

ABSTRACT**TEACHING APPARATUS OF ROBOT AND TEACHING METHOD OF ROBOT**

A teaching method of a robot which supports a transported matter with a hand
5 and transports the transported matter between two or more reception spots, includes: a jig
disposing process of disposing a positioning jig at the reception spot so as to have the
same center axis as the transported matter when the transported matter is placed at the
reception spot; and a teaching process of moving the hand to a position at which an
abutting portion of the hand abuts the positioning jig at each of the reception spots and
10 teaching the position of the hand to a controller.

Figure 4