

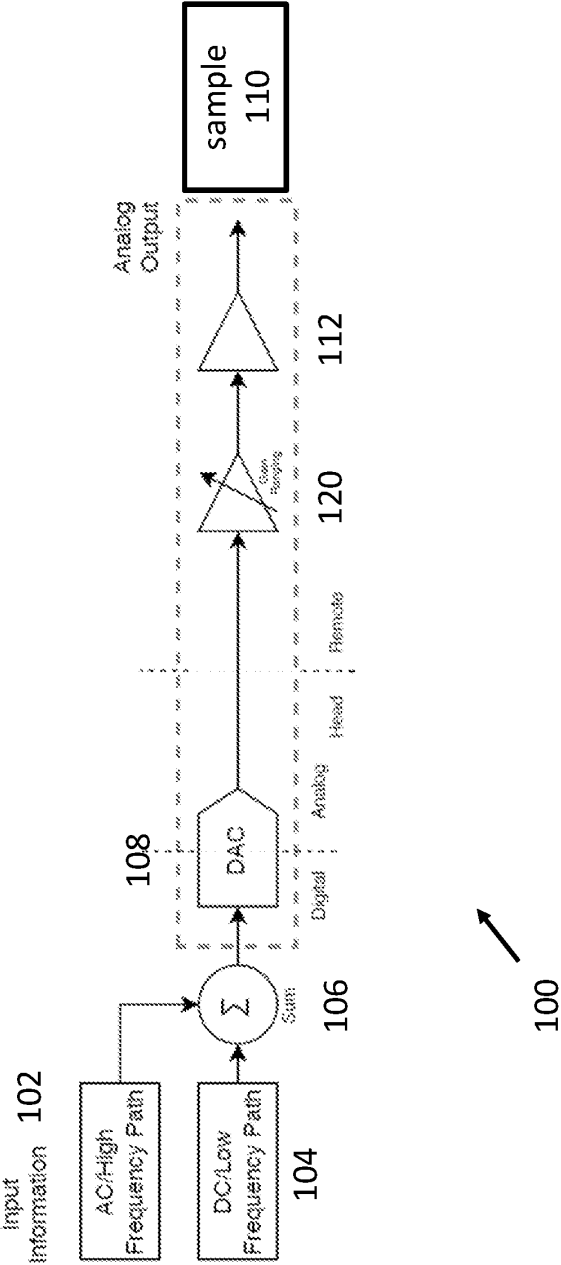


FIG. 1A

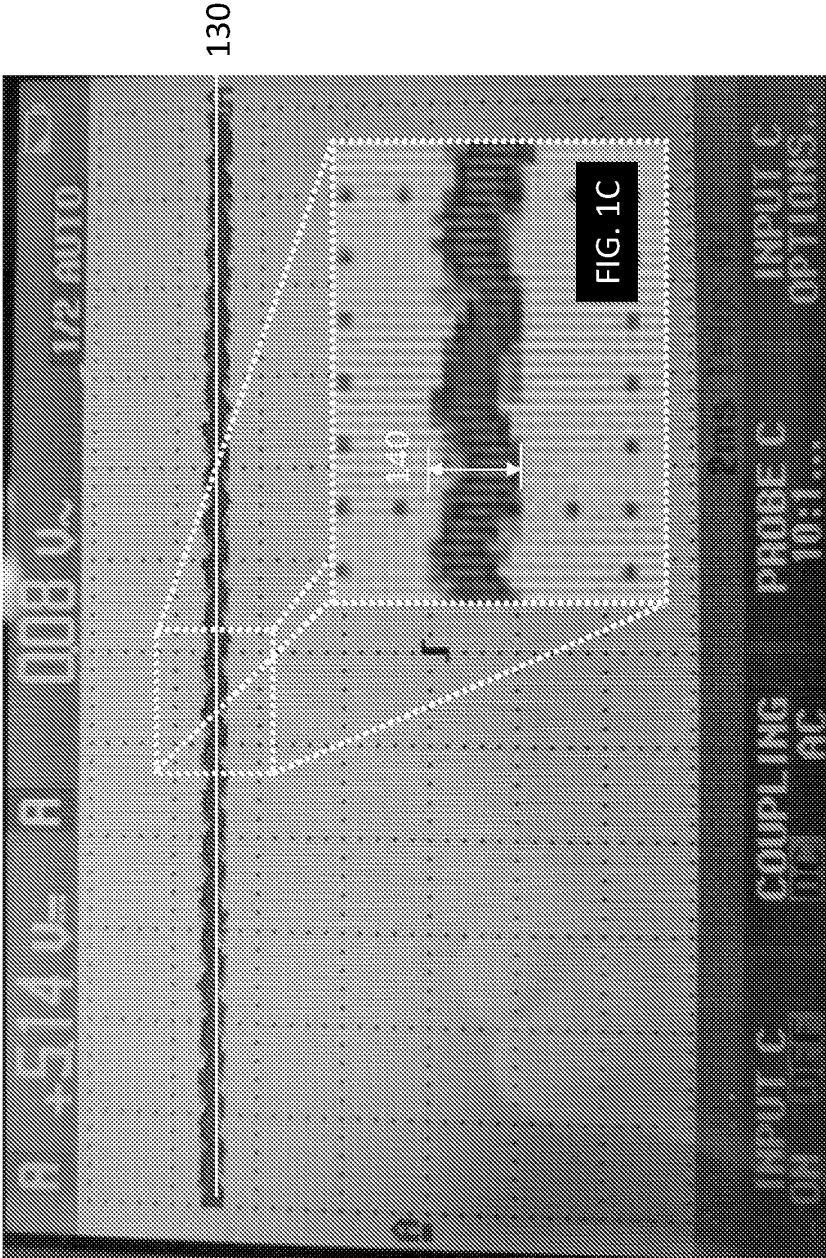


FIG. 1B

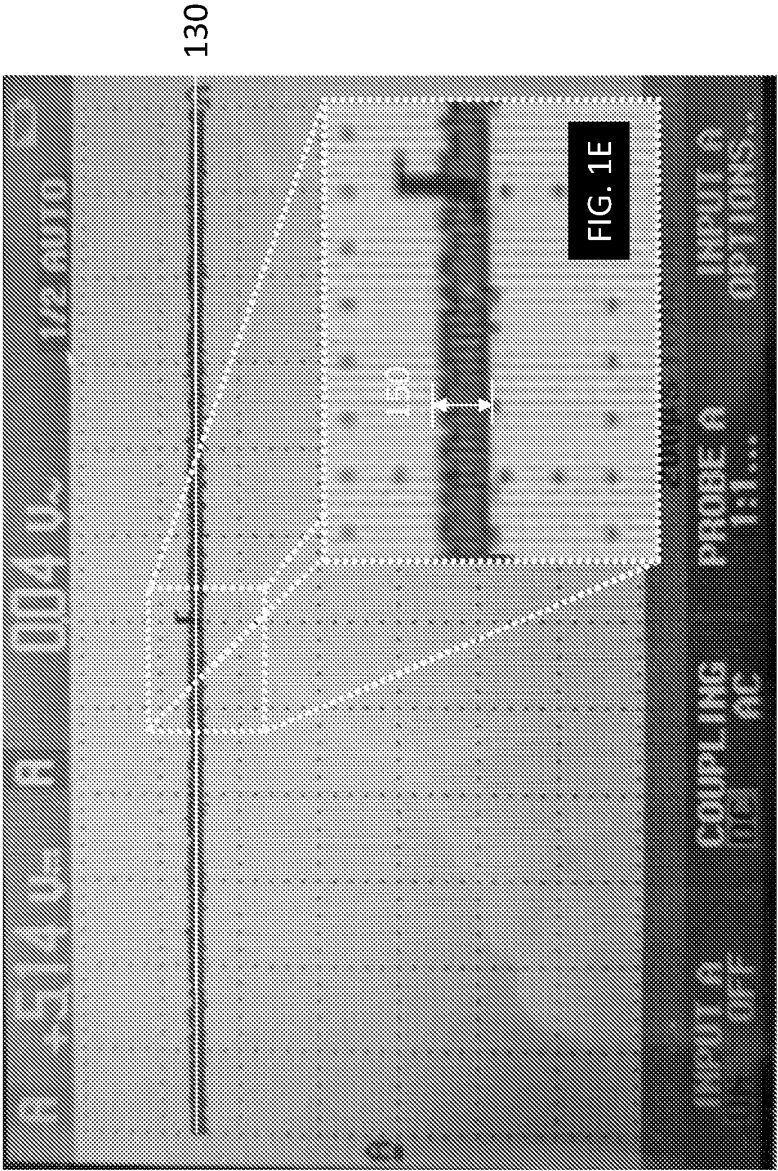


FIG. 1D

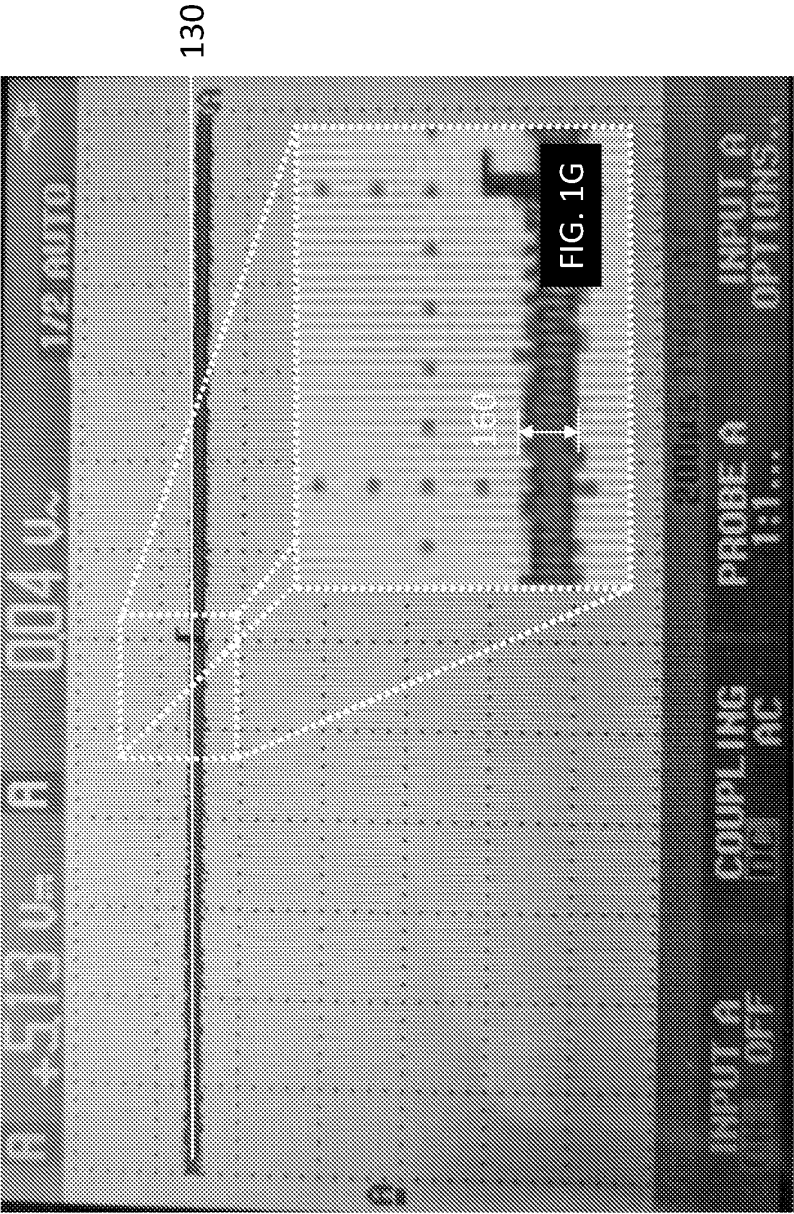


FIG. 1F

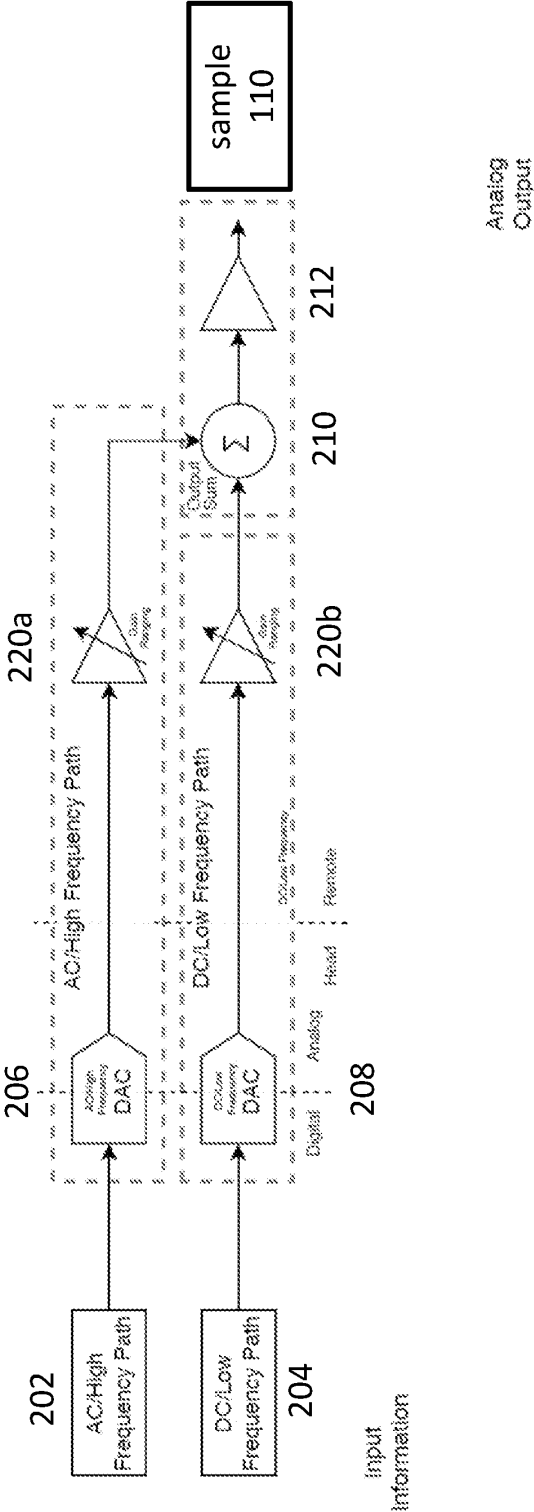


FIG. 2

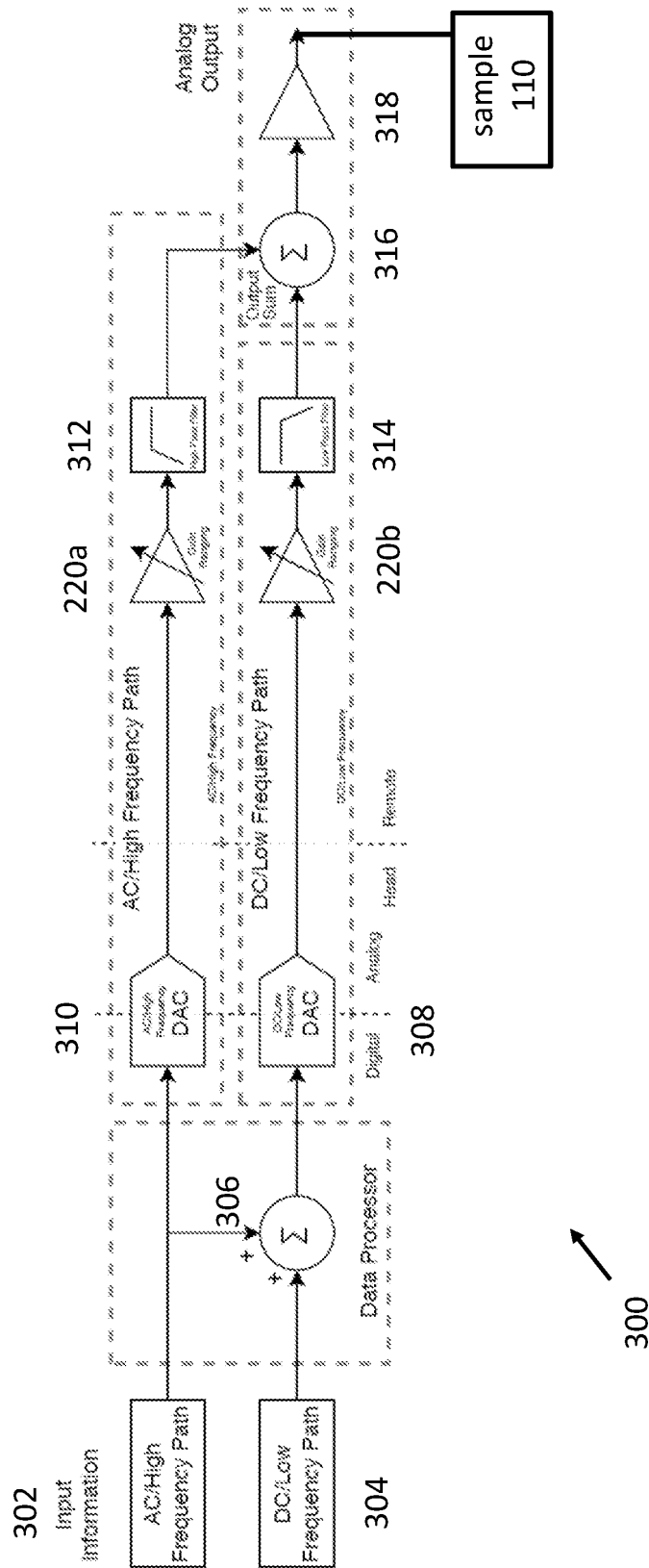


FIG. 3

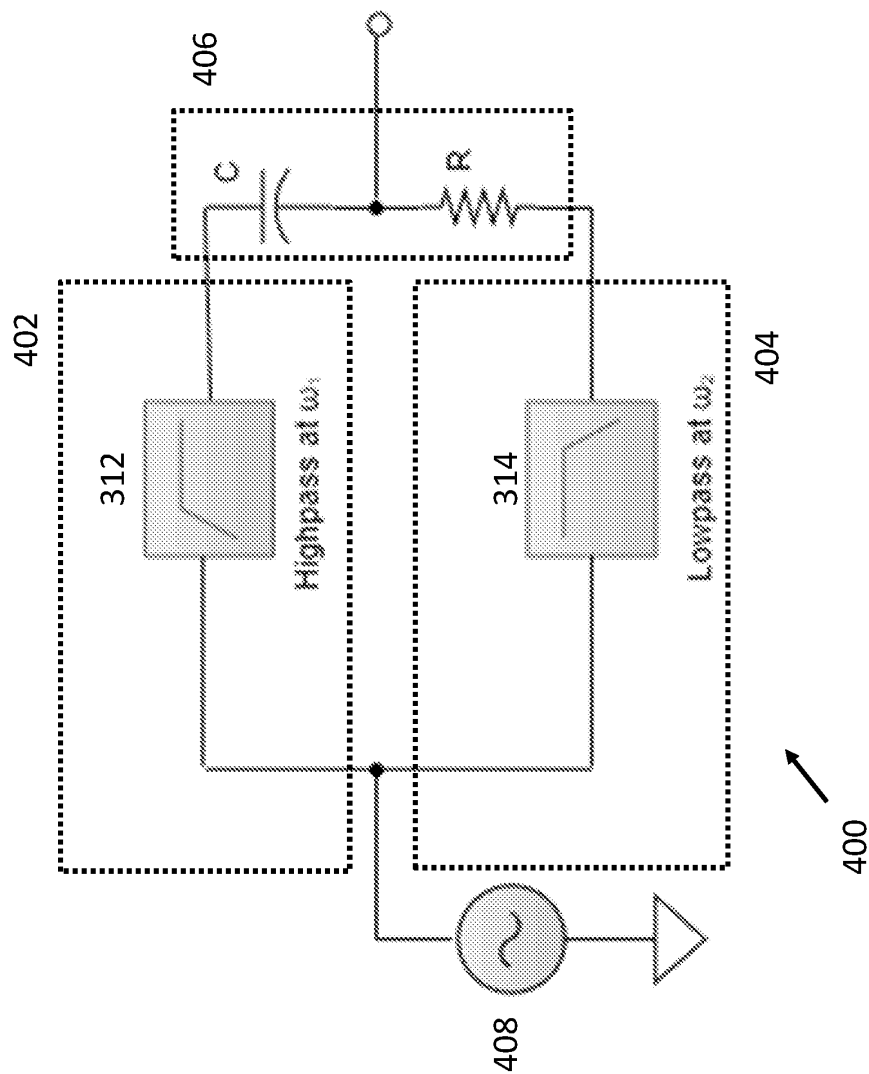


FIG. 4

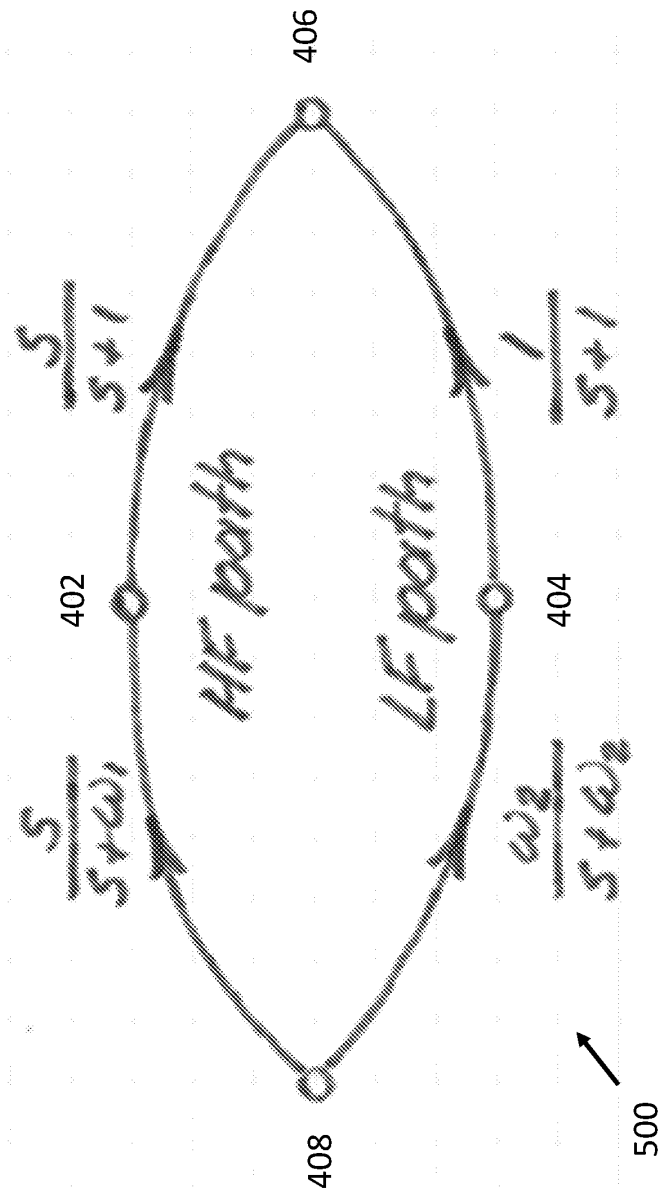


FIG. 5

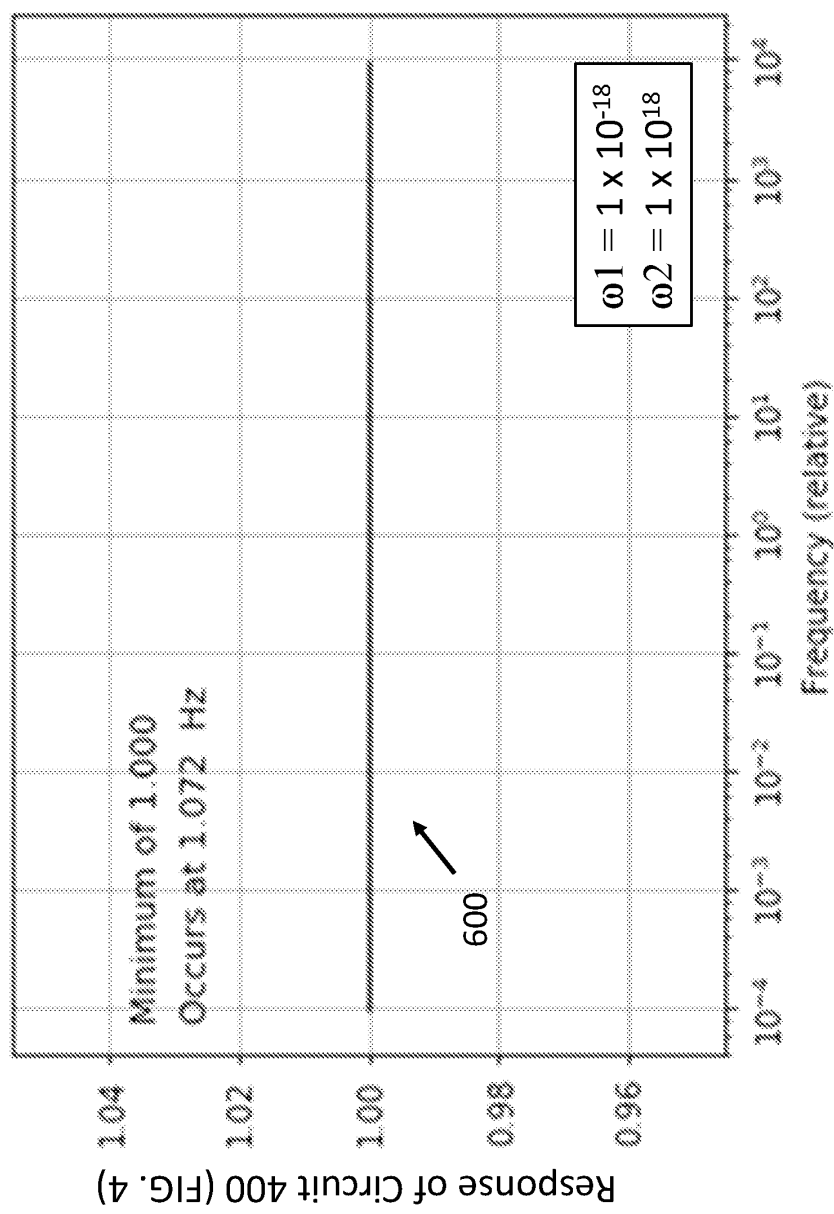


FIG. 6

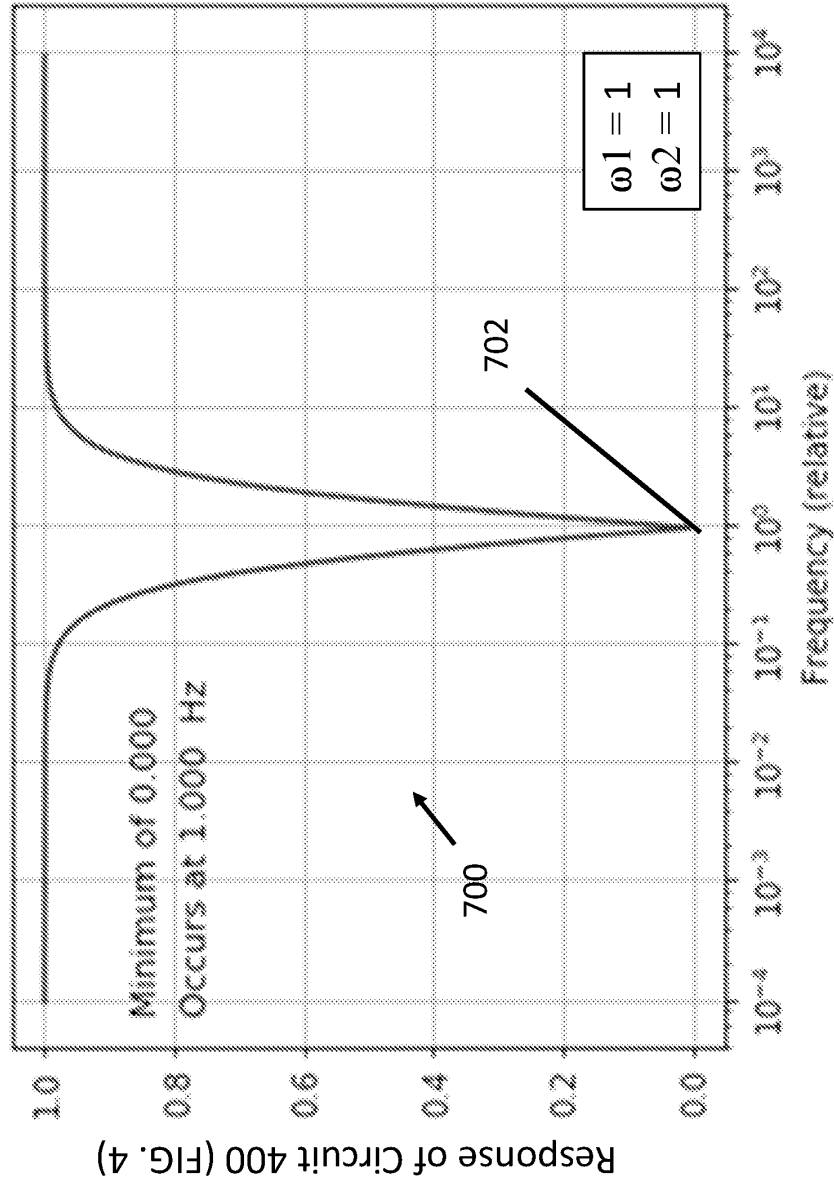


FIG. 7

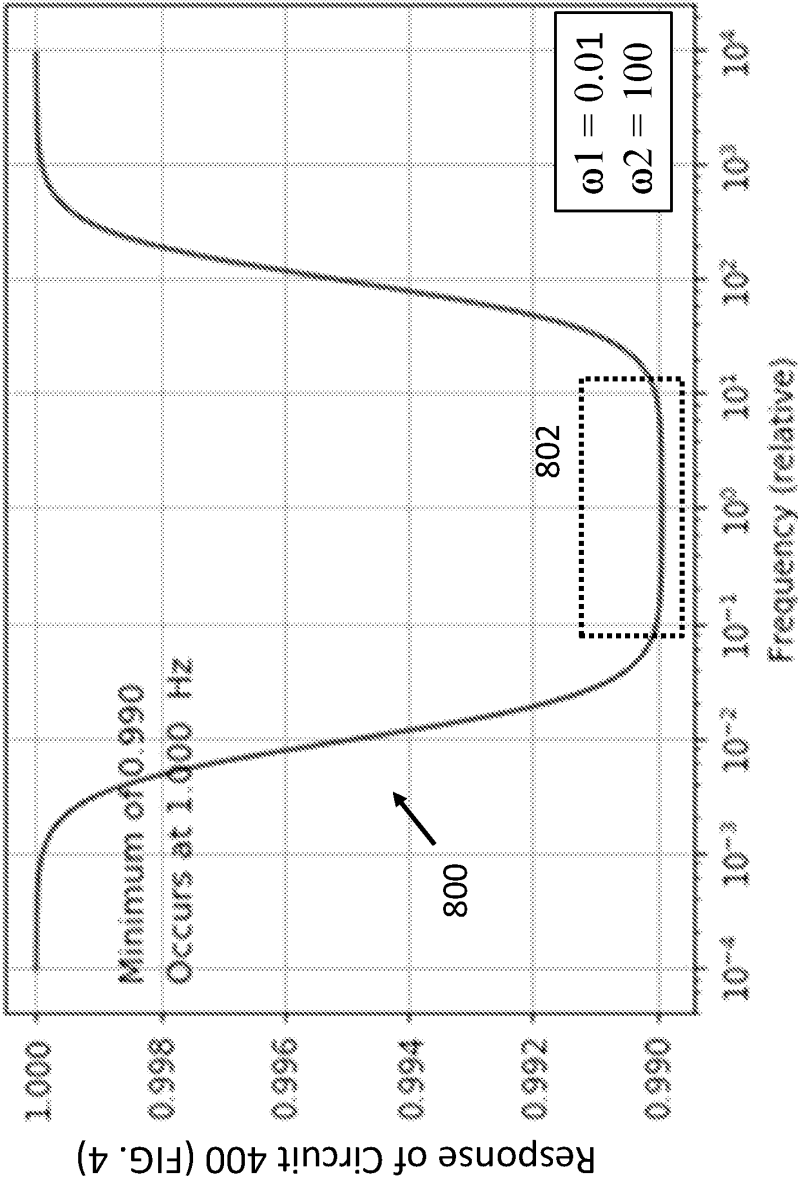


FIG. 8

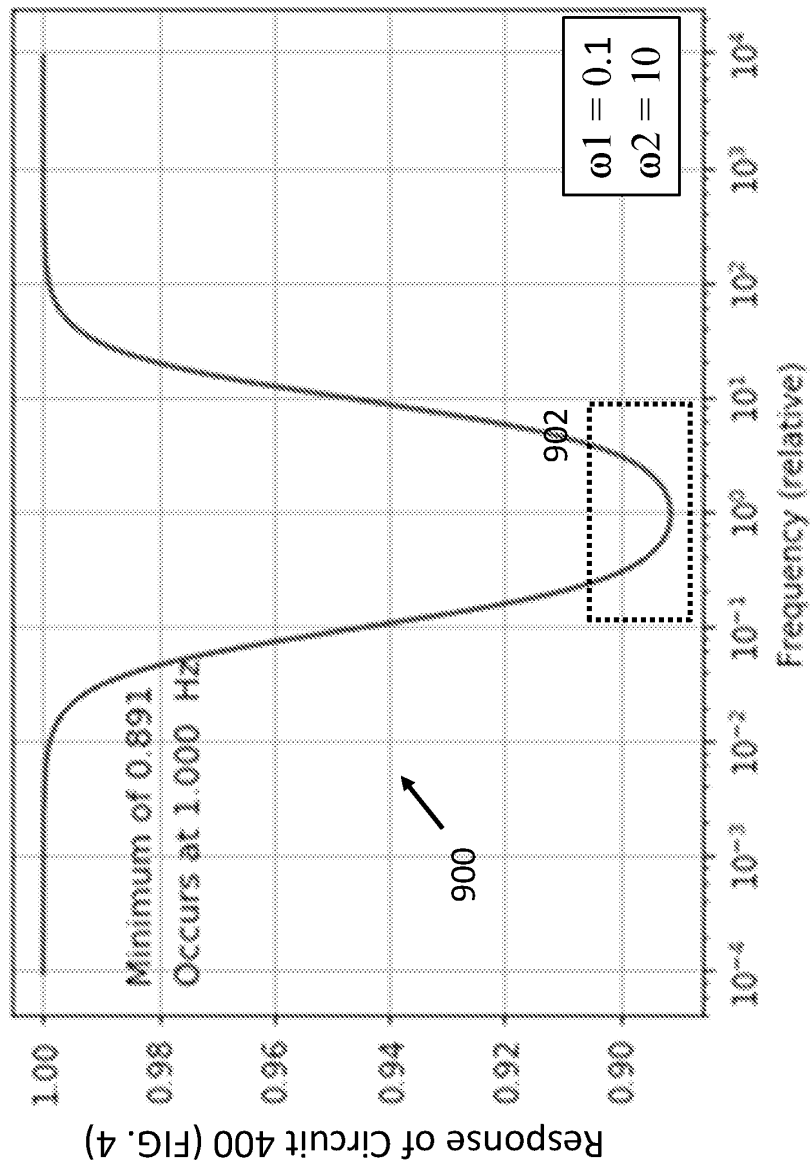


FIG. 9

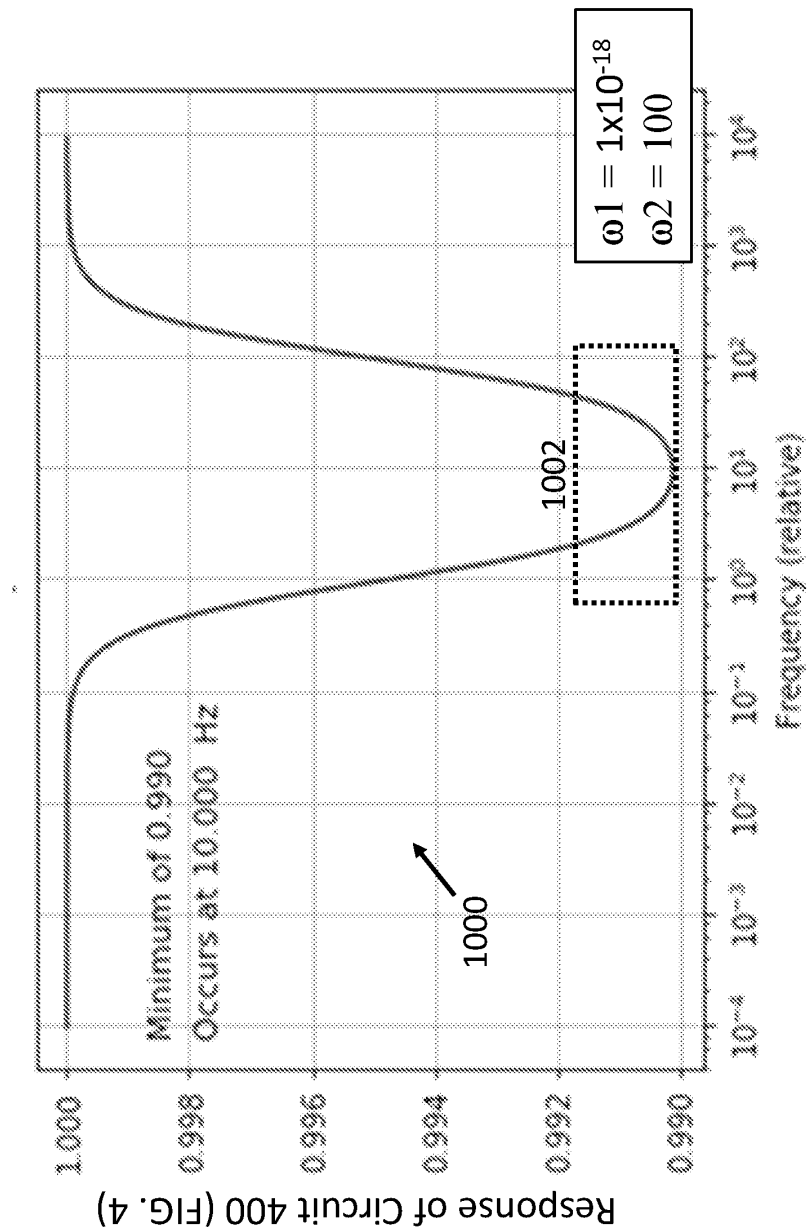


FIG. 10

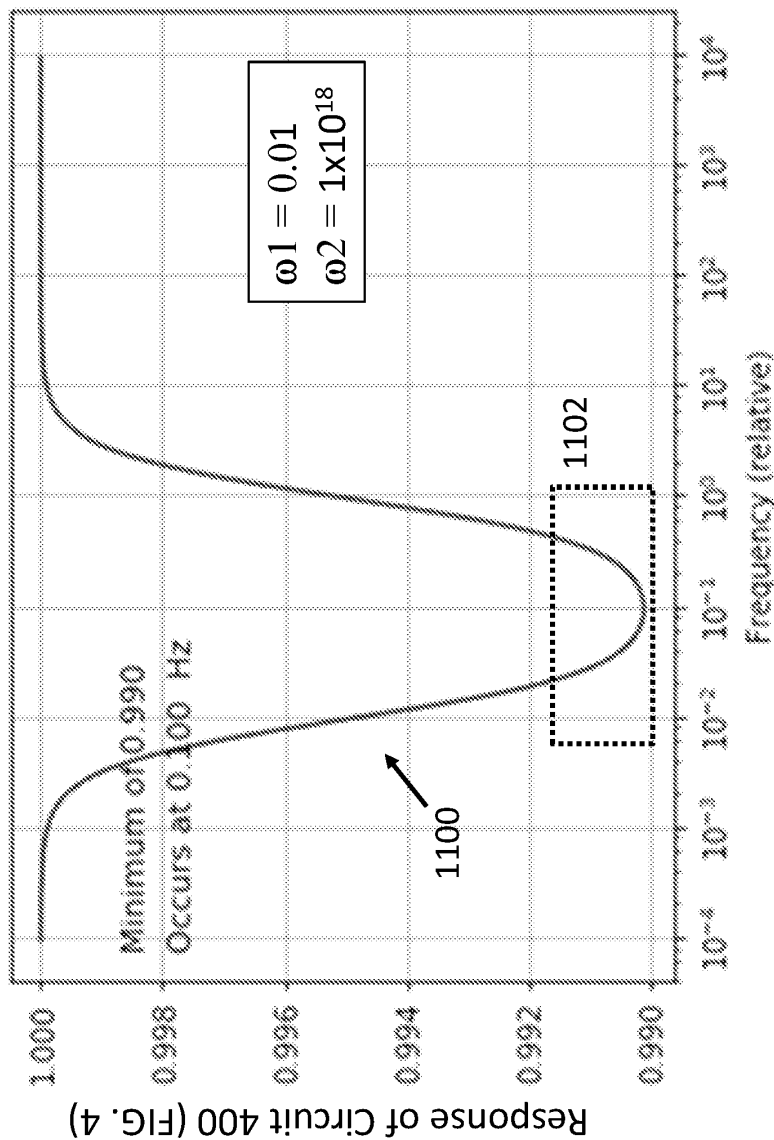


FIG. 11

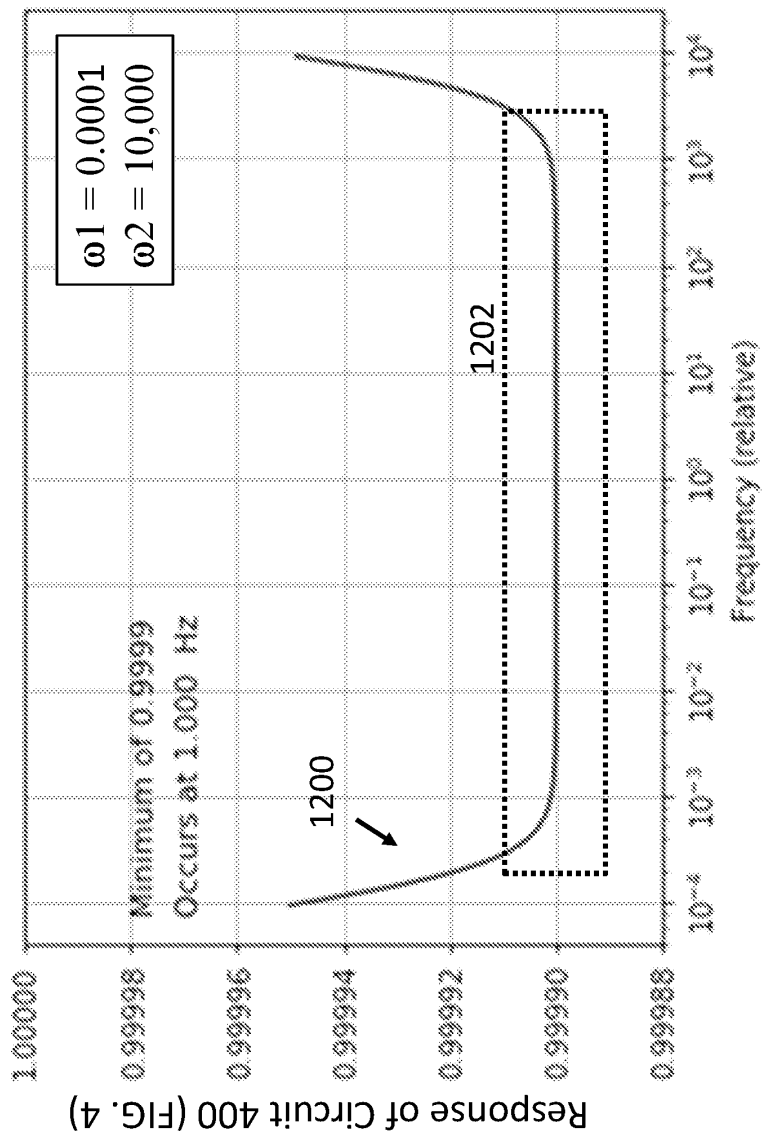


FIG. 12

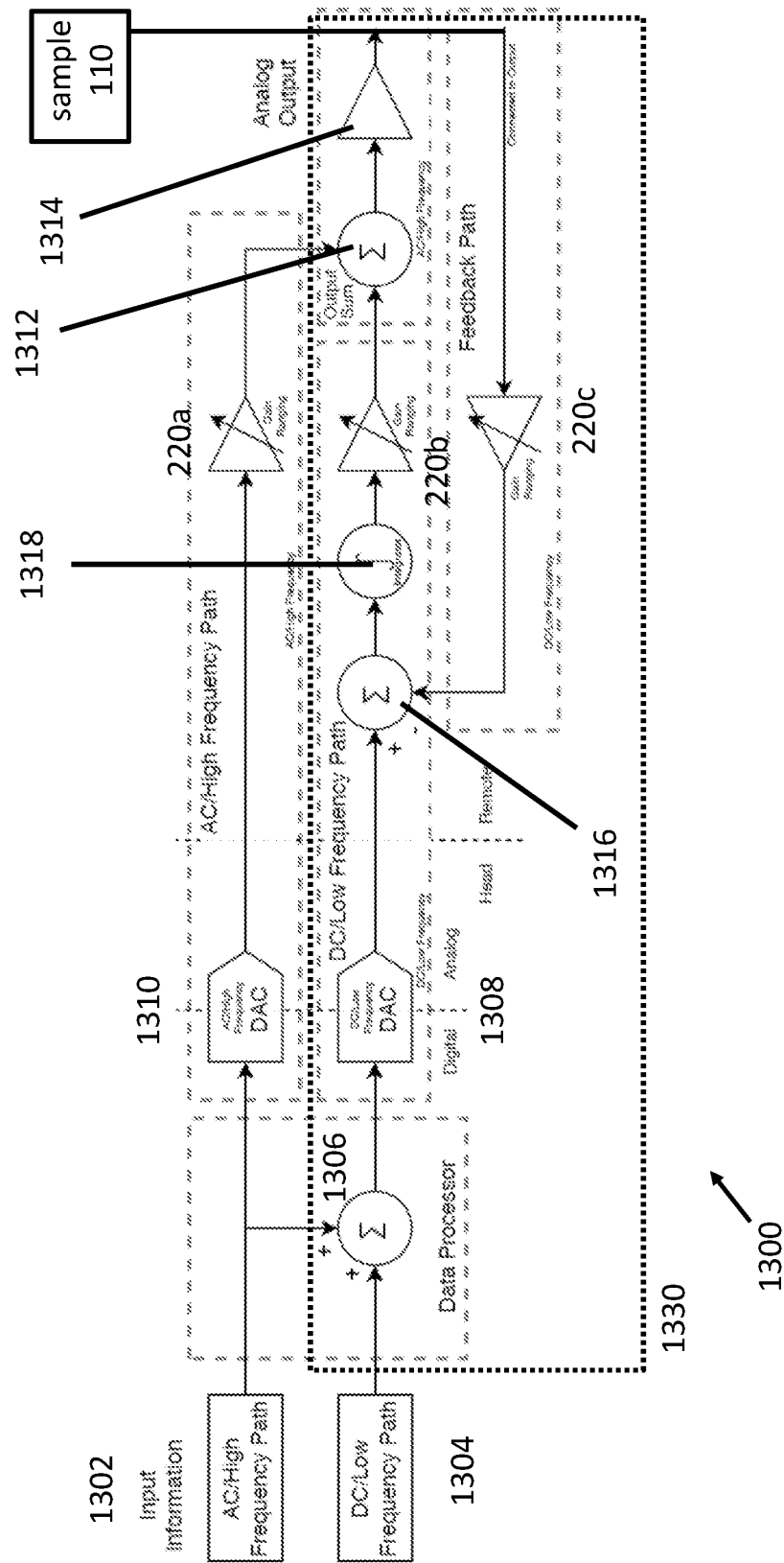


FIG. 13

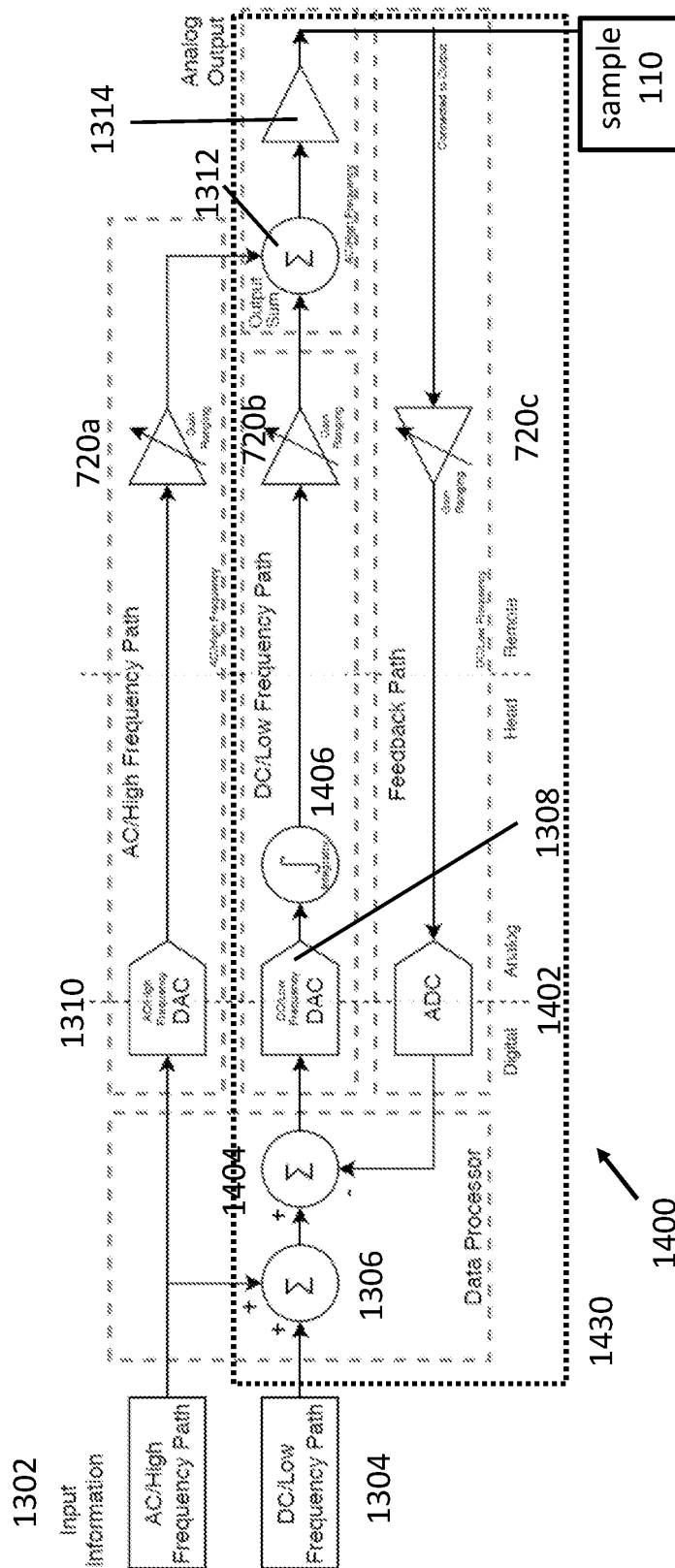


FIG. 14

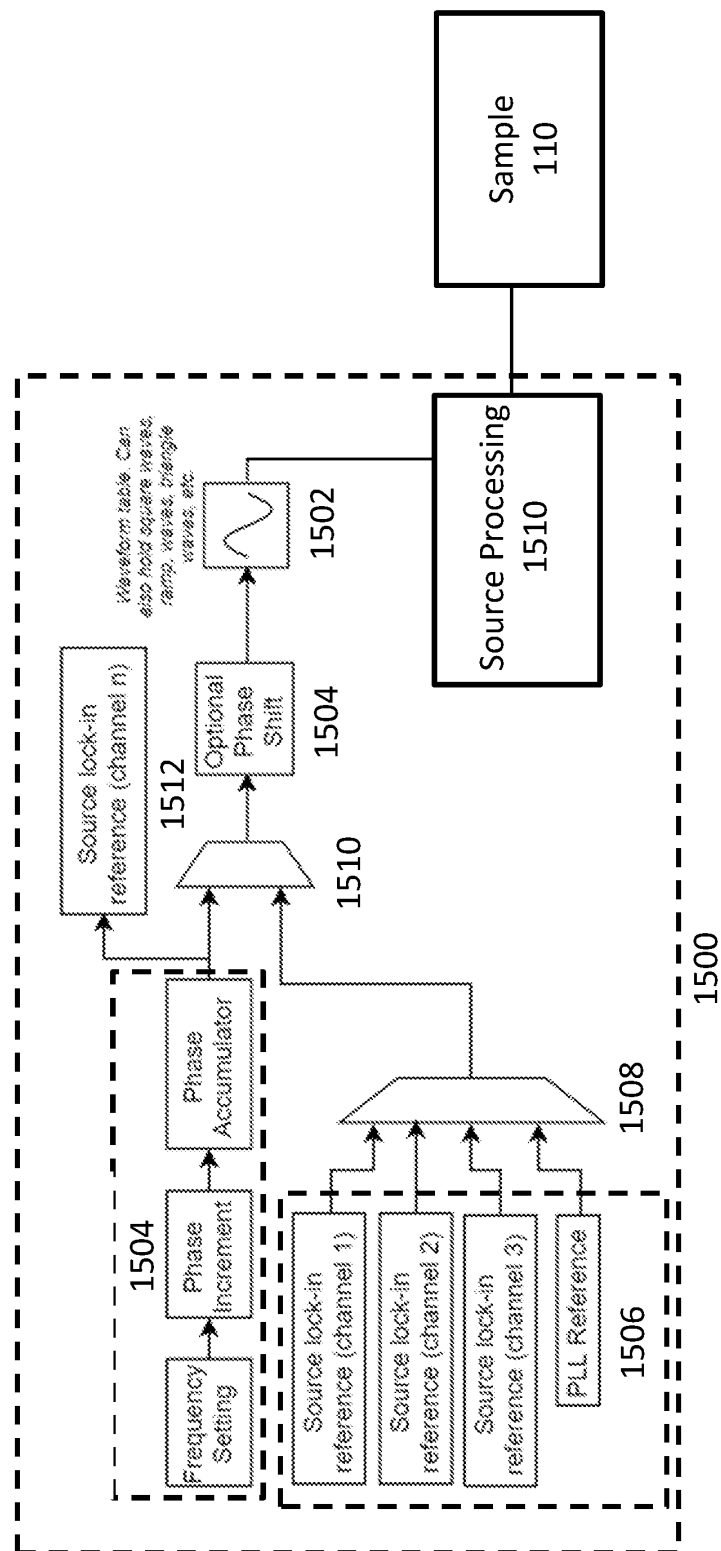


FIG. 15

1600

| Position | Output |
|----------|--------|
| 0        | 0.000  |
| 1        | 0.500  |
| 2        | 0.866  |
| 3        | 1.000  |
| 4        | 0.866  |
| 5        | 0.500  |
| 6        | 0.000  |
| 7        | -0.500 |
| 8        | -0.866 |
| 9        | -1.000 |
| 10       | -0.866 |
| 11       | -0.500 |

FIG. 16

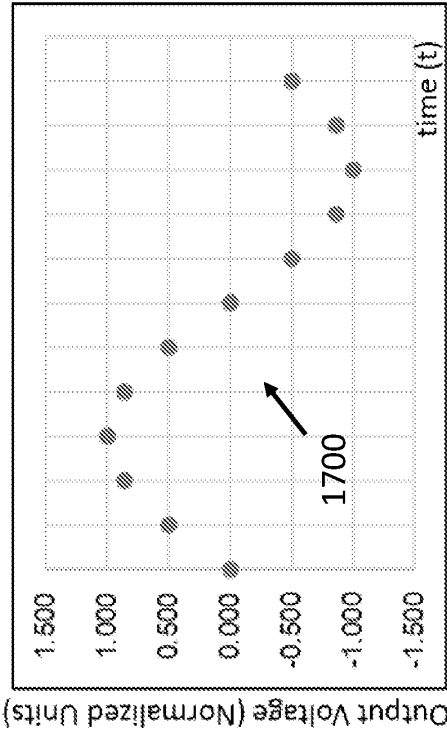
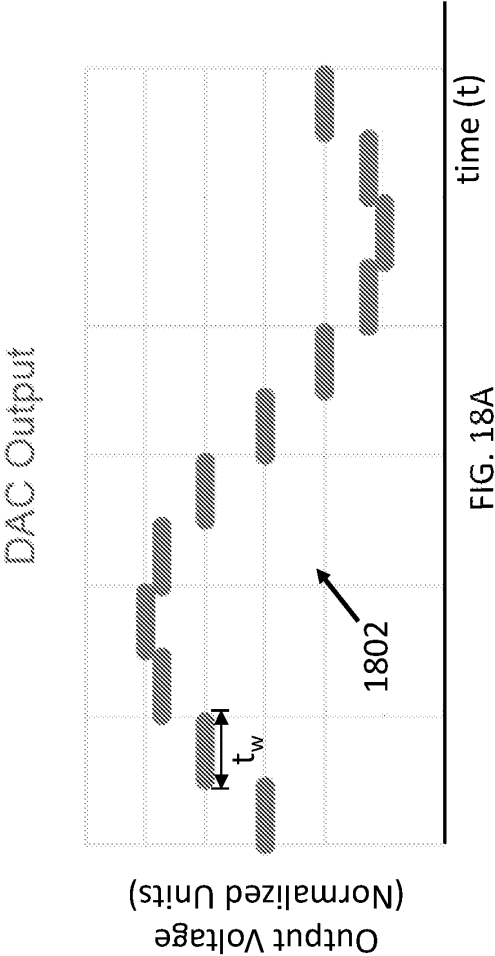
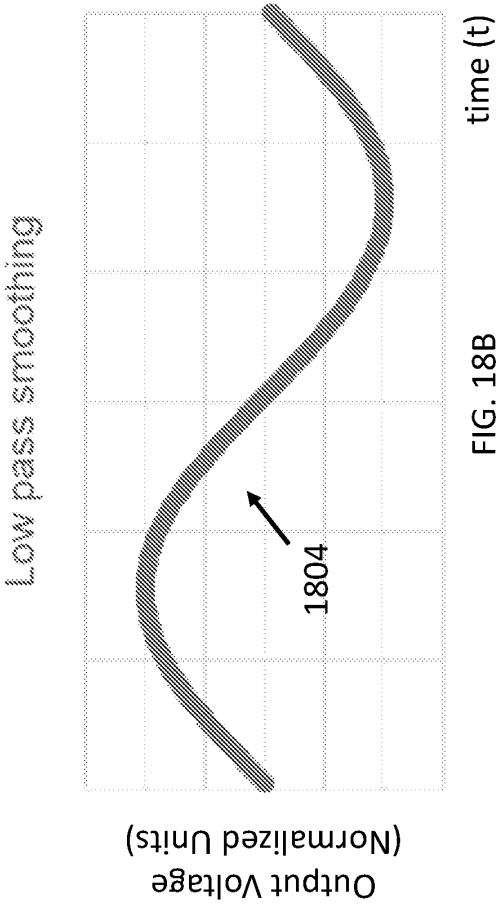


FIG. 17





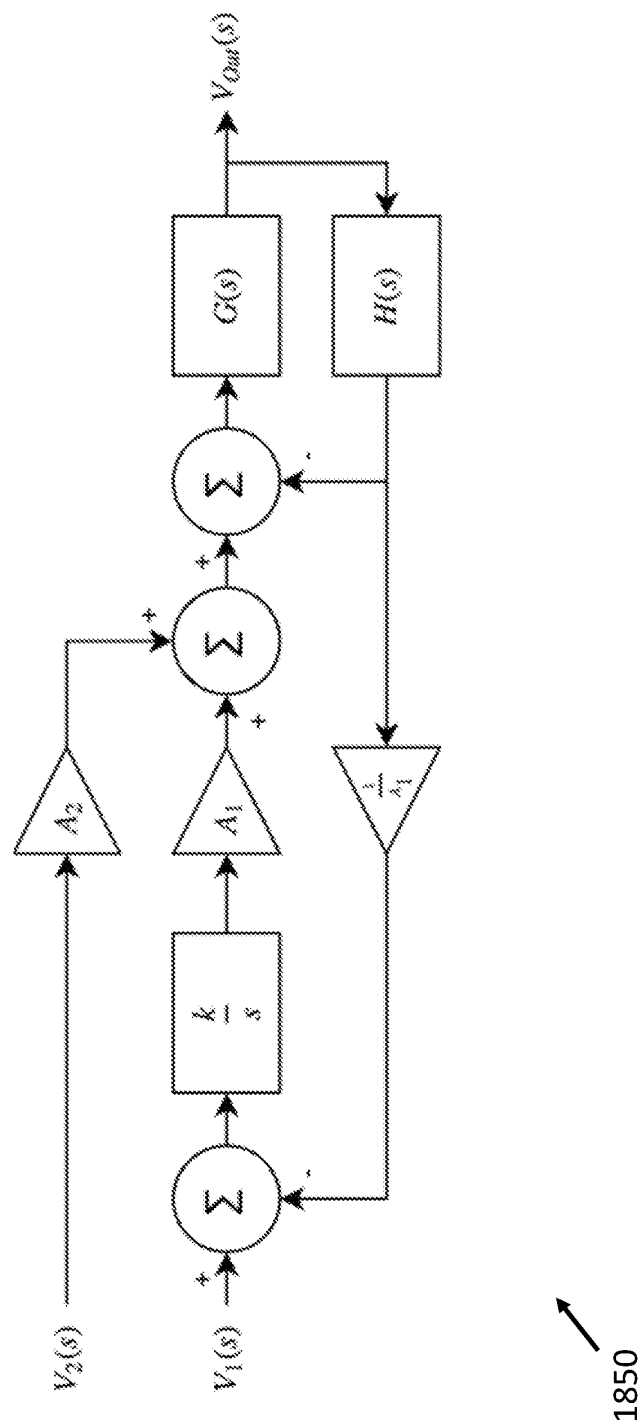


FIG. 18C

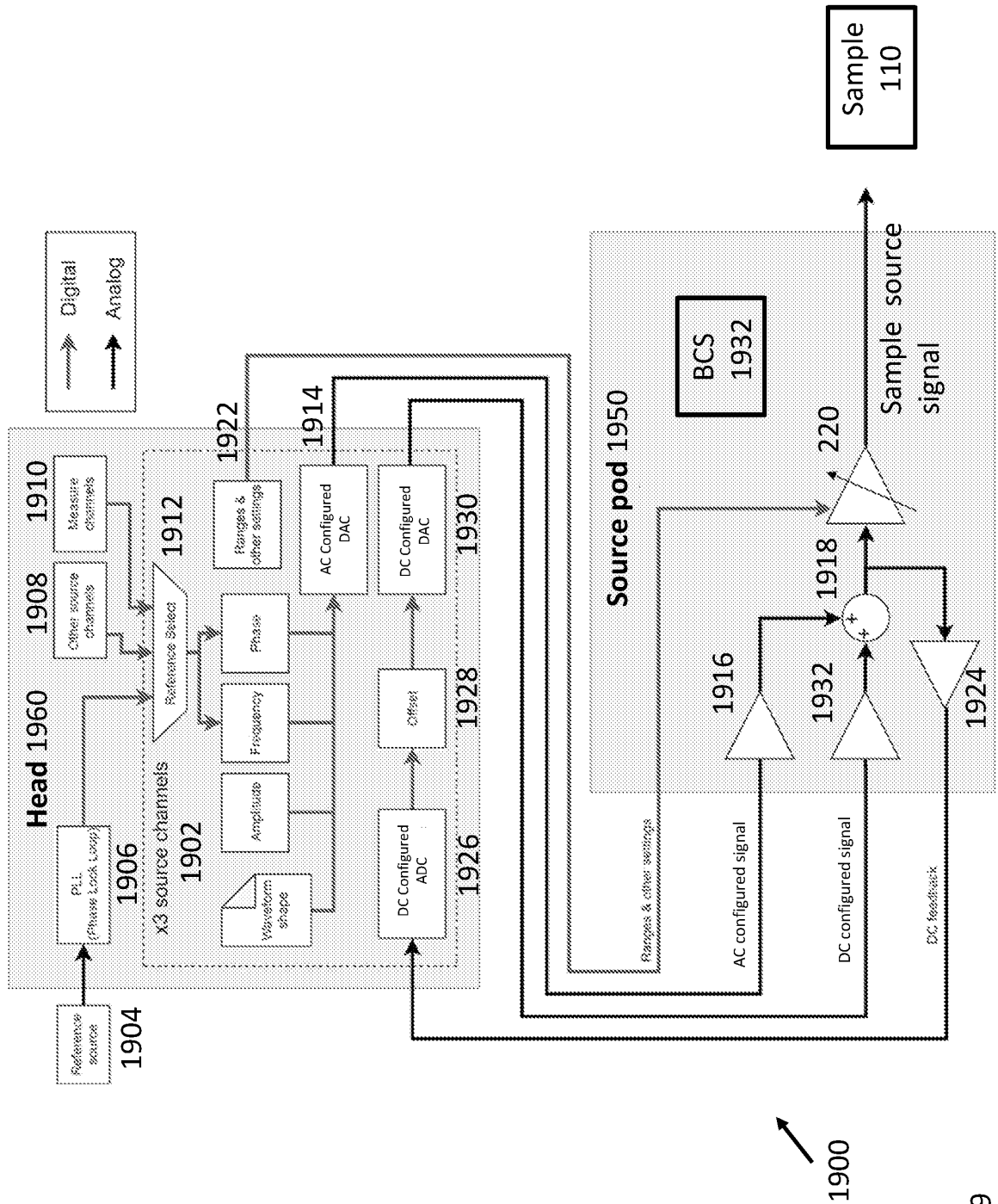


FIG. 19

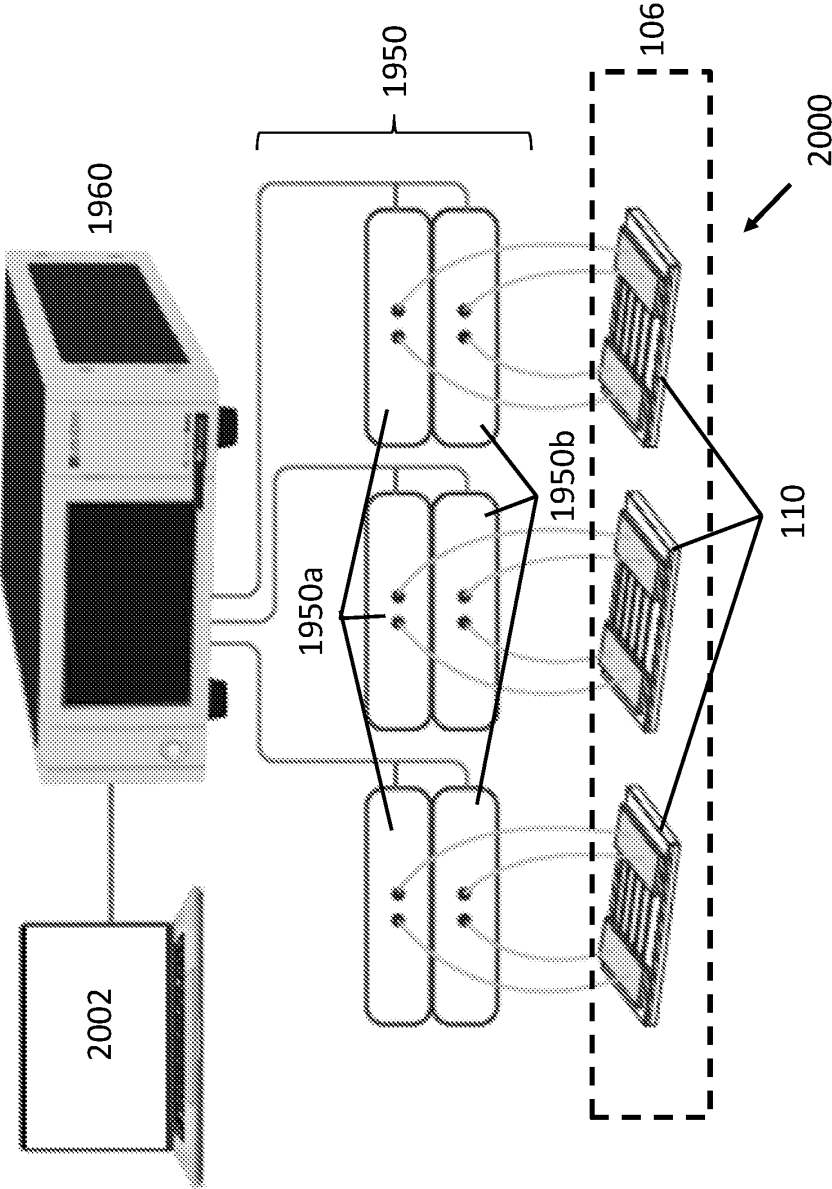


FIG. 20