WHAT IS CLAIMED IS:

1. A handler, comprising:

a boom mount configured to be coupled to a boom;

a clamp mounting structure coupled to the boom mount and having a central portion and a first arm and a second arm, each arm extending from the central portion;

a first clamp coupled to the first arm and comprising a first set of actuatable tongs and a first saddle plate having a first arcuate surface, the first arcuate surface having a first radius corresponding to a first cylindrical body having a first diameter; and

a second clamp coupled to the second arm and comprising a second set of actuatable tongs and a second saddle plate having a second arcuate surface, the second arcuate surface having a second radius corresponding to a second cylindrical body having a second diameter, wherein the first diameter is greater than the second diameter and the first arcuate surface and the second arcuate surface are disposed to hold the first cylindrical body in coaxial alignment with the second cylindrical body.

2. The handler of claim 1 wherein the clamp mounting structure has a first axis of rotation with respect to the boom mount and a second axis of rotation with respect to the boom mount.

3. The handler of claim 2 wherein the first axis of rotation is orthogonal to the second axis of rotation.

4. The handler of claim 2 wherein the clamp mounting structure is rotatable at least 360 degrees with respect to the first axis of rotation and rotatable at least 360 degrees with respect to the second axis of rotation.

5. The handler of claim 1 wherein the boom is part of an excavator and hydraulic fluid to actuate the first and second set of actuatable tongs is supplied by a hydraulic system of the excavator.

6. The handler of claim 1 wherein the clamp mounting structure is rotatable about a first axis of rotation with respect to the boom mount and is rotatable about a second axis of rotation with respect to the boom mount, and further comprising a first motor operable to rotate the clamp mounting structure with respect to the first axis of rotation and a second motor operable to rotate the clamp mounting structure with respect to the second axis of rotation.

7. The handler of claim 6 wherein rotation of the clamp mounting structure about the first and second axes of rotation is facilitated by worm drive gear arrangements.

8. The handler of claim 1 wherein the first saddle plate comprises a pair of first removable saddle plates and the second saddle plate comprises a pair of second removable saddle plates.

9. The handler of claim 8 wherein the first set of actuatable tongs is disposed between the pair of first removable saddle plates and the second set of actuatable tongs is disposed between the pair of second removable saddle plates.

10. The handler of claim 1 wherein the first set of actuatable tongs is operable to actuate independently of the second set of actuatable tongs.

11. The handler of claim 1 wherein the first arm includes a telescoping member configured to adjust a distance between the first clamp and the second clamp.

12. The handler of claim 1 wherein the first arcuate surface is disposed with respect to the second arcuate surface such that seating the first cylindrical body in the first arcuate surface and seating the second cylindrical body in the second arcuate surface disposes the first cylindrical body coaxially aligned with the second cylindrical body.

13. The handler of claim 1 wherein the first arcuate surface is disposed with respect to the second arcuate surface such that when the first arcuate surface is in full contact with the first cylindrical body and the second arcuate surface is in full contact with the second cylindrical body, the first cylindrical body will be coaxially aligned with the second cylindrical body.

14. A handler, comprising:

an excavator mount configured to be coupled to a boom of an excavator;

a clamp support structure coupled to the excavator mount and having a central portion and a first arm and a second arm each arm extending from the central portion;

a first clamp coupled to the first arm comprising a first set of hydraulically actuated tongs and a pair of first saddle plates, and the first saddle plates each having a first arcuate surface, each of the first arcuate surfaces having a first radius corresponding to a first cylindrical body having a first diameter;

a second clamp coupled to the second arm comprising a second set of hydraulically actuated tongs and a pair of second saddle plates, and the second saddle plates each having a second arcuate surface, each of the second arcuate surfaces having a second radius

corresponding to a second cylindrical body having a second diameter, wherein the first diameter is greater than the second diameter; and

wherein the first clamp is operable to grip the first diameter cylindrical body and the second clamp is operable to grip the second diameter cylindrical body simultaneously with the first clamp gripping the first diameter cylindrical body and with the first and second diameter cylindrical bodies being coaxially aligned.

15. The handler of claim 14 wherein the excavator supplies hydraulic fluid to actuate the first and second set of hydraulically actuated tongs.

16. The handler of claim 14 wherein the first set of hydraulically actuated tongs is disposed between the pair of first saddle plates and the second set of hydraulically actuated tongs is disposed between the pair of second saddle plates.

17. The handler of claim 14 wherein the clamp support structure is rotatable at least 360 degrees about a first axis of rotation with respect to the excavator mount and is rotatable at least 360 degrees about a second axis of rotation with respect to the excavator mount, the second axis of rotation being orthogonal to the first axis of rotation, and further comprising a first motor operable to rotate the clamp support structure with respect to the first axis of rotation and a second motor operable to rotate the clamp support structure with respect to the second axis of rotation.

18. The handler of claim 14 wherein the first arm includes a telescoping member configured to adjust a distance between the first clamp and the second clamp.

19. The handler of claim 14 wherein the first diameter is greater than the second diameter and wherein the first arcuate surface is disposed with respect to the second arcuate surface such that when the first arcuate surface is in full contact with the first diameter cylindrical body and the second arcuate surface is in full contact with the second diameter cylindrical body, the first diameter cylindrical body will be coaxially aligned with the second diameter cylindrical body.

20. The handler of claim 14 wherein the pair of first saddle plates and the pair of second saddle plates are removable.

21. A handler, comprising:

an excavator mount configured to be coupled to a boom of an excavator;

a clamp support structure coupled to the excavator mount and having a central

portion and a first arm and a second arm each arm extending from the central portion;

a first clamp coupled to the first arm comprising a first set of hydraulically actuated tongs disposed between a pair of first saddle plates, and the first saddle plates each having a first arcuate surface, each of the first arcuate surfaces having a first radius corresponding to a first cylindrical body having a first diameter;

a second clamp coupled to the second arm comprising a second set of hydraulically actuated tongs disposed between a pair of second saddle plates, and the second saddle plates each having a second arcuate surface, each of the second arcuate surfaces having a second radius corresponding to a second cylindrical body having a second diameter, wherein the first diameter is greater than the second diameter;

a first motor operable to rotate the clamp support structure about a first axis of rotation with respect to the excavator mount; and

a second motor operable to rotate the clamp support structure with respect to a second axis of rotation with respect to the excavator mount, the second axis of rotation being orthogonal to the first axis of rotation;

wherein the first arcuate surface is disposed with respect to the second arcuate surface such that when the first arcuate surface is in full contact with the first cylindrical body and the second arcuate surface is in full contact with the second cylindrical body, the first cylindrical body will be coaxially aligned with the second cylindrical body.

22. The handler of claim 21 wherein rotation of the clamp support structure about the first and second axes of rotation is facilitated by worm drive gear arrangements.

23. The handler of claim 21 wherein the pair of first saddle plates and the pair of second saddle plates are removable.