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(54) Title: AN INTEGRATED MOBILE MANIPULATOR ROBOT WITH ACCESSORY INTERFACES

(57) Abstract: A robot comprises a mobile base, a robotic arm operatively coupled to the mobile base, and at least one interface configured to enable selective coupling to at least one accessory. The at least one interface comprises an electrical interface configured to transmit power and/or data between the robot and the at least one accessory, and a mechanical interface configured to enable physical coupling between the robot and the at least one accessory.

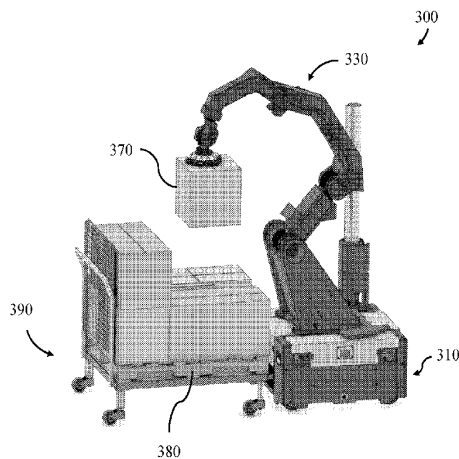


FIG. 3B

WO 2022/204026 A1

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