ABSTRACT

Provided is a method for controlling virtual robots. The method includes: starting a plurality of virtual robots constructed by using a finite state machine, wherein the virtual robots are configured to simulate, in a plurality of loops, a user operating an application program, and the finite state machine comprises a plurality of states, a plurality of events occurring at the plurality of states, and actions triggered by the plurality of events; determining, in each loop, a view in which the virtual robots are located in the application program, and determining the view as the state; simulating, in each loop, the user to select a service in the view, and determining the selected service as the event; and driving, in each loop, the virtual robots to execute, in the view, a user operation configured to trigger the service, and determining the user operation as the action.

Fig. 1