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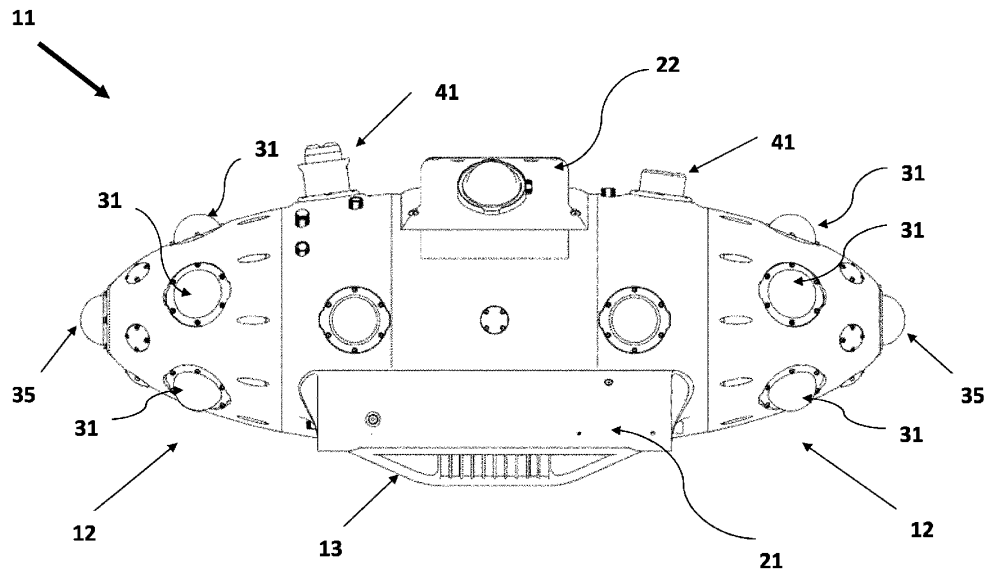


FIGURE1

(57) Abstract: An underwater probe (11), comprises a submersible body having an elongated body with a hydrodynamic effective shape for travel in at least one longitudinal direction. There is a power system including two longitudinal side thrusters (21) for allowing the controllable driving of the submersible body in the at least one longitudinal direction and a top thruster (22) for allowing manoeuvring in a lateral plane to the longitudinal axis E-E. Also there is a visual image capture system including a plurality of optical cameras (31, 35) locatable on or at the surface of the elongated body. The probe is modular and has readily connectable and disconnectable modules that can be reconfigured to readily form differing volume and different payload ballast remotely controllable adjustable buoyant probes.

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