

Abstract

Care Robot

A care robot (1) is provided with a base (10), and a pair of underarm holding
5 sections (65a and 65b) provided on the base (10) and capable of holding the
underarms of a care receiver (M1), and the care robot assists the care receiver
(M1) to stand up or sit down. Further, the pair of underarm holding sections (65a
and 65b) are provided to be swingable around a fulcrum (C) provided further
away from the care receiver (M1) than portions (S) that hold at least the
10 underarms of the care receiver (M1).

(Fig. 6B)