

ABSTRACT

A smart logistics vehicle control method and control device is proposed, the method comprising: identifying a mission situation of a smart logistics vehicle; on the basis of map information in which different route selection-based scores are assigned to at least some virtual lanes within an operation boundary for each mission situation, determining a driving route so that the smart logistics vehicle moves along a virtual lane corresponding to the identified mission situation on the basis of a route selection-based score corresponding to the identified mission situation; and transmitting route information corresponding to the determined driving route to the smart logistics vehicle.

FIG. 6