[CLAIMS]

~~[Claim 1]~~

~~A remote operation device for remotely operating a transport vehicle, the remote operation device comprising:~~

~~a first operation unit; and~~

~~a control unit configured to wirelessly transmit a command signal for causing the transport vehicle to travel a prescribed distance to the transport vehicle every time the first operation unit is operated.~~

~~[Claim 2]~~

~~The remote operation device according to claim 1,~~

~~wherein the first operation unit includes:~~

~~a forward movement operation unit; and~~

~~a backward movement operation unit, and~~

~~the control unit wirelessly transmits a first command signal for causing the transport vehicle to move a first distance forward to the transport vehicle every time the forward movement operation unit is operated, and wirelessly transmits a second command signal for causing the transport vehicle to move a second distance backward to the transport vehicle every time the backward movement operation unit is operated.~~

~~[Claim 3]~~

~~The remote operation device according to claim 2, further comprising:~~

~~a second operation unit configured to be able to adjust at least one of the first distance and the second distance.~~

[Claim 4<u>1</u>]

A remote operation system comprising:

a remote operation device configured to remotely operate a transport vehicle; ~~and~~

a control device mounted in the transport vehicle and configured to control traveling of the transport vehicle according to wireless communication with the remote operation device<u>; and</u>

a measurement device configured to measure a weight of a transport target object that is transported by the transport vehicle,

wherein the remote operation device includes:

a first operation unit; and

a control unit configured to wirelessly transmit a command signal for causing the transport vehicle to travel a prescribed distance to the transport vehicle every time the first operation unit is operated, ~~and~~

the control device includes an actuator and a control unit,

when the control unit has received the command signal ~~has been received~~ from the remote operation device according to the wireless communication and the actuator has acquired a control signal output from the control unit, the actuator~~control device causes the transport vehicle to be stopped by~~ is configured to operate~~ing~~ a brake of the transport vehicle when a prescribed time period has elapsed after the actuator operates an accelerator of the transport vehicle ~~was operated~~ by a prescribed amount, to stop the transport vehicle, and

the control device is configured to receive information about the weight measured by the measurement device according to communication, and adjust at least one of the prescribed amount and the prescribed time period on the basis of the weight that has been received.

[Claim ~~5~~2]

The remote operation system according to claim 41,

wherein the remote operation device further includes:

a second operation unit configured to adjust the prescribed distance,

the control unit is configured to wirelessly transmit~~s~~ an operation signal based on an operation on the second operation unit to the control device, and

when the operation signal has been received from the remote operation device according to the wireless communication, the control device is configured to adjust~~s~~ at least one of the prescribed amount and the prescribed time period in accordance with the operation signal.

~~[Claim 6]~~

~~The remote operation system according to claim 4, further comprising:~~

~~a measurement device configured to measure a weight of a transport target object that is transported by the transport vehicle,~~

~~wherein the control device receives information about the weight measured by the measurement device according to communication, and adjusts at least one of the prescribed amount and the prescribed time period on the basis of the weight that has been received.~~