

FIG. 1A

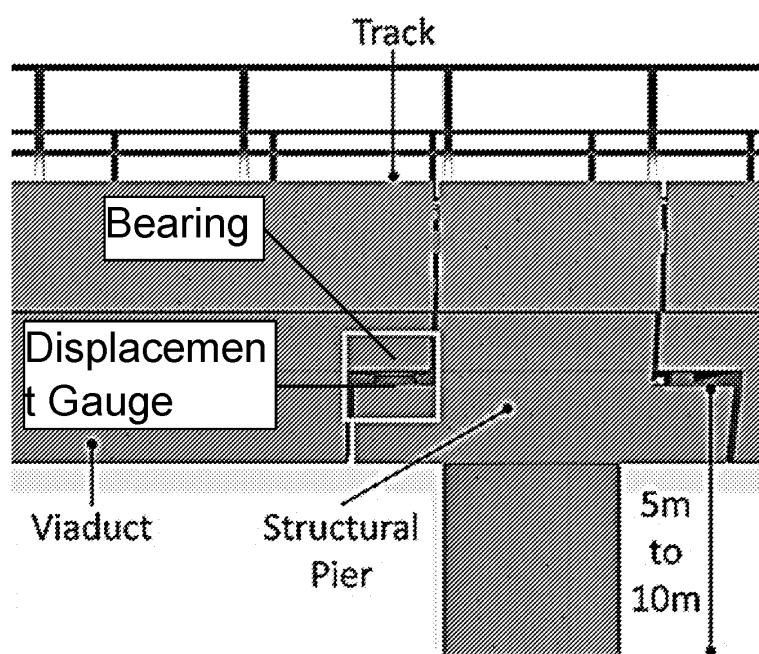


FIG. 1B

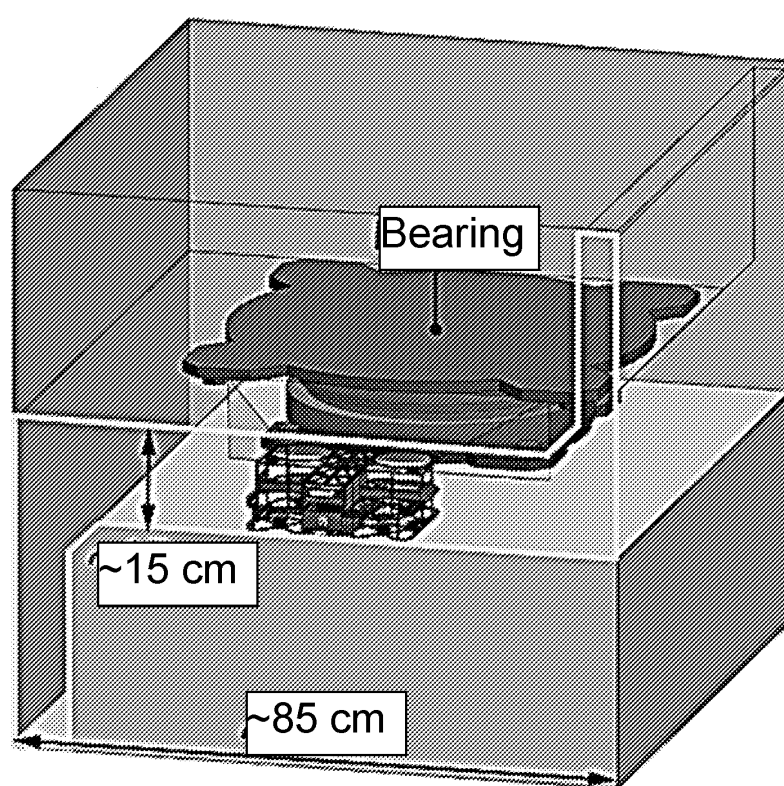


FIG. 2

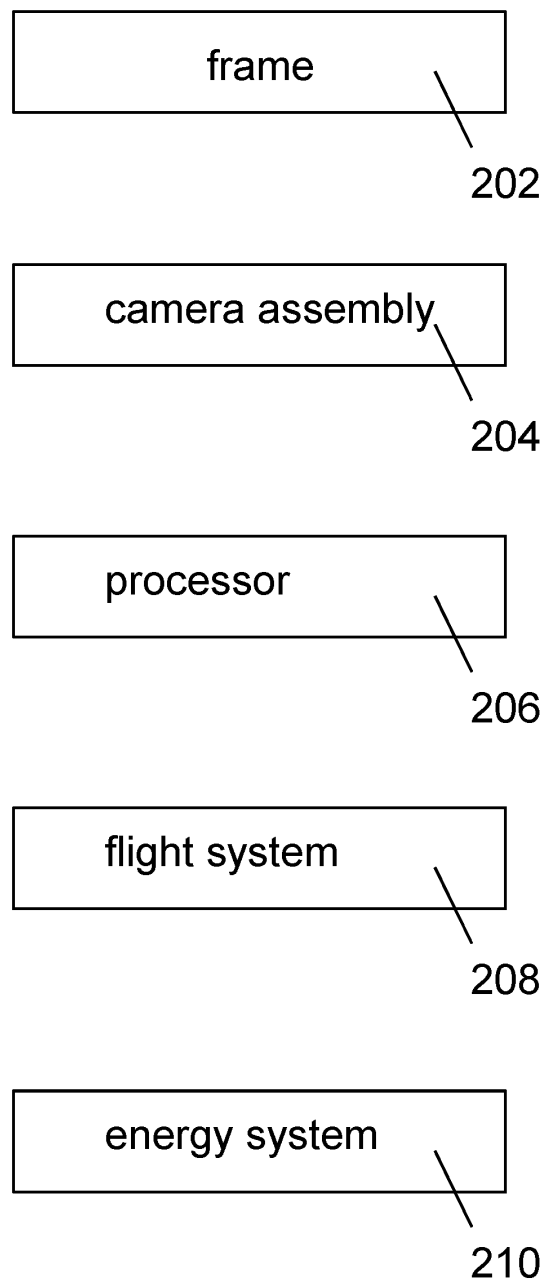


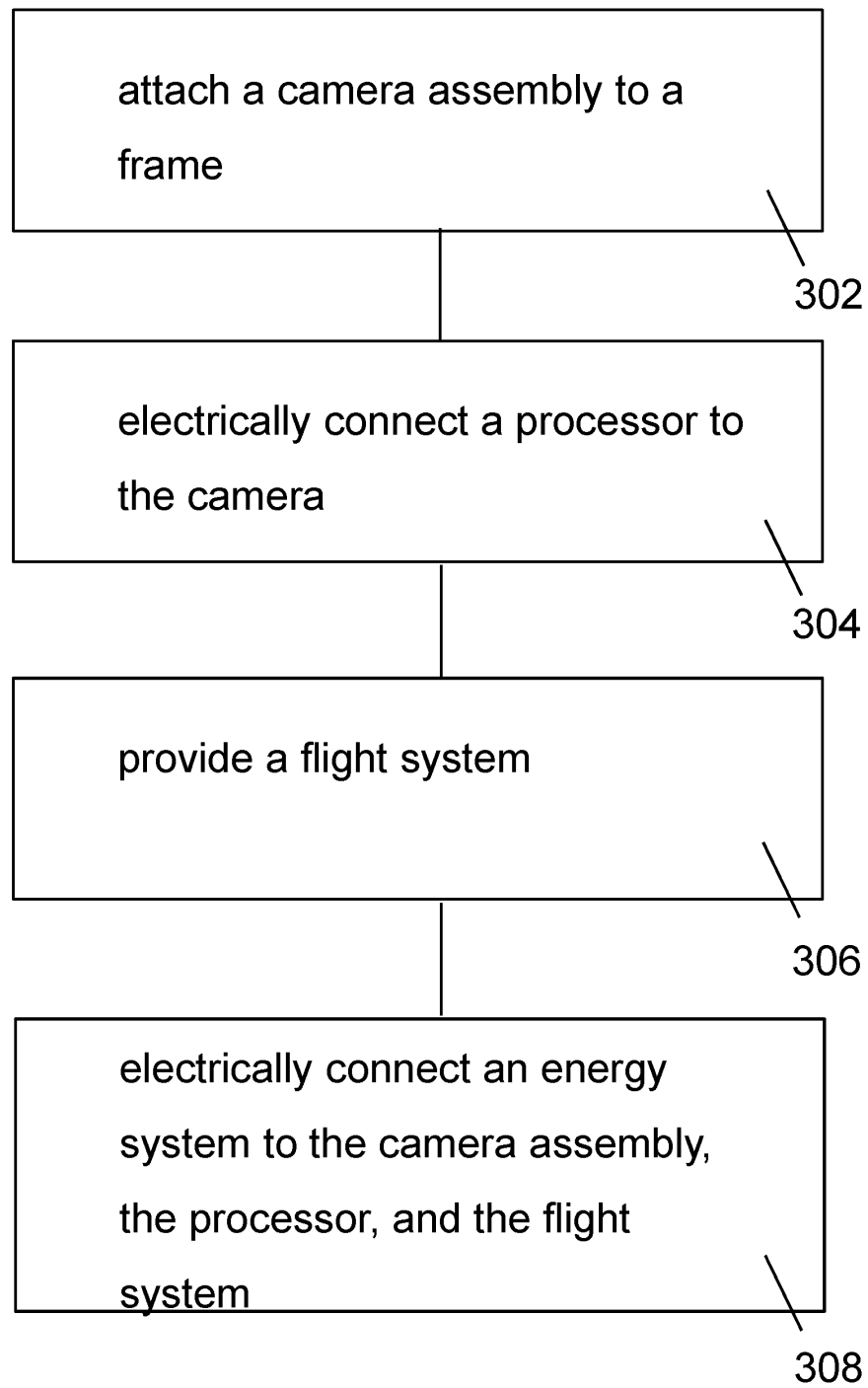
FIG. 3

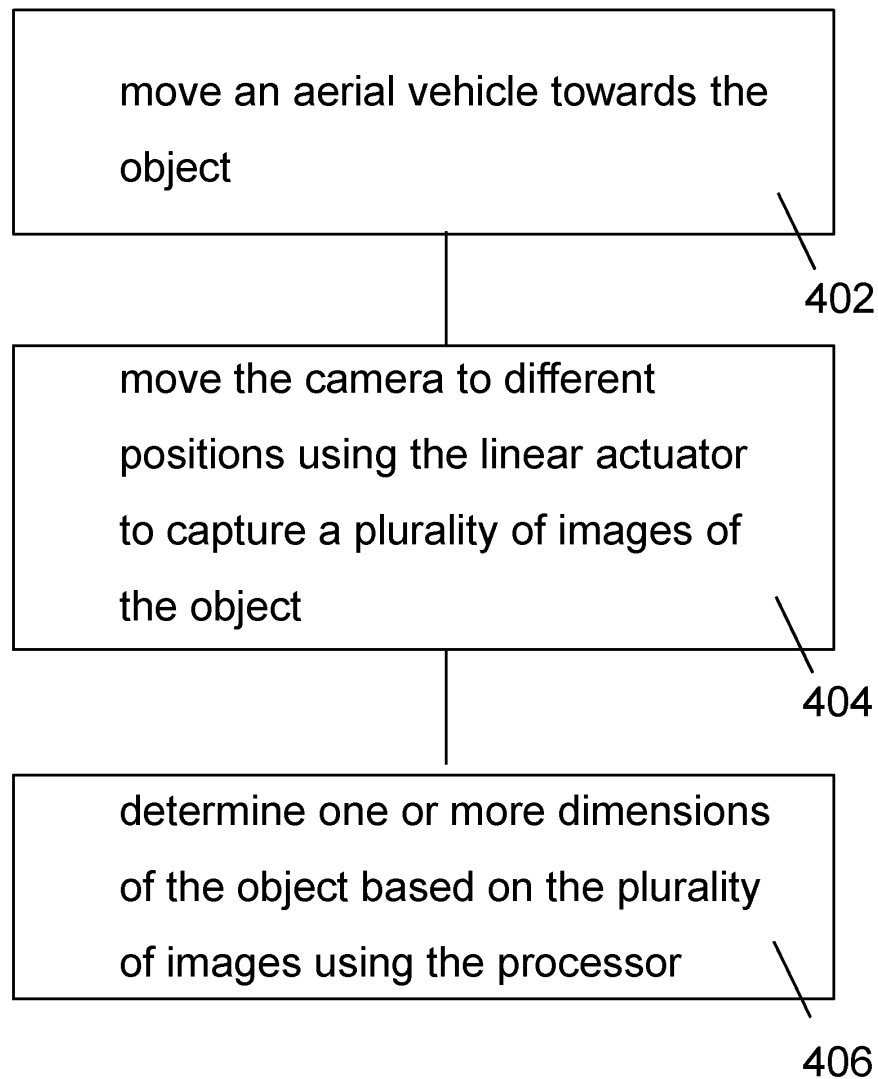
FIG. 4

FIG. 5

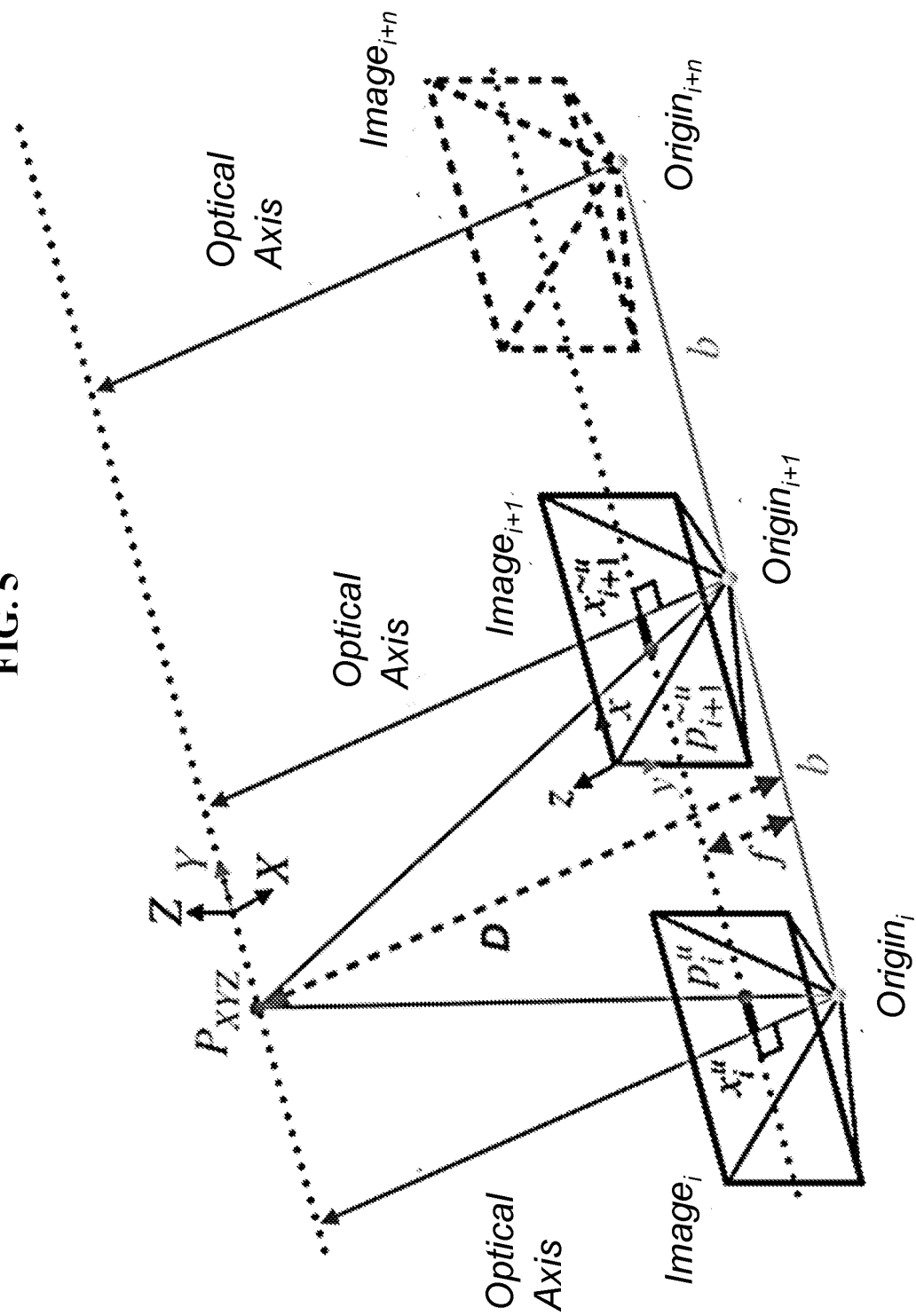


FIG. 6A

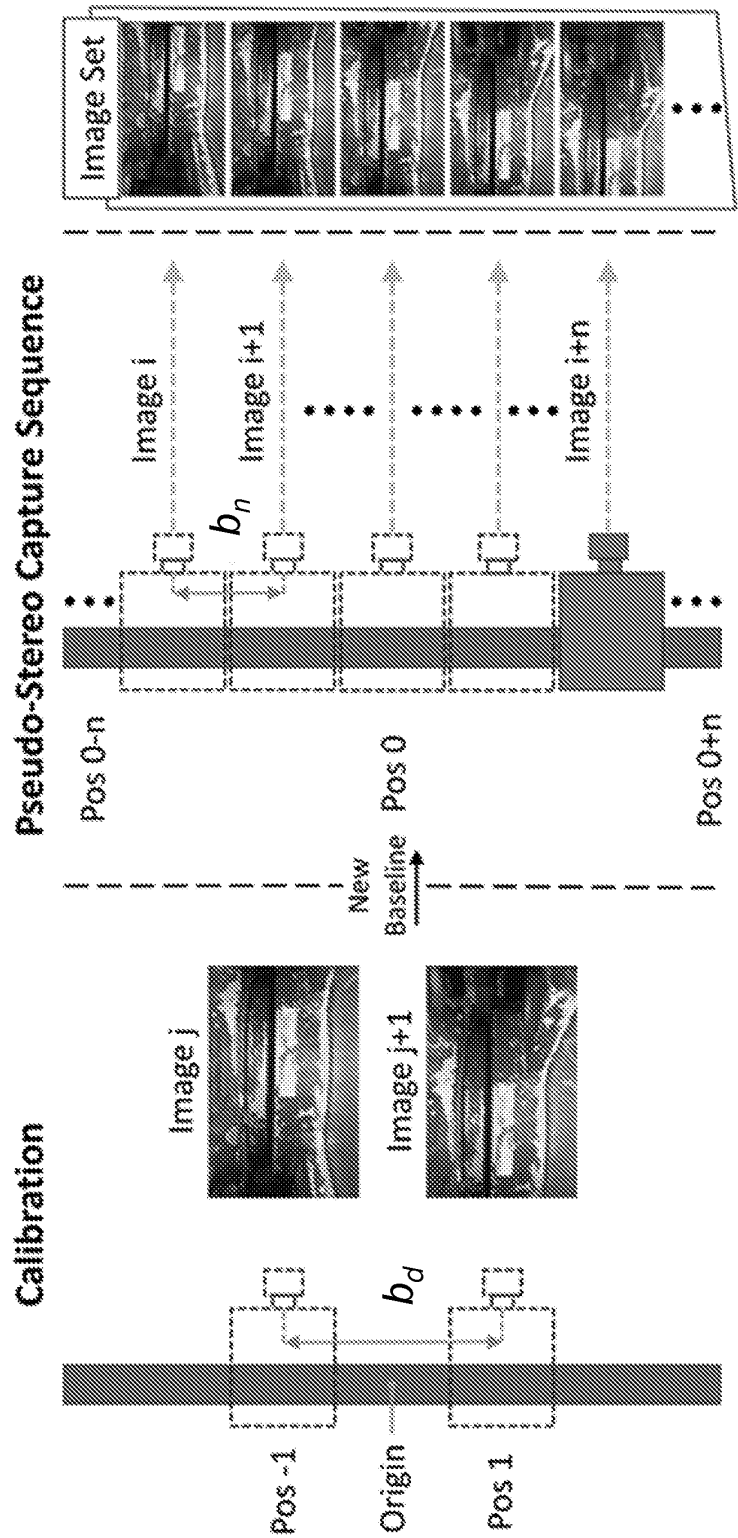


FIG. 6B

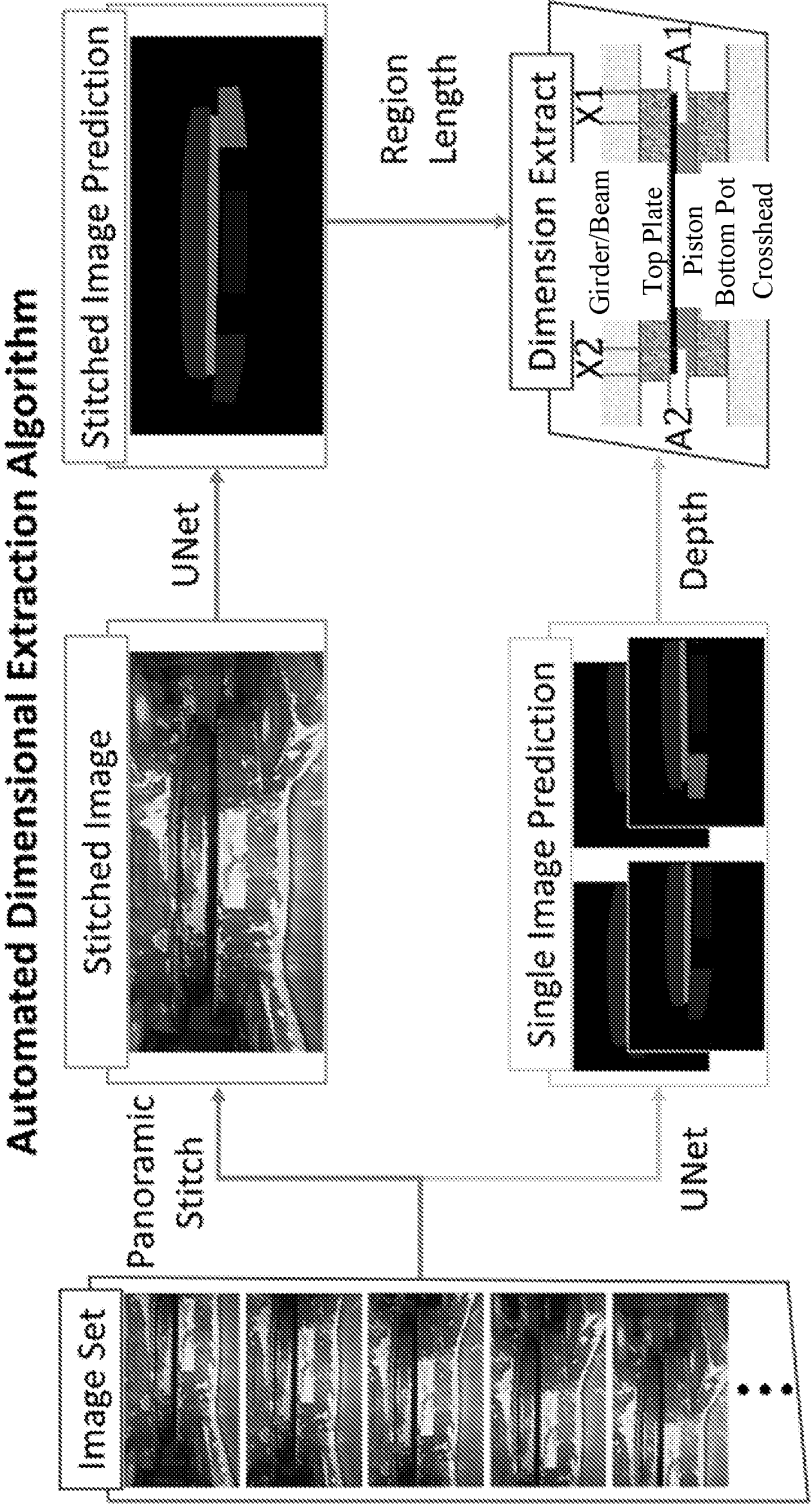


FIG. 7A

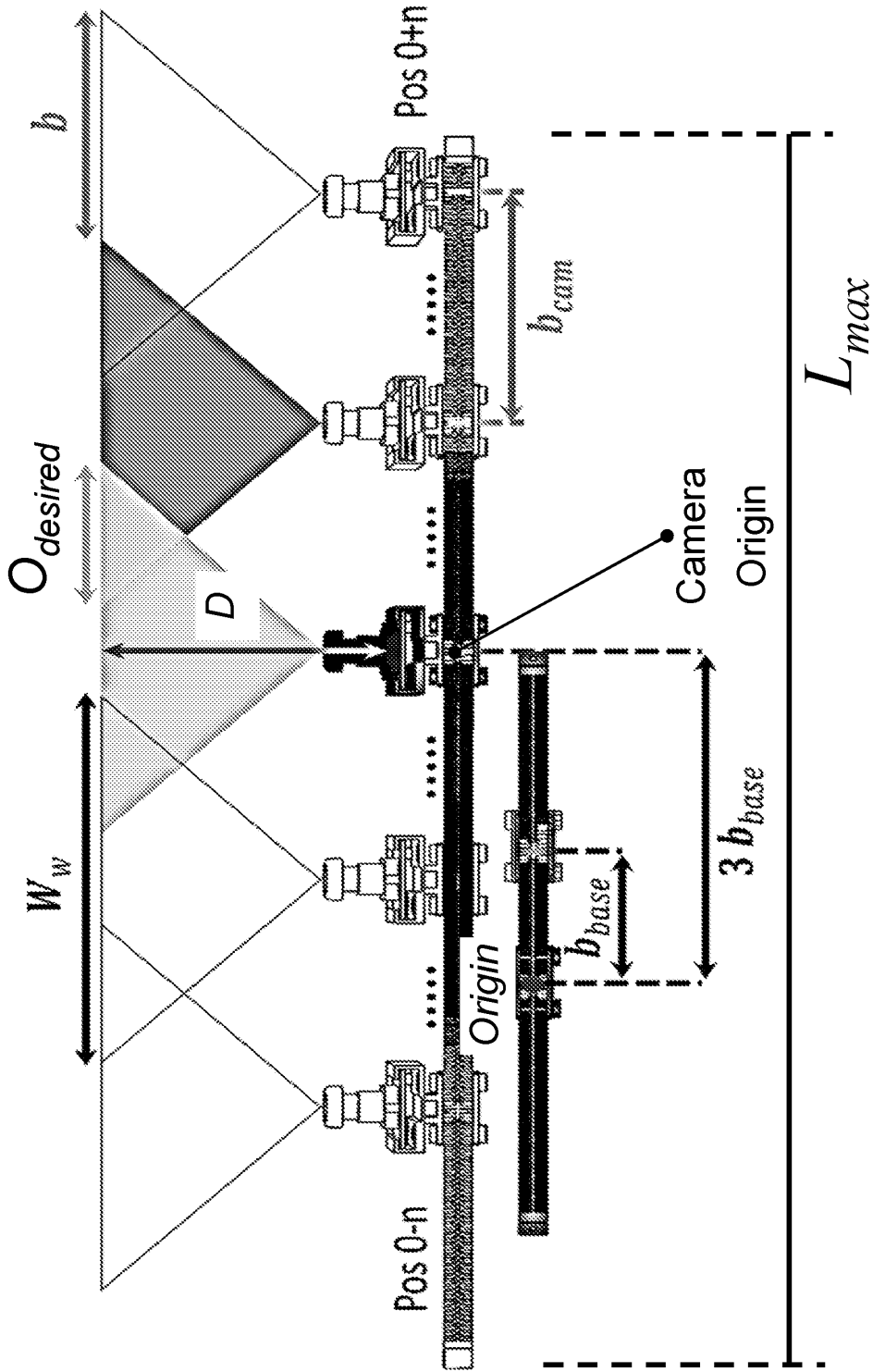


FIG. 7B

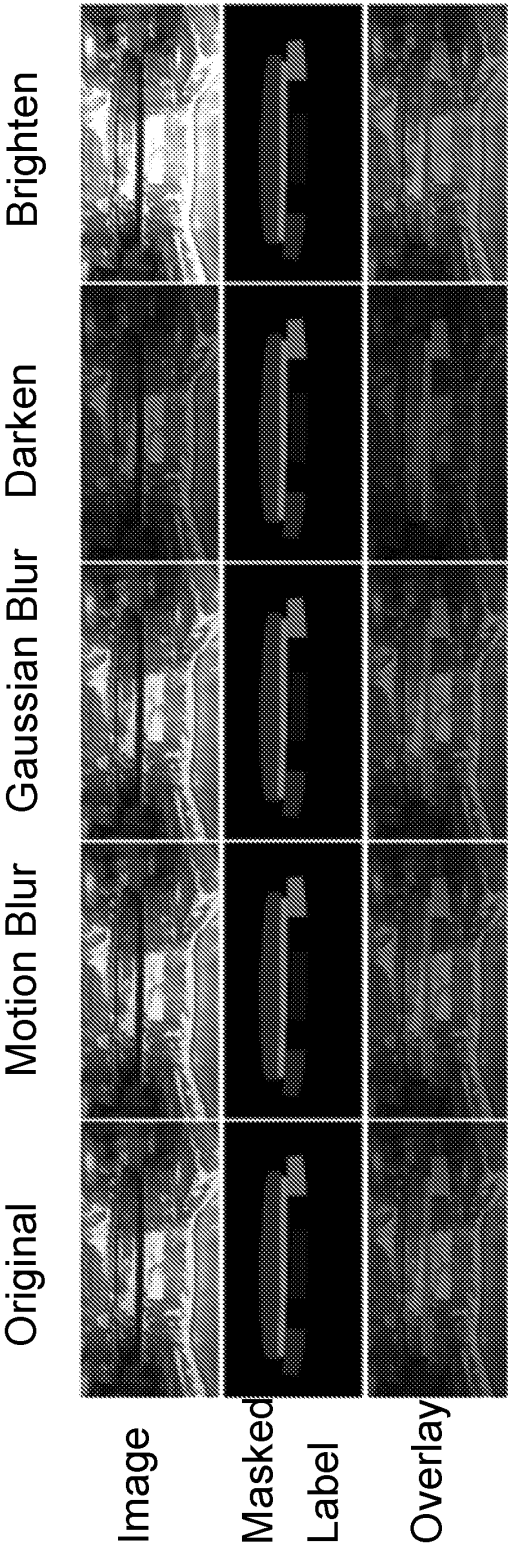


FIG. 8

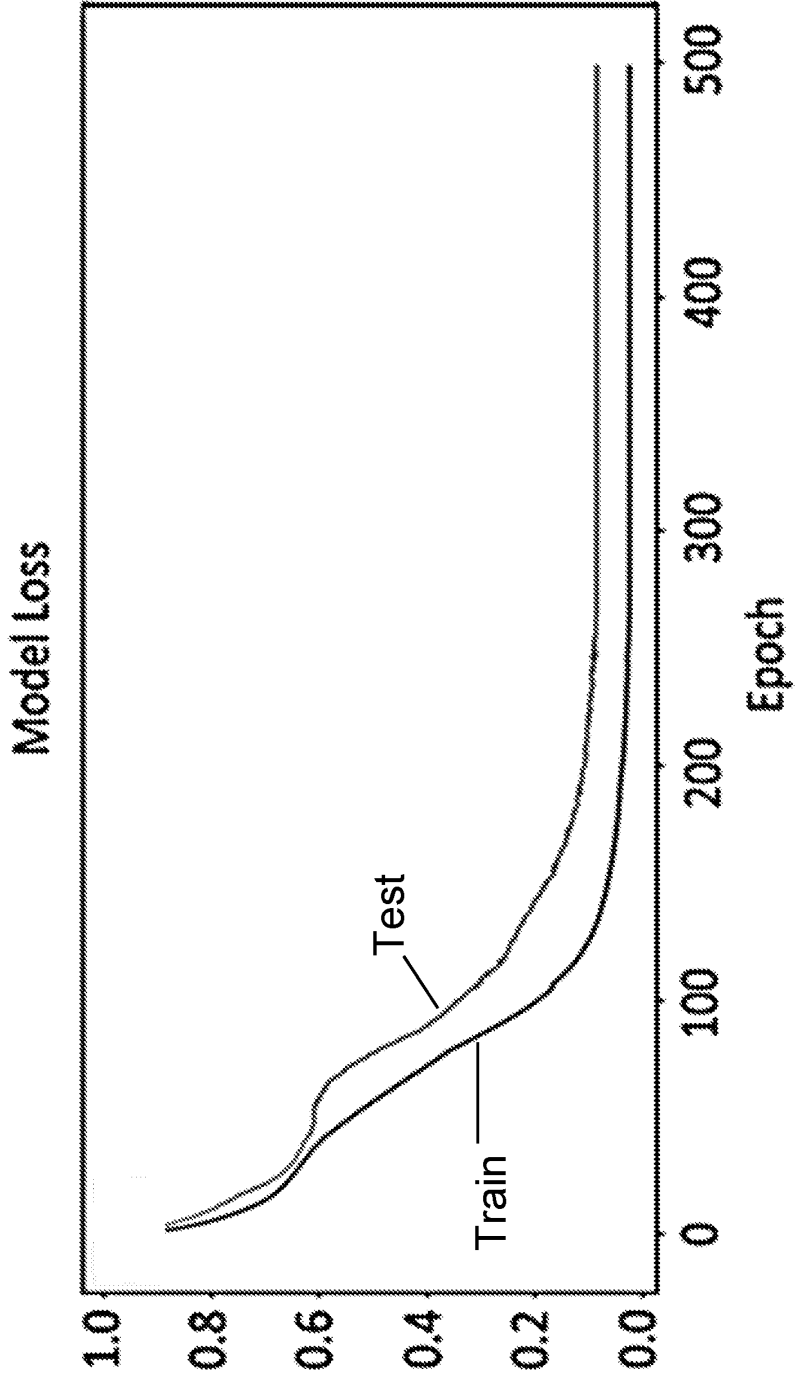


FIG. 9

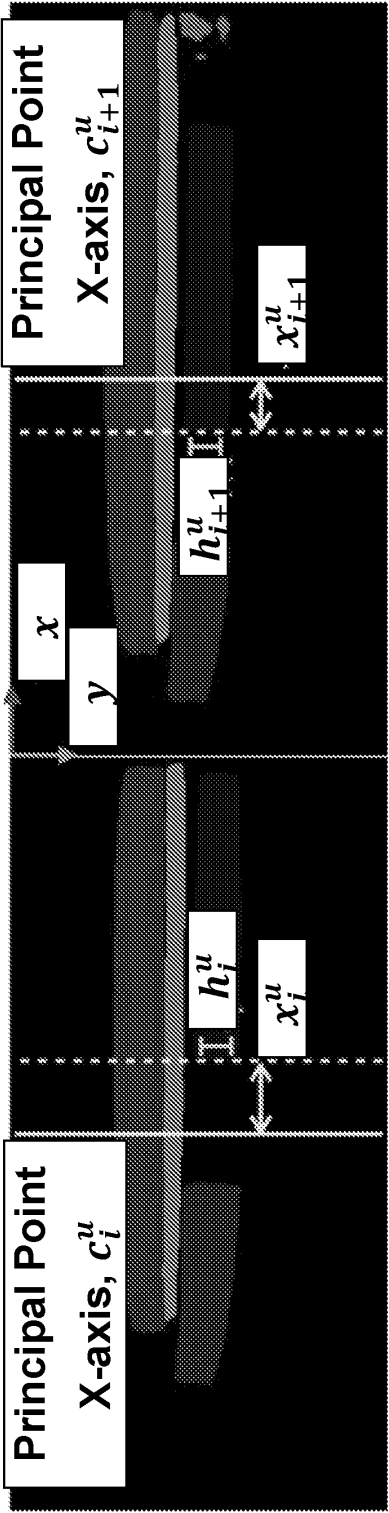


FIG. 10

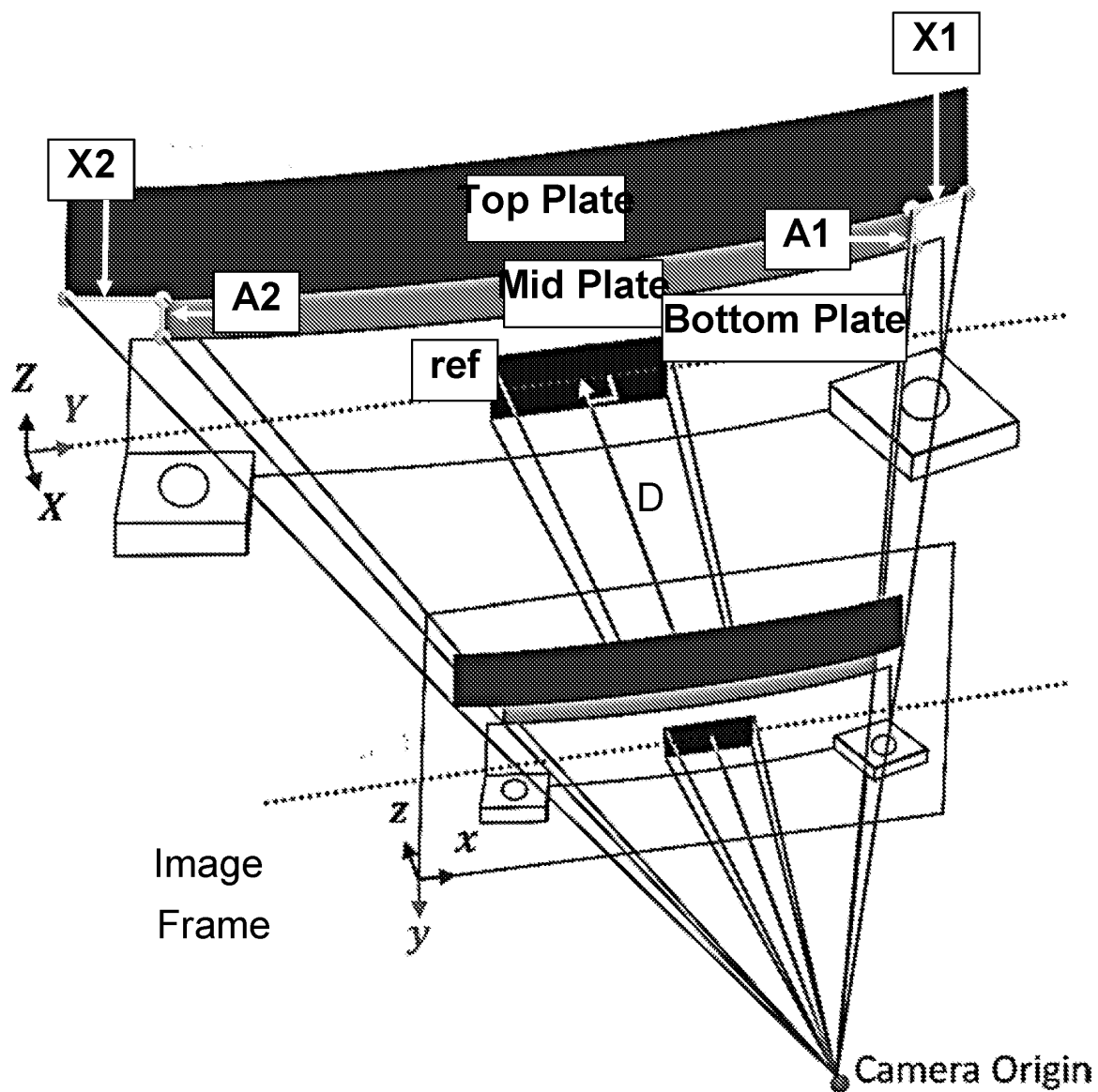


FIG. 11A

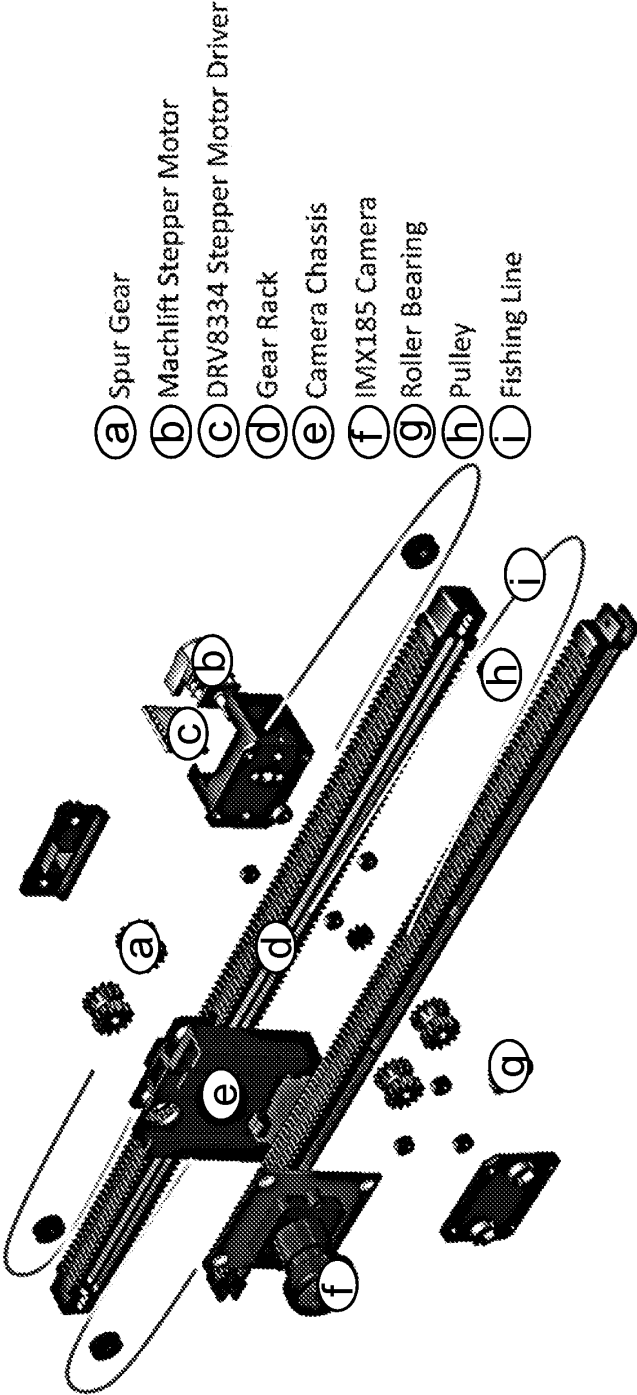


FIG. 11B

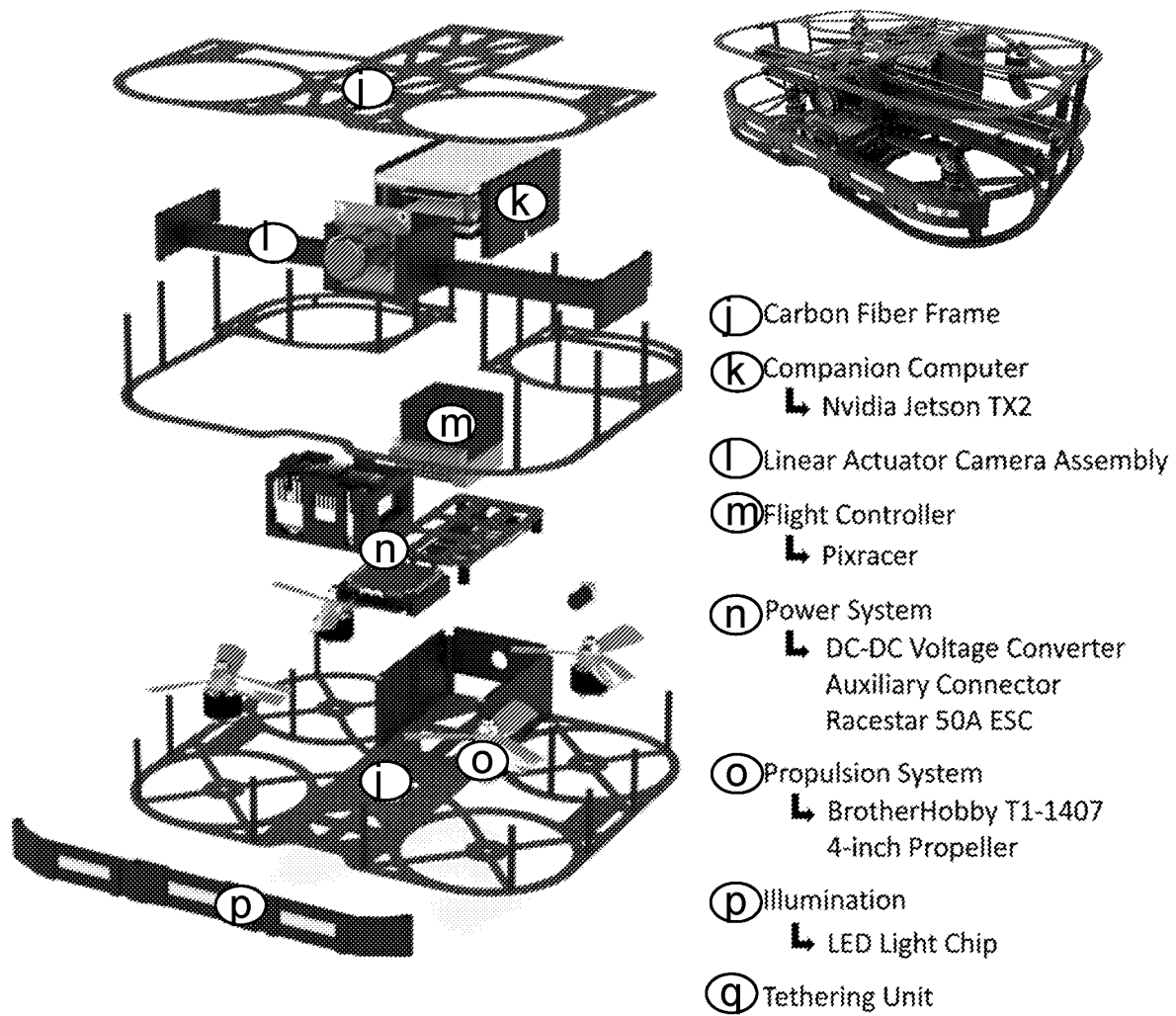


FIG. 11C

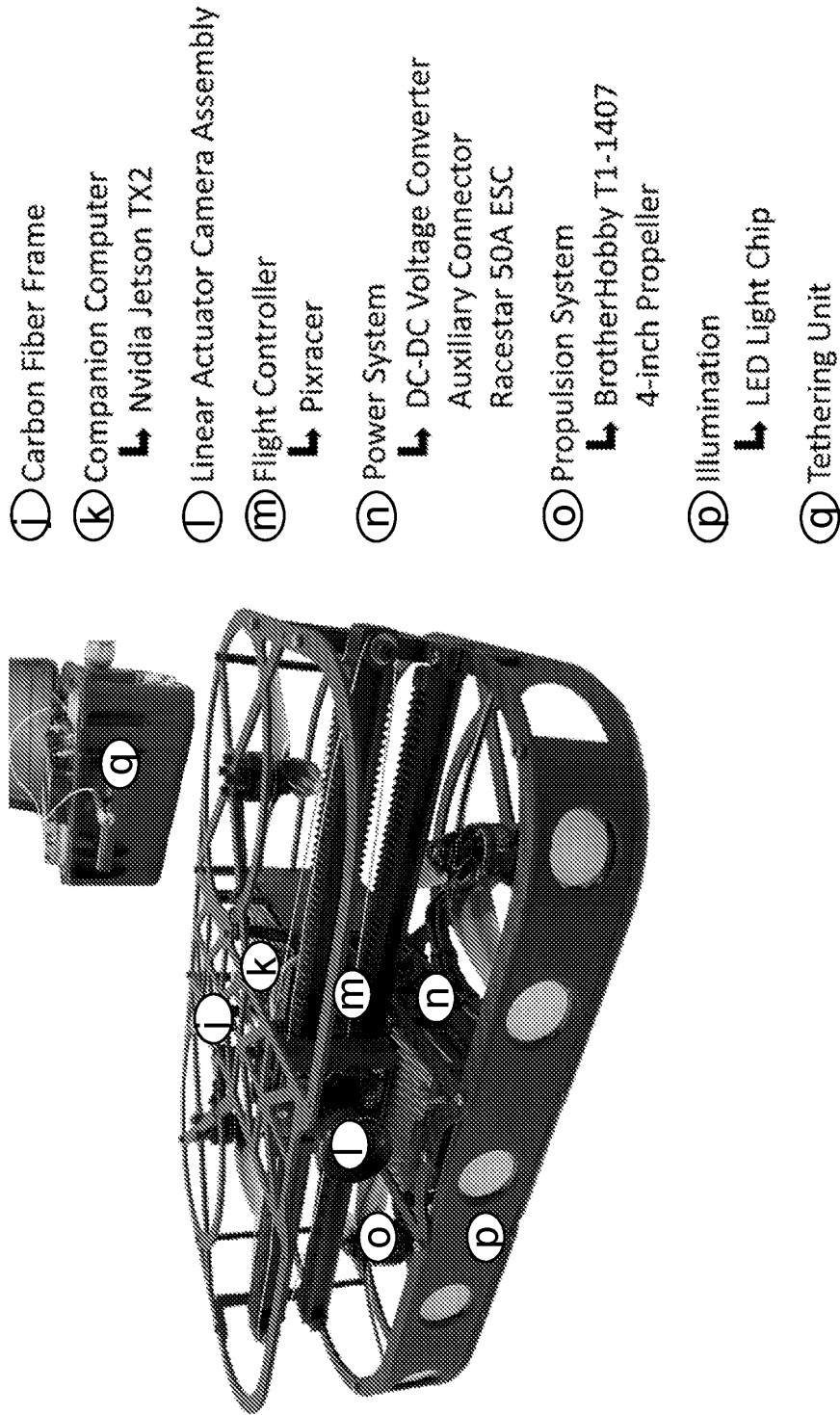


FIG. 11D

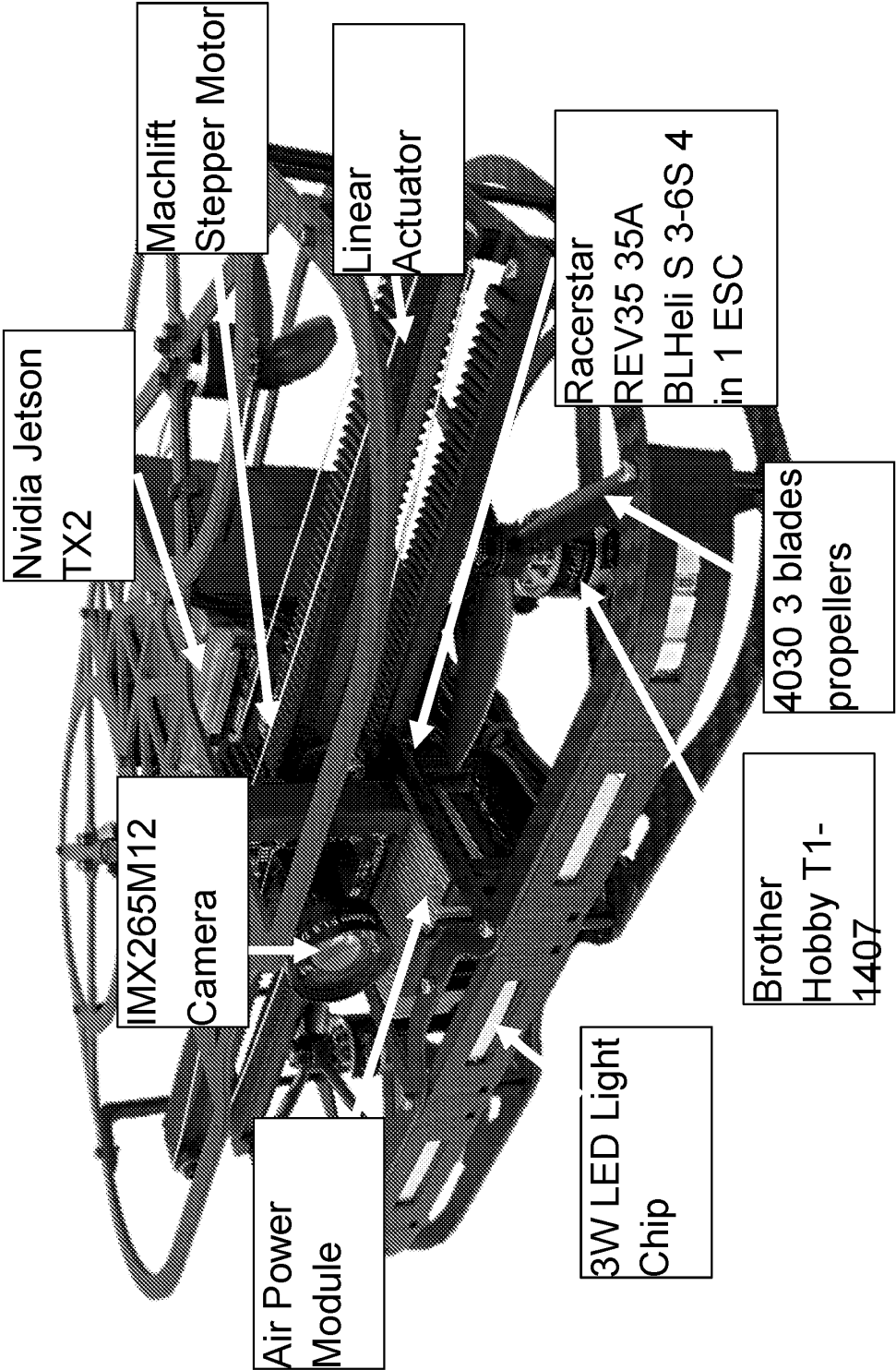


FIG. 11E

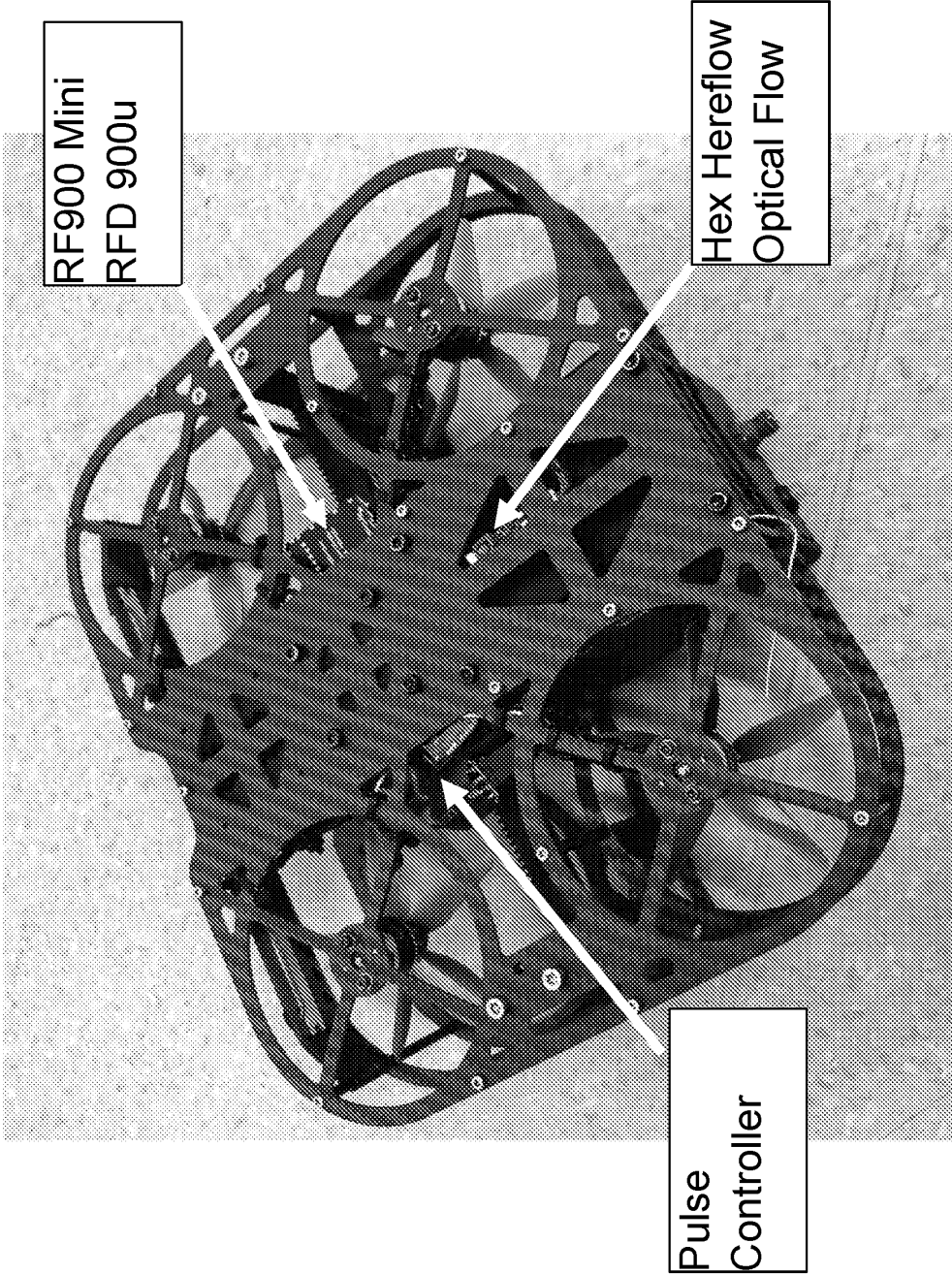


FIG. 12

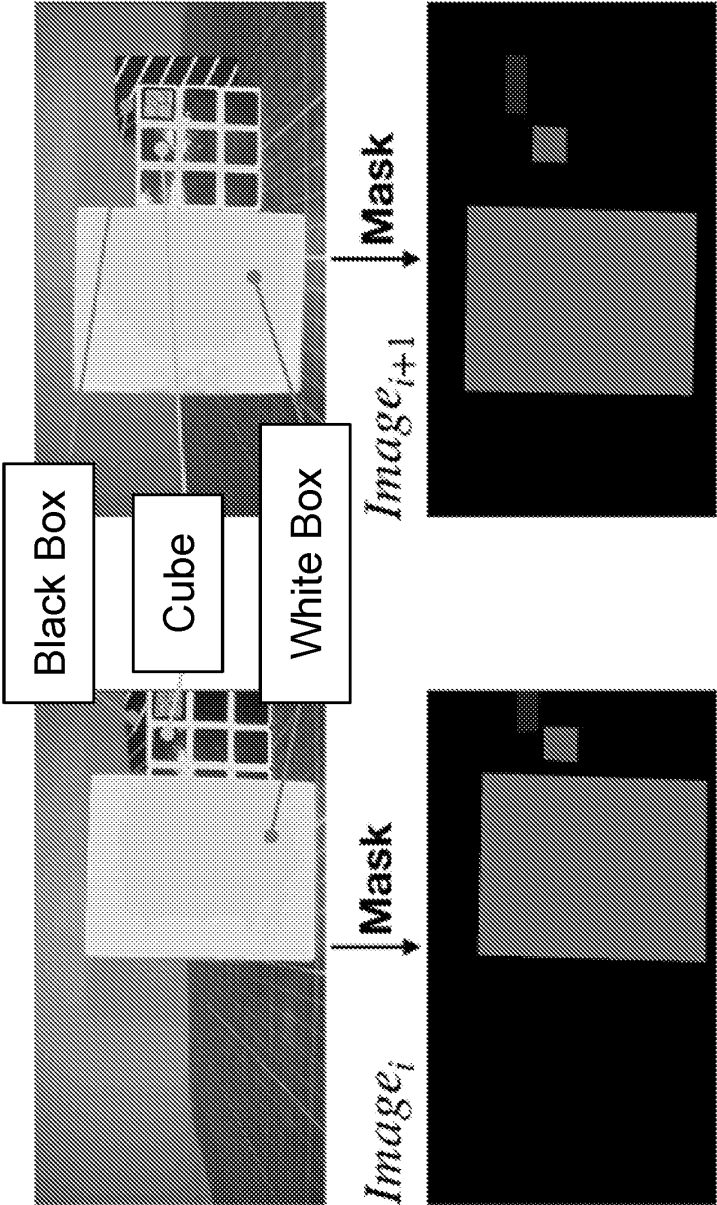
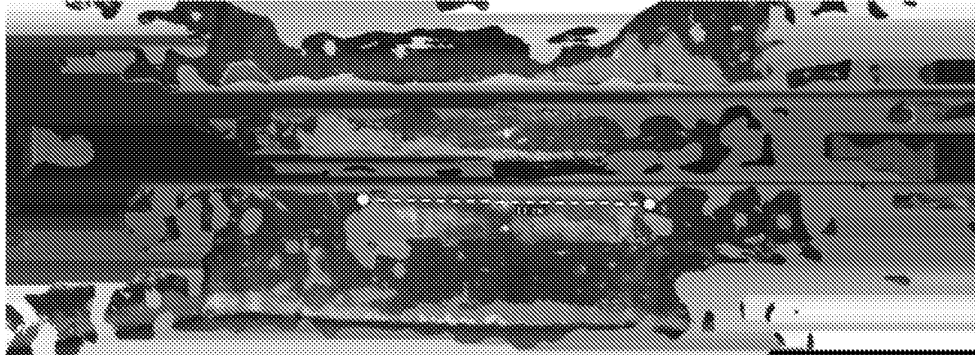


FIG. 13

Depth map generated by Intel Realsense 435i (Depth 300mm)



Stitched image generated by proposed algorithm (Depth 170mm)

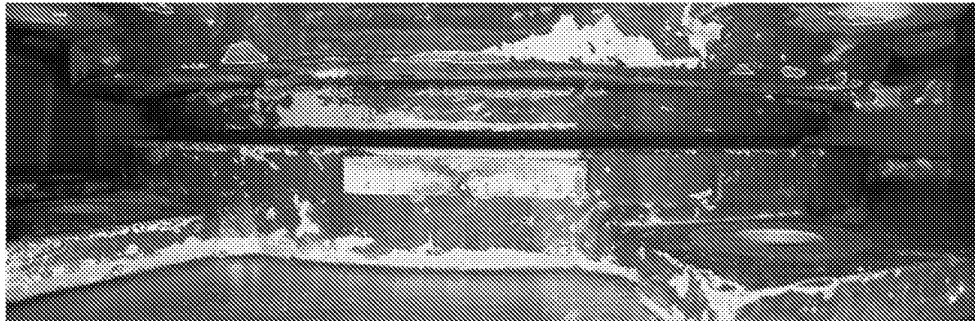


FIG. 14

