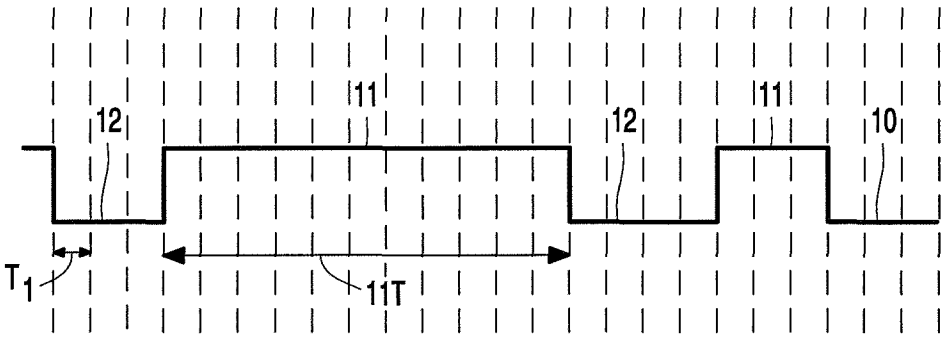


FIG. 1a

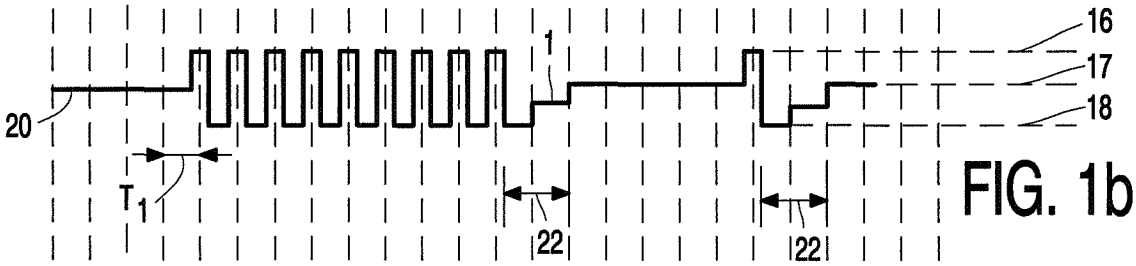


FIG. 1b

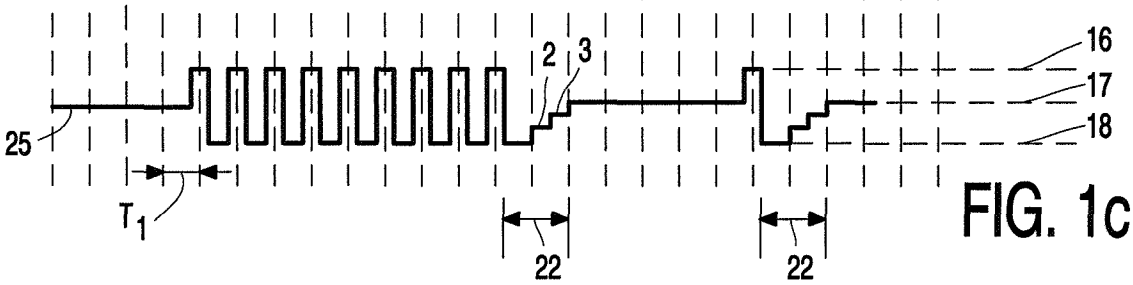


FIG. 1c

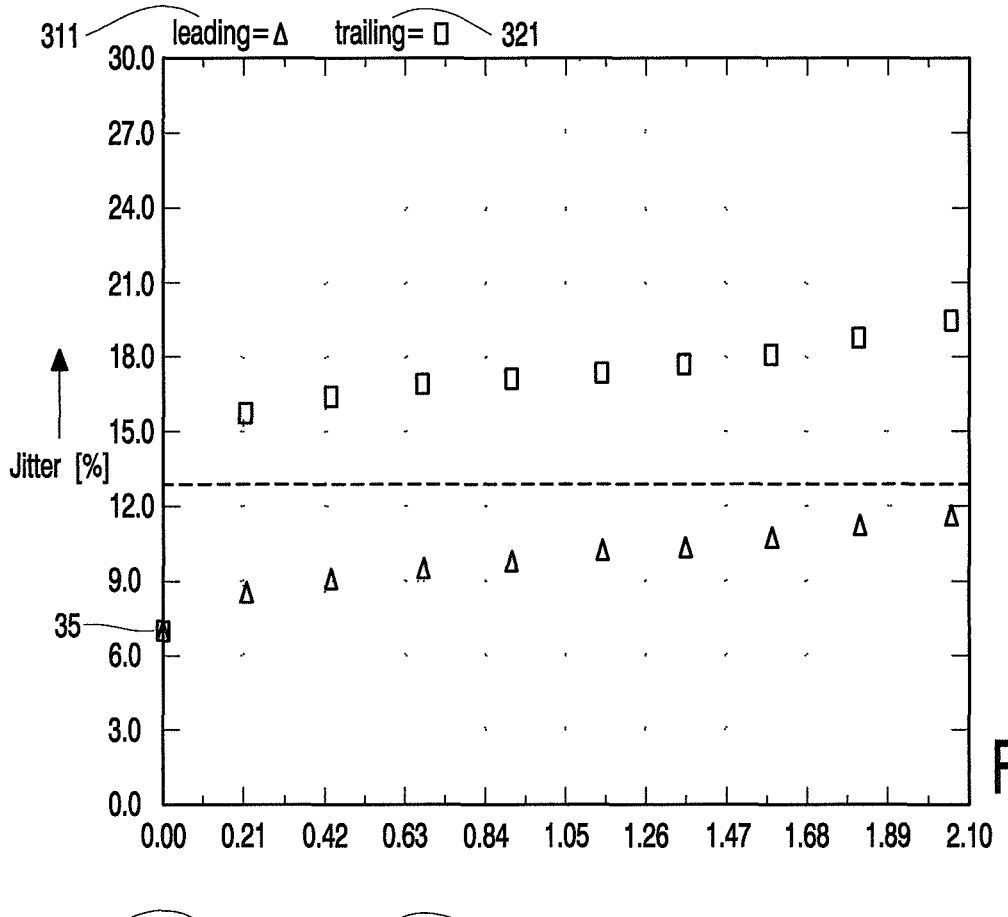

311
leading=Δ
trailing=□
321
30.0
27.0
24.0
21.0
18.0
15.0
12.0
9.0
6.0
3.0
0.0
Jitter [%]
35
0.00
0.21
0.42
0.63
0.84
1.05
1.26
1.47
1.68
1.89
2.10
P_c [mW]

FIG. 2

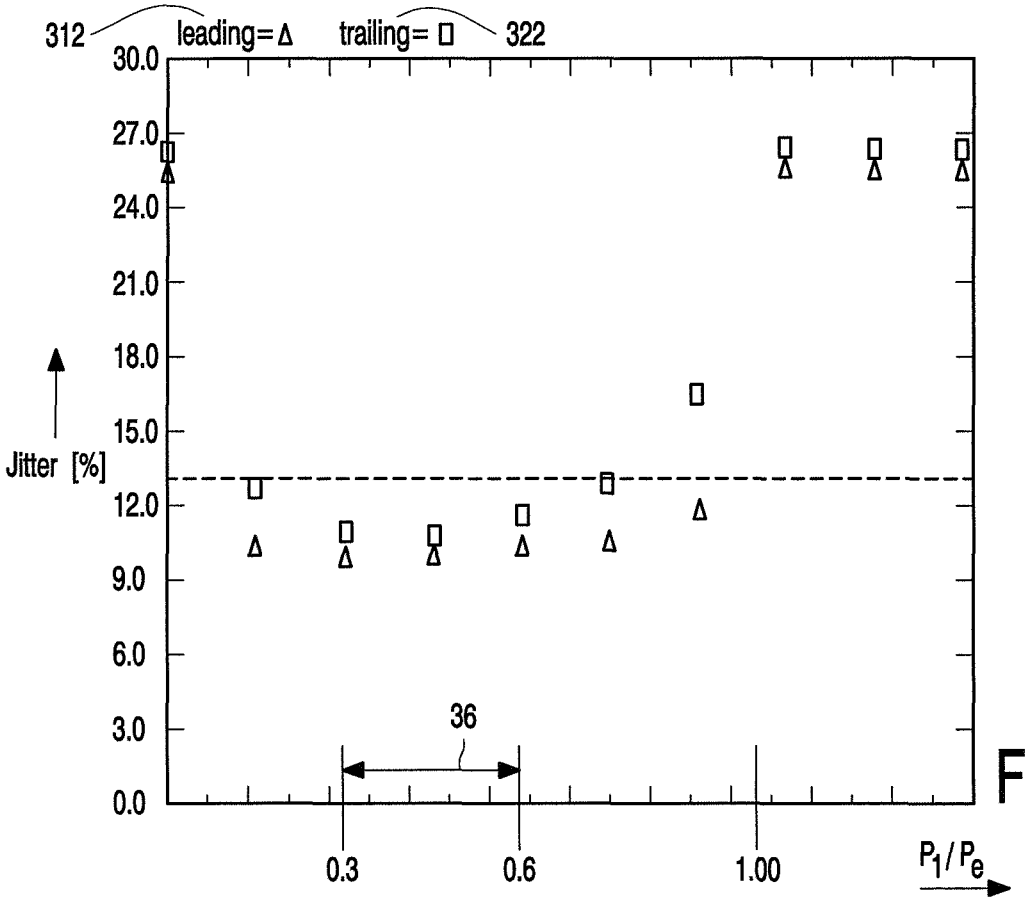

312
leading=Δ
trailing=□
322
30.0
27.0
24.0
21.0
18.0
15.0
12.0
9.0
6.0
3.0
0.0
Jitter [%]
36
0.3
0.6
1.00
P_1/P_e

FIG. 3

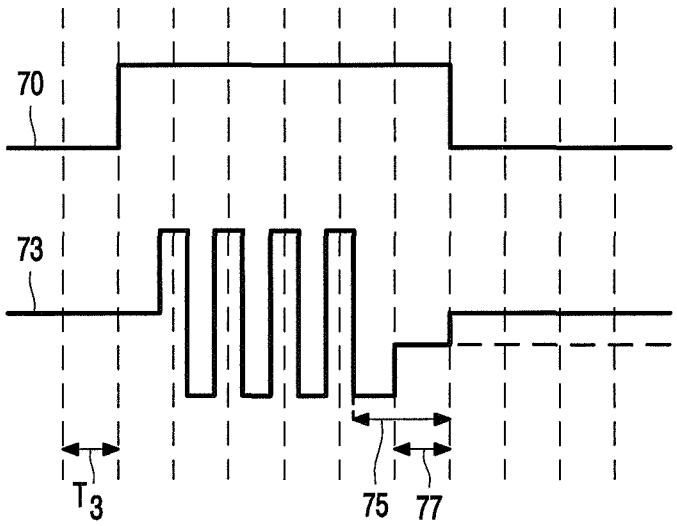


FIG. 4a

FIG. 4b

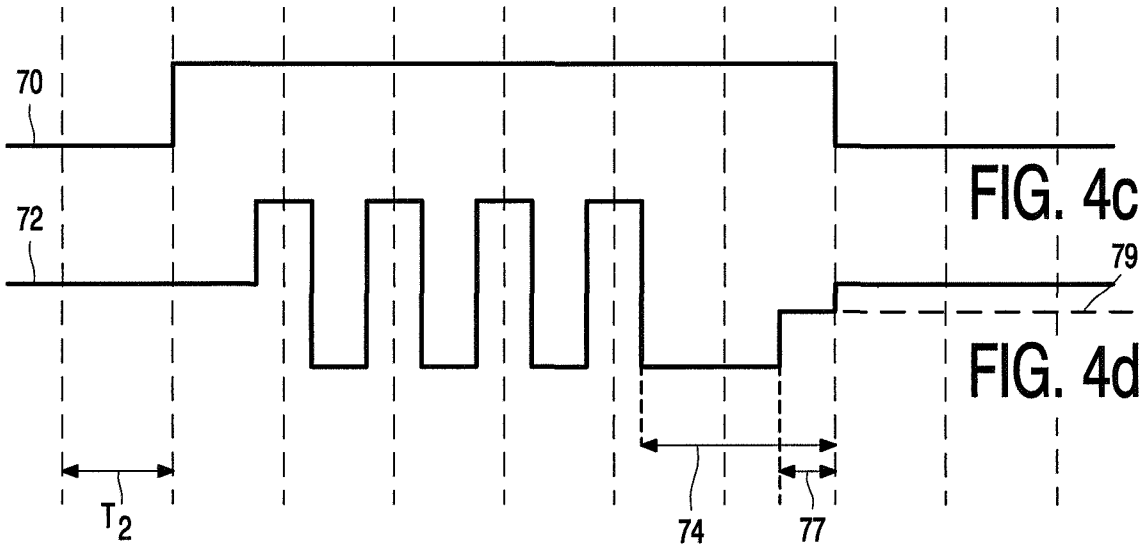


FIG. 4c

FIG. 4d

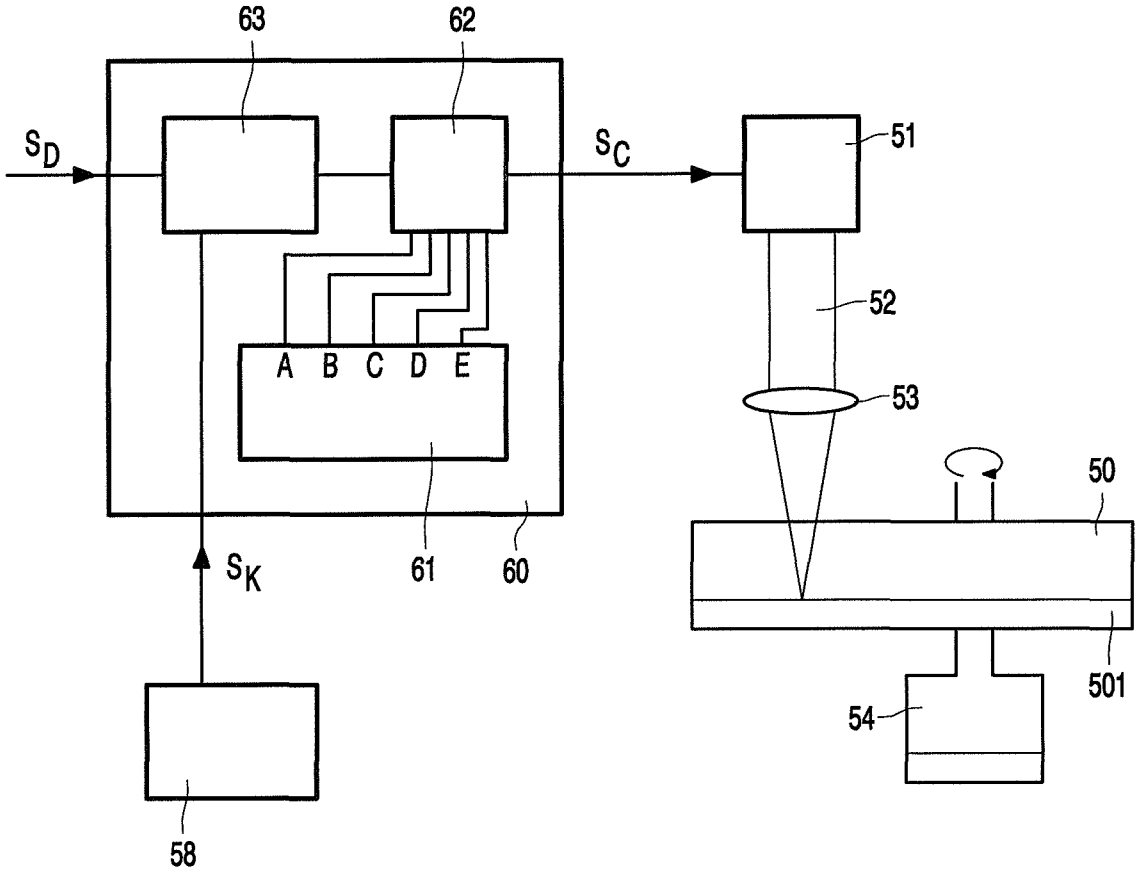


FIG. 5