

ABSTRACT

ASSISTING ROBOT

An assisting robot (1) that can suppress discomfort to
5 a care receiver (M) during a standing-assistance operation is
provided. A control device (80) for the assisting robot (1)
executes a first operation that coordinates lowering of an
elevator (30) and forward rotation of an arm (40) for at least
a part of a period from when the care receiver (M) is in an
10 initial sitting posture to an intermediate posture. The
control device (80) executes a second operation that raises
the elevator (30) during a period from time of the intermediate
posture to time of a standing posture.

15 (Fig.3)