

CONTROL METHOD FOR CLEANING ROBOT

ABSTRACT

The present disclosure provides a control method for cleaning robot, the method comprises: in case where a wet cleaning assembly performs a cleaning task on the operating surface at least in a mopping state, the cleaning robot is being hijacked and the time of being hijacked is greater than a preset time, the wet cleaning assembly changes from the mopping state to a mop folding state, wherein the being hijacked means that the cleaning robot leaves the operating surface; the cleaning robot quits being hijacked and continues to perform the cleaning task, in case where the operating surface is a floor or ceramic tile, the cleaning assembly switches from the mop folding state to the mopping state; in case where the operating surface is a carpet, the cleaning assembly remains in the mop folding state, the mopping state means that the mop is in the state of being released.

FIG. 1