

Abstract

The present invention provides a facial acupoint locating method, an acupuncture method, an acupuncture robot, and a storage medium. The facial acupoint locating method includes: collecting an RGB image and a depth image of a face by using a depth
5 camera, and generating three-dimensional point cloud data of the face based on the RGB image and the depth image; inputting the three-dimensional point cloud data of the face into a trained face segmentation model to obtain a plurality of facial feature regions, where the plurality of the facial feature regions include eyebrow regions, eye regions, a nose region, and a mouth region; and acquiring an association relationship between the
10 plurality of the facial feature regions and key acupoint points, and determining locations of the facial acupoints based on the association relationship and the plurality of the facial feature regions.

[FIG. 1]