect" function is enabled. If so, then flow goes to query 198 to examine whether a rearrangement is in progress. If so, then flow will loop via path 200 until rearrangement is no longer in process.

10 Although FIGURE 5 shows disconnect as occurring subsequent to completing any necessary rearrangement, the present method and system may process a disconnect request in parallel with rearrangement. Therefore, if the system of the present invention seeks to direct

15 connections to the most used part of matrix first so as to pack calls after a disconnect, the rearrangement-in-progress query of block 198, prevents attempting to pack during rearrangement.

 If a rearrangement is not in progress, from query

20 block 198, the next step is to determine the connections to the packed in the space at step 202. The next step of flow chart 140, then, is to pack connections in the space domain using a hitless roll at block 204. And then, at block 206, the step is to determine the

25 connections to be packed in time, after which the connections are packed at block 206 in time using an automatically hitless roll. Program flow then returns to point 210 to continue the previously described operations of flow chart 140.

30 The following discussion describes how steps of flow chart 140 of FIGURE 5 relate to the square matrix 110 of FIGURE 4. Recall that after updating square matrix 110 or similar table at step 158, the method of the preferred embodiment detects whether a rearrangeably blocked

35 condition exists. Thus, when the dedicated element (either a time slot in the time domain or center stage



switch in the space domain) in a matrix connection configuration is used to make an immediate connection between an idle input gate and an idle output gate, the existence of a rearrangeable blocking condition is automatically detected.

Steps 162 and 178 execute Paull's Method to find the path requiring the fewest rearrangements. Specifically, with the blocked cell denoted (r_1, c_1) such as cell 121 of FIGURE 4, the method tests to find all symbol pairs (A, B) such that if A is in row 1, but not in column 1, and B is in column 1, but not in row 1. For given pairs of symbols, say (A, B) , there are two possible rearrangement sequences, one of which will be shorter. Making this determination is part of step 16 in the space domain and step 182 in the time domain.

The sequence "X-A" denotes a sequence that starts with an immediate connection through the dedicated element (e.g., center stage switch 17 of FIGURE 2 for the space domain and the time slot 128 in FIGURE 1 for the time domain) and ends with the blocked cell being assigned to element A. The sequence begins, for example, by starting with the blocked cell (r_1, c_1) at 121 of FIGURE 4). Since there is no B in row r_1 , the search for an A in r_1 takes place. There must be an A in row r_1 , otherwise the matrix is not blocked. Once the A in row r_1 is found, it is circled or tagged.

In general, then, suppose that the circled A is in (r_j, c_k) , $1 \leq j, k \leq 8$. Then, a search for a B in column c_k takes place. If there is no B in column c_k , the sequence ends and then the next step is to find connections to be rearranged at block 164 or 180, as appropriate. If a B appears in column c_k , the next step is to circle the B and continue. If the circled B is in the (r_k, c_j) position, then a search for an A in row r_k takes place. The sequence X-A continues to alternate between circling B's in columns in A's in rows, until there exists a



column with no B to circle or a row with no A to circle. Note that not all A's and all B's get circled, only those encountered in the above search.

Generating the X-B sequence occurs in similar fashion, as follows. Starting with the blocked cell
5 (r_1, c_1) 121 of FIGURE 4, for example, there is no A in column 1, so the search begins for a B in column c_1 . There must be a B in column c_1 , otherwise the matrix would not be blocked. Then, procedure is to circle that
10 B. Since the circled B is in position (r_3, c_1) , the search for an A in row r_3 begins. If there is no A in r_3 , then this sequence ends and program flow continues to step 164 or 180, as appropriate for the space or time domain. Otherwise, the procedure is to circle the A and continue.
15 In this example, the circled A is in position (r_3, c_3) , then the search begins for a B in column c_3 . If there is no B in column c_3 , then the sequence ends. Otherwise, the sequence is to circle the B and continue. This procedure continues to alternate between circling B's in
20 columns and A's in rows until either a column with no B to circle or a row with no A to circle is found. Note, not all A's nor all B's get circled, only those encountered in the above search.

For a given pair of symbols (A,B), the next step is
25 to choose the path generated by the sequence (either the X-A sequence or the X-B sequence) that contains the least number of circled symbols (i.e., A's or B's). For all such pairs of symbols, the step is to choose the pair (A,B) that contains the least number of circled symbols
30 (either A's or B's). This sequence determines the minimum number of rearrangements necessary to establish a path from the input to the output of the rearrangeable matrix.

Rather than completely generating all the X-A and
35 X-B sequences, the preferred embodiment generates the shortest sequence. This is accomplished in block 164 in



the space domain and block 180 in the time domain using a technique of the preferred embodiment that shall hereinafter be called a flooding algorithm. The flooding algorithm starts by finding the first element of the X-A sequence. If the X-A sequence is not ended, the first element of the X-B sequence is found. Then, if the X-B sequence is not ended, the next element of the X-A sequence is found. This process continues until the shorter of the two sequences is generated. At the time that the shorter of the two sequences is generated, the search terminates.

The point at which flooding algorithm terminates determines the path of the minimum number of rearrangements as indicated in block 166 in the space domain and block 182 in the time domain.

In step 172 for the space domain and step 188 for the time domain, rearrangements take place using a hitless roll. The sequence of circled symbols, either A's or B's, that the above steps determined are then changed to clear the blocked cell using the appropriate X-A or X-B roll depending on which yields the minimum number of rearrangements.

The following Table 1 and accompanying text describe the steps of making the connections to yield rearrangement of the center stage switches when X-A results in the minimum number of connection rearrangements:



TABLE 1	
STEP	ACTION
1	$X-(r_1, c_1)$
2	$\textcircled{B}-\textcircled{B}, X$
3	$\textcircled{B}, X-X$
4	$\textcircled{A}-\textcircled{A}, B$
5	$\textcircled{A}, B-B$
6	$X-X, A$
7	$X, A-A$

If the X-A sequence yields the minimum number of rearrangements, then, referring to square matrix 110 of FIGURE 4, step 172 or 188 of FIGURE 5, as appropriate, the method is to put an "X" in the (r_1, c_1) position indicating the connection was made through the extra center stage switch, (TABLE 1, Step 1 indicates this action). Then for the circled B's, the roll first adds X's (Step 2) and then removes the circled B's (Step 3). Next, for the circled A's, the roll first adds the B's (Step 4) and then removes the circled A's (Step 5). Then, for X's appearing in the matrix, A's are first added (Step 6) and then the X's are removed (Step 7).

The following Table 2 and accompanying text describe the steps of making the connection to yield rearrangement of the center stage switches when X-B results in the minimum number of connection rearrangements:

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TABLE 2	
STEP	ACTION
1	$X-(r_1, c_1)$
2	$\textcircled{A}-\textcircled{A}, X$
3	$\textcircled{A}, X-X$
4	$\textcircled{B}-\textcircled{B}, A$
5	$\textcircled{B}, A-A$
6	$X-X, B$
7	$X, B-B$

The X-B roll occurs in similar fashion to that of the X-A roll. For example, the first step is to put an X in the position (r_1, c_1) indicating the connection was made through the extra center stage (TABLE 2, Step 1). For the circled A's, the roll first adds X's (Step 2) and then removes the circled A's (Step 3). Next, for the circled B's, the roll adds A's (Step 4) and then removes the circled B's (Step 5). Then, for the X's, the roll adds the B's (Step 6) and finally removes the X's (Step 7).

Rearrangement is performed as necessary using a "head-end-bridge" and a "receive-end-switch" to effect a hitless roll (including the initial connection placed in the designated or extra element) to the lower numbered elements of the matrix. The terms head-end-bridge and receive-end-switch are defined and explained illustratively in connection with the example of FIGURES 15 through 34 below. These steps leave the extra element



clear and ready for the next immediate connection in a rearrangeably blocked condition.

Although it is believed that the present specification and drawings fully and accurately describe the system and provide sufficient information so that anyone skilled in the art may practice the inventive concept, "Unpublished Appendix A" is provided herewith to remain unprinted. Unpublished Appendix A includes a listing of the working source code to enable a computer to operate and perform the immediate connect method of the present method and system.

OPERATION

Having explained generally the processes of the preferred embodiment, the following illustrative example shows how the preferred embodiment provides an immediate connect in the presence of a rearrangeably blocked condition in the space domain. The time domain method becomes obvious upon understanding implementation of the space domain method.

FIGURES 6 through 14 illustrate an example of the immediate connect method of the preferred embodiment. In the square matrix 110 of FIGURE 6, cell (1,1) is marked as blocked because the present connection algorithm detected that the dedicated center stage switch is the only center stage switch having both an idle link to input switch 1 and an idle link to output switch 1.

In response to this condition, the connection algorithm in effect puts an X at (r_1, c_1) to make the connection, as FIGURE 6 shows. The use of the notation "X" herein denotes the use of the dedicated or extra center stage switch in a rearrangeably blocked condition. When the designated dedicated center stage switch of the large matrix configuration is used by the connection



algorithm, a rearrangeable blocking condition is automatically detected.

Since the connection pair (1,1) is rearrangeably blocked, in order for a connection to be possible, there must exist an idle link between input switch 1 and some center stage switch, say A. Furthermore, there must exist an idle link between output switch 1 and some center stage switch, say B. The pair (A,B) is one pair of center stage switches to be considered for rearrangement. In this example, the pair (A,B) is the only pair of center stage switches that meets the above criteria. Since the pair (A,B) constitutes the entire set of pairs to be searched, (A,B) is the pair that requires the fewest rearrangements.

FIGURE 7, shows the X→A sequence and FIGURE 8 shows the X→B sequence of the immediate connect algorithm of the preferred embodiment. Together, FIGURES 7 and 8 show the operation of the flooding algorithm of the preferred embodiment. For example, the first step starts off in FIGURE 7 at row r_1 and finds an A in (r_1, c_2) which is circled. FIGURE 8 shows the second step of the flooding algorithm which uses the X→B sequence and starts off in column c_1 to find a circled B in (r_3, c_1) . Then, the third step takes place back in FIGURE 7 wherein column c_2 is examined for a B. This is found at position (r_2, c_2) and circled. Since there are no A's row r_2 , this X→A sequence is complete. The two symbols in FIGURE 7 indicate two rearrangements are required.

Although the flooding algorithm of the present method ends at the third step, if it were to continue, in FIGURE 8 row r_3 would be examined for an A, which would be found in position (r_3, c_3) . This procedure would continue to alternate between circling B's in columns and A's in rows until either a column with no B to circle or a row with no A to circle. The four circled symbols in



FIGURE 8, therefore, indicate four rearrangements are necessary in the example.

5 Since the X-A sequence requires only two rearrangements, and the X-B requires four rearrangements, the preferred embodiment chooses the X-A sequence for the pair (A,B). Since the pair (A,B) is the only pair of center stage switches being considered, the X-A sequence yields the minimum number of rearrangements.

10 The next step is to execute the rearrangements using the previously mentioned "hitless roll." Since the X-A sequence yields the minimum number of rearrangements, the preferred embodiment uses the X-A roll in this example. The hitless roll includes the initial connection placed in the dedicated center stage switch. This roll takes
15 place by first performing the necessary rearrangement using a head-end-bridge and receive-end-switch.

FIGURES 9 through 14 illustrate executing the X-A hitless roll. The method changes the sequence of previously circled symbols A and B to clear the blocked
20 cell as follows:

For the circled B's add X's as FIGURE 9 shows. In this example, this step corresponds to setting up a head-end-bridge through the center stage switch at the extra switch X for the existing connection from input switch 2
25 through center stage switch B and a receive-end-switch through center switch X for the existing connection and from center stage B to output stage 2.

30 The next step is to remove the circled B's as FIGURE 10 shows. In this example, when a connection exists through center stage switch X, and output switch 2 receives a good signal, the next step is to take down the connection from input switch 2 through center stage switch B to output switch 2.

35 Then, as FIGURE 11 shows for the circled A's add B's. In this example, this step corresponds to setting up a head-end-bridge through the center stage switch B



for the existing connection from input switch 1 through center stage switch A and a receive-end-switch through center stage switch B for the existing connection from center stage switch A to output switch 2. Then, as
5 FIGURE 12 shows, the circled A's are removed. In this example, when a connection exists through center stage switch B and output switch 2 receives a good signal, the next step is to take down the connection from input switch 2 through center stage switch A to output switch
10 2.

Then, the next step is to add A's to the positions containing the X's, as FIGURE 13 shows. In this example, this corresponds to setting up a head-end-bridge through center stage switch A for both the connection from input
15 switch 2 through center switch X to output switch 2 and the immediate connection from input switch 1 through center switch X to output switch 1.

The final step is to remove the X's as FIGURE 14 illustrates. In this example, when each connection
20 through center stage switch A exists and the corresponding output switch receives a good signal, the corresponding connection from the input switch through center switch X to the corresponding output switch may be taken down. Note that the extra center stage switch X is
25 left idle, since all connections are rolled off the extra center stage switch X to the appropriate center stage switch.

Having described in detail the operation of the preferred method and system, the following discussion
30 illustrates the connection path selection method and system of the preferred embodiment. For simplicity in describing this aspect of the present invention, the example considers connections in a further reduced $N(5,4,4)$ space matrix 220 of FIGURE 15.

35 FIGURE 15 illustrates the state of a simplified $N(5,4,4)$ space matrix 220 after initialization. Note



that the fifth center stage switch 224 is labeled X to indicate that it is the dedicated or extra center stage switch. As legend 226 shows, short-dashed lines 228 indicate an idle link, continuous line 230 indicates a
5 busy link, and long-dashed line 232 shows a switch connection. Since there are no inputs connected to any outputs in FIGURE 15, there are no input stage, center stage, or output stage switch connections and all of the links between the switches are idle.

10 With the simplified $N(5,4,4)$ space matrix in mind, it is possible to detail how to implement computer software to accomplish the connection path selection and other purposes of the present invention. Note, however, that the size of space matrix 220 does not limit the
15 utility or applicability of the software implementation. To assist in understanding the software implementation, the following discussion introduces data definitions and notations relevant in manipulating the matrices 222, 234, 236, 238, and 240 of FIGURE 16. Note, also, that for
20 ease in understanding connections, FIGURE 15 uses the same reference numerals for input gates 90, input stage switches 92, etc. appearing in the generalized $N(m,n,r)$ matrix of FIGURE 3. The following data definitions are useful in the description of the present connection
25 method and system.

In a software implementation, input/output gate or line conversions occur. For example, a connection may be requested in the form of $IL-m-OL-n$. In other words,
input line m to output line n . The input line number is
30 converted to an input switch stage number i and an input number for that input switch stage j such that $IL-m-I(i,j)$. Similarly, the output line number is converted to an output switch stage number k and an
output number for that output switch stage l such that
35 $OL-n-O(k,l)$.



More formally, $I(i,j)$ is determined from $IL-m$ and $O(k,l)$ is determined from $OL-n$ by:

$$i = 1 + \text{Quot}_N(m-1)$$

$$j = 1 + \text{Rem}_N(m-1)$$

$$k = 1 + \text{Quot}_N(n-1)$$

$$l = 1 + \text{Rem}_N(n-1)$$

where N is the number of first (input) stage switches, which is equal to the number of third (output) stage switches;

Quot_N is the integer quotient of the argument divided by N ; and

Rem_N is the integer remainder after the argument has been divided by N .

The following statements and data definitions may be understood with reference to FIGURES 15 and 16 to provide computer-generated matrices to accomplish the purposes of the present invention.

Data Definition:	<code>space_in_mat(in_stage,in_num)</code>
------------------	--

In FIGURE 16, the space input matrix 222 for the FIGURE 15 $N(5,4,4)$ example is a 4×4 matrix which represents the connection of the input stage switches in the SSS such as switch 92. Each row of space input matrix 222 corresponds to one of the input stage switches 92. The columns of space input matrix 222 correspond to the input gates 90 to each of the first stage switches. The entries in the space input matrix correspond to the outputs of the first stage switches such as outputs 94. Since the output of each of the input stage switches is connected to the center stage switch of the same number, the entries in the space input matrix may be viewed as



the center stage switch to which that particular input stage switch (row), input (column) is connected.

As a result, the statement

5

Statement:	<code>space_in_mat(i,j) = c</code>
------------	------------------------------------

causes space input matrix 222 to indicate a connection from the j^{th} input of the i^{th} first stage switch to center stage switch c .

10

The entries in space input matrix 222 range from 0 to X using the simplified example of FIGURE 15. A 0 indicates that no connection has been assigned. Entries of 1 through 4 are normal connections. A numerical entry in matrix 222 of 5, in this example corresponds to the entry of "X" in FIGURE 6 and indicates that the extra center stage switch 224 has been assigned and the rearrangement process has been invoked.

15

Data Definition:	<code>space_cnt_mat[cnt_stage,in_stage]</code>
------------------	--

20

Space center matrix 234 is a 5x4 matrix which represents the connection map of the center switches in the space domain such as center stage switches 96. Each row of the space center matrix corresponds to one of the center stage switches 96. The columns of the space center matrix correspond to the inputs to each of the center stage switches such as inputs 94. The entries in the space center matrix correspond to the outputs of the center stage switches such as output 98. Since the output of each of the center stage switches 96 connects to the output stage switch of the same number, the entries in the space center matrix 234 may be viewed as the output stage switch to which that particular center stage switch (row), input column connects.

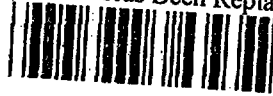
25

30

As a result, the statement

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Statement:

 $\text{space_cnt_mat}(c, j) = k$

causes space center matrix 234 to indicate a connection from the j^{th} input of the center stage switch "c" to the k^{th} output stage switch. The entries in space center matrix 234 range from 0 to 4. A 0 indicates that no connection has been assigned. Entries of 1 through 4 are normal connections. A zero entry in x^{th} row (i.e., the 5th row in this example) indicates that the extra center stage switch 224 has been assigned and the rearrangement process has been invoked.

Data Definition:

 $\text{space_out_mat}[\text{out_stage}, \text{out_num}]$

Space output matrix 236 is a 4x4 matrix which represents the connection map of the output stage of the space matrix in the space domain. Each row of space output matrix 236 corresponds to one of the output switches such as output switch 100. The columns of space output matrix 236 correspond to the output from each of the output switches such as output gates 102. The entries in space output matrix 236 correspond to the input to which that output connects such as connections 98. Since the input of each output switch connects to the center stage switch of the same number, the entries in space output matrix 236 may be viewed as the center stage switch to which that particular output switch 100 (row), output gate 102 (column) connects.

As a result, the statement

Statement:

 $\text{space_out_mat}(k, l) = c$

causes space output matrix 236 to indicate a connection from center stage switch "c" to the l^{th} output of the k^{th}



output stage switch. The entries in space output matrix range 236 from 0 to X. A 0 indicates that no connection has been assigned. Entries of 1 through 4 are normal connections. An entry of X (i.e., 5 in this example) indicates that extra center stage switch 224 as been assigned and the rearrangement process has been invoked.

Continuing with reference to FIGURES 15 and 16, the following discussion details how to implement the preferred embodiment to represent an idle link between an input gate and an output gate. In normal operation, the present connection method attempts to make a given connection through the lowest-numbered center stage switch. In order to make a connection from a given input stage switch, such as input switch 92, to a given output stage switch such as output switch 100, there must exist a certain center stage switch, such as center switch 96, with the property that there is an idle input link from input switch 92 to center switch 96 and an idle output link from center switch 96 to output switch 100.

The present method and system track idle input links and idle output links by using two different bit map arrays (one for input links and one for output links). Each bit array map has a separate row for each row of the space center matrices. The method uses a group of primitives to operate upon the bit maps to effect the connect and disconnect operations. The primitives, in turn, invoke the rearrangement process when required.

Data Definition:	space_in_link[in_stage,cnt_stage]
------------------	-----------------------------------

For the example of FIGURES 15 and 16, space input idle link bit map 238 is a 4x5 bit array that represents the idle input links 94 between the input switches 92 and the center switches 96 in the space domain. Each row of space input idle link bit map 238 corresponds to one of the input stage switches 92. The entries in space input



idle link bit map 238 for a given row (input stage) and column (center stage) indicate the idle state of the input link 94 between that input stage and center stage. An entry of 1 indicates that the input link is idle and available for assignment. A 0 value indicates that the input link is in use and is not available for assignment. A 0 entry in column X indicates that the extra center stage switch 234 is in use and the rearrangement method is in progress.

Data Definition:	space_out_link[out_stage,cnt_stage]
------------------	-------------------------------------

Space output idle link bit map 240 is a 4x5 bit array that represents the idle output links between the output and the center switches 96 in the space domain. Each row of space output idle link bit map 240 corresponds to one of the output stage switches 100. The entries in the space output idle link bit map 240 for a given row (output switch) and column (center switch) indicate the idle state of the output link 98 between that output switch and center switch. An entry of 1 indicates that the output link is idle and available for assignment. A 0 value indicates that the output links is in use and is not available for assignment. A 0 entry in column X indicates that the extra center stage switch 224 is in use and the rearrangement method is in progress.

Having described the maps for representation idle links, the following describes primitive operations useful to manipulate the space idle link bit maps 238 and 240 for connect and disconnect operations.

Primitive:	init_links()
------------	--------------

The initialize idle link bit maps primitive (used only for start-up operations) creates both space input

idle link bit map 238 and space output idle link bit map 240 for the preferred embodiment. All entries in the idle link bit maps are initialized to 1, indicating that all links are idle.

5

Primitive:	set_link(i/o, j, k)
------------	---------------------

This primitive sets the k^{th} bit of the j^{th} row of the bit map specified by the "i/o" parameter to 1. If the bit map contains n elements and the value of j exceeds n, then the computer returns an error flag. Otherwise, the k^{th} element is set to 1.

10

Primitive:	clear_link (i/o, j, k)
------------	------------------------

15

This primitive clears (resets) the k^{th} bit of the j^{th} row of the bit map specified by the i/o parameter to 0. If the bit map contains n elements and the value of j exceeds n then the computer returns an error flag. Otherwise, the k^{th} element is set to 0.

20

Primitive:	pump_link(space_in_link[i],space_out_link[k])
------------	---

25

The preferred method and system connect between an input switch stage i and an output switch stage k using the lowest numbered center stage switch available. This is accomplished by a process that hereinafter shall be called "pumping" space_n_link[i] and space_out_link[k]. That is, space_in_link[i] is logically "ANDed" with space_out_link[k] to determine c, the lowest numbered center stage switch with both an idle link to input stage i and an idle link to output stage k. The index of the first non-zero entry in the result of the logical AND is

30



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PATENT APPLICATION

c, the lowest numbered center stage switch with both an idle link to input stage i and an idle link to output stage k. The two links to c are then marked as "busy" in space_in_link[i] and space_out_link[k] and the center stage number c is returned. Table 3 illustrates an embodiment of this primitive macro.

TABLE 3

PUMP LIST MACRO FLOW CHART

```

10 pump_link(space_in_link[1], space_out_link[k]
    int c, i, k, x[xtra_stage];
    {
    int j;
    x = space_in_link[i] && space_out_link[k];
    for (j = 1; j <= x[xtra_stage]; j++)
15 {
    if (X(j) == 1)
    {
    c = j;
    break;
20 }
    }
    clear_link(space_in_line, i, c);
    clear_link(space_out_link, k, c);
    if (c == x[xtra_stage])
25 {
    rearrange = 1;
    }
    return(c);
30 {

```

FIGURE 16 illustrates the implementation data matrices after initialization. The corresponding entries in the connection path selection matrices space_in_mat 222, space_cnt_mat 234, and space_out_mat 236, for the

example, are illustrated in FIGURE 16. Since there are no switch connections, all of the entries are 0. The contents of the space_in_link 238 and space_out_link 240 bit maps are as shown at initialization. Note that each input stage switch and each output stage switch has a 1 element for each idle center stage switch. In this example, after initialization, all five center stage switches are marked as "idle".

FIGURE 17 shows the implementation data after the first connection. Suppose the first connection requested is to connect input line 1 to output line 1, or more simply, IL-1-OL-1. The first step is to convert the input line number to an input switch stage number and an input number for that input switch stage. In this case, IL-1-I(1,1). Similarly, the output line number is converted to an output switch stage number and an output number for that output switch stage. In this case, OL-1-O(1,1). So, we are going to make a connection between input stage 1 and output stage 1.

The present method and system attempt to make the connection between input stage 1 and output stage 1 by using the lowest numbered center stage switch available, which in this case is center stage 1. This is accomplished by using the pump_list macro of TABLE 3 to compare space_in_link[1] with space_out_link[1] in FIGURE 16 and set the idle connects of the lowest center stage number common to both bit maps to "0". Then, the space_in_mat(i,j) and the space_out_mat(k,l) are set equal to that center stage number, and the space_cnt_mat(c,j) is set equal to k. The corresponding space matrix data entries are shown in FIGURE 17 and the resultant state of the space matrix 220 is shown in FIGURE 18.

The following statements accomplish this process:

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TABLE 4	
CONNECT STATEMENTS	
5	<pre> x = pump_list(space_in_link[i], space_out_link[k]); space_in_mat(i,j) = c; space_cnt_mat(c,i) = k; space_out_mat(k,l) = c; where, in this case, i=j=k=l=m=c-1. </pre>

10 Assume the procedure of adding connections continues until n^2-2 connections have been made (presumably without rearrangement) with the resultant space matrix shown in FIGURE 19 and connection path selection matrix data shown in FIGURE 20.

15 Then, the request to connect IL-13 to OL-7 is received. The request to connect IL-13 to OL-7 converts to a request connect I(4,1)-O(2,3). The present method and system attempt to make the connection between input stage 4 and output stage 2 by using the lowest numbered center stage switch available, which in this case, is
 20 center stage switch number 4, as illustrated in FIGURE 20. The pump_list macro of Table 1 compares space_in_link[4] with space_out_link[2], determines the lowest center stage number common to both bit maps, and sets the
 25 idle status to "busy" in both bit maps. Then the space_in_mat(i,j) and the space_out_mat(k,l) are set equal to that center stage number and the space_cnt_mat(c,j) is set equal to k.

30 The corresponding space matrix data entries are shown in FIGURE 21 and the resultant state of the space matrix is shown in FIGURE 22. This process is accomplished using the following statements from the connect routine as before:

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TABLE 5

CONNECT STATEMENTS

```

x = pump_list(space_in_link[i], space_out_link[k]);
    space_in_mat(i,j) = c;
5    space_cnt_mat(c,i) = k;
    space_out_mat(k,l) = c;
where in this case, i=4 j=1 k=2 l=3 m=13 n = 7 and c=4.

```

10 Suppose the next request is to disconnect IL-13 from
OL-7 (which takes down the connection that was just
made). The request to disconnect IL-13 from OL-7
converts to a request to disconnect I(4,1)-O(2,3). The
put_back macro accomplishes the disconnect by breaking
15 the connection between input stage 4 and output stage 2
and putting the freed-up center stage switch, number 4,
back on the input/output stacks for subsequent use. More
specifically, the put_back macro determines the freed-up
center stage switch number and puts it back in the proper
positions on both of the ordered-linked lists in
20 space_in_link[4] and space_out_link[2]. Then, the
space_in_mat(i,j), the space_cnt_mat(c,j), and the
space_out_mat(k,l) are set equal to 0.

25 The corresponding space matrix data entries are
shown in FIGURE 23 and the resultant state of the space
matrix is same as shown before FIGURE 18. The disconnect
is accomplished using the following statements from the
put_back macro:

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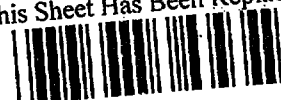


TABLE 6

DISCONNECT STATEMENTS

```

c = space_in_mat (i,j);
    set_link(space_in_link, i, c);
    set_link(space_out_link, k, c);
    space_in_mat(i,j) = 0;
    space_cnt_mat(c,i) = 0;
    space_out_mat(k,l) = 0;
where in this case, i=4 j=1 k=2 l=3 m=13, n=7, and c=4.

```

Next, suppose we receive a request to connect IL-13 to OL-12. The request to connect IL-13 to OL-12 converts to a request to connect I(4,1)~O(3,4). The present method and system attempt to make the connection between input stage 4 and output stage 3 by using the lowest numbered center stage switch available. In this case, the X^{th} or extra center stage switch 224 is the lowest number available center stage switch, as illustrated in FIGURE 25.

As before, the pump_list macro accomplishes this by comparing space_in_stack[4] with space_out_stack[3] in FIGURE 23, determining the lowest center stage number common to both bit maps (which in this case is center stage switch "X"), and setting the idle status to "busy" in both bit maps. Then, the space_n_mat(i,j) and the space_out_mat(k,l) are set equal to that center stage number and the space_cnt_mat(c,j) is set equal to k. An entry of 5 indicates that the X^{th} center stage switch has been assigned and the rearrangement process is automatically invoked. The corresponding space matrix data entries during rearrangement are shown in FIGURE 24 and the resultant state of the space matrix during arrangement is shown in FIGURE 25.



The following immediate connect statements accomplish this:

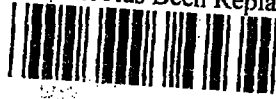
TABLE 7
IMMEDIATE CONNECT STATEMENTS
<pre> x = pump_list(space_in_stack[i],space_out_stack[k]); space_in_mat(i,j) = c; space_cnt_mat(c,i) = k; space_out_mat(k,l) = c; where in this case, i=4 j=1 k=3 l=4 m=13, n=12, and c=5. </pre>

As a result of the rearrangement algorithm the connection I(4,3)→O(2,1) that FIGURE 26 shows is "rolled" from center stage switch number 2 onto center stage switch number 4. This roll is performed hitlessly by creating a head-end-bridge at input stage switch 4 and a receive-end-switch at output stage switch 2 as shown in FIGURE 27. When the correct path is received at output stage switch 2 from center stage switch 4, the original connection through center stage switch 2 is dropped as shown in FIGURE 28 and the space matrix data is updated as shown in FIGURE 29.

The previous roll now allows the immediate connection, I(4,1)→O(3,4), as FIGURE 31 shows, which is on center stage switch X 224, to be rolled onto center stage switch 2.

This roll is performed hitlessly by creating a head-end-bridge at input stage switch 4 and an receive-end-switch at output stage switch 3 as shown in FIGURE 31. When the correct path is received at outputs stage switch 3 from center stage switch 2, the original connection through center stage X 224 is dropped.





Rolling the immediate connection, $I(4,1) \rightarrow O(3,4)$, off the extra center stage switch completes the rearrangement process for this connection. Note that this process leaves the extra center stage switch clear and ready for a next connection when a rearrangeable blocking condition occurs. FIGURE 32 shows the resulting state of the space matrix after rearrangement. FIGURE 33 shows the corresponding space matrix data entries after rearrangement.

In FIGURE 34, the rearrangement aspects of the preferred embodiment are applied to the above example appear. Once the preferred embodiment uses dedicated center stage switch 224 to make the immediate connection, the system of the preferred embodiment invokes the rearrangement process automatically. First, the system determines two center stage switches which will participate in the rearrangement process. This is accomplished using Paull's Method which is restated as follows:

If (r_1, c_1) is blocked, test all symbol pairs (A, B) , such that A is in row r_1 , but not in column c_1 and B is in c_1 , but not in r_1 , to find which pair will require the fewest changes. The method then carries out the changing algorithm on that pair.

Returning to the space matrix example of FIGURE 25, it is preferred to first transform the space_cnt_mat matrix data in FIGURE 24 into the format of FIGURE 4. FIGURE 34 illustrates the results of this transformation.

The use of the dedicated center stage switch is indicated by the X in (r_4, c_3) of FIGURE 34. The next step is to find all symbol pairs (A, B) such that A is in row r_4 , but not in column c_3 , and B is in column c_3 , but not in row r_4 . In this example, there is a 2 in row r_4 , but no 2 in column c_3 , so A is set to 2. Similarly, there is a 4 in column c_3 , but no 4 in row r_4 , so B is set to 4. Since there is only one value for A and one value for B,

the (A,B) pair that requires the least changes is, obviously, the pair (2,4).

For a given pair of symbols (A,B) there are two possible rearrangement sequences. One of these two
5 generally will be shorter. The following steps generate the X-A and X-B sequences for this example.

The X-A sequence starts with the immediate connection through the extra element and ends up with the blocked cell being assigned to element A or 2, in this
10 case. Starting with the blocked cell (r_3, c_4) , there is no 4 in row r_3 , so this step requires a circle around the 2 in row r_3 . Now, the circled 2 is in (r_4, c_2) . Then, a search for a 4 in column c_2 is necessary. Since there is none, this sequence is complete. (Note that not all 2's
15 get circled.)

The X-B sequence starts with an immediate connection through the dedicated element 224 and ends up with the blocked cell being assigned to element B or 4, in this
case. Starting with the blocked cell (r_3, c_4) , there is no
20 2 in c_4 , so a circle goes around the 2 in c_4 . Now, the circled 4 is in (r_3, c_3) . Then, a search for a 2 in r_3 takes place. Since there is none, the sequence generation process is complete. (Note that not all 4's
get circled.)

25 The flooding algorithm starts by finding the first element of the X-A sequence. If the X-A sequence is not ended, the first element of X-B sequence is found. Then, if the X-B sequence is not ended, the next element of the X-A sequence is found. This process continues until the
30 shorter of the two sequences is completed. (So, the X-B sequence shown in FIGURE 34 is not really generated. It is shown here as an illustration of the alternate path.)

In summary, a method and system are provided for finding an optimal path or connection configuration
35 through a communications matrix in which an input stage array represents the assignment of input gates through an



input switch to a center stage and has values that
associate an input stage switch with an input gate and a
center stage switch, a center stage array represents
center stage switch connections between an output stage
5 and input stage, and an output stage array represents
output stage connections and has values that associate an
output stage switch with an output gate and a center
stage switch, and, further, wherein an idle input array
represents idle input gates and an idle output array
10 represents idle output gates, and in which the optimal
connection path or configuration is determined by pumping
the input stage array and the output stage array to
determine an optimal center stage switch having idle
connections between a predetermined input gate and a
15 predetermined output gate. One important aspect of the
present invention is its use in identifying the presence
of a rearrangeably blocked condition of a rearrangeable
communications matrix.

As a result of the above, although the invention has
20 been described with reference to the above embodiments,
its description is not meant to be construed in a
limiting sense. Various modifications of the disclosed
embodiment, as well as alternative embodiments of the
invention will become apparent to person skilled in the
25 art upon reference to the above description. It is
therefore contemplated that the appended claims will
cover such modifications that fall within the true scope
of the invention.

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APPENDIX A

Bowdon's Immediate Connect Algorithm (BICA)

To begin proceed to the main program at the end of the the listing. */

```
#include <stdio.h>
#include <math.h>
#include <malloc.h>
#include <sys/types.h>
#include <sys/timeb.h>
#include <sys/time.h>
```

Global variables for immediate connection algorithm. */

```
int in_line,
    out_line;
int in_stage,
    in_num;
int out_stage,
    out_num;
int n,
    m;
int command_count,
    command_end = 10;
int rearrange_space,
    rearrange_time;

int space_in_mat[16][16];
int space_cnt_mat[17][16];
int space_out_mat[16][16];
int space_in_link[16][17];
int space_out_link[16][17];
int xtra_stage = 17;
int traffic[2][28672];
```

Global variables for rearrangement algorithm. */

```
int BTOA_MV[31][3],
    ATOB_MV[31][3];
int flag_A = 0,
    flag_B = 0;

int *sort_array ();
int *chk_space_in_status ();
int *chk_space_out_status ();
int *chk_space_blocking ();
int *shuffle ();
int *implement_PM2 ();

char name_in[13];
char name_out[13];

static int in_file[22];
int *fp_in,
    *fp_out;
int seed_array[10];
int p_level;
```

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APPENDIX A

structure to hold current network permutation before rearranging. */
 struct p_coordinate

```
int      x;
int      y;
int      z;
```

struct p_mat_pos

```
struct p_coordinate position[256];
```

struct p_mat_pos rearrange_3d;

Structure to hold the output of the rearrangement sequence. */
 struct seq_len

```
int input_sw;
int old_mid_sw;
int new_mid_sw;
int output_sw;
```

struct rearrange_seq

```
struct seq_len move[15];
```

struct rearrange_seq rearrange_moves;

```
*****
This is the subprogram for BICA's number of moves from B calc.
*****
```

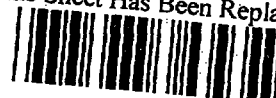
```
*****
This function first reads the rearrangement structure and picks out
the connections in the middle switch pair (A, B). The arguments to
this function are the starting point (RB, CB) and the pair (A, B).
The function returns the number of moves starting from B. For
reference, the starting point is described by Paull as (R1, C2).
*****
```

nk_Paull_mat_BTOA (RB, CB, B_least, A_least)

```
it      RB,
        CB;
it      A_least,
        B_least;
```

```
int      i,
        j,
        m = 0,
        n = 0,
        y1 = 0,
        y2 = 0,
        y3 = 0,
        n1 = 0,
```

This Sheet Has Been Replaced



APPENDIX A

```

int      n2 = 0;
        x1 = 0,
        x2 = 0,
        x3 = 0,
        k1 = 0,
        m1 = 0,
        m2 = 0;
int      flag1 = 0,
        flag2 = 0,
        flag3 = 0,
        temp_flag = 0,
        k2 = 0;
int      r_temp = 0,
        c_temp = 0,
        F2 = 0;
int      chosen_msw_A[16][3],
        chosen_msw_B[16][3];

```

This Sheet Has Been Replaced



```

c_temp = CB;
m = 1;
n = 2;

```

```

zero (chosen_msw_A, 48);          /* Initialize target matrices. */
zero (chosen_msw_B, 48);

```

```

for (i = 0; i < 256; i++)
{
    x1 = rearrange_3d.position[i].x; /* Read rearrangement struct. */
    x2 = rearrange_3d.position[i].y;
    x3 = rearrange_3d.position[i].z;

    if (x3 == B_least)
    {
        chosen_msw_B[m1][0] = x1; /* Pick out connections from */
        chosen_msw_B[m1][1] = x2; /* middle switch B and store */
        chosen_msw_B[m1][2] = x3; /* in chosen_msw_B. */
        m1++;
    }

    if (x3 == A_least)
    {
        chosen_msw_A[m2][0] = x1; /* Pick out connections from */
        chosen_msw_A[m2][1] = x2; /* middle switch A and store */
        chosen_msw_A[m2][2] = x3; /* chosen_msw_A. */
        m2++;
    }
}

```

```

while (temp_flag == 0)
{
    k1 = 0;
    for (i = 0; i < 16; i++) /* Start from (R1, C2), check */
    { /* A's in the same column. */
        x1 = chosen_msw_A[i][0];
        x2 = chosen_msw_A[i][1];
        x3 = chosen_msw_A[i][2];

        if (x2 == c_temp && x3 == A_least) /* Found an B? */
        {
            BTOA_MV[m][0] = x1; /* Yes, then store current */

```

APPENDIX A

```

        BTOA_MV[m] ] = x2;      /* connection . BTOA_MV. */
        BTOA_MV[m][2] = x3;
        m++;
        r_temp = x1;
        break;
    }

    k1++;
}

if (k1 == 16)
{
    flag1 = 1;
    temp_flag = 1;
    F2 = m;
}

if (flag1 == 0)
{
    k2 = 0;
    for (i = 0; i < 16; i++)      /* Start from (R1, C2), check */
    {                               /* B's in the same row. */

        x1 = chosen_msw_B[i][0];
        x2 = chosen_msw_B[i][1];
        x3 = chosen_msw_B[i][2];

        if (x1 == r_temp && x3 == B_least)      /* Found an B? */
        {
            BTOA_MV[m][0] = x1;      /* Yes, then store */
            BTOA_MV[m][1] = x2;      /* current connection */
            BTOA_MV[m][2] = x3;      /* in BTOA_MOV. */
            m++;
            c_temp = x2;
            break;
        }

        k2++;
    }

    if (k2 == 16)
    {
        flag2 = 1;
        temp_flag = 1;
        F2 = m;
    }
}

return (F2);      /* Return the number of moves from B. */

```

```

/******
/*
/* This is the subprogram for BICA's number of moves from A calc.
/*
/******
/******
/* This function first reads the rearrangement structure and picks out
/* the connections in the middle switch pair (A, B). The arguments to
/*

```

This Sheet Has Been Replaced



APPENDIX A

```

/* this function are the starting point (RA, CA) and the pair (A, B). */
/* The function returns the number of moves starting from A. For */
/* reference, the starting point is described by Paull as (R2, C1). */
/*******/

```

```

chk_Paull_mat_ATOB (RA, CA, B_least, A_least)

```

```

int      RA,
int      CA;
int      B_least,
int      A_least;

{
    int      i,
             j,
             m = 0,
             n = 0,
             y1 = 0,
             y2 = 0,
             y3 = 0,
             n1 = 0,
             n2 = 0;
    int      x1 = 0,
             x2 = 0,
             x3 = 0,
             k1 = 0,
             m1 = 0,
             m2 = 0;
    int      flag1 = 0,
             flag2 = 0,
             flag3 = 0,
             temp_flag = 0,
             k2 = 0;
    int      r_temp = 0,
             c_temp = 0,
             F1 = 0,
             F2 = 0;
    int      chosen_msw_A[16][3],
             chosen_msw_B[16][3];

    r_temp = RA;
    m = 1;
    n = 2;

    zero (chosen_msw_A, 48);
    zero (chosen_msw_B, 48);
    /* Initialize target matrices. */

    for (i = 0; i < 256; i++)
    {
        x1 = rearrange_3d.position[i].x; /* Read rearrangement struct. */
        x2 = rearrange_3d.position[i].y;
        x3 = rearrange_3d.position[i].z;

        if (x3 == B_least)
        {
            chosen_msw_B[m1][0] = x1; /* Pick out connections from */
            chosen_msw_B[m1][1] = x2; /* middle switch B and store */
            chosen_msw_B[m1][2] = x3; /* in chosen_msw_B. */
            m1++;
        }
    }
}

```

This Sheet Has Been Replaced



```

if (x3 == A_least)
{
    chosen_msw_A[m2][0] = x1;    /* Pick out connections from */
    chosen_msw_A[m2][1] = x2;    /* middle switch A and store */
    chosen_msw_A[m2][2] = x3;    /* in chosen_msw_A. */
    m2++;
}
}

while (temp_flag == 0)
{
    k1 = 0;
    for (i = 0; i < 16; i++)    /* Start from (R2, C1), check */
    {                            /* B's in the same row. */
        x1 = chosen_msw_B[i][0];
        x2 = chosen_msw_B[i][1];
        x3 = chosen_msw_B[i][2];

        if (x1 == r_temp && x3 == B_least)    /* Found an A? */
        {
            ATOB_MV[m][0] = x1;    /* Yes, then store current */
            ATOB_MV[m][1] = x2;    /* connection in ATOB_MV. */
            ATOB_MV[m][2] = x3;
            m++;
            c_temp = x2;
            break;
        }
        k1++;
    }

    if (k1 == 16)
    {
        flag1 = 1;
        temp_flag = 1;
        F1 = m;
    }

    if (flag1 != 1)
    {
        k2 = 0;
        for (i = 0; i < 16; i++)    /* Start from (R2, C1), check */
        {                            /* A's in the same column. */
            x1 = chosen_msw_A[i][0];
            x2 = chosen_msw_A[i][1];
            x3 = chosen_msw_A[i][2];

            if (x2 == c_temp && x3 == A_least)    /* Found an A? */
            {
                ATOB_MV[m][0] = x1;    /* Yes, then store */
                ATOB_MV[m][1] = x2;    /* current connection */
                ATOB_MV[m][2] = x3;    /* in ATOB_MV. */
                m++;
                r_temp = x1;
                break;
            }
            k2++;
        }

        if (k2 == 16)

```

This Sheet Has Been Replaced



APPENDIX A

```

    [
        flag2 = 1;
        temp_flag = 1;
        Fl = m;
    ]
}
return (Fl);                                /* Return the number of moves from A. */

*****
/* This is the subprogram for BICA's rearrange output. */
*****

*****
/* This function is the output of the rearrangement procedure. The */
/* arguments to this function are the required number of moves and the */
/* pair (A, B). The sequence of moves is written into the output */
/* structure rearrange_moves. */
*****

*****
/* The output of the rearrangement process is a structure of the form: */
/* */
/* struct seq_len */
/* { */
/*     int input_sw; */
/*     int old_mid_sw; */
/*     int new_mid_sw; */
/*     int out_sw; */
/* } */
*****

nt      rearrangement_output (no_moves, AR, BR)
nt      no_moves;
nt      AR;
nt      BR;

int      i,
          j,
          k,
          m,
          n;
int      x1 = 0,
          x2 = 0,
          x3 = 0;
int      y1 = 0,
          y2 = 0,
          y3 = 0;

for (j = 0; j < no_moves; j++)
{
    if (flag_A == 1 && flag_B == 0) /* Is sequence from A smaller? */
    {
        y1 = ATOB_MV[j][0];        /* Read Input switch */
        y2 = ATOB_MV[j][1];        /* Read Output switch */
    }
}

```

This Sheet Has Been Replaced



APPENDIX A

```

        y3 = ATOB_MV[j][2];          /* Read Middle switch */
    }

    if (flag_B == 1 && flag_A == 0) /* Is sequence from B smaller? */
    {
        y1 = BTOA_MV[j][0];          /* Read Input switch */
        y2 = BTOA_MV[j][1];          /* Read Output switch */
        y3 = BTOA_MV[j][2];          /* Read Middle switch */
    }

    rearrange_moves.move[j].input_sw = y1; /* Store Input switch */
    rearrange_moves.move[j].old_mid_sw = y3; /* Store Old Middle switch */

    rearrange_moves.move[j].output_sw = y2; /* Store Output switch */

    /* Store New Middle switch */
    if (y3 == AR)                    /* Change A's to B's. */
        rearrange_moves.move[j].new_mid_sw = BR;

    if (y3 == BR)                    /* Change B's to A's. */
        rearrange_moves.move[j].new_mid_sw = AR;
}
return;

```

 This is the subprogram for BICA's zero function.

```

    zero (A, n)
    *A;
    n;

    int i;

    for (i = 0; i < n; i++)
        *(A + i) = 0;
    return;

```

 This is the subprogram for BICA's hunt algorithm starting point set.

 This function sets the starting points for the hunting algorithm
 from A & B and executes the algorithm. The set of connections to be
 moved are stored in either ATOB_MV or BTOA_MV if either the sequence
 from A is shorter or the sequence from B is shorter, respectively.
 The arguments to this function are the middle switch pair (A,B),
 an index and the blocked matrix position (R1,C1). The function
 returns the length of the shortest sequence.

This Sheet Has Been Replaced



APPENDIX A

```
rearrange_req (r1_B, cl_A, sw_index, R1, C1)
```

```
r1_B;
```

```
cl_A;
```

```
sw_index;
```

```
R1;
```

```
C1;
```

```
int      i,
          j,
          k = 0,
          x1 = 0,
          x2 = 0,
          x3 = 0,
          m,
          n,
          temp_mov = 0,
          temp = 0;
int      num_moves = 0,
          mr = 0,
          mc = 0,
          w_seq = 0;
int      R[3],
          C[3],
          undef_flag = 0;
int      num_moves_A = 0,
          num_moves_B = 0,
          F1 = 0;
int      F2 = 0,
          R1_CONN[16][3],
          C1_CONN[16][3];
```

```
zero (R, 15);
zero (C, 15);
zero (ATO_B_MV, 93);
zero (BTO_A_MV, 93);
zero (R1_CONN, 48);
zero (C1_CONN, 48);
```

```
m = 0;
n = 0;
```

```
R[0] = R1;
C[0] = C1;
```

```
BTO_A_MV[0][0] = R[0];
ATO_B_MV[0][1] = C[0];
```

```
for (i = 0; i < 256; i++) /* Pick out middle switches in (R1,C1). */
{
    x1 = rearrange_3d.position[i].x; /* Read structure. */
    x2 = rearrange_3d.position[i].y;
    x3 = rearrange_3d.position[i].z;

    if (x1 == R1)
    {
        R1_CONN[m][0] = x1; /* Store middle switches in R1. */
        R1_CONN[m][1] = x2;
        R1_CONN[m][2] = x3;
        m++;
    }
}
```

This Sheet Has Been Replaced.



APPENDIX A

```

if (x2 == C1)
{
    C1_CONN[n][0] = x1;          /* Store middle switches in C1. */
    C1_CONN[n][1] = x2;
    C1_CONN[n][2] = x3;
    n++;
}
}

for (i = 0; i < 15; i++)        /* Find the matrix position R2, C2. */
{
    x1 = R1_CONN[i][2];         /* R1_CONN is the connections in R1 */
    x2 = C1_CONN[i][2];         /* C1_CONN is the connections in C1 */

    if (x1 == r1_B)
        C[1] = R1_CONN[i][1];
    if (x2 == c1_A)
        R[1] = C1_CONN[i][0];
}

BTOA_MV[0][1] = C[1];          /* Set start point for search from A&B. */
ATOB_MV[0][0] = R[1];          /* A is from (R2, C1); B from (R1, C2). */

BTOA_MV[0][2] = r1_B;          /* The 3rd element of BTOA_MV & ATOB_MV */
ATOB_MV[0][2] = c1_A;          /* is alternating sequence of A's & B's */
                                /* A's are changed to B's & B's to A's. */

/* Set starting point for A. */
mr = R[1];
mc = C[0];

/* Hunting algorithm from A. */
num_moves_A = chk_Paull_mat_ATOB (mr, mc, r1_B, c1_A); /* REPLACE */
                                                        /* w/ FLOOD */

/* Set starting point for B. */
mr = R[0];
mc = C[1];
/* Hunting algorithm from B */

num_moves_B = chk_Paull_mat_BTOA (mr, mc, r1_B, c1_A); /* REPLACE */
                                                        /* w/ FLOOD */

F1 = num_moves_A;
F2 = num_moves_B;

if (F1 < F2)                    /* Is num_moves_A < num_moves_B ? */
{
    w_seq = 1;                  /* If yes, set flag_A = 1, flag_B = 0. */
    num_moves = F1;
    flag_A = 1;
    flag_B = 0;
}

if (F2 < F1)                    /* Is num_moves_B < number_moves_A ? */
{
    w_seq = 2;                  /* If yes, set flag_A = 0, flag_B = 1. */
    num_moves = F2;
    flag_A = 0;
    flag_B = 1;
}

```

This Sheet Has Been Replaced



APPENDIX A

```

}
if (F1 == F2)          /* Is number_moves_A = number_moves_B ? */
{
    w_seq = 1;          /* If yes, default to sequence from A. */
    num_moves = F1;
    flag_A = 1;          /* and set flag_A = 1, flag_B = 0. */
    flag_B = 0;
}
return (num_moves);     /* Return the least number of moves. */

```

```

*****/
*
* This is the subprogram for BICA's implement change algorithm.
*
*
*****/

```

```

*****/
*
* This function implements the hunting algorithm to find the sequence
* of moves required for rearrangement. The arguments to this function
* are the middle switch pair (msw_A, msw_B) and the index.
*
*****/

```

```

int      implement_change (msw_B, msw_A, index)
int      msw_B;
int      msw_A;
int      index;

```

```

int      i,
          j,
          k;
int      len_of_seq = 0;

```

```

len_of_seq = rearrange_seq (msw_B, msw_A, index);
rearrangement_output (len_of_seq, msw_A, msw_B);
return (len_of_seq);

```

```

*****/
*
* This is the subprogram for BICA's calculate number of moves.
*
*
*****/

```

```

*****/
*
* This routine uses the implement_change_algorithm function to find
* the number of moves required for the sequence of moves from sw_A and
* and for the sequence of moves from sw_B for the existing connections
* in the center stage switch pair (A, B) and returns the number of
* moves required for the smaller of the two sequences.
*
*****/

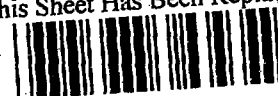
```

```

int      calc_nom (sw_B, sw_A, index)
int      sw_B,
          sw_A,
          index;

```

This Sheet Has Been Replaced



APPENDIX A

```
int      num_moves;
num_moves = implement_change (sw_B, sw_A, index);
return(num_moves);
```

```
*****/
This is the subprogram for BICA's matrix model conversion.
*****/
```

```
*****/
The present implementation of Paull's method needs the connect data
in the following structure.
*****/
```

```
struct p_coordinate
{
    int input_sw;
    int output_sw;
    int cnt_sw;
}

struct p_mat_pos
{
    struct p_coordinate[256];
}
```

```
id_      matrix_model_conversion ()
```

```
int      i,
         j,
         x1,
         x2,
         x3,
         ml = 0;

for(i = 1; i <= 17; i++)
{
    for(j = 1; j <= 17; j++)
    {
        x1 = i;
        x2 = j;
        x3 = space_cnt_mat[i][j];
        if(x3 != 0)
        {
            rearrange_3d.position[ml].x = x2;    /* Input switch */
            rearrange_3d.position[ml].y = x3;    /* Output switch */
            rearrange_3d.position[ml].z = x1;    /* Middle switch */
            ml++;
        }
    }
}
return;
```

```
*****/
This is the subprogram for BICA's version of Paull's method II.
*****/
```



APPENDIX A

```

*****. *****
This function uses Paull's method II to search for (A, B) pairs.
*****

t      *implement_PM2 ()

int      i,
          j,
          k,
          x1,
          x2,
          m = 0,
          n = 0;
int      *selected_pair,
          R1_cnt_sw[16],
          C1_cnt_sw[16];
int      listofB[16],
          listofA[16],
          A_temp = 0,
          B_temp = 0;
int      cnt_stage_pairs[8][2],
          op_flag;
int      num_moves,
          least_moves,
          least_pair;

/* convert from 3 matrix model to rearrangement structure. */
/* Return pointer to structure or Global must be visible. */

matrix_model_conversion ();      /* Converts 2nd of 3-matrix model. */

selected_pair = (int *) calloc (2, sizeof (int));

Given a connect request (I,O), where I is an INPUT SWITCH and O is
an OUTPUT SWITCH, read the row vectors in matrices 1 & 2. Then, XOR
the two vectors to get a list of candidates for (A,B).

for (j = 1; j < 17; j++)
{
    R1_cnt_sw[j] = space_in_mat[in_stage][j];
    C1_cnt_sw[j] = space_cnt_mat[out_stage][j];
}

for (j = 0; j < 16; j++)
{
    x1 = R1_cnt_sw[j];
    x2 = C1_cnt_sw[j];

    if (x1 == 0 && x2 != 0)
    {
        listofA[m] = x2;
        m++;
    }
    if (x1 != 0 && x2 == 0)
    {
        listofB[n] = x1;
        n++;
    }
}

```

/* The XOR operation. */

This Sheet Has Been Replaced



APPENDIX A

```

    }
}

m = 0;
n = 0;
i = 0;
while ((x1 = listofB[i]) != 0)      /* Create all combinations of */
{                                   /* elements of listofA's      */
    j = 0;                          /* & listofB's.                */
    while ((x2 = listofA[j]) != 0)
    {
        cnt_stage_pairs[m][0] = x1;
        cnt_stage_pairs[m][1] = x2;
        m++;
        j++;
    }
    i++;
}

least_moves = xtra_stage;
for (k = 0; k < m; k++)             /* For each combination of middle */
{                                   /* switches, calculate least num. */
    B_temp = cnt_stage_pairs[k][0]; /* of moves that are required. */
    A_temp = cnt_stage_pairs[k][1];
    if (B_temp != 0 && A_temp != 0)
    {
        num_moves = calc_nom (B_temp, A_temp, k);
    }
    if (num_moves < least_moves)
    {
        least_moves = num_moves;
        least_pair = m;
    }
}

*(selected_pair + 0) = cnt_stage_pairs[least_pair][1];
*(selected_pair + 1) = cnt_stage_pairs[least_pair][0];

return (selected_pair);

```

```

*****/
*****/
The following are the revised subprograms and main program for BICA. */
*****/
*****/
*****/
This is the subprogram for BICA's hitless time rearrangement. */
*****/

```

hitless_time_rearrange ()

This Sheet Has Been Replaced



APPENDIX A

```
/* Use Include File. :
return;
```

```
*****
This is the subprogram for BICA's flood time algorithm.
*****
```

```
      flood_time ()
```

```
/* Use Include File. */
return;
```

```
*****
This is the subprogram for BICA's select two time slots.
*****
```

```
      select_time_slots ()
```

```
/* Use Include File. */
return;
```

```
*****
This is the subprogram for BICA's hitless space rearrangement.
*****
```

```
      hitless_space_rearrange ()
```

```
/* Use Include File. */
return;
```

```
*****
This is the subprogram for BICA's flood space algorithm.
*****
```

```
      flood_space ()
```

```
/* Use Include File. */
return;
```

```
*****
This is the subprogram for BICA's pump link macro.
*****
```

This Sheet Has Been Replaced



APPENDIX A

This macro logically "and" space_in_link[i] with space_out_link[k] to determine the lowest numbered center stage switch, "c," having both an idle link to input stage "i" and an idle link to output stage "k." The first non-zero entry in the result of the logical "and" is "c" and the two links to "c" are reset to "0" (marked as busy) in space_in_link[i] and space_out_link[k]. The macro returns the value "c."

```

at      pump_link ()

int      c,
         j,
         x;

for (j = 1; j <= xtra_stage; j++)
{
    x = space_in_link[in_stage][j] && space_out_link[out_stage][j];

    if (x == 1)
    {
        c = j;
        break;
    }
}

clear_link(space_in_link, in_stage, c);
clear_link(space_out_link, out_stage, c);

if (c == xtra_stage)
{
    rearrange_space = 1;
}

/* Return center stage. */
return(c);

```

This is the subprogram for BICA's clear idle link bit (to 0).

This primitive is used to clear (reset) the kth bit of the jth row of the bit map specified by io to "0." If the bit map contains n elements and the value of j > n, then an error flag is returned. Otherwise, the kth element is reset to "0."

```

t      clear_link(io, j, k)
t      io[16][17],
         j,
         k;

```

```

int      error_flag;

```

```

if(k <= xtra_stage)
{

```

This Sheet Has Been Replaced



APPENDIX A

```

io[j][k] = 0;
error_flag = 0;
}
else
{
    error_flag = 1;
}
return(error_flag);

*****
This is the subprogram for BICA's set idle link bit (to 1).
*****

*****
This primitive is used to set the kth bit of the jth row of the bit
map specified by io to "1." If the bit map contains n elements and
the value of j > n, then an error flag is returned. Otherwise, the
kth element is set to "1."
*****

        set_link(io, j, k)
        io[16][17],
        j,
        k;

int          error_flag;
if(k <= xtra_stage)
{
    io[j][k] = 1;
    error_flag = 0;
}
else
{
    error_flag = 1;
}
return(error_flag);

*****
This is the subprogram for BICA's select two center stage switches.
*****

        select_cnt_stage ()

int *center_stage_pair;
center_stage_pair = (int *)calloc(2, sizeof(int));
select middle stage switch pair */
center_stage_pair = implement_PM2 ();
return(*center_stage_pair);

```

This Sheet Has Been Replaced



APPENDIX A

```

*****
This is the subprogram for BICA's time rearrangement.
*****

```

Node D */

id time_rearrange ()

```

int      XtoA = 0,
          XtoB = 0;
char     last;

```

```

/* Select Two Time Slots for Rearrangement. */
select_time_slots ();

```

```

/* Find Connections to be Rearranged. */
flood_time ();

```

```

/* Q6: Which Path Requires Least Number of Rearrangements? */

```

```

if (last == 'A')

```

```

{
    XtoA = 1;
}

```

```

else

```

```

{
    if (last == 'B')
    {
        XtoB = 1;
    }
}

```

```

hitless_time_rearrange ();

```

```

rearrange_time = 0;

```

```

return;

```

```

*****
This is the subprogram for BICA's space rearrangement.
*****

```

Node C */

id space_rearrange ()

```

int      XtoA = 0,
          XtoB = 0;
int      *cnt_stage_pair;

```

```

char     last;

```

```

/* allocate memory for pointer to list of connections to be moved. */
cnt_stage_pair = (int *)calloc(2, sizeof(int));

```

```

/* Select Two Center Stage Switches for Rearrangement.

```

```

*cnt_stage_pair = select_cnt_stage ();

```

```

/* Find Connections to be Rearranged. */

```

```

flood_space ();

```

This Sheet Has Been Replaced



APPENDIX A

```

/* Q5: Which Path Requires Least Number of Rearrangements? */
if (last == 'A')
{
    XtoA = 1;
}
else
{
    if (last == 'B')
    {
        XtoB = 1;
    }
}
hitless_space_rearrange ();
rearrange_space = 0;
return;

```

```

*****
This is the subprogram for BICA's remainder function.
*****
This function produces the remainder after the divisor has been
subtracted from the dividend as many (integer) times as possible.
*****

```

```

t      rem(dividend, divisor)
t      dividend,
      divisor;

int      remainder;

if (dividend <= 0)
{
    remainder = 0;
}
else
    remainder = dividend;
while (remainder >= divisor)
{
    remainder = remainder - divisor;
}
return(remainder);

```

```

*****
This is the subprogram for BICA's quotient function.
*****
This function produces the quotient by subtracting the divisor from
the dividend as many (integer) times as possible.
*****

```

```

t      quot(dividend, divisor)
t      dividend,

```

This Sheet Has Been Replaced



divisor;

```

int          quotient,
            remainder;

quotient = 0;
if (dividend <= 0)
{
    remainder = 0;
}
else
    remainder = dividend;
while (remainder >= divisor)
{
    remainder = remainder - divisor;
    quotient++;
}
return(quotient);

```

```

*****
This is the subprogram for BICA's convert I/O line numbers.
*****

```

```

*****
This subprogram uses the quotient and remainder functions to convert
the I/O line numbers for a connect or disconnect to a pair of I/O
stage switch numbers and I/O stage switch pin number.
*****

```

```

id          convert_line ()

int          r = 16,
            in_line_minus_1,
            out_line_minus_1;

in_line_minus_1 = in_line - 1;
in_stage = quot(in_line_minus_1, r) + 1;
in_num = rem(in_line_minus_1, r) + 1;

out_line_minus_1 = out_line - 1;
out_stage = quot(out_line_minus_1, r) + 1;
out_num = rem(out_line_minus_1, r) + 1;

return;

```

```

*****
This is the subprogram for BICA's print statistics - n and m.
*****

```

```

        print_stats ()

/* Test case for print_stats. */
printf ("BICA performed %d connect(s) and %d disconnect(s).\n", n, m);

```



return;

APPENDIX A

```
*****
This is the subprogram for BICA's disconnect - input from output.
*****

Node B */
id disconnect ()

int cnt_stage,
    csw; /* csw for Center Stage switch. */

Convert IL-m -> OL-n Disconnect Request to I(i,j) >< O(k,l) Format. */
convert_line ();
convert_line ();

Remove Connections as Requested. */
csw = space_in_mat[in_stage][in_num];
space_in_mat[in_stage][in_num] = 0;
space_cnt_mat[csw][in_stage] = 0;
space_out_mat[out_stage][out_num] = 0;

Update Tables. */
set_link(space_in_link, in_stage, csw);
set_link(space_out_link, out_stage, csw);

Q7: Pack Connections After A Disconnect Enabled? */
if (rearrange_space == 1)
    /* A3 = YES -> Node C. */
    {
        space_rearrange ();
    }
/* A3 = NO. */
else
    /* End Space Domain. */
    {
        /* Q4: Time Rearrangement Required? */
        if (rearrange_time == 1)
            /* A4 = YES -> Node D. */
            {
                time_rearrange ();
            }
        /* A4 = NO. */
        /* End Time Domain. */
    }
return;
```

```
*****
This is the subprogram for BICA's connect - input to output.
*****

*****
This routine connects an input line to an output line through the
space matrix. Variables are defined as follows:
*****
```

This Sheet Has Been Replaced



APPENDIX A

```

in_line:    an input to the space matrix,          */
             0 <= in_line <= 255                    */
out_line:    an output from the space matrix,        */
             0 <= out_line <= 255                    */
in_stage:    an input stage of the space matrix,     */
             0 <= in_stage <= 15                     */
in_num:      an input to an input stage of the space matrix, */
             0 <= in_number <= 15                     */
out_stage:    an output stage from the space matrix, */
             0 <= out_stage <= 15                     */
out_num:      an output from an output stage of the space matrix, */
             0 <= out_number <= 15                     */
cnt_stage:    a center stage of the space matrix,    */
             0, 1 <= center_stage <= 17               */
NOTE:        center_stage = 0, means that no center stage of the */
             space matrix has been assigned.           */
             center_stage = 1, ..., 16 means that the corresponding */
             center stage of the space matrix is assigned.         */
             center_stage = 17 is the extra stage of the space */
             matrix, and rearrangement is in progress.             */
*****

Node A */
id      connect ()

int      csw;          /* csw for Center Stage switch. */

Convert IL-m -> OL-n Connection Request to I(i,j) -> O(k,l) Format. */
convert_line ();

Begin Time Domain. */

Select Lowest Numbered Time Slot Available for Connection. */

Begin Space Domain. */

Select Lowest Numbered Center Stage Available for Connection. */
csw = pump_link ();

Make Connection and Update Tables. */
space_in_mat[in_stage][in_num] = csw;
space_cnt_mat[csw][in_stage] = out_stage;
space_out_mat[out_stage][out_num] = csw;

/* Q3: Space Rearrangement Required? */
if (rearrange_space == 1)
    /* A3 = YES -> Node C. */
    {
        space_rearrange ();
    }
/* A3 = NO. */
else
    /* End Space Domain. */
    {
        /* Q4: Time Rearrangement Required? */

```

This Sheet Has Been Replaced



APPENDIX A

```

if (rearrange_time = 1)
/* A4 = YES -> Node D. */
{
    time_rearrange ();
}
/* A4 = NO. */
/* End Time Domain. */
}
return;

```

```

*****
This is the subprogram for BICA's get command.
*****

```

```

        get_command ()

int          command;

/* Test case for get_command. */
if (command_count < command_end)
{
    /* command = 1 => connect. */
    command = 1;
    command_count++;
    in_line = command_count;
    out_line = command_count;
}
else if (command_count == command_end)
{
    /* command = -1 => disconnect. */
    command = -1;
    command_count++;
}
else
{
    /* command = 0 => end. */
    command = 0;
}
return(command);

```

```

*****
his is the subprogram for BICA's space rearrange initialization.
*****

```

```

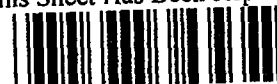
        initialize_rearrange ()

int          i;

for (i = 0; i < 256; i++)
{
    rearrange_3d.position[i].x = 0;
    rearrange_3d.position[i].y = 0;
    rearrange_3d.position[i].z = 0;
}

```

This Sheet Has Been Replaced



APPENDIX A

```
for (i = 0; i < 15; i++)
{
    rearrange_moves.move[i].input_sw = 0;
    rearrange_moves.move[i].old_mid_sw = 0;
    rearrange_moves.move[i].new_mid_sw = 0;
    rearrange_moves.move[i].output_sw = 0;
}
return;
```

```
*****//
this is the subprogram for BICA's space matrix initialization. */
*****//
```

```
*****//
this routine is used initially to clear (reset) the space matrices. */
*****//
```

initialize_space_mat()

```
int i, j;
for(i = 0; i < xtra_stage; i++)
{
    for(j = 0; j < xtra_stage; j++)
    {
        space_in_mat[i][j] = 0;
        space_cnt_mat[i][j] = 0;
        space_out_mat[i][j] = 0;
    }
    space_cnt_mat[xtra_stage][i] = 0;
}
return;
```

```
*****//
this is the subprogram for BICA's initialize idle link bit maps. */
*****//
```

```
*****//
the initialize link bit maps primitive (used only for start-up */
operations) initializes both the space input idle link bit map and */
the space output link bit map. All entries in the idle link bit */
maps are initialized to "1," indicating that all links are idle. */
*****//
```

init_links()

```
int i, j;
for(i = 0; i < xtra_stage; i++)
{
    for(j = 0; j <= xtra_stage; j++)
    {
        space_in_link[i][j] = 1;
```

This Sheet Has Been Replaced



```
space_out_1in[j] = 1;
```

```

*****
/*
/* the subprogram for BICA's initialization.
/*
*****

```

```
initialize ()
```

```
- data for commands. */
```

```

:
:

```

```
count = 0;
```

```
space = 0;
```

```
time = 0;
```

```
- initialize all matrices. */
```

```
init_ks();
```

```
init_space_mat ();
```

```
init_rearrange ();
```

```


```

```

*****
/*
/* the main program for Bowdon's Immediate Connect Algorithm.
/*
*****

```

```
command;
```

```
- Program Flow Here. */
```

```
init ();
```

```


```

```
command = get_command ();
```

```
Q1: Pair of Ports Presented for Connection? */
```

```
command = 1 => connect. */
```

```
command = 0
```

```
/* A1 = YES -> Node A. */
```

```
connect ();
```

```
A = N--;
```

```
A1 = NC. */
```

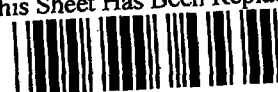
```


```

```
/* Q2: Pair of Ports Presented for Disconnect? */
```

```
/* command = -1 => disconnect. */
```

This Sheet Has Been Replaced



APPENDIX A

```

if (command = 1)
    /* A2 = YES -> Node B. */
    {
        disconnect ();
        m = m++;
    }
    /* A2 = NO. */
    continue;
}
/* command = 0 -> end. */
while (command != 0);
{
    print_stats ();
}

```

This Sheet Has Been Replaced





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92AD025

PATENT APPLICATION

WHAT IS CLAIMED IS:

1. A method for finding a path through a communications matrix, comprising the steps of:

5 representing the assignment of a center stage switch through an input switch to input gates using an input stage array;

representing center stage switch connections between an input stage and an output stage using a center stage array;

10 representing the assignment of a center stage switch through an output stage switch to output gates by an output stage array;

15 representing idle input switch links to said center stage switch by an idle input link array and idle output switch links from said center stage switch by an idle output link array;

20 pumping said input stage array and said output stage array and said center stage array using information from said idle input link array and said idle output link away to determine an optimal center stage switch having an idle connection between a predetermined input gate and a predetermined output gate; and

25 tracking said idle input switch links and said idle output switch links using said idle input link array and said idle output link array.

This Sheet Has Been Replaced





92AD025

PATENT APPLICATION

2. A system for finding a path through a communications matrix, comprising the steps of:

an input stage array for representing the assignment of a center stage switch through an input switch to input gates;

a center stage array for representing center stage switch connections between an input stage and an output stage;

an output stage array for representing the assignment of a center stage switch through output stage switch to output gates;

an idle input link array for representing the idle input links to said center stage switch;

an idle output link array for representing idle output links from the center stage switch;

pumping means for pumping said input stage array and said output stage array using information from said idle input link array and the idle output link array to determine an optimal center stage switch having an idle connection between a predetermined input gate and a predetermined output gate; and

tracking means for tracking said idle input switch links using said idle input link array and said idle output switch links using said idle output link array.

This Sheet Has Been Replaced





92AD025

PATENT APPLICATION

3. A method for finding an optimal path through a communications matrix, comprising the steps of:

5 representing the assignment of a center stage switch through an input switch to input gates using an input stage array;

representing center stage switch connections between an input stage switch and an output stage switch by a center stage array;

10 representing the assignment of a center stage switch through an output stage switch to output gates by an output stage array; and

15 pumping said input stage array, said output stage array, and said center stage array to determine an optimal center stage switch having both an idle input link between a predetermined input gate switch and said optimal center stage switch and an idle output link from said optimal center stage switch and the predetermined output stage gate.

This Sheet Has Been Replaced



92AD025



PATENT APPLICATION

4. A system for finding an optimal connection configuration through a communications matrix, comprising:

5 an input stage array for representing the assignment of a center stage switch through an input switch to input gates;

a center stage array for representing center stage switch connections between an input stage and an output stage;

10 an output stage array for representing the output stage switch to output gates; and

pumping means for pumping said input stage array, said output stage array, and said center stage array to determine an optimal center stage switch having both an
15 idle input link between a predetermined input gate and said optimal center stage switch and an idle output link between said optimal center stage switch and a predetermined output stage gate.

This Sheet Has Been Replaced





5. A method for finding a connection configuration through a communications matrix, comprising the steps of:

representing the assignment of a center stage switch through an input switch to input gates using an input stage array;

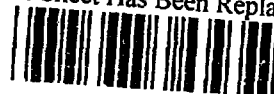
representing center stage switch connections between an input stage and an output stage switch by a center stage array;

representing the assignment of a center stage switch through an output stage switch to output gates stage array;

representing idle input switch links to said center stage switch by status indicators of an idle input link array and idle output switch links from the center stage by status indicators of an idle output link array and;

associating said input stage array, said output stage array, and said center stage array according to the values of said idle input link array and said idle output link array to determine an optimal center stage switch having an idle input link between a predetermined input gate and said optimal center stage switch and an idle output link between said optimal center stage and a predetermined output gate.

This Sheet Has Been Replaced





6. A system for finding a path through a communications matrix, comprising the steps of:

an input stage array for representing the assignment of a center stage switch through an input switch to input gates;

5

a center stage array for representing center stage switch connections between an input stage and an output stage switch, said center stage array comprising a set of elements for associating a dedicated center stage switch with a plurality of input stage switches and output stage switches;

10

an output stage array for representing the output stage switch to output gates;

an idle input link array for representing idle input switch links to the center stage switch and an idle output link array for representing idle output switch links from the center stage switch; and

15

means for associating said input stage array, said output stage array, and said center stage array using information from said idle input link array and said idle output link array determine an optimal center stage switch said optimal center stage switch potentially including said dedicated center stage switch and having an idle connection between a predetermined input gate and a predetermined output gate.

20

25

This Sheet Has Been Replaced

